Connor F. Henley

https://connorhenley.engineer

OBJECTIVE: To be selected as a Resident Advisor, which will allow me to assist residents with their transition to

college life and help them succeed during their time at RIT.

EDUCATION: Rochester Institute of Technology Rochester, NY

> Master of Science in Computer Engineering Expected May 2021

> Bachelor of Science in Computer Engineering, Minor in Computer Science Expected May 2021

GPA: 3.46

COURSES: Assembly Language Programming Introduction to Software Engineering

> Circuits I Mechanics of Programming Computer Organization Multi-variable Calculus Digital Systems Design I & II University Physics I & II

SKILLS: Software: Arduino IDE, Cura, Git, Linux, Microsoft Office, Windows

Programming Languages: ARM Assembly, C, Java, IATEX, Python 3, VHDL

Oct 2009 - Present **EXPERIENCE:** FIRST Robotics

> • Volunteered at events to keep the event running smoothly Apr 2014 - Present • Elected to co-captain position on FRC Team 1699 Sept 2012 - May 2016 Oct 2009 - Dec 2011

> • Directed the local FLL (FIRST Lego League) team

Grader for Department of Computer Science Aug 2017 - Present

Rochester Institute of Technology, Rochester NY

• Graded Mechanics of Programming programs (written in C) of students in a Linux environment

• Collaborated with another grader and the professor to ensure fair grading of all students

Public Relations for RIT FIRST

May 2017 - Present

Rochester NY

• Coordinated events and mentorship for FIRST teams near RIT

• Worked with other members of the Executive Board to ensure that everything ran smoothly

PROJECTS AND LABS:

Arduino Clock

• Created a internet-enabled clock using an Arduino Uno, TFT screen, Ethernet module, C++ code, and a custom 3D printed case

RIT FIRST's ImagineRIT Project

- Collaborated with other engineers and programmers to build small robots that are driven by attendees of ImagineRIT
- Led the redesign of the project for ImagineRIT 2018

Swerve Code for FRC (FIRST Robotics Competition) Team 1699

• Programmed a swerve drive-train (and accompanying libraries), which is a complex drive base where all wheels can turn 360° and are independently steered and driven.

WebCheckers for Intro to Software Engineering

- Worked in a team of students to complete a web application for playing checkers (including an AI and game spectating)
- Utilized Java, git, Spark micro-webframework, Apache Mayen, and JUnit

AWARDS:

- Chairman's Award from FRC Team 1699
- Dean's List Nominee from FRC Team 1699
- Dean's List from Kate Gleason College of Engineering, Spring 2017

ACTIVITIES AND HOBBIES:

RIT FIRST Robotics Club

Sept 2016 - Present

- Mentored local FIRST robotics teams, assisting with programming, electronics, team building, and game analysis
- Elected for the Executive Board in the Public Relations position May 2016 - Present

3D Printing Enthusiast

BrickHack 3 Hacker Feb 11 and 12 2017