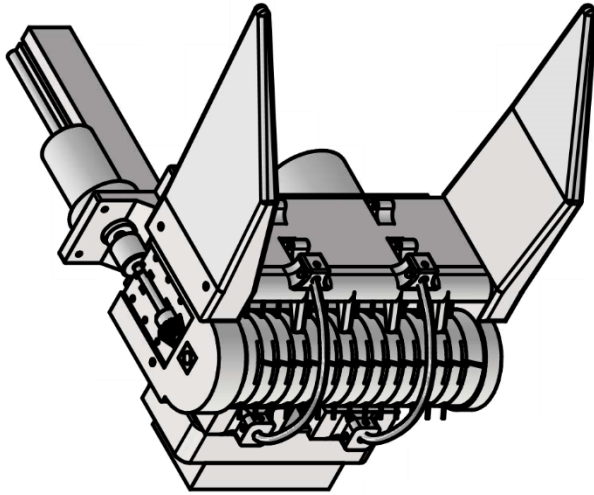
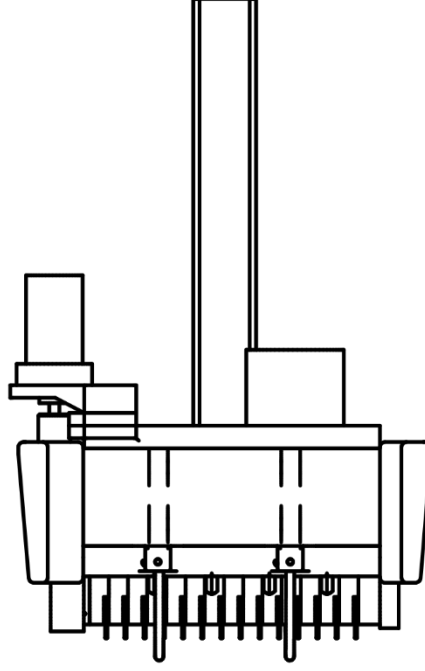
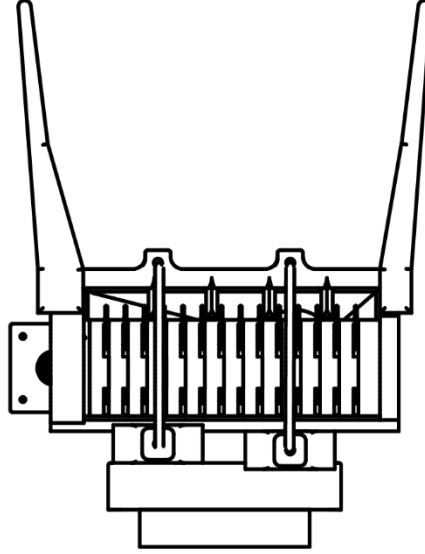
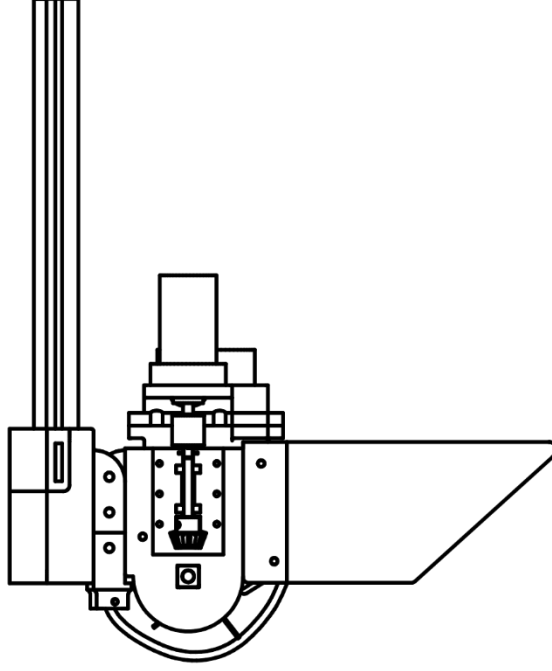


