## Additive Operations on Flow Graphs

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#### Abstract

This paper extends the theory of graphic arithmetic, an extension of classical arithmetic on  $\mathbb N$  to a larger model  $\mathcal F$  defined on the set of all flow graphs—finite directed connected multigraphs having a pair of distinguished vertices. We give a graph-theoretic characterization for a flow graph to be reducible into a proper sum, and use this to develop a canonical decomposition of flow graphs into irreducible summands. Such decompositions enable us to characterize commutativity conditions for addition, which in turn, reveal the structure of additive centralizers in  $\mathcal{F}$ .

**Keywords:** multi-graphs, flow graphs, canonical decomposition, graph arithmetic.

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### 1. Introduction

There have been previous attempts to define algebraic structures on the set of all graphs, notably via ordinals and partially ordered sets [3, 4, 11, 13, 8], the classical operations on graphs [15], including graph products [6]. In considering binary operations on graphs, considerable prior work has addressed the Cartesian product [12], Kronecker products [14], tensor products [1], zig-zag and sandwich products [10], and the rooted product [5], and others. For each of these, there is, of course, a corresponding nascient algebraic theory. With respect to Cartesian products, for example, Li considers the problem of enumerating prime graphs [9], while Kaveh and Laknejadi recently addressed issues surrounding factorization [7], In our own prior work [2], we generalized arithmetic (classically defined over the natural numbers  $\mathbb{N} = \{0, 1, 2, \ldots\}$ ), to the set F consisting of all flow graphs, providing within the larger model an interpretation of the language of arithmetic  $\mathcal{L}$  which consists of two constants 0 and 1, one binary relation  $\leq$ , and two binary operations + and  $\times$ . We give a brief synopsis of these prior results on graphic arithmetic below.

Following [2], a flow graph  $A = (G, s_A, t_A)$  is a finite directed connected multigraph G = (V[A], E[A]) together with vertices  $s_A, t_A \in V[A]$  which are designated as the source and target of A. The standard model  $\mathcal{N} = \langle \mathbb{N}, 0, 1, \leq +, \times \rangle$  embeds into a model on the set of flow graphs  $\mathcal{F} = \langle F, 0, 1, \triangleleft, \oplus, \otimes \rangle$  via an embedding  $i : \mathcal{N} \hookrightarrow \mathcal{F}$  which maps each natural number n to flow the graph  $F_n = (P_n, s_n, t_n)$  in which  $P_n$  is the directed chain of on n+1vertices and  $s_n$  (resp.  $t_n$ ) is the unique vertex with in-degree (resp. out-degree) 0. The addition of A with another flow graph  $B = (H, s_B, t_B)$  is carried out by taking  $A \oplus B$  to be the graph obtained upon identifying  $t_A$  with  $s_B$  and taking  $s_A$  and  $t_B$  as the source and target vertices in  $A \oplus B$ , respectively. Scalar left multiplication of flow graphs by positive integers is interpreted by taking kA as shorthand for the flow graph obtained when A is added to itself k times. Addition (illustrated in Figure 1) is an associative operation in  $\mathcal{F}$ , though not generally commutative. We take  $i(1) = F_1 = 1$  and  $i(0) = F_0 = 0$ , referring to the latter as the trivial flow graph. Inside  $\mathcal{F}$ , the flow graphs  $\mathring{0}$  serves as the unique additive identity. We say that a non-trivial flow graph is infinitesimal if its source and target vertices coincide. The sum of two flow graphs is infinitesimal if and only if both summands are infinitesimal. We say  $A \triangleleft B$  if flow graph B can be transformed into A by a series of edge contractions. Results relating the theorems of classical arithmetic (including the interplay of addition and multiplication) to the theory of  $\mathcal{F}$  are found in [2].

Certainly the theory of natural numbers has had a profound historical impact in the development of computability theory, which, in turn, has yielded many practical applications in cryptography. Given that the natural numbers  $\mathcal{N}$  are a submodel of  $\mathcal{F}$ , it is our hope that in advancing a deeper understanding of the larger ambient structure we will obtain theorems that provide new insights and richer perspectives on the results of classical number theory. Towards such objectives, in this paper, we further develop the theory of the additive semigroup in  $\mathcal{F}$ , obtaining a description of the structure of the (additive) centralizers of an arbitrary flow graph. Specifically, we show here that if two flow graphs A and B commute with respect to  $\oplus$  then they must both necessarily be scalar multiples of some flow graph C. Along the way, we present a graph-theoretic criterion for a flow graph to be irreducible as a proper sum of (non-trivial) flow graphs, and use this as the foundation for defining the canonical decomposition of a flow graph in terms of irreducible summands. Such decompositions also enable us to formally demonstrate (additive) cancellation laws for  $\mathcal{F}$ .

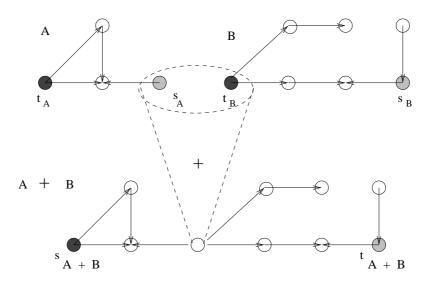


Figure 1: Flow graph addition.

#### 2. Results

A flow graph A is called  $\oplus$ -reducible if there exist non-trivial flow graphs B, C, for which  $A = B \oplus C$ . Otherwise, A is called  $\oplus$ -irreducible. Towards a graph-theoretic characterization of  $\oplus$ -irreducibility, we introduce the operation of \*-deletion on graphs.

