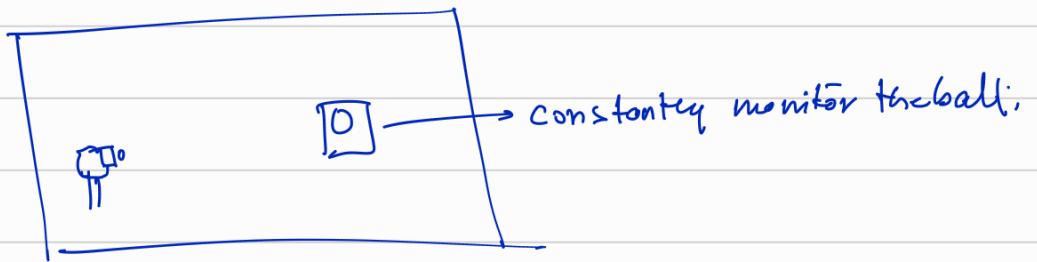
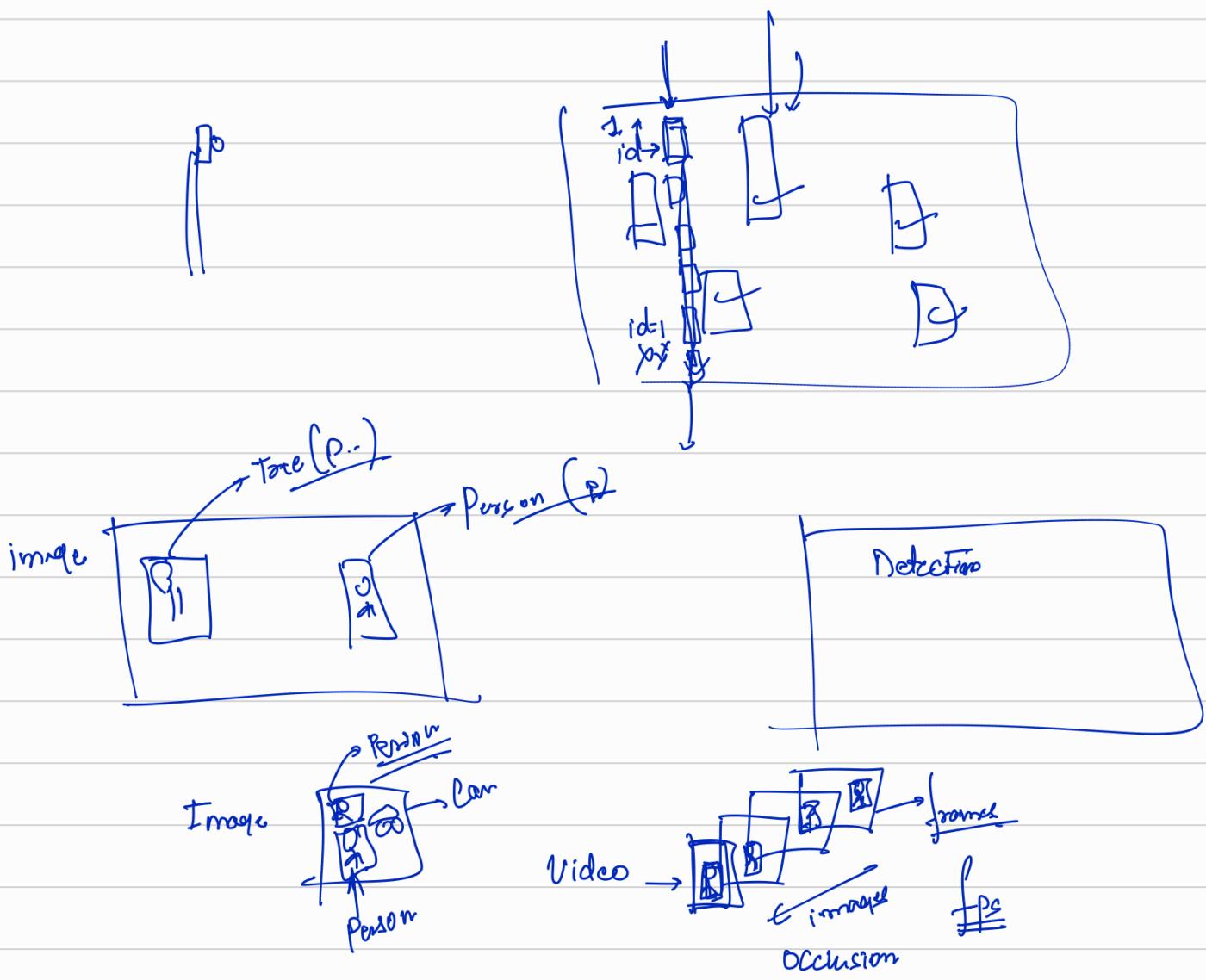


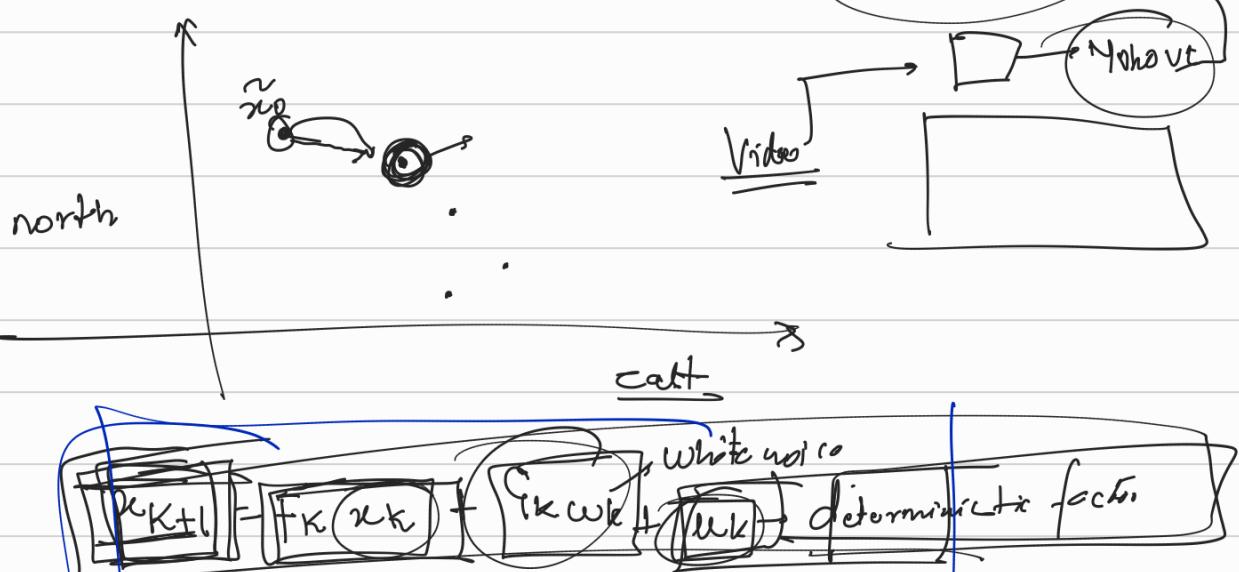
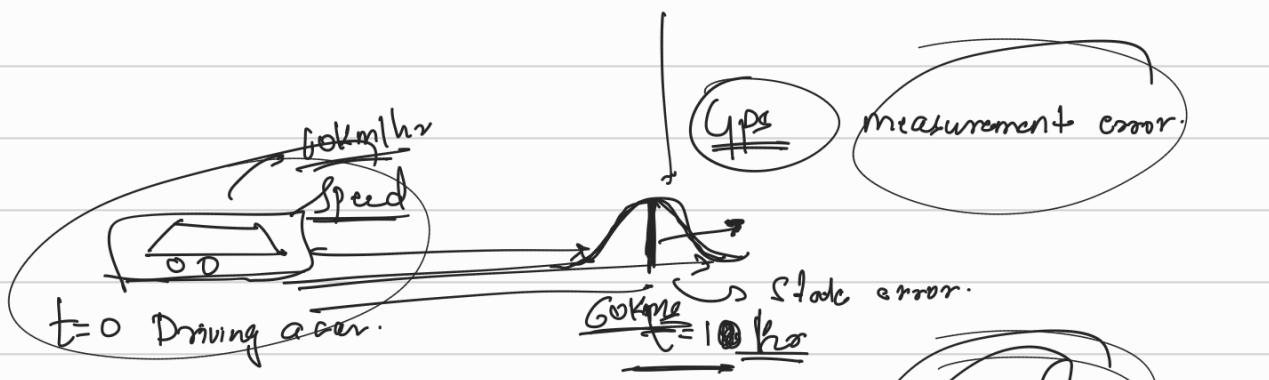
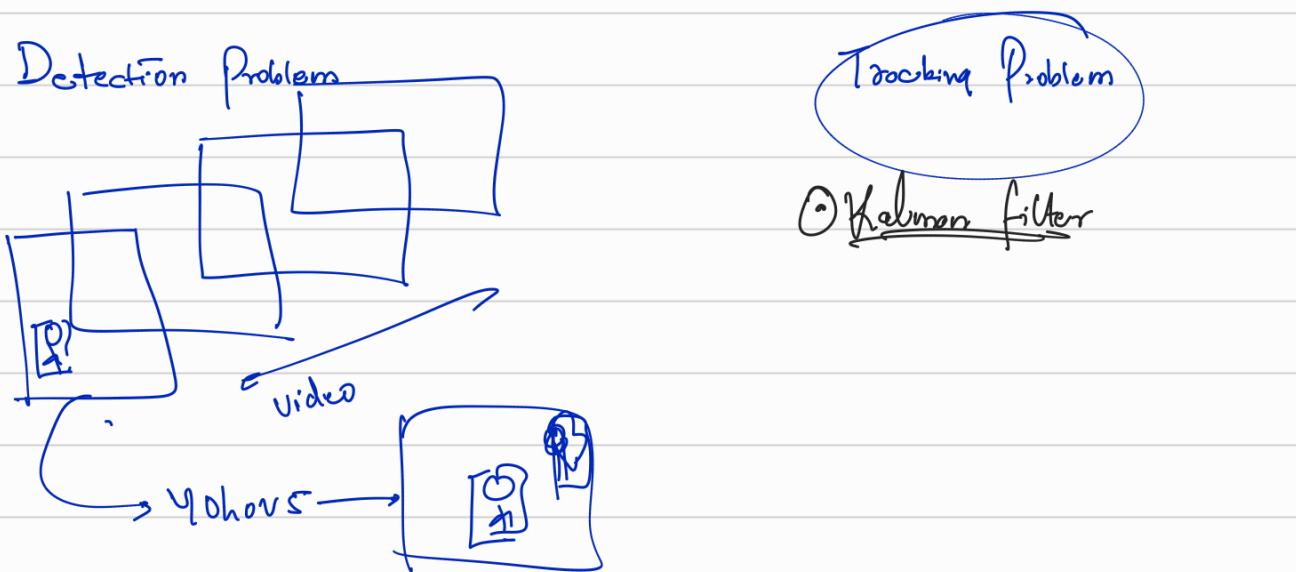
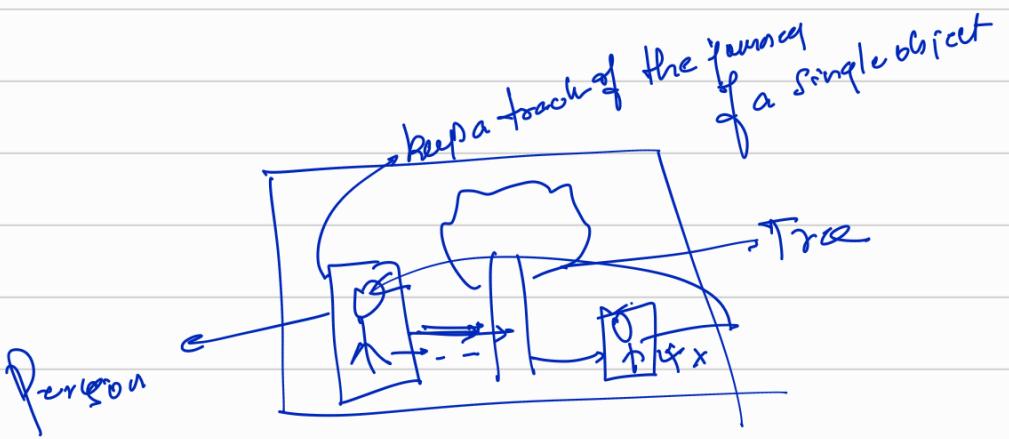
## Object detection