APPENDICES

A. SUPPLEMENTARY INFORMATION (Detail Drawings)



End-Effector Assembly



UNIVERSITY OF
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Thesis Title on:

"Development of a Robotic Cotton Harvesting System Based on the Approach of Harvesting Multiple Cotton Bolls at a Time"

DESIGNED BY: SHEKHAR THAPA

Project Title: End-Effector Assembly

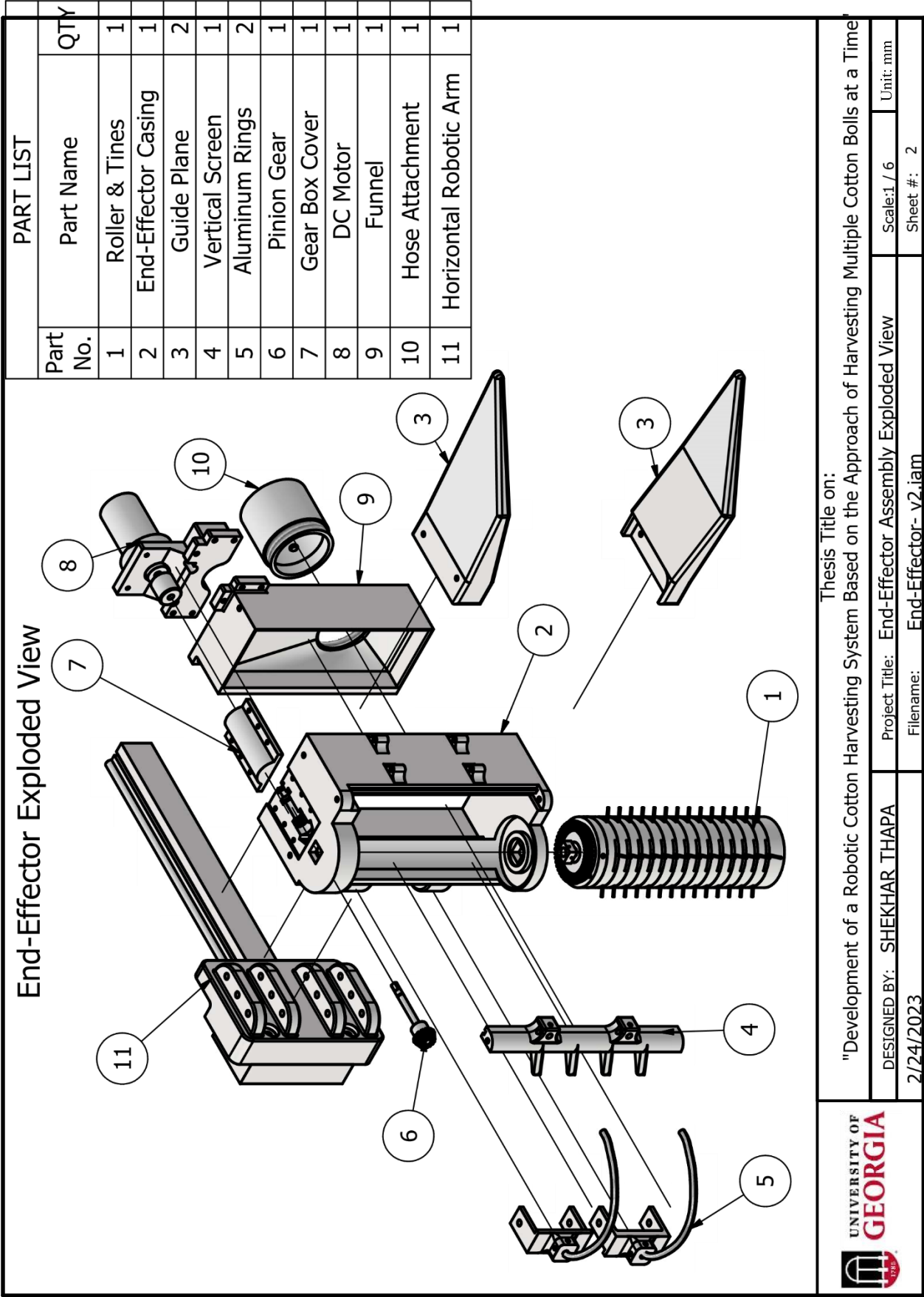
Unit: mm

Scale: 1 / 6

2/24/2023

Filename: End-Effector- v2.iam

Sheet #: 2



Technical drawing of a circular component. The component has a central square hole. A dimension line with arrows at both ends is