**Definition 2.1** (\*-deletion). Let G = (V, E) be directed connected multigraph, and fix a vertex  $w \in V$ . Let  $G \setminus_* w = \{G_1^*, \dots, G_{k(w)}^*\}$  be defined as the outcome of the following 7 step process:

- 1. For each edge e = (w, u) where  $u \neq w$ , add a vertex  $v_e$ , and replace e by edges  $(w, v_e)$ ,  $(v_e, u)$ .
- 2. For each edge e = (u, w) where  $u \neq w$ , add a vertex  $v_e$ , and replace e by edges  $(u, v_e)$ ,  $(v_e, w)$ .
- 3. For each edge e = (w, w), add a vertex  $v_e$ , and replace e by edges  $(w, v_e)$ ,  $(v_e, v_e)$ .
- 4. Delete w and all incident edges, denote resulting components as  $G_1, \ldots, G_{k(w)}$ .
- 5. Let P be the vertices added in (1-3) and define relation  $(v_1, v_2) \in R$  iff  $v_1, v_2$  are in the same component  $G_i$ .
- 6. Identify the vertices in P that are related by R and denote the resulting components as  $G_1^*, \ldots, G_{k(w)}^*$ .
- 7. Index the elements of  $P/R_w$  as  $\{w_1, w_2, \ldots, w_{k(w)}\}$  so that  $w_i$  lies in  $G_i^*$  for  $i = 1, \ldots, k(w)$ .

The first four steps depicted in Figure 3 (pp. 137) and Figure 2 (pp. 136) illustrate the process of  $\ast$ -deletion.

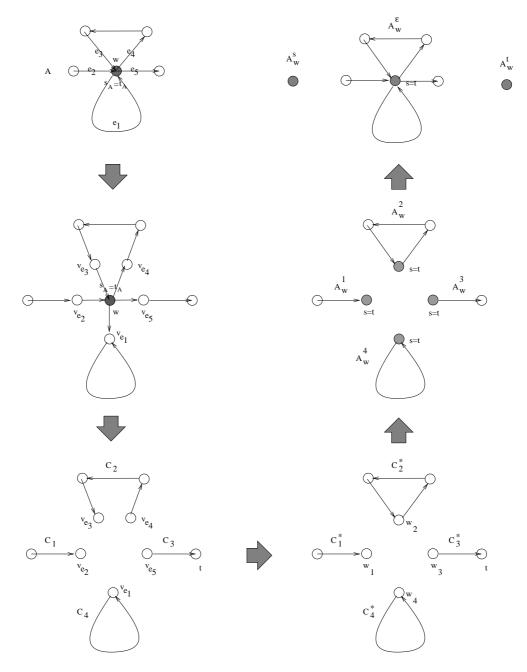


Figure 2: The w-splitting of an infinitesimal flow graph A, yielding a trivial splitting.

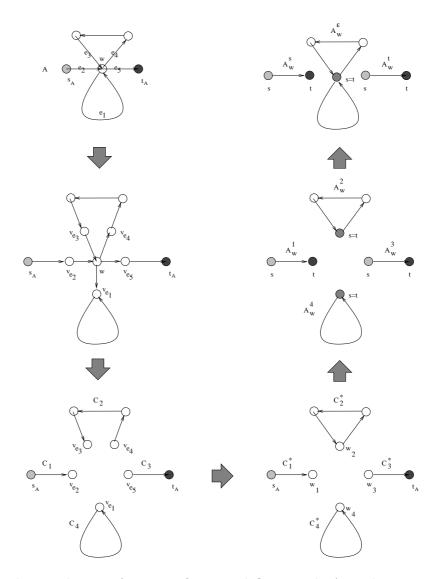


Figure 3: The w-splitting of a non-infinitesimal flow graph A resulting in a non-trivial splitting.

**Definition 2.2** (Splitting vertex). Given a flow graph  $A = (G, s_A, t_A)$ , with G = (V[A], E[A]) and  $w \in V[A]$ , let  $G \setminus_* w = (G_1^*, \ldots, G_{k(w)}^*)$  be the \*-deletion of w from G. We say that w is a splitting vertex of A if either:

- 1.  $s_A \neq w \neq t_A$ , and  $s_A$  and  $t_A$  lie in distinct members of  $G \setminus w$ ; or
- 2.  $w = s_A$  or  $w = t_A$  (or both), and  $k(w) \ge 2$ .

Let  $\chi(A) \subset V[G]$  be the set of all splitting vertices of A.

**Remark 2.3.** If A is an infinitesimal flow graph, then  $s_A = t_A$ , so if w is a splitting vertex of A then it must satisfy condition (2) of Definition 2.2. Thus, necessarily  $w = s_A = t_A$  and  $G \setminus_* w$  contains at least two components.

**Remark 2.4.** If w is a splitting vertex of a flow graph  $A = (G, s_A, t_A)$  then w is a cut vertex in the graph G. The converse is false, as seen in the flow graph B in Figure 1 (pp. 135) which contains two cut vertices at distance 1 from  $t_A$ , of which only one is a splitting vertex.

**Definition 2.5** (w-Splitting of a flow graph). Let  $A = (G, s_A, t_A)$  be a flow graph and w a splitting vertex of A.