### ↳ Object Tracking



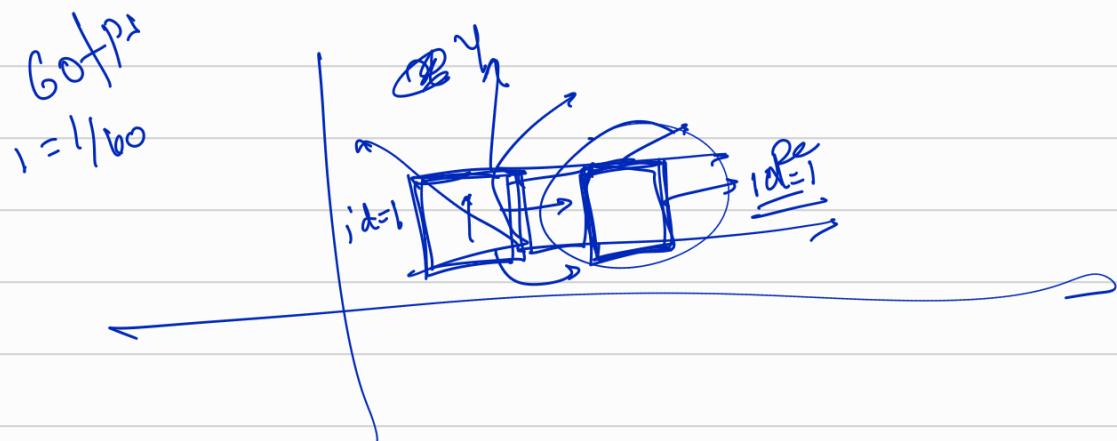
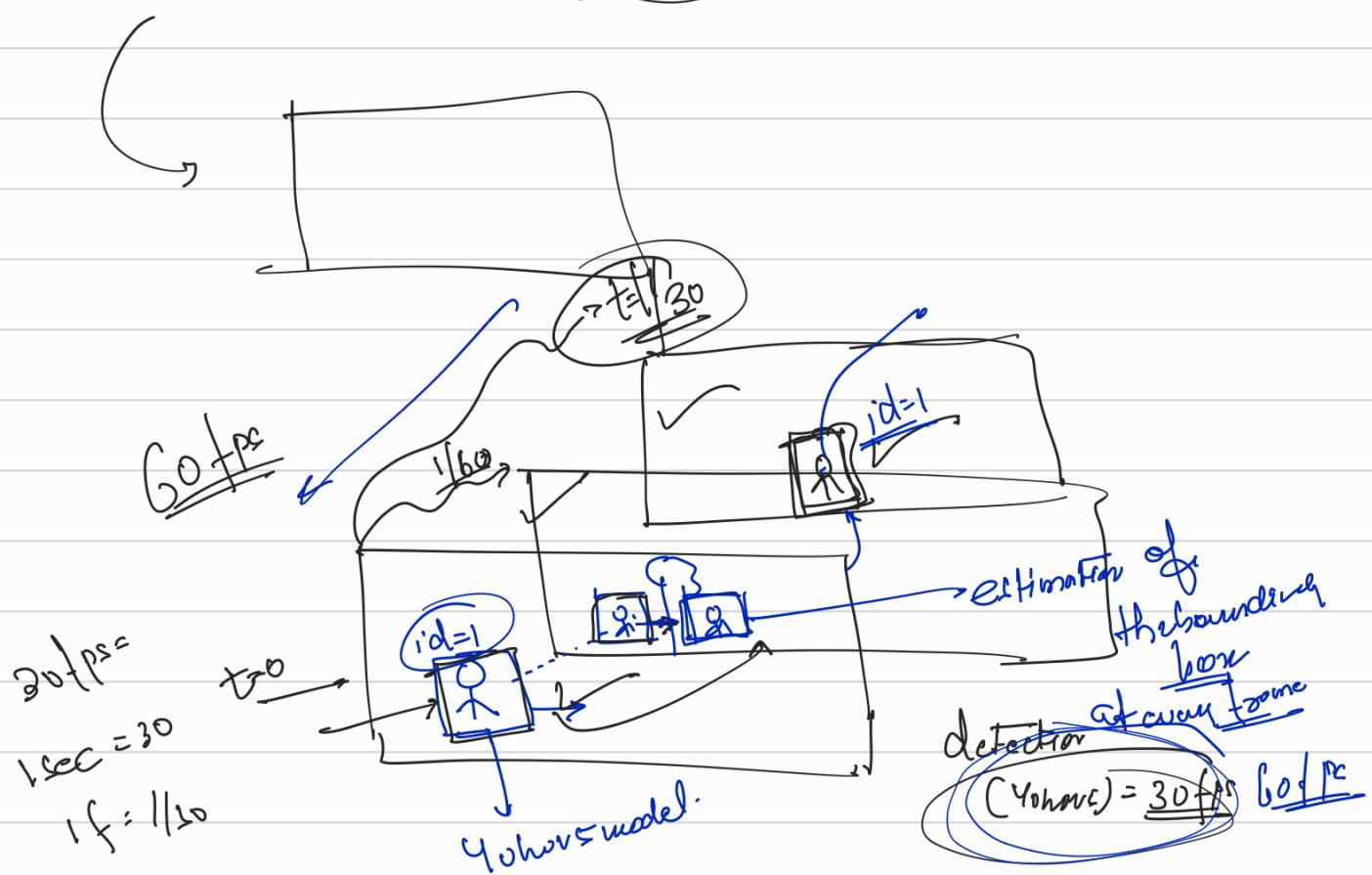
CCV footage → Traffic cone