shown below the component, indicating a diameter of 76.20. The dimension is labeled as $\varnothing 76.20$.

Technical drawing of a 12-pin DIN connector. The drawing shows a side view of the connector with 12 pins. A dimension line at the bottom indicates a length of 244.36.

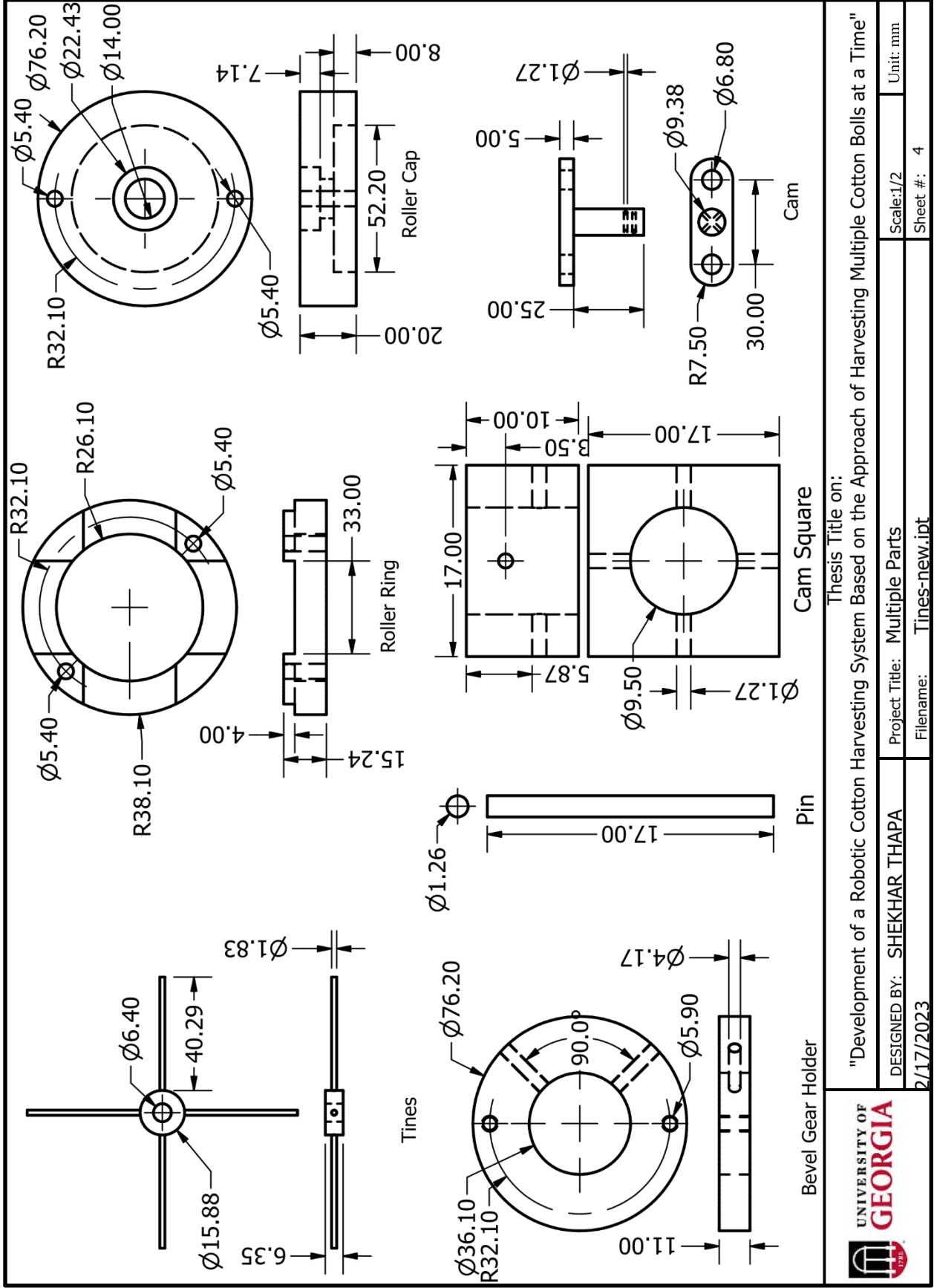
An exploded view diagram of a mechanical assembly. The components are numbered 1 through 10. Component 1 is a long, thin rod. Component 2 is a circular flange with a central hole. Component 3 is a cross-shaped bracket. Component 4 is a long, thin rod. Component 5 is a small cylindrical pin. Component 6 is a circular flange with a central hole. Component 7 is a gear. Component 8 is a small cylindrical pin. Component 9 is a small cylindrical pin. Component 10 is a small cylindrical pin. The diagram shows the assembly sequence: Component 1 is inserted into Component 2. Component 3 is attached to Component 1. Component 4 is inserted into Component 1. Component 5 is inserted into Component 1. Component 6 is attached to Component 1. Component 7 is attached to Component 1. Component 8 is inserted into Component 1. Component 9 is inserted into Component 1. Component 10 is inserted into Component 1.