Let  $G\setminus w = (G_1^*, \ldots, G_{k(w)}^*)$  be the \*-deletion of w from G. Define flow graphs

$$A_w^i = \begin{cases} (G_i^*, s_A, w_i) & \text{if } s_A \in V[G_i^*] \\ (G_i^*, w_i, t_A) & \text{if } t_A \in V[G_i^*] \\ (G_i^*, w_i, w_i) & \text{otherwise.} \end{cases} i = 1, \dots k(w)$$

Let  $\epsilon_w = \{i \mid s_A, t_A \notin V[G_i^*]\};$  we define the w-splitting of A, denoted  $A \setminus_* w = (A_w^s, A_w^\epsilon, A_w^t),$  by taking

$$A_w^s = \begin{cases} A_w^i & \text{if} \quad s_A \in V[G_i^*] \\ \mathring{0} & \text{if} \quad w = s_A \end{cases}$$

$$A_w^t = \begin{cases} A_w^i & \text{if} \quad t_A \in V[G_i^*] \\ \mathring{0} & \text{if} \quad w = t_A \end{cases}$$

$$A_w^{\epsilon} = \bigoplus_{1 \in \epsilon_w} A_w^i$$

Note that  $A = A_w^s \oplus A_w^\epsilon \oplus A_w^t$ . Figure 3 (pp. 137) provides an example of a w-splitting.

Remark 2.6. In Definition 2.5, each  $A_w^i$  (i = 1, ..., k(w)) is non-trivial, since in steps 1-4 of the construction of  $G_w$  (see Definition 2.1) no component  $G_i$  can have fewer than 1 edge, and  $G_i^*$  is obtained by identifying vertices in  $G_i$ .

Remark 2.7. In Definition 2.5, each  $A_w^i$  ( $i \in \epsilon_w$ ) is infinitesimal and contains no splitting vertex. To see the latter assertion, suppose, towards contradiction, that some  $A_w^i$  contains a splitting vertex w. Then  $w = s_{A_w^i} = t_{A_w^i}$  by Remark 2.3. But  $w_i$  (in  $G_i^*$ ) is the identification of a set of vertices in the connected graph  $G_i$  (see step 6 of Definition 2.1). Hence,  $w_i$  is not a cut vertex in  $G_i^*$ , and so by Remark 2.4 cannot be a splitting vertex of A.

If w is a splitting vertex of A then was deleted in the construction of  $G \setminus_* w$  (see step 4 of Definition 2.1), so  $w \notin V[A_u^s]$  and  $w \notin V[A_u^t]$ . There are natural injections of the vertices of  $A_w^s$ ,  $A_w^t$  and  $A_w^\epsilon$  into the vertices of A. The splitting vertices of  $A_w^s$  are also splitting vertices of A. The splitting vertices of A which lie in  $A_w^s$  (resp.  $A_w^t$ ) are

splitting vertices of  $A_w^s$  (resp.  $A_w^t$ ). Since  $A_w^{\epsilon}$  is infinitesimal, its has at most one splitting vertex, that being its source/target. The implications of these facts are collected in the next observation.

**Observation 2.8.** For any flow graph  $A = (G, s_A, t_A)$ 

- a. For all  $u \in \chi(A)$ ,  $u \notin \chi(A_u^s)$  and  $u \notin \chi(A_u^t)$ .
- b.  $\chi(A) \cap A_u^s = \chi(A_u^s)$  and  $\chi(A) \cap A_u^t = \chi(A_u^t)$ .
- c. For all  $w \in \chi(A)$ , if  $u \in \chi(A_w^s)$  and  $v \in \chi(A_u^s)$ , then  $v \in \chi(A_w^s)$ .
- d. For all  $w \in \chi(A)$ , if  $u \in \chi(A_w^t)$  and  $v \in \chi(A_u^t)$ , then  $v \in \chi(A_w^t)$
- e. Let u, v be distinct vertices in  $\chi(A)$  then  $u \notin A_v^{\epsilon}$  and  $v \notin A_u^{\epsilon}$ .

**Lemma 2.9.** Let A be a flow graph with splitting vertex w. Then

- (i)  $A_w^{\epsilon}$  is infinitesimal.
- (ii)  $A_w^s$  and  $A_w^t$  are each either trivial, or non-infinitesimal.
- (iii) No two adjacent elements in the triple  $(A_w^s, A_w^\epsilon, A_w^t)$  are trivial flow graphs.
- *Proof.* (i) By Definition 2.5, if  $\epsilon = \emptyset$  then  $A_w^{\epsilon} = \mathring{0}$ ; otherwise,  $A_w^{\epsilon}$  is the sum of flow graphs which are each (by Remark 2.7) infinitesimal, and since the sum of infinitesimals is infinitesimal, the result follows.
- (ii) If  $A_w^s$  is non-trivial, then  $A_w^s = A_w^i$  for some i in  $\{1, \ldots, k(w)\}$ , with  $s_A \in V[G_i^*]$ . Since  $s_A \neq w_i$  in  $V[G_i^*]$ , by Definition 2.5 we know  $A_w^s$  is not infinitesimal. The proof for  $A_w^t$  is analogous.
- (iii) If w satisfies condition (1) of Definition 2.2, then  $s_A$  and  $t_A$  lie in distinct components of  $G\setminus_* w$ , but then by Remark 2.6,  $A_w^s$  and  $A_w^t$  are both non-trivial. On the other hand, if w satisfies condition (2) of Definition 2.2, then either  $w = s_A$ , or  $w = t_A$ , or both—hence either  $A_w^t = \mathring{0}$ , or  $A_w^s = \mathring{0}$ , or both—and since  $G\setminus_* w$  contains at least two non-trivial components, Definition 2.5 implies  $|\epsilon_w| \ge 1$ , and hence  $A_w^\epsilon \ne \mathring{0}$ .