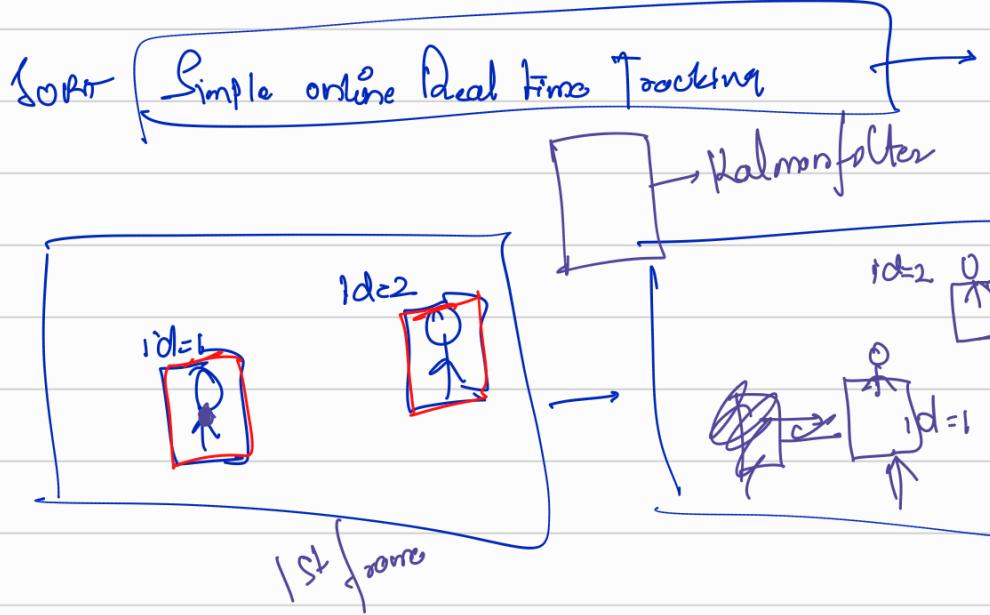




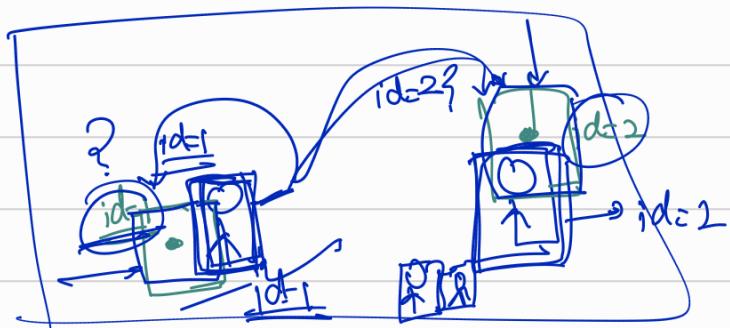
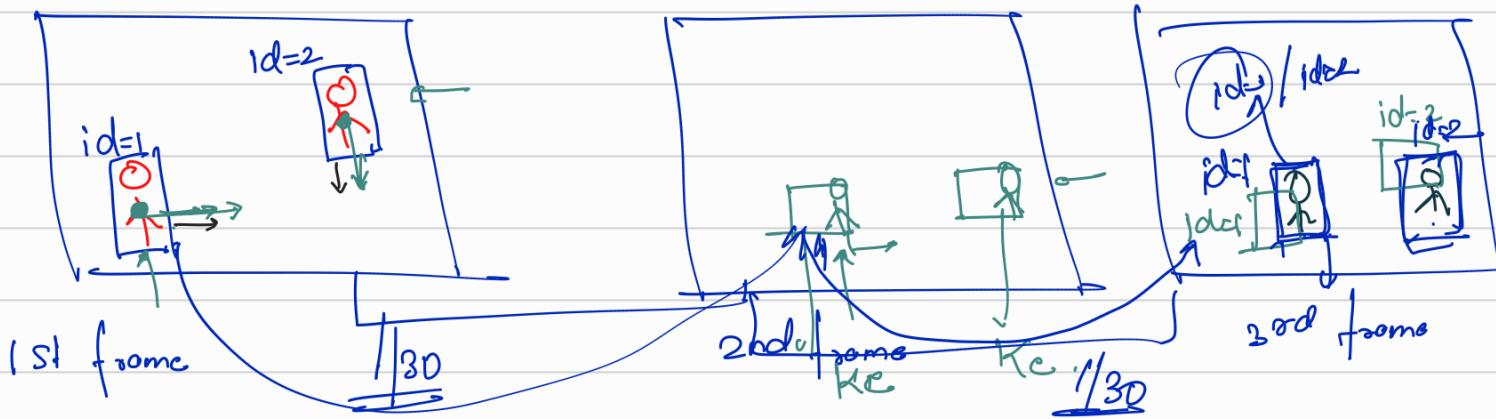
$$z_k = H_k x_k + v_k \rightarrow \text{measurement/noise}$$

measurement / observed position



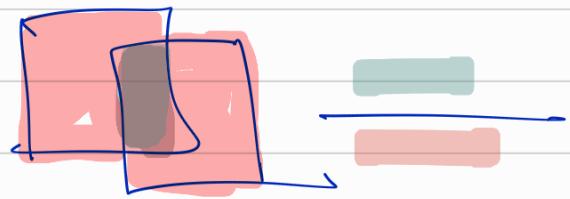
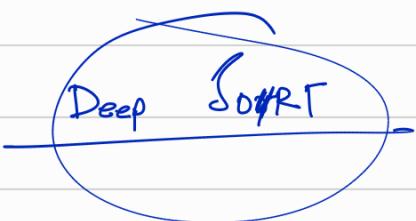


→  $Ke$    →  $YD$



Intersection Over Union

Deep SORT



60 FPS

1st frame

2nd frame

~~global tracker~~



1:1m

150 Km/hr

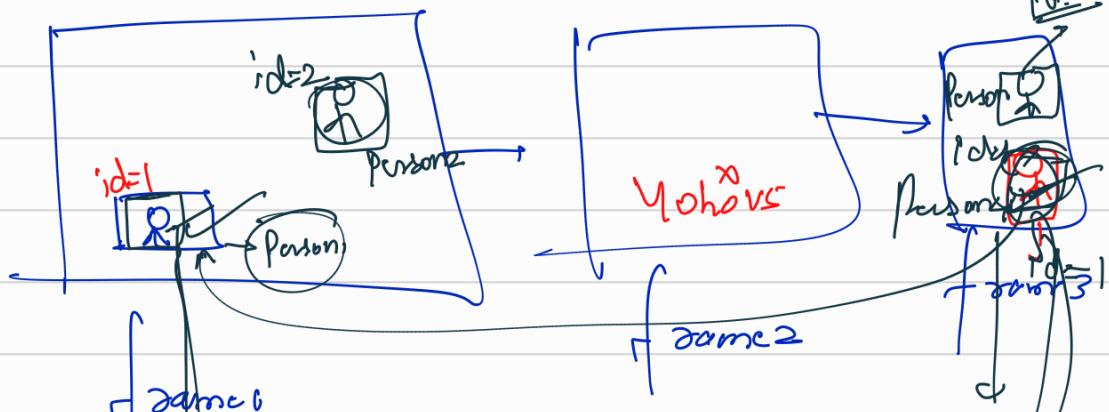
1/60 of seconds

$$\frac{150 \text{ Km}}{3600} \times \frac{1}{60}$$

+ 0.001

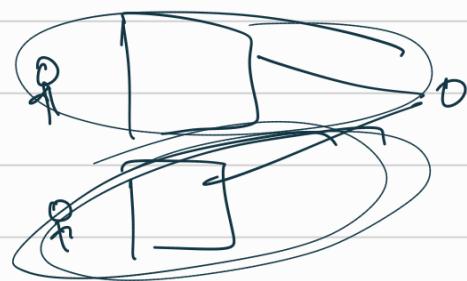
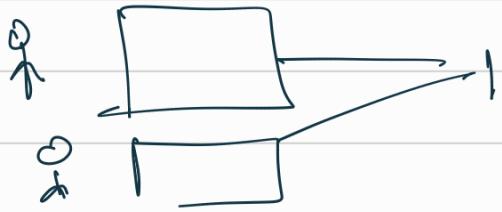
1 m