TABLE		
Part No.	Part Name	QTY
1	Roller Ring	14
2	Roller Cap	1
3	Tines-new	14
4	Cam Rod	1
5	Cam	2
6	Bevel Gear Holder	1
7	Metal Bevel Gear	1
8	Bearing	2
9	Cam Square	2
10	Pin	4

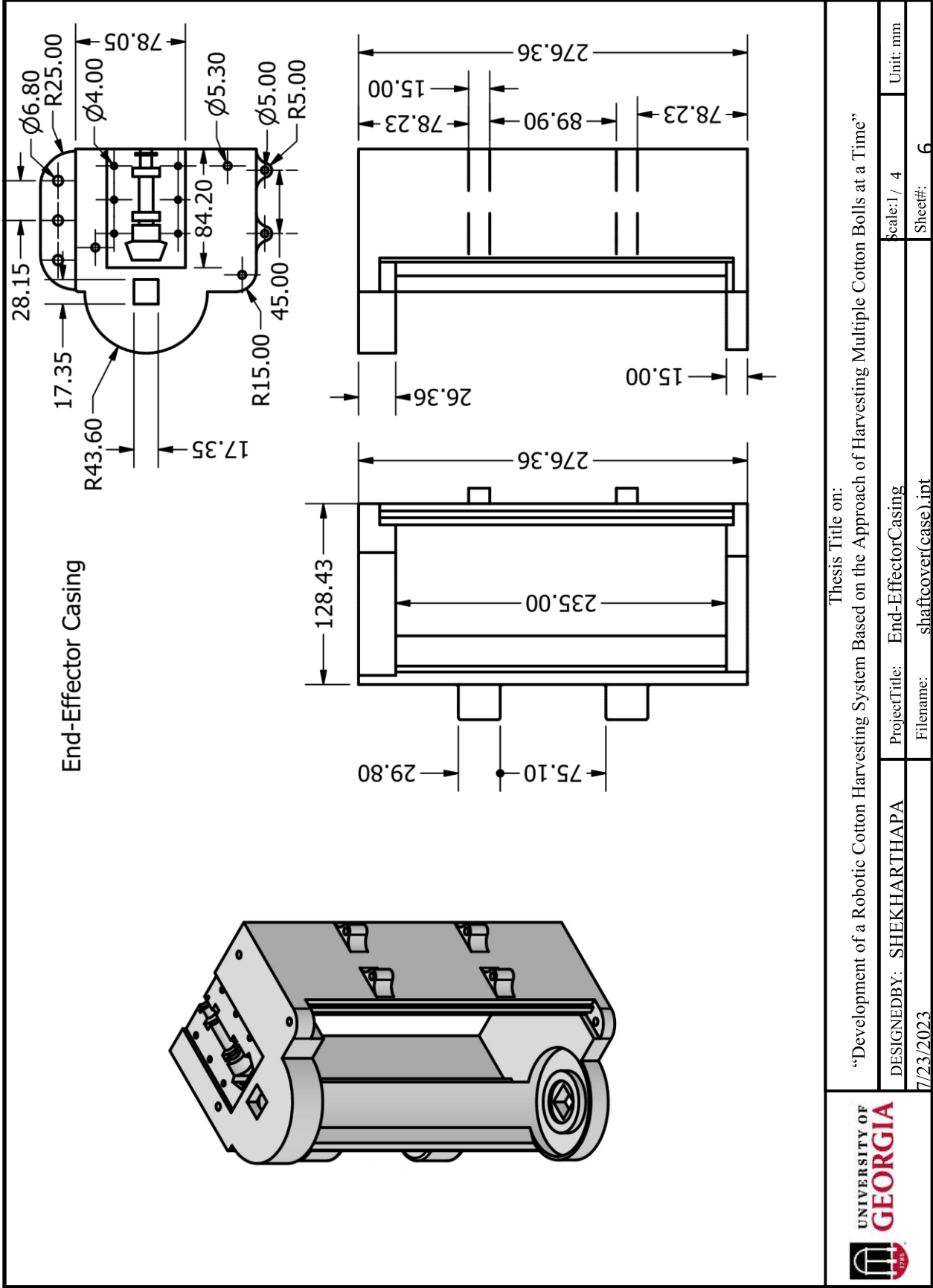
"Development of a Robotic Cotton Harvesting System Based on the Approach of Harvesting Multiple Cotton Bolls at a Time"

Unit: mm

Sheet #: 3



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DESIGNED BY: SHEKHAR THAPA	Project Title: Multiple Parts	Scale: 1/2	Unit: mm
2/17/2023	Filename: Tines-new.ipt	Sheet #: 4	