The next Proposition provides a graph-theoretic characterization of ⊕-reducibility.

**Proposition 2.10** ( $\oplus$ -Irreducibility Lemma). A flow graph  $A = (G, s_A, t_A)$  is  $\oplus$ -reducible if A has a splitting vertex.

Proof. ( $\Rightarrow$ ) Suppose  $A = B \oplus C$ . Take  $w = t_B = s_C$  to be the vertex in V[A] which is the identification of  $t_B$  with  $s_C$ . If B is not infinitesimal,  $t_B \neq s_B$ ; but  $s_A = s_B$ , so  $w \neq s_A$ ; thus even after w is deleted  $s_A$  will be found in some component  $A_w^i$ , so  $A_w^s \neq 0$ . By a similar argument, if C is not infinitesimal  $t_A = t_C$  is in some component  $A_w^i$ , and  $A_w^t \neq 0$ . If B is infinitesimal, then  $t_B = s_B$ ; but  $s_B = s_A$ , so  $w = s_A$ ; thus after w is deleted  $s_A$  will not be found in any component  $A_w^i$  (for  $i = 1, \ldots, k(w)$ ), hence  $A_w^s = 0$ . By a similar argument, if C is infinitesimal,  $A_w^t = 0$ 

- If B and C are both not infinitesimal then  $s_A$  and  $t_A$  are in different components, i.e.  $i \neq j$ , since  $s_B$  and  $t_C$  came from different summands. Thus w is a splitting vertex by case (1) of Definition 2.2.
- If exactly one of the flow graphs, say B, is infinitesimal (and C is not). then  $A_w^s = 0$ , then part (iii) of Lemma 2.9 indicates that  $A_w^{\epsilon} \neq 0$ . Since C is not infinitesimal,  $A_w^t \neq 0$ . Thus, there are at least two non-trivial flow graphs in  $\{A_w^1, \ldots, A_w^{k(w)}\}$ , so w is a splitting vertex by case (2) of Definition 2.2. A similar argument holds when C is infinitesimal and B is not.
- If B, C are both infinitesimal, then so is A and by Remark 2.3, the set  $\{A_w^i \mid i \in \epsilon_w\}$  contains at least two non-trivial flow graphs, so w is a splitting vertex by case (2) of Definition 2.2.
- ( $\Leftarrow$ ) Let w be a splitting vertex of A. If w satisfies case (1) of Definition 2.2, then  $A_w^s$  and  $A_w^t$  are both non-trivial, and we can take  $B = A_w^s$  and  $C = A_w^\epsilon \oplus A_w^t$ , which expresses A as the sum of two flow graphs that are both non-trivial (by part (iii) of Lemma 2.9). If w satisfies case (2) of Definition 2.2, then either  $A_w^s$  is trivial or  $A_w^t$  or both.
  - If only  $A_w^s$  is trivial, then taking  $B = A_w^{\epsilon}$  and  $C = A_w^t$ , we can express A as the sum of two flow graphs which are each non-trivial by part (iii) of Lemma 2.9. An analogous approach applies in the case when only  $A_w^t$  is trivial.
  - If both  $A_w^s$  and  $A_w^t$  are trivial, then A is infinitesimal and so  $k(w) \ge 2$  by Remark 2.3. We can therefore partition  $\epsilon_w = \epsilon_w^1 \sqcup \epsilon_w^2$ , taking  $B = \bigoplus_{i \in \epsilon_w^1} A_w^i$  and  $C = \bigoplus_{i \in \epsilon_w^1} A_w^i$ , thus expressing A as the sum of two flow graphs which are each non-trivial.

In all cases, A is  $\oplus reducible$ .

A splitting of the form  $(\mathring{0}, A, \mathring{0})$  is called a *trivial splitting*; an example is illustrated in Figure Figure 2 (pp. 136).

**Proposition 2.11.** All the w-splittings of an infinitesimal flow graph are trivial splittings.

*Proof.* If A is infinitesimal, and w a splitting vertex of A, then  $w = s_A = t_A$  by Remark 2.3. Since step 4 in the construction of  $G\setminus_* w$  (see Definition 2.1) requires deleting w, it follows that  $s_A = t_A$  are not in any of the components  $G_i^*$ . By Definition 2.5, we have  $A_w^s = A_w^t = \mathring{0}$ , and  $A_w^\epsilon = A$ ; thus  $A\setminus_* w = (\mathring{0}, A, \mathring{0})$ .

**Definition 2.12** (Splitting vertex ranking). Given flow graph  $A = (G, s_A, t_A)$ , define the s-ranking and t-ranking functions  $r_s, r_t : \chi(A) \to \mathbb{N}$  as follows:

$$r_s(w) = |V[A_w^s] \cap \chi(A)|,$$
  
$$r_t(w) = |V[A_w^t] \cap \chi(A)|.$$

**Lemma 2.13.** Let  $w \in \chi(A)$  be a splitting vertex for flow graph  $A = (G, s_A, t_A)$ . Then for all  $u \in V[A_w^s] \cap \chi(A)$ :

$$r_s(u) < r_s(w),$$
  
 $r_t(u) > r_t(w);$ 

and for all  $u \in V[A_w^t] \cap \chi(A)$ :

$$r_s(u) > r_s(w),$$
  
 $r_t(u) < r_t(w).$ 

Proof. Take  $u \in V[A_w^s] \cap \chi(A)$ . To show  $r_s(u) < r_s(w)$ , it suffices to demonstrate that  $V[A_u^s] \cap \chi(A)$  is a proper subset of  $V[A_w^s] \cap \chi(A)$ . Let  $v \in V[A_u^s] \cap \chi(A)$ . Then by Observation 2.8b,  $v \in \chi(A_w^s)$ . Since  $u \in V[A_w^s]$  and  $u \in \chi(A)$ , it follows by Observation 2.8b, that  $u \in \chi(A_w^s)$ . Now  $v \in \chi(A_u^s)$  and  $u \in \chi(A_w^s)$ , so by Observation 2.8c, it follows that  $v \in \chi(A_w^s)$ . To see that the set inclusion is proper, note that  $u \notin \chi(A_u^s)$  by Observation 2.8a, but  $u \in \chi(A_w^s)$ . Analogous arguments prove the other three assertions.