Deep SORT

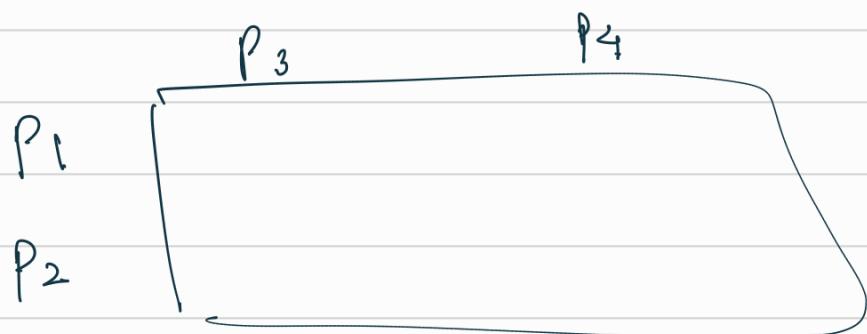


id assignment  
problem





$id=1$



$P_2, P_3 \quad P_2 P_4$

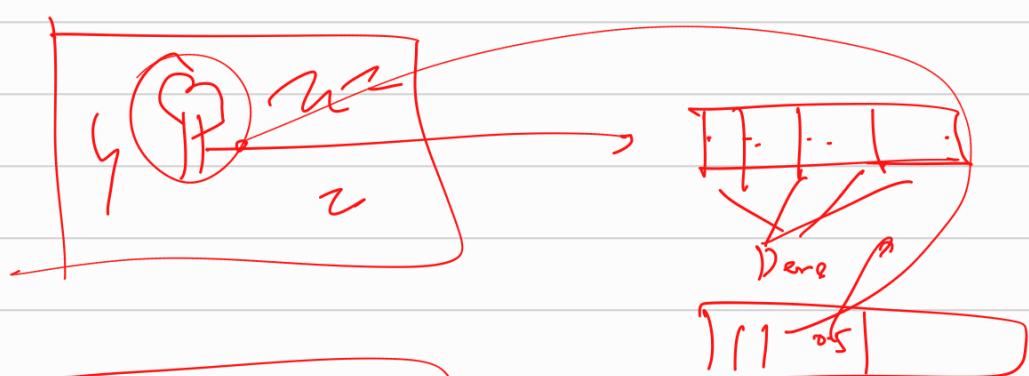
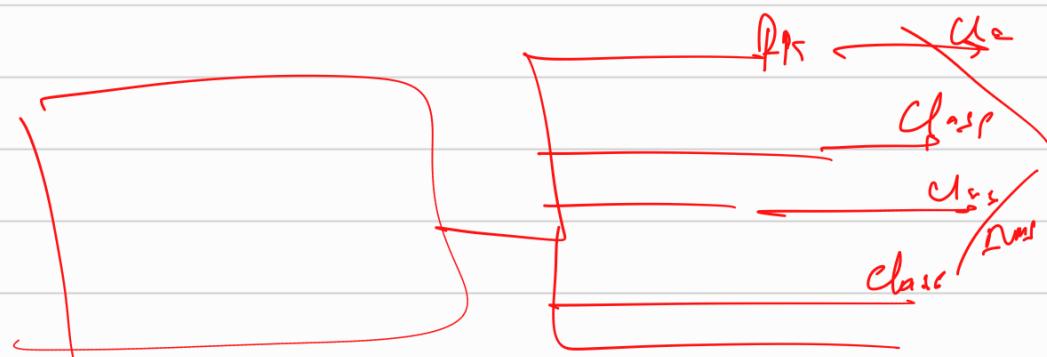
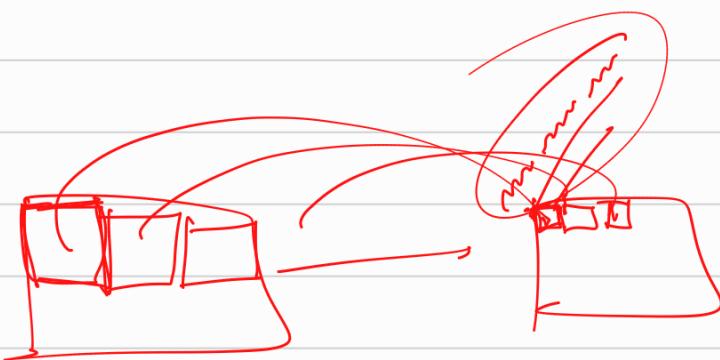
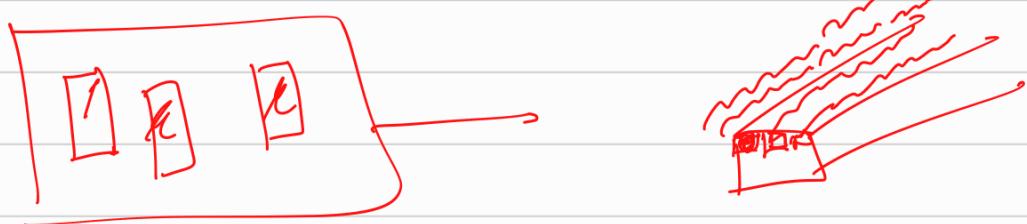
Deep Sort T  
Combined output (IOT + Euclidean dist.)

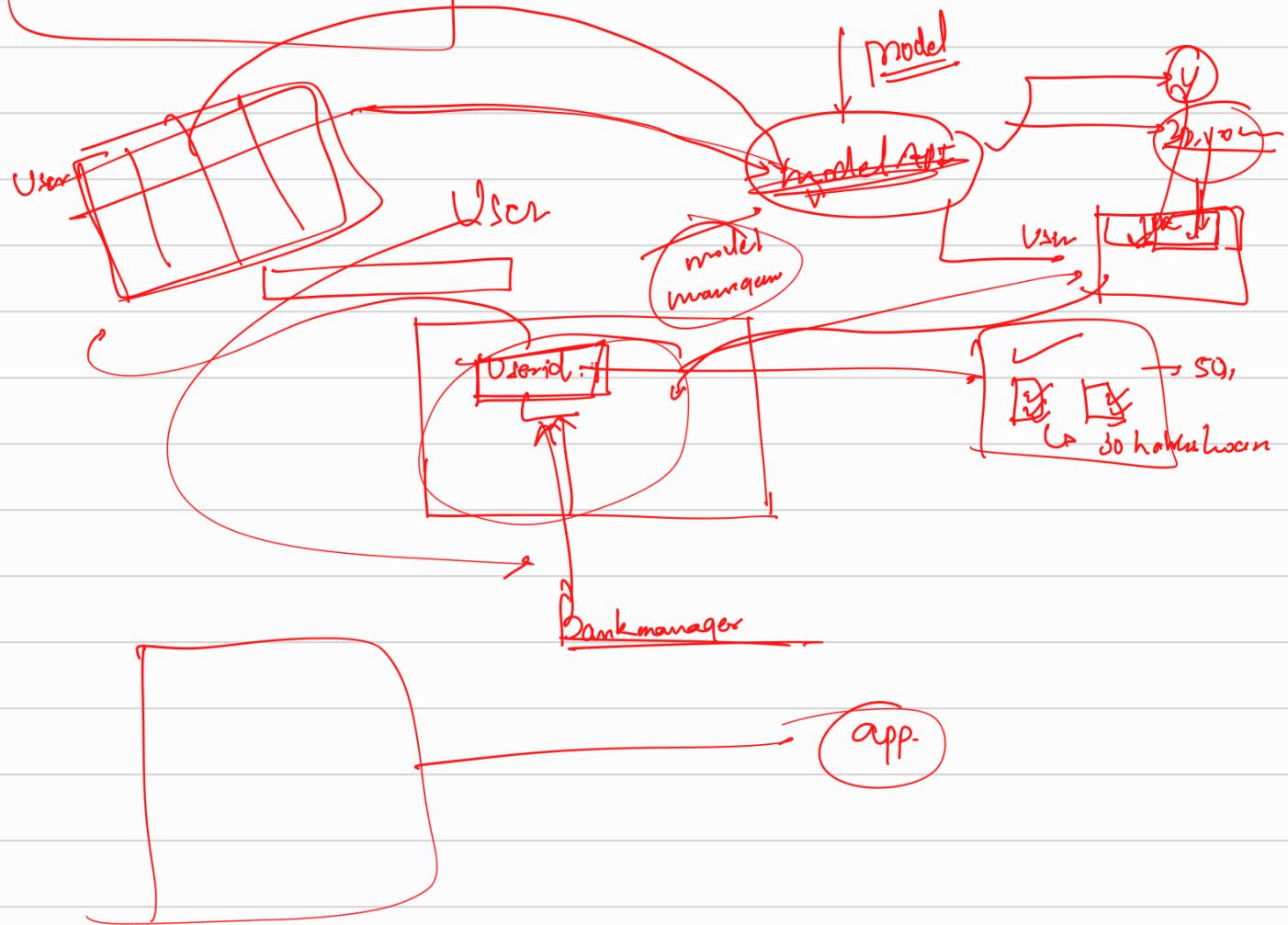
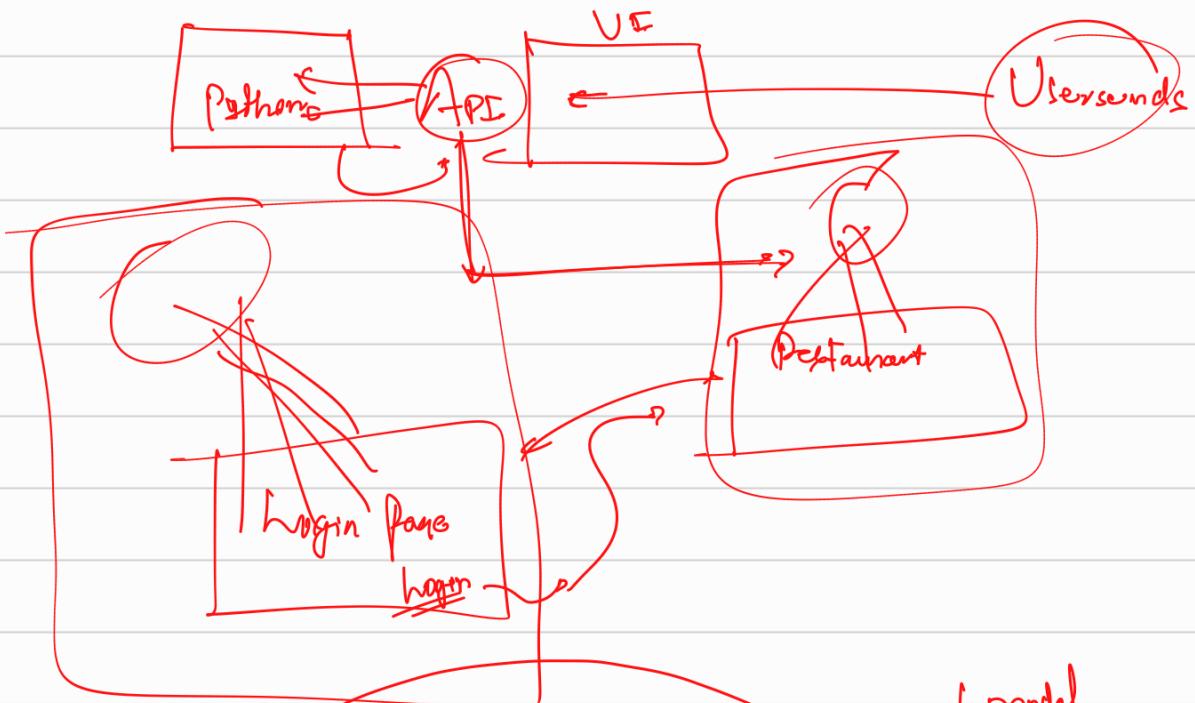
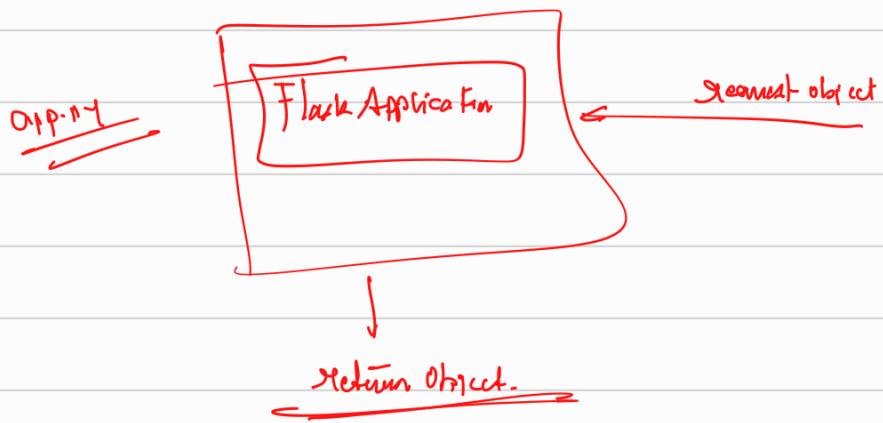
9:20 pm → 9:30 pm  
9:30 → 10:15 Code.