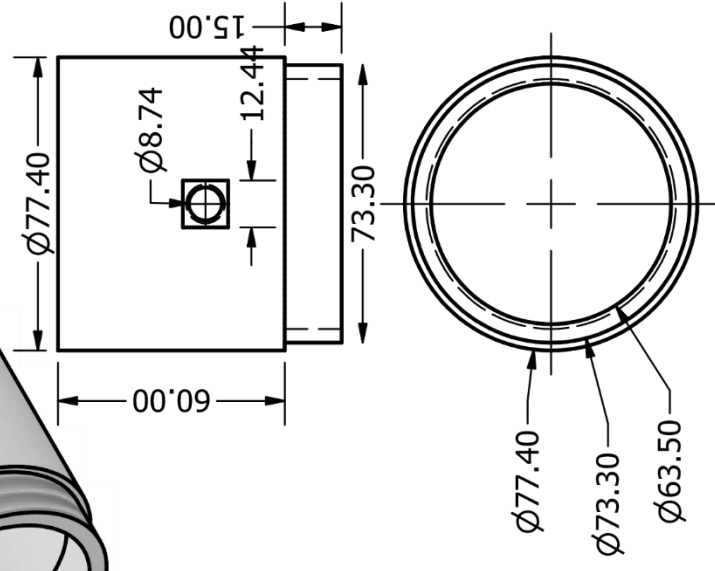
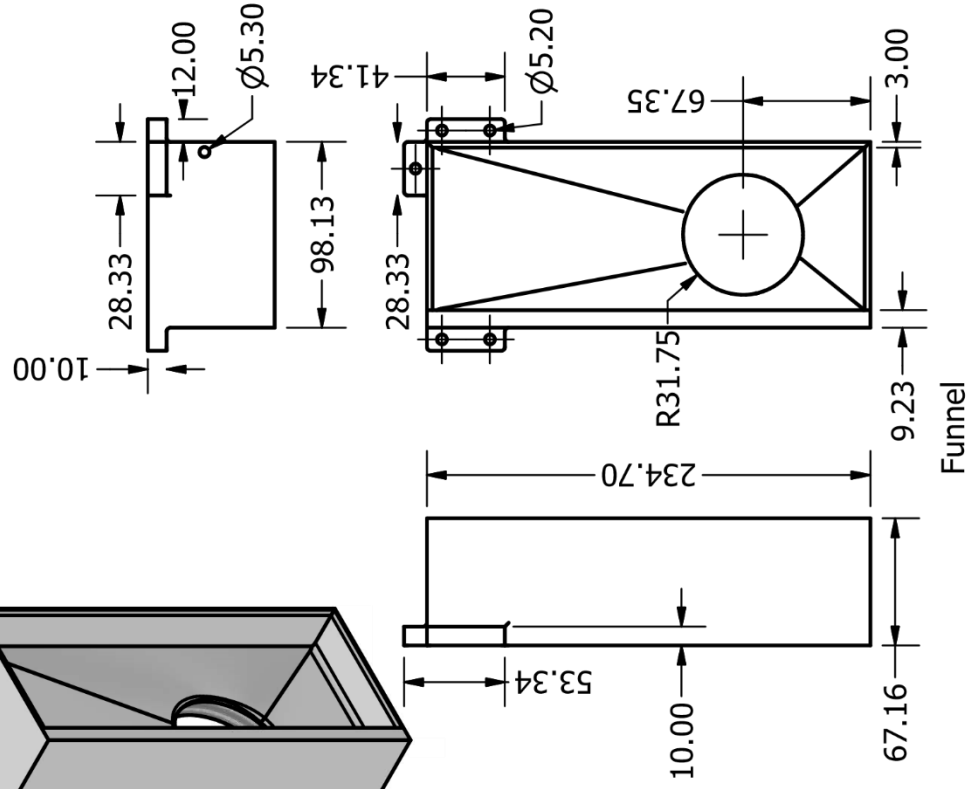
Thesis Title on: "Development of a Robotic Cotton Harvesting System Based on the Approach of Harvesting Multiple Cotton Bolls at a Time"

DESIGNEDBY: SHEKHARTHAPA	ProjectTitle: End-EffectorCasing	Scale: 1 / 4	Unit: mm
7/23/2023	Filename: shaftcover(case).ipt	Sheet#: 6	