**Lemma 2.14.** Let u, v be distinct vertices in  $\chi(A)$  then  $r_s(u) \neq r_s(v)$  and  $r_t(u) \neq r_t(v)$ .

*Proof.* Since  $u \neq v$ , by Observation 2.8e, either  $u \in A_v^s$  or  $u \in A_v^t$ . If  $u \in A_v^t$ , then  $v \in A_u^s$ , and by Lemma 2.13,  $r_s(v) < r_s(u)$ . If  $u \in A_v^s$ , then  $v \in A_u^t$ , and by Lemma 2.13,  $r_t(v) < r_t(u)$ .

**Lemma 2.15.** Given a flow graph  $A = (G, s_A, t_A)$ , for each  $i = 0, 1, ..., |\chi(A)| - 1$  there is a unique vertex  $v_i$  in  $\chi(A)$  with the property that  $r_s(v_i) = i$ .

*Proof.* Given two distinct vertices v, v' in  $\chi(A)$ , either  $v \in V[A_{v'}^s]$  or  $v \in V[A_{v'}^t]$ . In the latter circumstance,  $v' \in V[A_v^s]$  so it follows from Lemma 2.13 that  $r_s(v') < r_s(v)$ .

Base case, i=0. Let  $w_0$  be any vertex in  $\chi(A)$ . If  $r_s(w_0)>0$ , then  $V[A^s_{w_0}]\cap\chi(A)$  is not empty. So let  $w_1$  be any vertex in  $V[A^s_{w_0}]\cap\chi(A)$ . By Lemma 2.13,  $r_s(w_1)< r_s(w_0)$ . Repeating in this fashion, after finitely many steps  $w_0 \leadsto w_1 \leadsto \ldots$  we find some vertex  $v_0$  for which  $r_s(v_0)=0$ .

Inductive step i+1: Let  $v_i$  be the unique vertex in  $\chi(A)$  having  $r_s(v_i)=i$ . Define  $v_{i+1}$  to be the vertex in  $V[A^t_{v_i}] \cap \chi(A)$  for whose s-rank is minimum (which exists because the s-rank of all cut vertices are distinct, by Lemma 2.14). It now follows that  $r_s(v_{i+1})=r_s(v_i)+1=i+1$ , hence the result.

**Definition 2.16** (Canonical  $\oplus$ -decomposition). Let  $A = (G, s_A, t_A)$  be a flow graph. If  $\chi(A) = \emptyset$  and A is infinitesimal, then the canonical  $\oplus$ -decomposition of A is defined to be the formal sum  $\mathring{0} \oplus A \oplus \mathring{0}$ . If  $\chi(A) = \emptyset$  and A is non-infinitesimal, the canonical  $\oplus$ -decomposition of A is defined to be A.

Otherwise, let  $\chi(A) = \{v_0, v_1, \dots, v_{|\chi(A)|-1}\}$  be the non-empty set of splitting vertices of A, ordered according to the indexing scheme postulated in Lemma 2.15. Define  $A^{(0)} = A^s_{v_0}$ ,  $A^{(0)} = A^t_{v_0}$ , and then for each  $i = 1, 2, \dots, |\chi(A)| - 1$ , put

$$\begin{array}{rcl} A^{(i)} & = & (\bar{A}^{(i-1)})_{v_i}^s, \\ A^{\epsilon(i)} & = & (\bar{A}^{(i-1)})_{v_i}^\epsilon, \\ \bar{A}^{(i)} & = & (\bar{A}^{(i-1)})_{v_i}^t. \end{array}$$

We shall denote  $\bar{A}^{(|\chi(A)|-1)}$  as  $A^{(|\chi(A)|)}$ . The canonical  $\oplus$ -decomposition of A is defined to be the formal summation:

$$\langle A \rangle \stackrel{\text{def}}{=} A^{(0)} \oplus A^{\epsilon(0)} \oplus A^{(1)} \oplus A^{\epsilon(1)} \dots \oplus A^{(|\chi(A)|-1)} \oplus A^{\epsilon(|\chi(A)|-1)} \oplus A^{(|\chi(A)|)}.$$

Note that Lemma 2.15 and effectiveness of the definition above together guarantee the uniqueness of the decomposition.

**Definition 2.17** (Alternating sum). A sum  $A_0 \oplus A_1 \oplus \cdots \oplus A_{2k}$   $(k \in \mathbb{N})$  is called an alternating sum of weight k if

$$A_i \quad is \quad \left\{ \begin{array}{ll} either \ trivial \ or \ infinitesimal & i \ is \ odd, \\ non-trivial, \ non-infinitesimal, \ and \ \oplus -irreducible & 0 < i < 2k, \ i \ is \ even, \\ non-infinitesimal \ and \ \oplus -irreducible & i = 0 \ or \ i = 2k. \end{array} \right.$$

no two adjacent elements  $A_i, A_{i+1}$  (i = 0, ..., 2k - 1) are trivial.