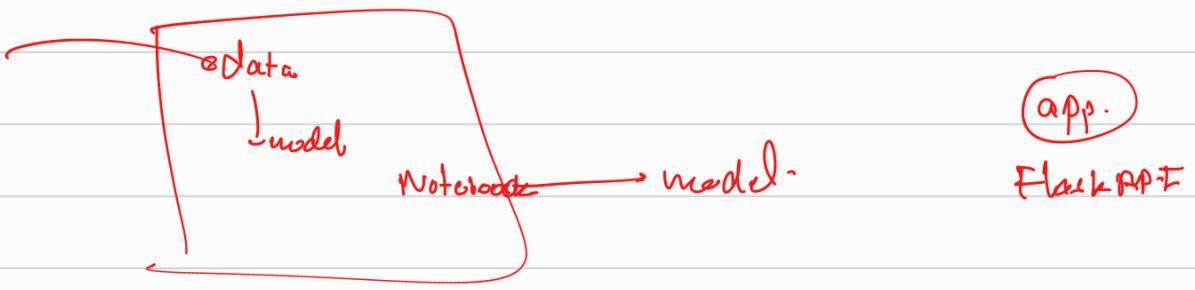
Cv → Image classification

- ① fast run video
- ② less resource for object tracking

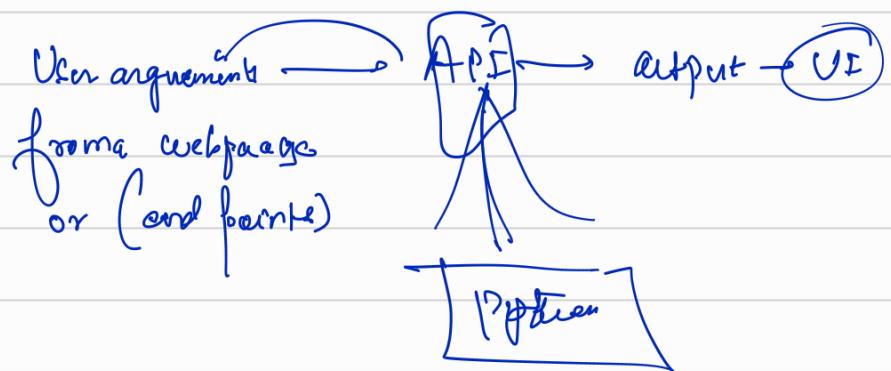




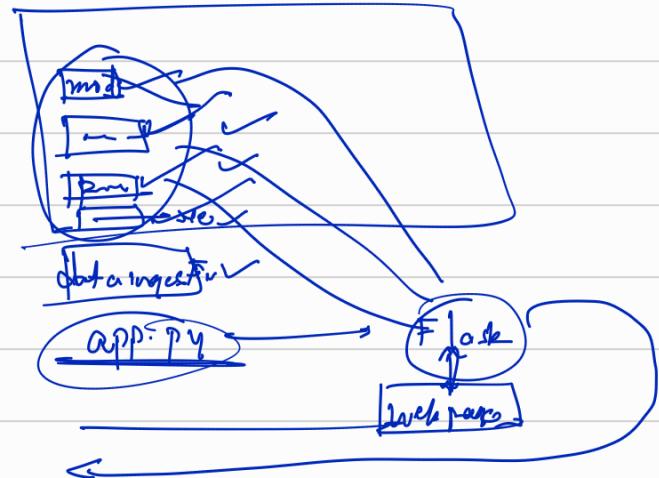