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Sheet #: 7



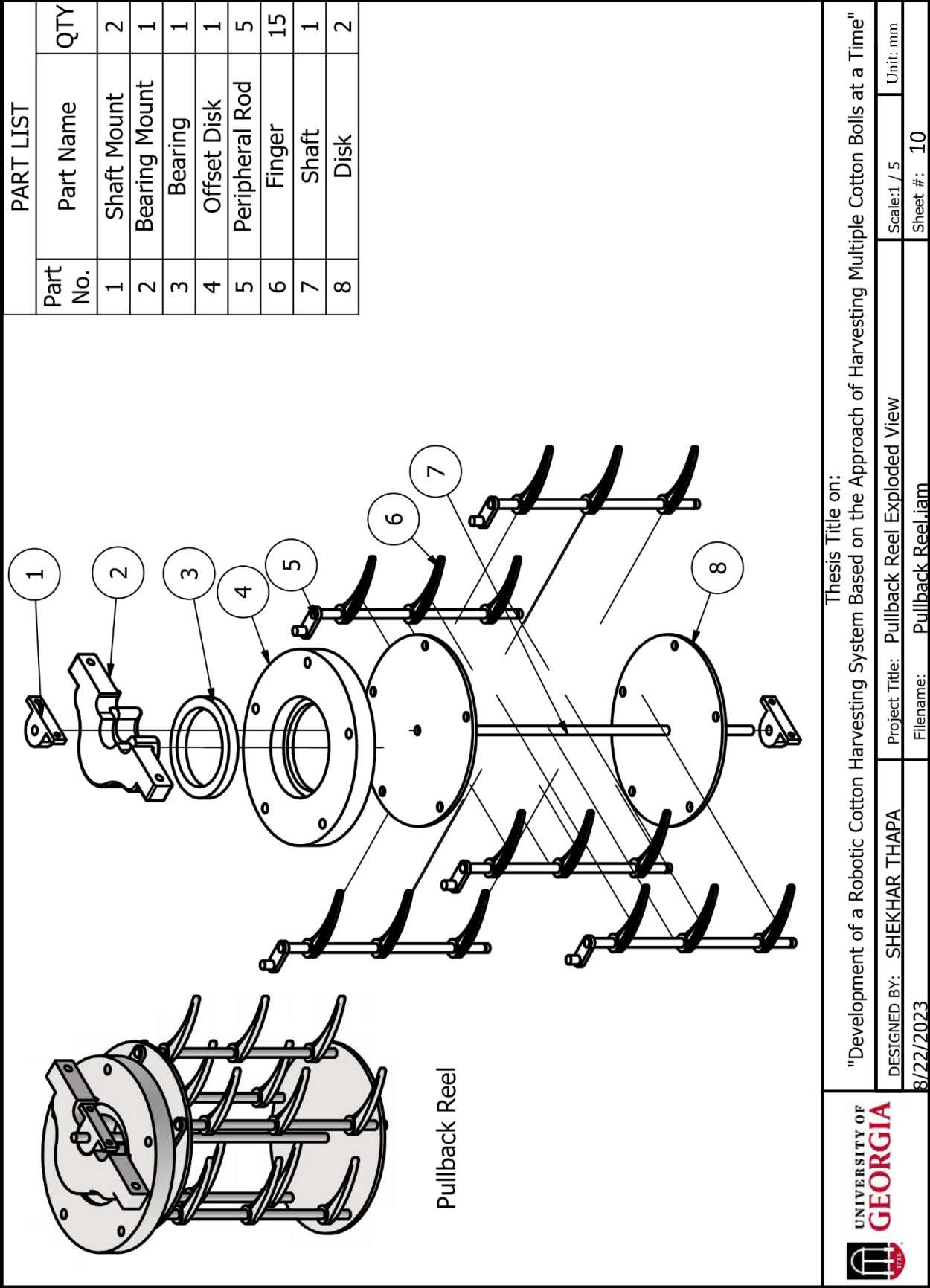
3 in Hose Attachment

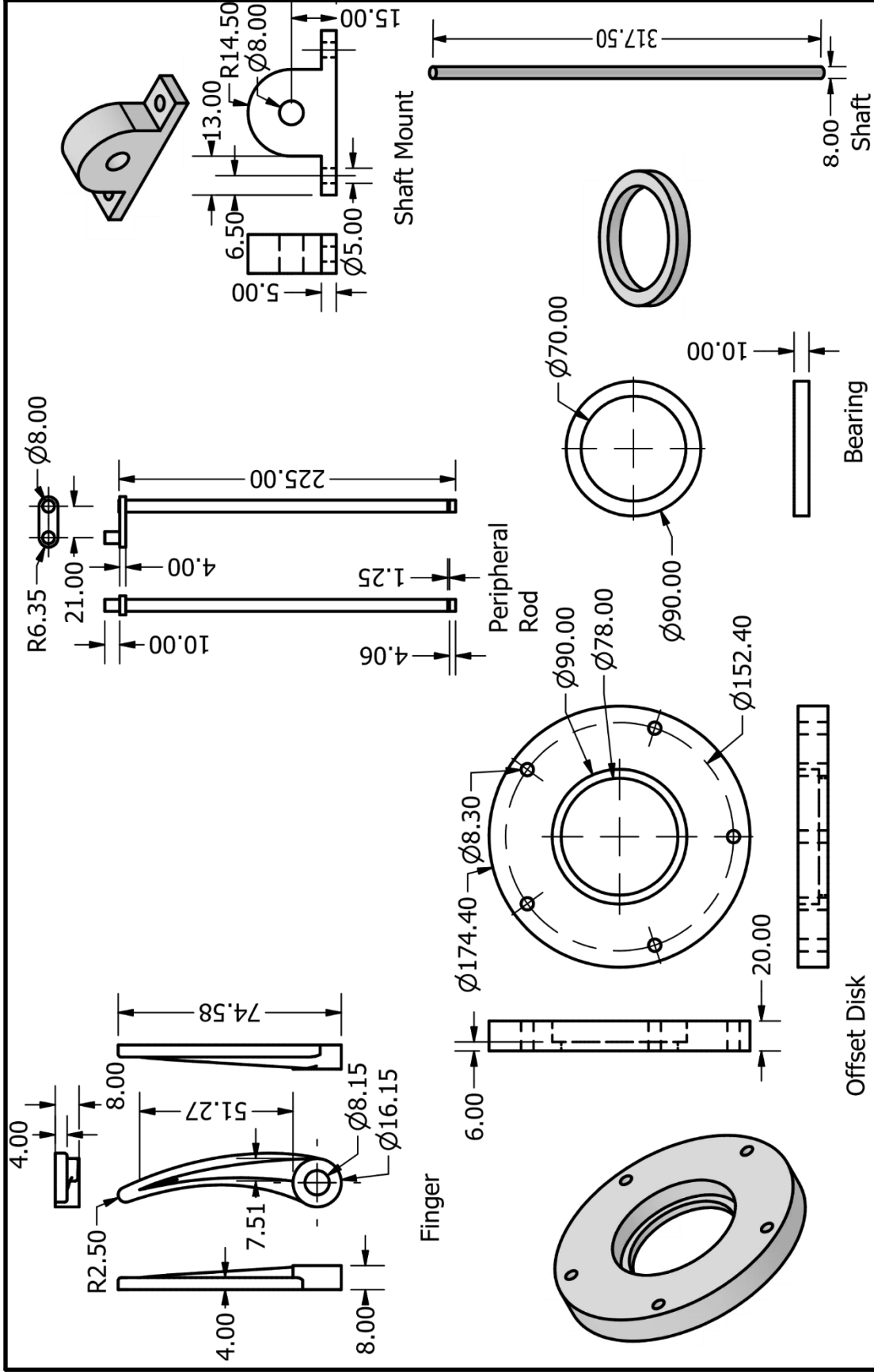
"Development of a Robotic Cotton Harvesting System Based on the Approach of Harvesting Multiple Cotton Bolls at a Time"


DESIGNED BY:

Unit: mm

Filename: 3 inch vac and endeffector attachment.ipt





		Thesis Title on:	
"Development of a Robotic Cotton Harvesting System Based on the Approach of Harvesting Multiple Cotton Bolls at a Time"		Project Title: Multiple Parts	
DESIGNED BY: SHEKHAR THAPA		Scale: 1 / 2	
8/26/2023		Unit: mm	
		Sheet #: 11	
		Filename: draper finger.ipt	