**Remark 2.18.** It is easy to see that given a flow graph A expressed as an alternating sum:

$$A = A_0 \oplus A_1 \oplus \cdots \oplus A_{2m}$$

the set of its splitting vertices  $\chi(A) = \chi(A_0 \oplus A_1 \oplus \cdots \oplus A_{2m})$  is precisely  $\{s_{A_i} \mid i \text{ odd}\}$  under the suitable embeddings of  $A_i \hookrightarrow A_0 \oplus A_1 \oplus \cdots \oplus A_{2m}$ .

**Proposition 2.19** (Correctness of the  $\oplus$ -decomposition). Let  $A = (G, s_A, t_A)$  be a flow graph. Then  $\langle A \rangle$  is an alternating sum of weight  $|\chi(A)|$  which satisfies  $\langle A \rangle = A$ .

Proof. We prove by induction on  $|\chi(A)|$ . If  $|\chi(A)| = 0$ , then  $\langle A \rangle = A$  trivially. Suppose  $|\chi(A)| = n > 1$ . Let w be the unique vertex for which  $r_s(w) = 0$ . As a formal summation,  $\langle A \rangle = A_w^s \oplus A_w^\epsilon \oplus \langle A_w^t \rangle$ . Since  $|\chi(A_w^t)| = n - 1$ , by inductive hypothesis,  $\langle A_w^t \rangle = A_w^t$  has weight n-1. This implies that  $\langle A \rangle = A_w^s \oplus A_w^\epsilon \oplus A_w^t$  has weight n, and so  $A_w^s \oplus A_w^\epsilon \oplus A_w^t \oplus A_w^t = A$ .

Given a flow graph A, we see that  $\langle A \rangle$  is an alternating sum. The next proposition shows that it is canonical, and that up to isomorphism, there is only one alternating sum which evaluates to A, namely  $\langle A \rangle$ .

**Proposition 2.20** (Component-wise decomposition of isomorphisms under  $\oplus$ ). Suppose A and B are two isomorphic flow graphs, expressed as alternating sums:

$$A = A_0 \oplus A_1 \oplus \cdots \oplus A_{2m},$$
  
$$B = B_0 \oplus B_1 \oplus \cdots \oplus B_{2n}$$

Then m = n and every isomorphism  $\phi: A \to B$  satisfies  $\phi(A_i) = B_i$  (for i = 1, ... m).

Proof. Clearly,  $\phi|_{\chi(A)}$  a bijection from  $\chi(A)$  to  $\chi(B)$ . By Remark 2.18, for each i in  $\{0,\ldots,|\chi(A)|-1\}$ , there exists some j in  $\mathbb{N}$ , such that  $\phi(s_{A_{2i+1}})=s_{B_{2j+1}}$ . Take  $u_i$  to be the image of  $s_{A_{2i+1}}$  in A under the natural embedding  $A_{2i+1} \hookrightarrow A$ , and  $v_j$  to be the image of  $s_{B_{2j+1}}$  in B under the natural embedding  $B_{2j+1} \hookrightarrow B$ . Then  $\phi(u_i)=v_j$  implies  $\phi$  maps  $\chi(A_{u_i}^s)$ , having size i, bijectively onto  $\chi(B_{v_j}^s)$ , having size j. It follows that i=j. Since  $\phi(u_i)=v_i$ , the  $u_i$  splitting of A equals the  $v_i$  splitting of B, i.e.

$$\phi(A_{u_i}^s) = B_{v_i}^s 
\phi(A_{u_i}^\epsilon) = B_{v_i}^\epsilon 
\phi(A_{u_i}^\epsilon) = B_{v_i}^t.$$

In the case when i = m - 1,  $u_{m-1} = s_{A_{2(m-1)+1}}$  and  $v_{m-1} = s_{B_{2(m-1)+1}}$ . Since  $\chi(A_{u_{m-1}}^t)$  is empty,  $\chi(B_{v_{m-1}}^t)$  must also be empty. Hence 2(m-1)+1=2n-1, and therefore m=n.

Now if  $|\chi(A)| = 0$  the theorem is trivially true. Suppose  $|\chi(A)| = m > 0$ . Then  $\phi(u_{m-1}) = v_{m-1}$  and so  $\phi(A^s_{u_{m-1}}) = B^s_{v_{m-1}}$ . Since  $|\chi(A^s_{u_{m-1}})| = m-1$  the inductive hypothesis applies and  $\phi$  maps  $A_0 \oplus A_1 \oplus \cdots \oplus A_{2(m-1)}$  component-wise onto  $B_0 \oplus B_1 \oplus \cdots \oplus B_{2(m-1)}$ . Since  $A_{m-1}$ ,  $B_{m-1}$  are infinitesimal or trivial, and  $A_m$ ,  $B_m$  are non-infinitesimal or trivial (but not both can be trivial, it follows that  $\phi$  maps  $A_{m-1}$  onto  $B_{m-1}$  and  $A_m$  onto  $B_m$ .

