

Opportunistic Channel Selection Strategy for Better QoS in Cooperative Networks with Cognitive Radio Capabilities

Ala Al-Fuqaha, Bilal Khan, Ammar Rayes, Mohsen Guizani, Osama Awwad, Ghassen Ben Brahim

Abstract—Mission-oriented MANETs are characterized by implicit common group objectives which make inter-node cooperation both logical and feasible. We propose new techniques to leverage two optimizations for cognitive radio networks that are specific to such contexts: *opportunistic channel selection* and *cooperative mobility*. We present a new formal model for MANETs consisting of cognitive radio capable nodes that are willing to be moved (at a cost). We develop an effective decentralized algorithm for mobility planning, and powerful new filtering and fuzzy based techniques for both channel estimation and channel selection. Our experiments are compelling and demonstrate that the communications infrastructure—specifically, connection bit error rates—can be significantly improved by leveraging our proposed techniques. In addition, we find that these cooperative/opportunistic optimization spaces do not trade-off significantly with one another, and thus can be used simultaneously to build superior hybrid schemes. Our results have significant applications in high-performance mission-oriented MANETs, such as battlefield communications and domestic response & rescue missions.

Index Terms—Cognitive radio, Cooperation, Quality of Service, Ad-hoc network, filter, fuzzy logic.

I. INTRODUCTION

MOBILE wireless ad-hoc networks (MANETs) serve as an important building block for modern networks, having found fruitful applications in both consumer and mission-oriented settings. Examples of the latter include battlefield and public safety scenarios where MANETs are considered especially well-suited because they support the rapid establishment of communications for mobile platforms over a shared wireless medium, and obviate the need to invest time and expense in developing a fixed infrastructure.

In the military setting, MANETs have been used to enable communication between mobile infantry units, command and control, field intelligence, aerial surveillance, etc. They can be built using Radio Frequency (RF) communication links both between and within infantry formations, ground armored vehicles (e.g., armored vehicles, tanks), airborne units (e.g., fighters, bombers), and naval/amphibious platforms (e.g., destroyers, troop carriers). The demanding requirements of end

users in military and public-safety sectors have led to the development of a variety of unmanned platforms [12]. More specifically, end-user demands have driven the development of Unmanned Ground Vehicles (UGVs) and Unmanned Air Vehicles (UAVs) for use within battlefield and public safety missions, e.g., the UAV-Ground Network [3]. These devices are mobile, mission-capable, and well-suited for use in dull, dirty, difficult, and dangerous settings, including collection of data from sensors [7]. In particular, the ability to maneuver UAVs and UGVs in small increments over a wide variety of terrains makes them well-suited to serve as relays, maintaining mobile communication links by optimizing the reception and transmission of signals among end users.

Surprisingly, while MANETs have been applied in mission-oriented rapid-deployment applications such as battlefield communications and domestic response & rescue missions, much of MANET research has not made a concerted effort to leverage the central difference between consumer MANETs and mission-oriented rapid-deployment MANETs: namely that the latter brings with them implicit common group objectives which make inter-node cooperation both logical and feasible. This willingness to cooperate provides designers of rapid-deployment mission-oriented MANETs additional opportunities for new optimizations which have not been thoroughly explored. In this paper, we will consider two such optimizations and describe the tradeoffs inherent between them.

Cooperative Mobility. Application-level cooperation has been studied in the context of specific tasks (e.g., in [10], Kuwata et al. describe how a group of UAVs can coordinate their activities by solving local optimization problems and then conveying aspects of these solutions to their neighbors). The objective of such investigations is to determine how team members should share and exchange high-level information to best achieve team objectives. In this work, we consider more fundamental questions on the role that cooperation can play in supporting *communication itself*. Prior work on the question of how cooperation can benefit communication [13], [8], [4], [6], [20], [19] has approached this issue from the vantage point of a node's willingness to forward messages along the next hop (toward the intended destination) along a multi-hop path. Almost all prior research adopts the consumer MANET model, where node mobility is considered the sacrosanct domain of the user, autonomously determined and non-negotiable. While this is an appropriate conception of current consumer (e.g., cell phone and laptop) applications, it fails to leverage the

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