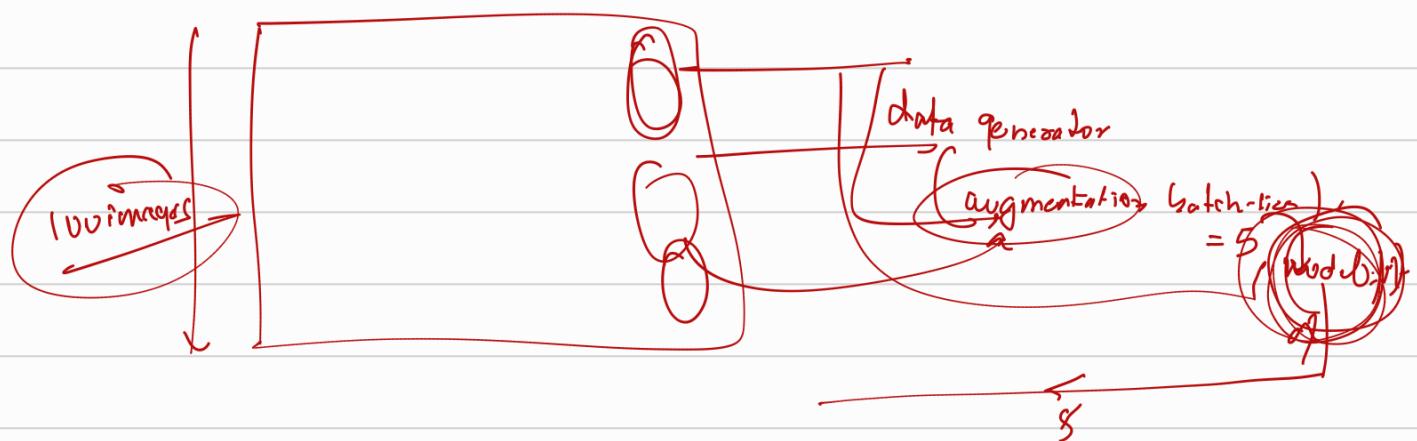
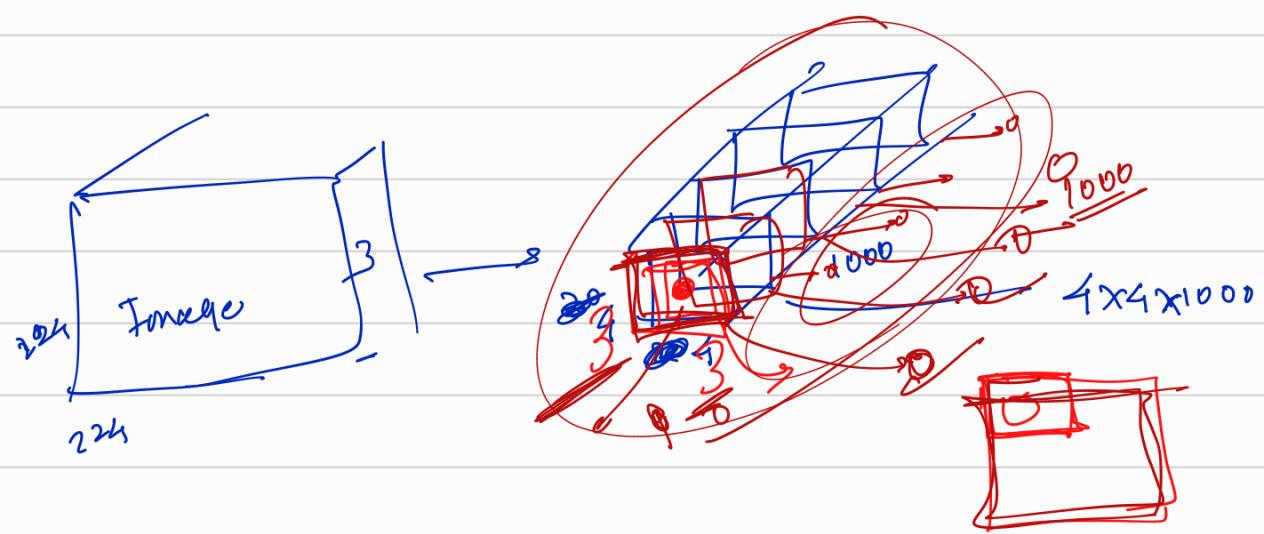
argument → Functions → output

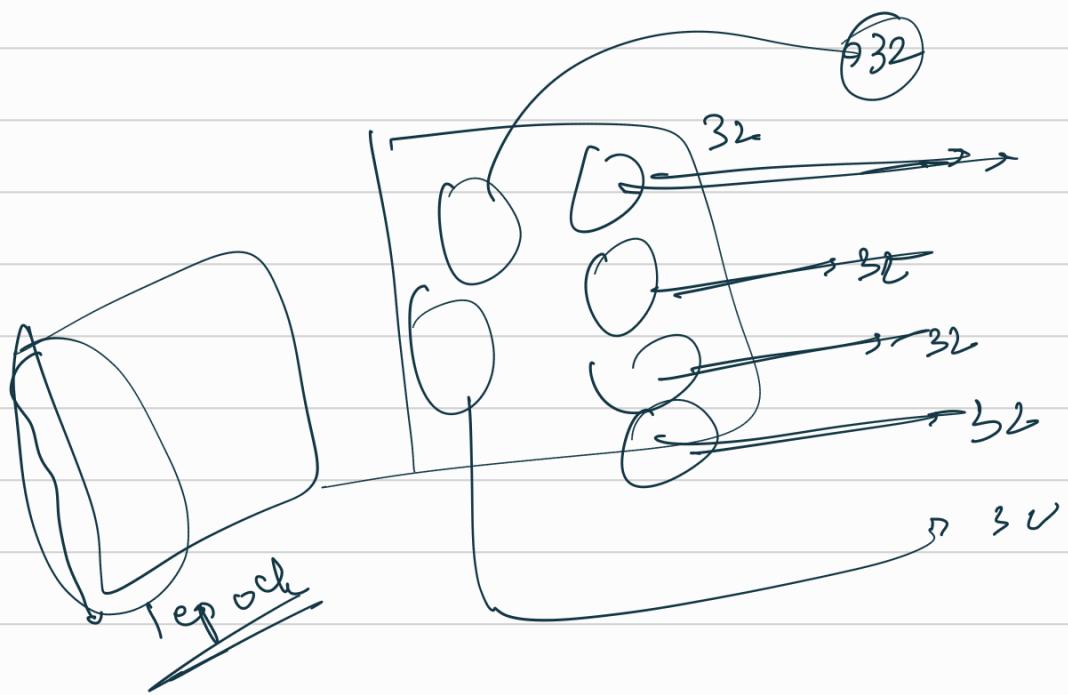
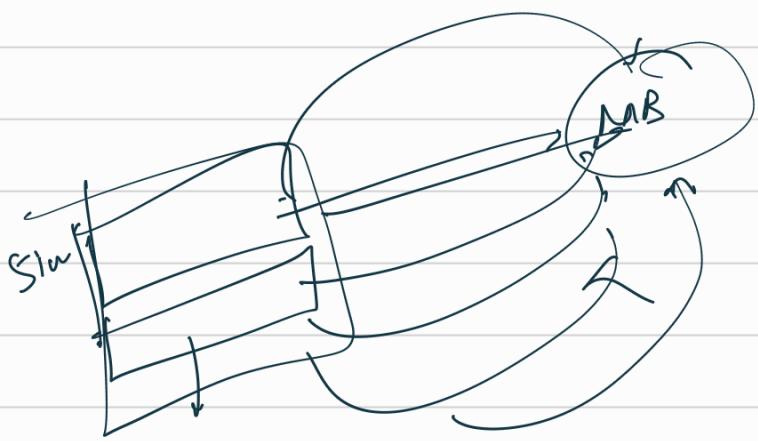
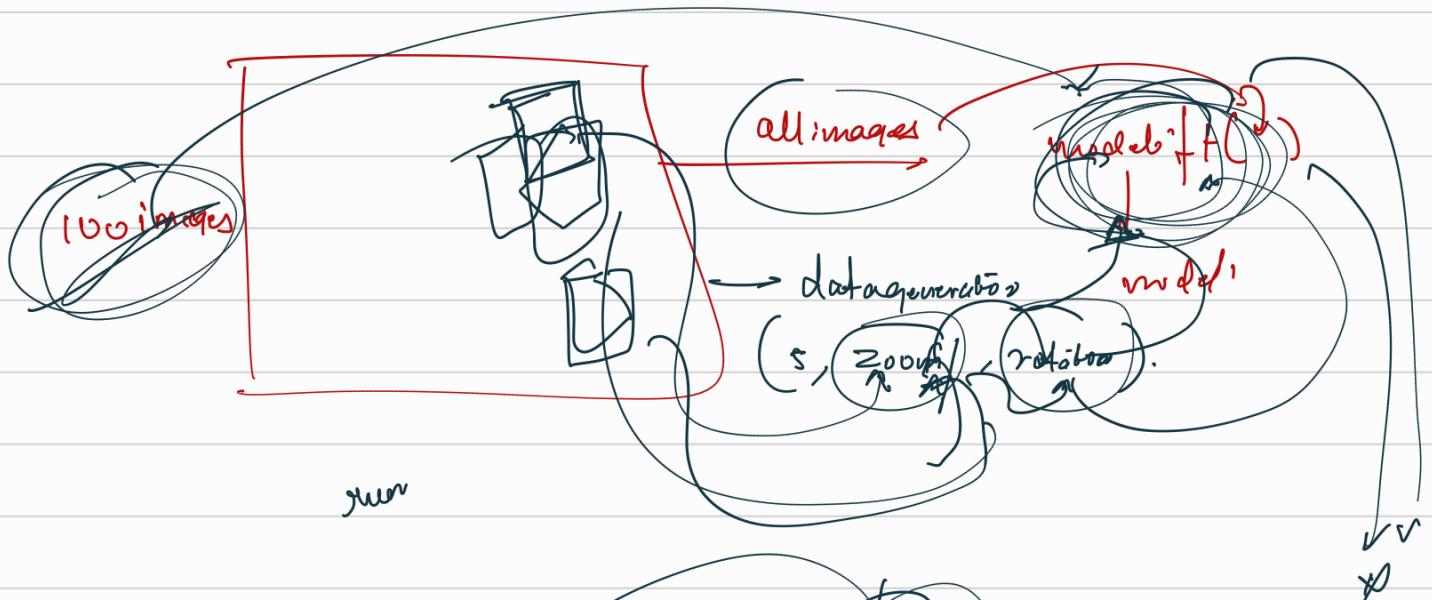