We might hope that the proposition above would enable us to convert an isomorphism  $\phi:A\oplus B\to A\oplus C$  into an isomorphism  $B\to C$ . However, the obvious candidate based on the natural embeddings

$$\sigma_{A,B}: A \hookrightarrow A \oplus B$$

$$\tau_{A,B}: B \hookrightarrow A \oplus B$$

$$\sigma_{A,C}: A \hookrightarrow A \oplus C$$

$$\tau_{A,C}: C \hookrightarrow A \oplus C$$

is  $\tau_{A,C}^{-1} \circ \phi|_B \circ \tau_{A,B}$ , but this is well-defined only when  $\phi(Im(\tau_{A,B})) = Im(\tau_{t_A,C})$ . Unfortunately, this may not be the case—a counterexample is given in Figure 4, where  $\phi$  is the isomorphism of rigid translation to the right, and the canonical embeddings  $\sigma$  and  $\tau$  are vertical translations. The next Lemma shows that one can make a surgical alteration to  $\phi$  to correct this difficulty.

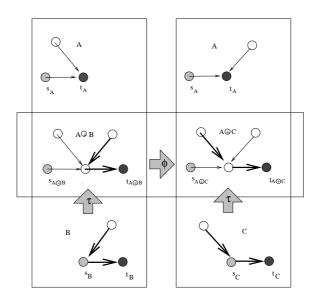


Figure 4: An example: component-wise decomposition of isomorphisms do not imply a cancellation law.

**Lemma 2.21** (Surgery Lemma). Let A, B, C be flow graphs satisfying  $A \oplus B = A \oplus C$  via isomorphism  $\phi : A \oplus B \to A \oplus C$ . Then there exists an isomorphism  $\psi : A \oplus B \to A \oplus C$  such that

$$\psi(Im(\sigma_{A,B})) = Im(\sigma_{A,C}),$$
  
$$\psi(Im(\tau_{A,B})) = Im(\tau_{A,C}).$$

*Proof.* If at most one of the two summands  $A^{(2|\chi(A)|)}$  and  $B^{(0)}$  are  $\mathring{0}$  then  $\langle A \oplus B \rangle$  is formally equal to  $\langle A \rangle \oplus \langle C \rangle$ . By Proposition 2.20 the result follows by taking  $\psi = \phi$ .

If both  $A^{(2|\chi(A)|)}=B^{(0)}=\mathring{0}$  and  $(A\oplus B)^{(2|\chi(A)|-1)}=A^{(2|\chi(A)|-1)}\oplus B^{(1)}$ . Let  $\psi_0$  be the identity function on  $A^{(2|\chi(A)|-1)}\oplus B^{(1)}$ , which each summand identically onto itself. Note that the corresponding restriction of  $\phi$  need not have this property. We define  $\psi$  as follows:

$$\begin{array}{rcl} \psi|_{\sigma(A_i)} & \equiv & \phi|_{\sigma(A_i)} & \text{if } i < 2|\chi(A)| - 1, \\ \psi|_{\tau(B_j)} & \equiv & \phi|_{\tau(B_j)} & \text{if } j > 1, \\ \psi|_{\sigma(A^{(2|\chi(A)|-1)})} & \equiv & \phi_0|_{\sigma^{-1}(A^{(2|\chi(A)|-1)})}, \\ \psi|_{\tau(B^{(1)})} & \equiv & \phi_0|_{\tau^{-1}(B^{(1)})}. \end{array}$$

By construction, the isomorphism  $\psi$  has the desired property.

**Corollary 2.22** (Cancellation laws). Let A, B, C be flow graphs;  $A \oplus B = A \oplus C \Rightarrow B = C$ , and  $B \oplus A = C \oplus A \Rightarrow B = C$ .

*Proof.* Suppose  $A \oplus B = A \oplus C$ . By Lemma 2.21, there is an isomorphism  $\psi : A \oplus B \to A \oplus C$  satisfying  $\psi(Im(\tau_{A,B})) = Im(\tau_{A,C})$ . Then  $\tau_{A,C}^{-1} \circ \phi|_B \circ \tau_{A,B} : B \to C$  is an isomorphism of flow graphs, and so B = C.

**Theorem 2.23** (Commutativity condition for  $\oplus$ ). Two non-trivial flow graphs  $A = (G, s_A, t_A)$  and  $B = (H, s_B, t_B)$ , commute with respect to addition iff there is a flow graph C and  $k_1$ ,  $k_2$  in  $\mathbb{N}$  such that  $A = k_1C$  and  $B = k_2C$ .

*Proof.*  $[\Leftarrow]$  If  $A = k_1C$  and  $B = k_2C$ , then  $A \oplus B = (k_1 + k_2)C = B \oplus A$ .

 $\Rightarrow$  Consider the canonical decompositions of A and B, viewed as alternating sums:

$$A = A_0 \oplus A_1 \oplus A_2 \oplus \cdots \oplus A_{2m-1} \oplus A_{2m},$$
  
$$B = B_0 \oplus B_1 \oplus B_2 \oplus \cdots \oplus B_{2n-1} \oplus B_{2n}.$$

The proof is carried by induction on  $\max(2m, 2n)$ .

If m=n then Proposition 2.20 tells us that an isomorphism  $\phi:A\oplus B\to B\oplus A$  can be surgically adjusted (see Lemma 2.21) to yield an isomorphism from A to B. So in this case, we can take C=A=B and  $k_1=k_2=1$ . This proves the case m=2n which forms the basis of the induction.

