

Connor F. Henley

<https://connorhenley.engineer>

OBJECTIVE:	To be selected as a Resident Advisor, which will allow me to assist residents with their transition to college life and help them succeed during their time at RIT.		
EDUCATION:	Rochester Institute of Technology	Rochester, NY	
	Master of Science in Computer Engineering	Expected May 2021	
	Bachelor of Science in Computer Engineering, Minor in Computer Science	Expected May 2021	
	GPA: 3.46		
COURSES:	Assembly Language Programming	Introduction to Software Engineering	
	Circuits I	Mechanics of Programming	
	Computer Organization	Multi-variable Calculus	
	Digital Systems Design I & II	University Physics I & II	
SKILLS:	Software: Arduino IDE, Cura, Git, Linux, Microsoft Office, Windows Programming Languages: ARM Assembly, C, Java, L ^A T _E X, Python 3, VHDL		
EXPERIENCE:	FIRST Robotics	Oct 2009 - Present	
	• Volunteered at events to keep the event running smoothly	Apr 2014 - Present	
	• Co-captain on FRC (FIRST Robotics Competition) Team 1699	Sept 2012 - May 2016	
	• Directed the local FLL (FIRST Lego League) team	Oct 2009 - Dec 2011	
	Grader for Department of Computer Science	Aug 2017 - Present	
	Rochester Institute of Technology, Rochester NY		
	• Graded Mechanics of Programming programs (written in C) of students in a Linux environment		
	• Collaborated with another grader and the professor to ensure fair grading of all students		
	Public Relations for RIT FIRST	May 2017 - Present	
	Rochester NY		
	• Coordinated events and mentorship for FIRST teams near RIT		
	• Worked with other members of the Executive Board to solve issues in the club		
PROJECTS AND LABS:	Arduino Clock		
	• Created a internet-enabled clock using an Arduino Uno, TFT screen, Ethernet module, C++ code, and a custom 3D printed case		
	RIT FIRST's ImagineRIT Project		
	• Collaborated with other engineers and programmers to build small robots that are driven by attendees of ImagineRIT		
	• Led the redesign of the project for ImagineRIT 2018		
	Swerve Code for FRC Team 1699		
	• Programmed a swerve drive-train (and accompanying libraries), which is a complex drive base where all wheels can turn 360° and are independently steered and driven.		
	WebCheckers for Intro to Software Engineering		
	• Worked in a team of students to complete a web application for playing checkers (including an AI and game spectating)		
	• Utilized Java, git, Spark micro-webframework, Apache Maven, and JUnit		
AWARDS:	• Chairman's Award from FRC Team 1699 • Dean's List Nominee from FRC Team 1699 • Dean's List from Kate Gleason College of Engineering, Spring 2017		
ACTIVITIES AND HOBBIES:	RIT FIRST Robotics Club	Sept 2016 - Present	
	• Mentored local FIRST robotics teams, assisting with programming, electronics, team building, and game analysis		
	• Elected for the Executive Board in the Public Relations position	May 2016 - Present	
	3D Printing Enthusiast		
	2017 Freshman Move-in Volunteer		
	BrickHack 3 Hacker	Feb 11 and 12 2017	