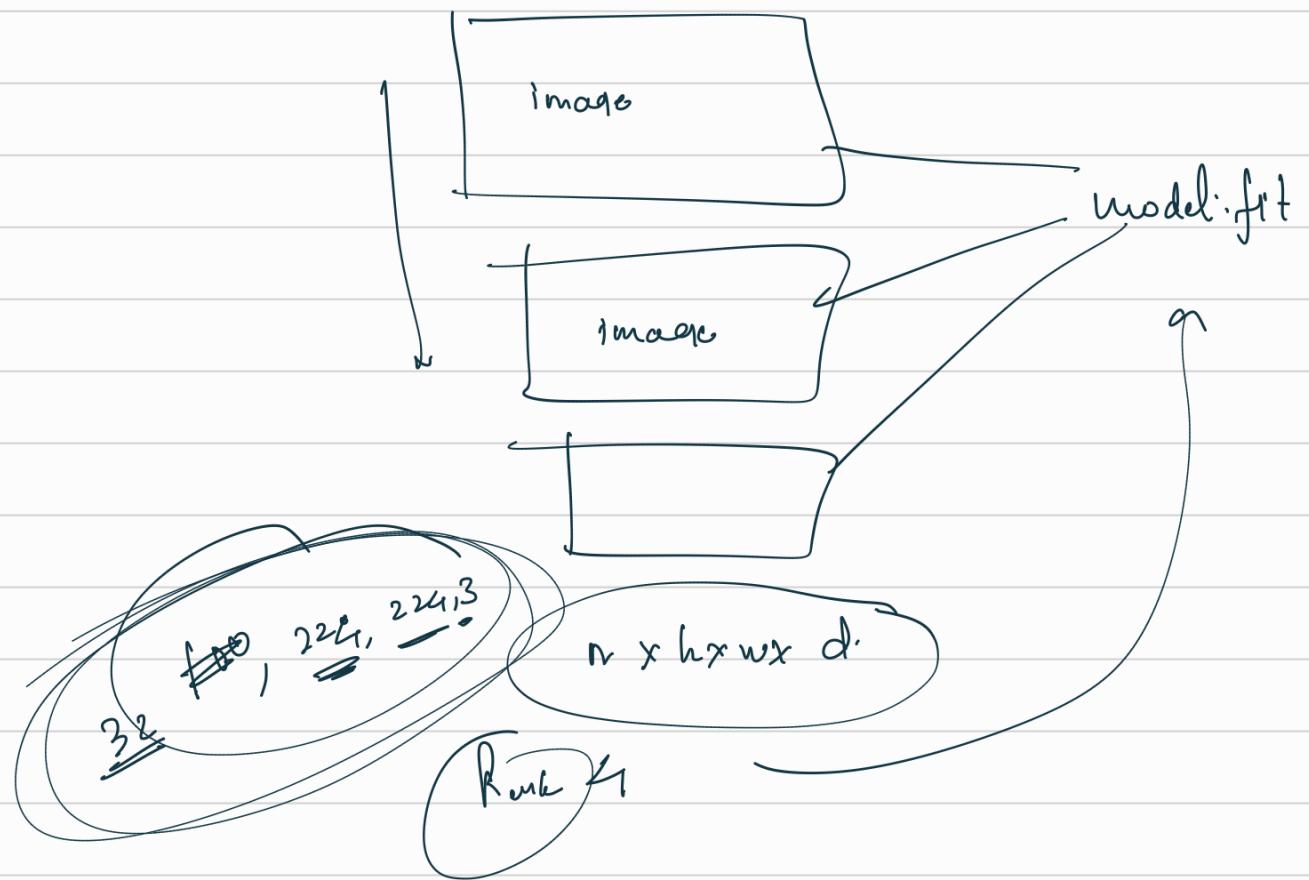
VS code



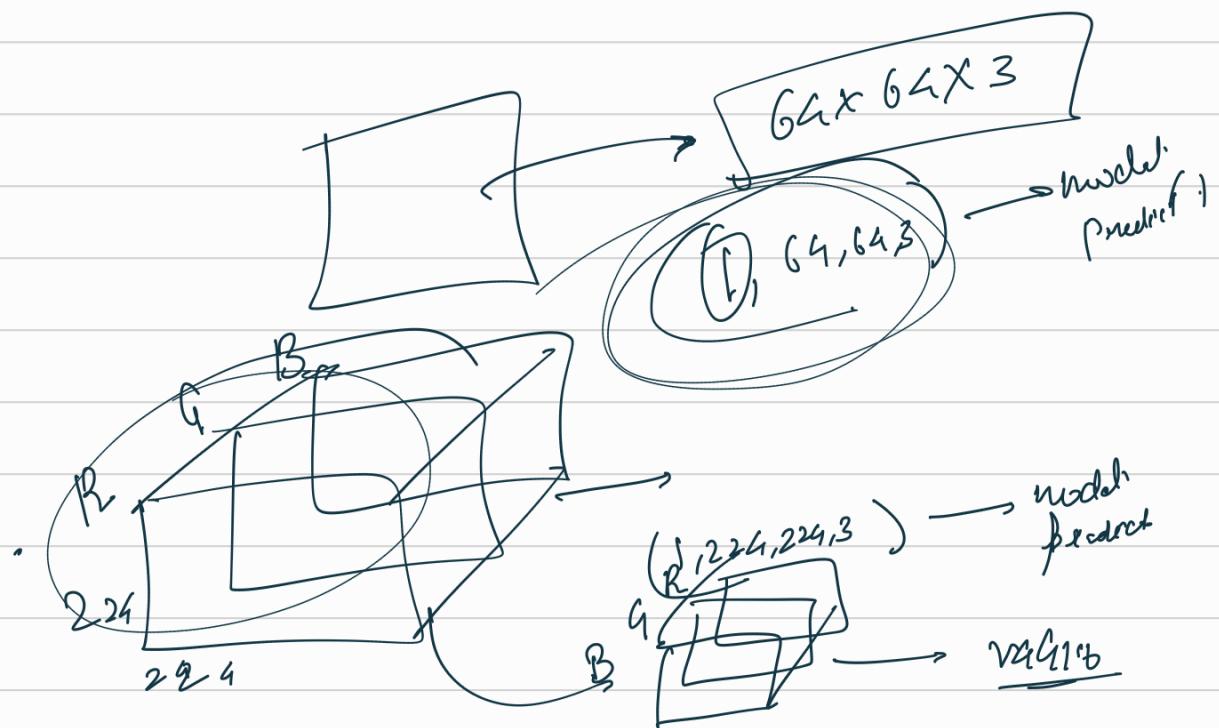
User

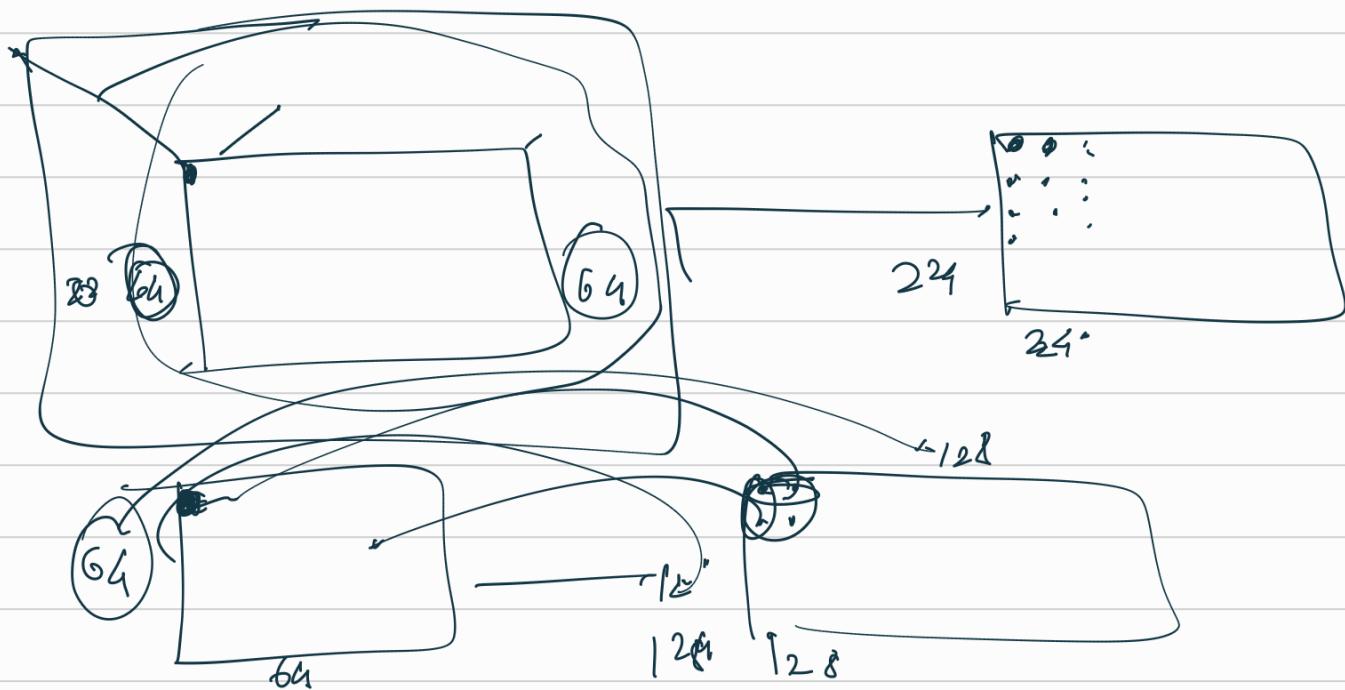
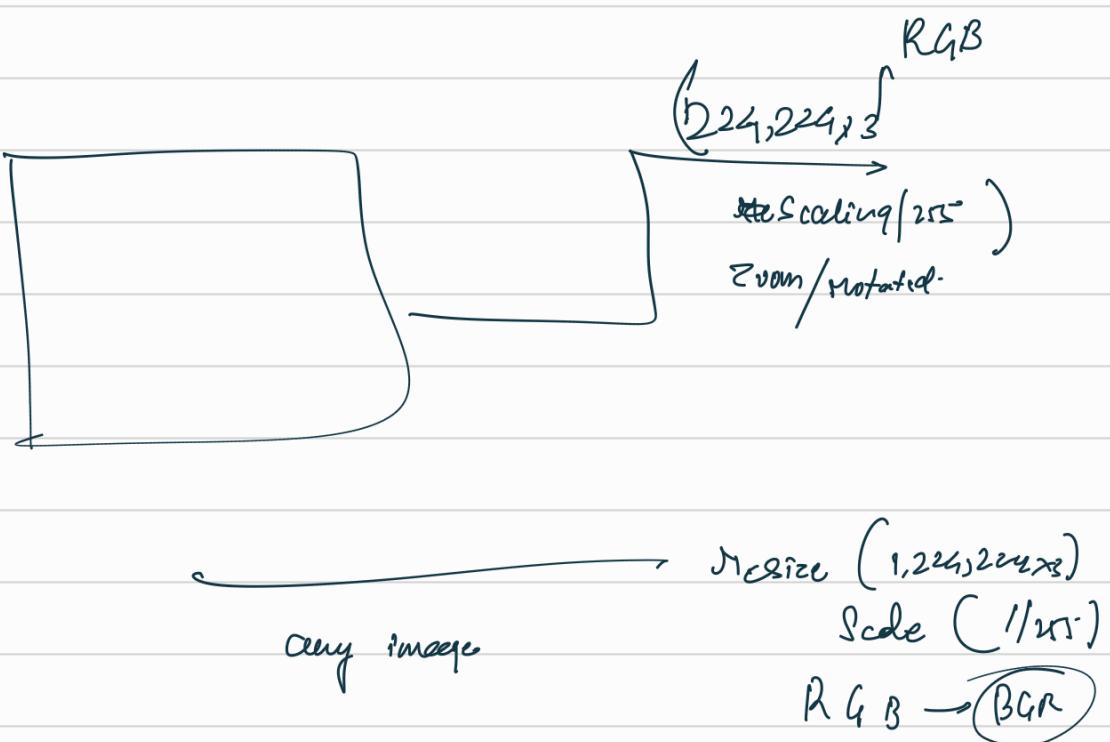
