view_frames Result Recorded at time: 1510732851.231 world Broadcaster: /ref_base_to_world Broadcaster: /base_to_world Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1510732851.231 sec old) Most recent transform: 0.000 (1510732851.231 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base L reference/base Broadcaster: /robot_ref_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.199 Hz Average rate: 50.210 Hz Average rate: 50.199 Hz Average rate: 50.210 Hz Average rate: 50.210 Hz Average rate: 50.210 Hz Average rate: 50.210 Hz Average rate: 50.199 Hz Average rate: 50.199 Hz Average rate: 50.199 Hz Most recent transform: 1510732851.714 (-0.483 sec old) | Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) Buffer length: 4.899 sec Buffer length: 4.899 sec Buffer length: 4.899 sec Buffer length: 4.899 sec Buffer length: 4.900 sec Buffer length: 4.899 sec Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec reference/pedestal_feet controller_box pedestal_feet pedestal reference/pedestal reference/right_arm_base_link reference/torso (torso right_arm_base_link reference/controller_box Broadcaster: /robot ref publisher Broadcaster: /robot_state_publisher Average rate: 39.388 Hz Average rate: 39.024 Hz Most recent transform: 1510732851.220 (0.011 sec old) Most recent transform: 1510732851.218 (0.013 sec old) Buffer length: 4.900 sec Buffer length: 4.920 sec right_10 reference/right_10 Broadcaster: /robot_state_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 39.388 Hz Average rate: 39.024 Hz Average rate: 39.388 Hz Average rate: 50.210 Hz Average rate: 39.024 Hz Average rate: 50.199 Hz Most recent transform: 1510732851.220 (0.011 sec old) | Most recent transform: 1510732851.220 (0.011 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.218 (0.013 sec old) Most recent transform: 1510732851.218 (0.013 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.899 sec Buffer length: 4.920 sec Buffer length: 4.920 sec Buffer length: 4.900 sec reference/head head right_11 reference/right_torso_itb reference/right_11 right_torso_itb Broadcaster: /robot_ref_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_ref_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: $50.2\overline{10}$ Hz Average rate: $50.2\overline{10}$ Hz Average rate: 39.388 Hz Average rate: 50.210 Hz Average rate: 39.024 Hz Average rate: 50.199 Hz Average rate: 50.199 Hz Average rate: 50.199 Hz Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.220 (0.011 Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) ost recent transform: 1510732851.218 (0.013 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) Buffer length: 4.900 sec Buffer length: 4.899 sec Buffer length: 4.899 sec Buffer length: 4.920 sec Buffer length: 4.899 sec Buffer length: 4.900 sec Buffer length: 4.900 sec Buffer length: 4.900 sec head_camera reference/head_camera reference/right_11_2 reference/right_12 reference/screen 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Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Average rate: 50.210 Hz Average rate: 39.024 Hz Average rate: 50.199 Hz Average rate: 50.199 Hz Average rate: 39.388 Hz Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.220 (0.011 sec old) Buffer length: 4.899 sec Buffer length: 4.900 sec Buffer length: 4.899 sec Buffer length: 4.920 sec Buffer length: 4.900 sec Buffer length: 4.900 sec right_15 reference/right_15 reference/right_14_2 reference/right_arm_itb right_arm_itb right_14_2 Broadcaster: /robot_ref_publisher Broadcaster: /robot ref publisher Broadcaster: /robot ref publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 39.388 Hz Average rate: 39.024 Hz Average rate: 50.210 Hz Average rate: 50.210 Hz Average rate: 50.199 Hz Average rate: 50.199 Hz Most recent transform: 1510732851.218 (0.013 sec old) 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right_gripper_base Broadcaster: /robot_ref_publisher Broadcaster: /robot_state_publisher Average rate: 50.210 Hz Average rate: 50.199 Hz Most recent transform: 1510732851.714 (-0.483 sec old) Most recent transform: 1510732851.714 (-0.483 sec old) Buffer length: 4.899 sec Buffer length: 4.900 sec reference/right_gripper right_gripper