Suppose that  $\max(m, n) > 0$ , and  $m \neq n$ . Without loss of generality, suppose m < n. Then  $A_i = B_i$  for  $i = 0, \dots, 2m$ . It follows that

$$B_{i+(2m+1)} = B_i \text{ for } i = 0, \dots, 2n - (2m+1),$$
 (1)

$$B_{i-(2m+1)} = B_i \text{ for } i = (2m+1), \dots, 2n.$$
 (2)

If (2n+1) is divisible by (2m+1), then expressions (1) and (2) above are in fact equivalent, and in this setting, we take C = A,  $k_1 = 1$  and  $k_2 = \frac{(2n+1)}{(2m+1)}$  in order to satisfy the proposition. Suppose now that (2n+1) is *not* divisible by (2m+1). Put

$$d = \left\lfloor \frac{(2n+1)}{(2m+1)} \right\rfloor, \text{ and}$$

$$r = (2n+1) \mod (2m+1).$$

and define

$$X = B_0 \oplus B_1 \cdots \oplus B_{r-1},$$
  

$$Y = B_r \oplus B_{r+1} \cdots \oplus B_{2m}.$$

Note that  $B = dA \oplus X$  and

$$A = A_0 \oplus A_1 \oplus A_2 \oplus \cdots \oplus A_{2m-1} \oplus A_{2m}$$
  
=  $B_0 \oplus B_1 \oplus \cdots \oplus B_{r-1} \oplus B_r \oplus B_{r+1} \cdots \oplus B_{2m-1} \oplus B_{2m}$   
=  $X \oplus Y$ .

It follows that  $B = d(X \oplus Y) \oplus X$ . On the other hand,  $X \oplus Y = A = Y \oplus X$  (see Figure 5), since

$$X \oplus Y = A$$

$$= A_0 \oplus A_1 \oplus \cdots \oplus A_{2m}$$

$$= B_0 \oplus B_1 \oplus \cdots \oplus B_r \oplus \cdots \oplus B_{2m-1} \oplus B_{2m}$$

$$= B_r \oplus \cdots \oplus B_{2n-1} \oplus B_{2n} \oplus B_0 \oplus \cdots \oplus B_{r-1}$$

$$= Y \oplus X.$$

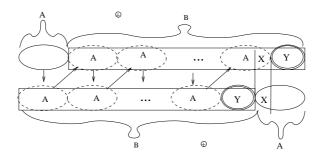


Figure 5: Inductive step showing  $X \oplus Y = A = Y \oplus X$ .

Since  $r \neq 0$  the inductive hypothesis applies to the flow graphs X, Y, i.e. there exists some flow graph Z and suitable integers  $l_1$ ,  $l_2$  so that  $X = l_1 Z$ ,  $Y = l_2 Z$ . It follows that

$$A = X \oplus Y = l_1 Z \oplus l_2 Z = (l_1 + l_2) Z$$
 and  $B = dA \oplus X = d(X \oplus Y) \oplus X = d(l_1 + l_2) Z \oplus l_1 Z = ((d+1)l_1 + l_2) Z.$ 

So taking C = Z,  $k_1 = l_1 + l_2$  and  $k_2 = (d+1)l_1 + l_2$ , the theorem is proved.

If A be a flow graph, then  $C_{\mathcal{F}}(\{A\}) = \{B \in F \mid A \oplus B = B \oplus A\}$  is called the *additive* centralizer of A in  $\mathcal{F}$ .

**Definition 2.24** (k-additive root). If A and B be flow graph, then the B is called the k-additive root of A if B is  $\oplus$ -irreducible and there exists a positive integer k such that A = kB.

**Lemma 2.25** (Additive roots). Additive roots are unique in  $\mathcal{F}$ .

*Proof.* If A trivial, or if A is non-trivial and  $\oplus$ -irreducible then A=1A and A is its own unique additive root. Suppose A is non-trivial and  $\oplus$ -reducible but  $A=k_1B_1$  and  $A=k_2B_2$ . Then the isomorphism from  $k_1B_1$  to  $k_2B_2$ , factors through their canonical decompositions to yield an isomorphism from  $B_1$  to  $B_2$ 

In light of the above lemma, we denote the additive root of A as  $\sqrt[\oplus]{A}$ . Theorem 2.23 and Lemma 2.25 now yield a characterization of additive centralizers.

**Corollary 2.26** (Additive centralizers). Let A be a flow graph. If  $A \neq 0$  then  $C_{\mathcal{F}}(\{A\}) = \{0\} \cup \{k \sqrt[6]{A} \mid k \in \mathbb{N}, k > 0\}$ ; If A is trivial,  $C_{\mathcal{F}}(\{A\}) = F$ , where F is the set of all flow graphs.

# 3 Conclusions

Building on a graph-theoretic characterization of flow graph  $\oplus$ -reducibility, we developed canonical (additive) decompositions for flow graph. Such decompositions enable us to restrict flow graph isomorphisms to irreducible summands, and carry out inductive arguments. This, in turn, permits us to verify cancellation laws, and explore the implications of additive commutation between flow graphs. On the latter question, we determine that if two flow graphs A and B commute with respect to  $\oplus$  then they must both necessarily be scalar multiples of some flow graph C. This, in turn allows us to show that the centralizer of any non-trivial flow graph A in  $\mathcal{F}$  "looks like"  $\mathbb{N}$ , in the sense that it consists of left scalar multiples of the additive root of A. The question of multiplicative centralizers remains open, and is to be the subject of subsequent inquiry.

While the results presented here advance our understanding of the additive semigroup, any future practical applications of this work to the development of cryptographic schemes will likely require parallel progress to be made on the properties of multiplication in  $\mathcal{F}$ . In particular, the structure of ideals and the difficulty of factorization remain areas of ongoing inquiry. It is our hope that once the theory of both addition and multiplication in  $\mathcal{F}$  have been more fully developed (and their interplay is better understood), new practical applications involving flow graph based cryptography will become accessible.

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