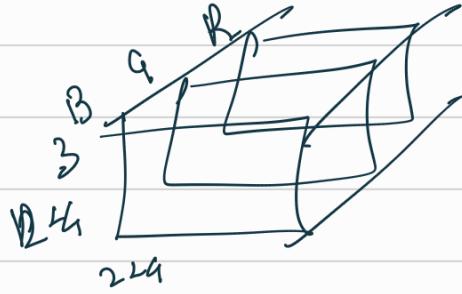


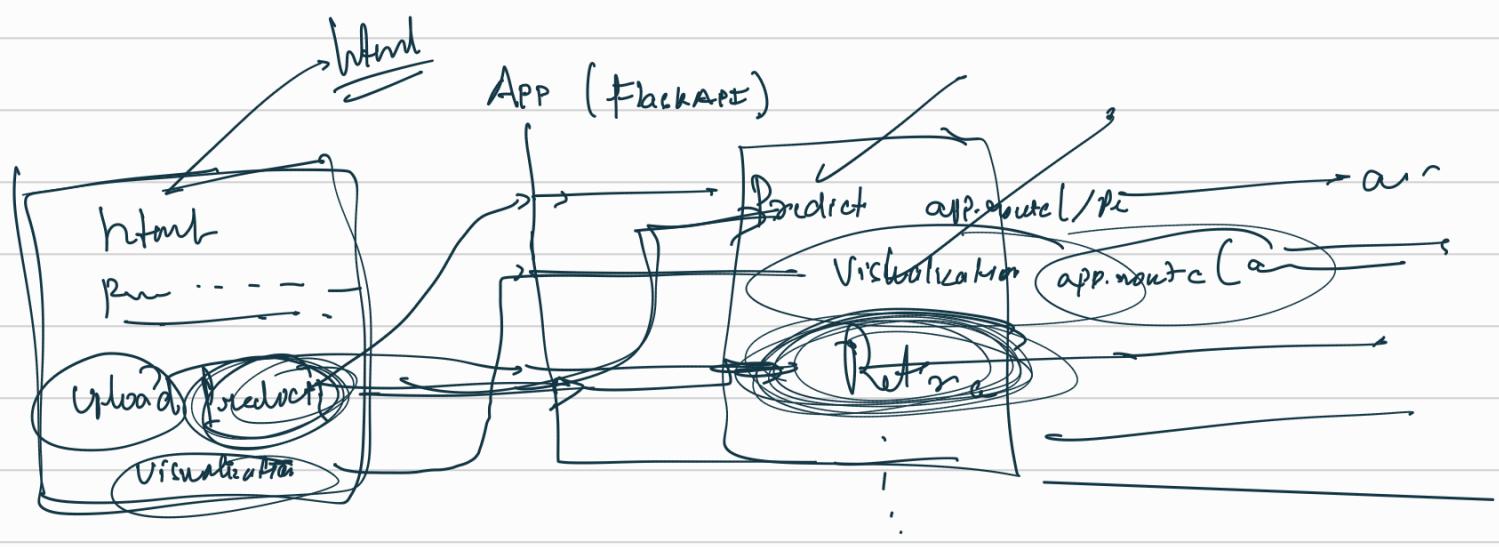
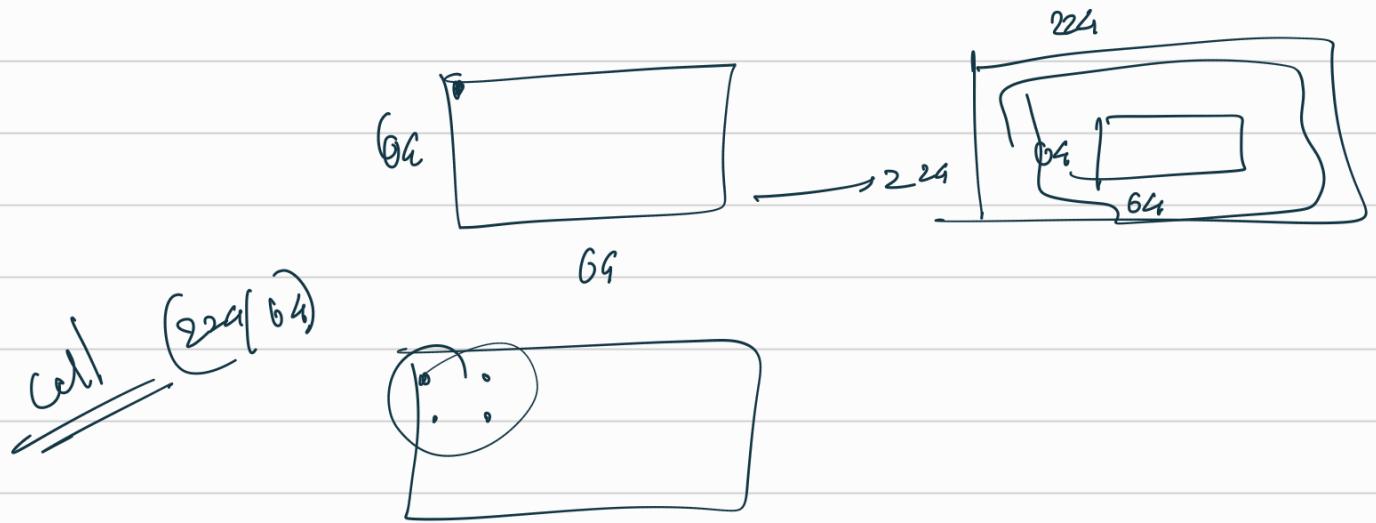




Keras



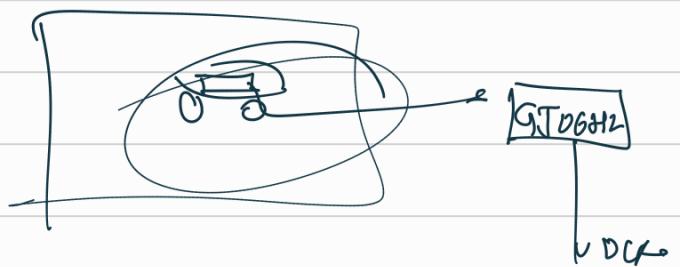
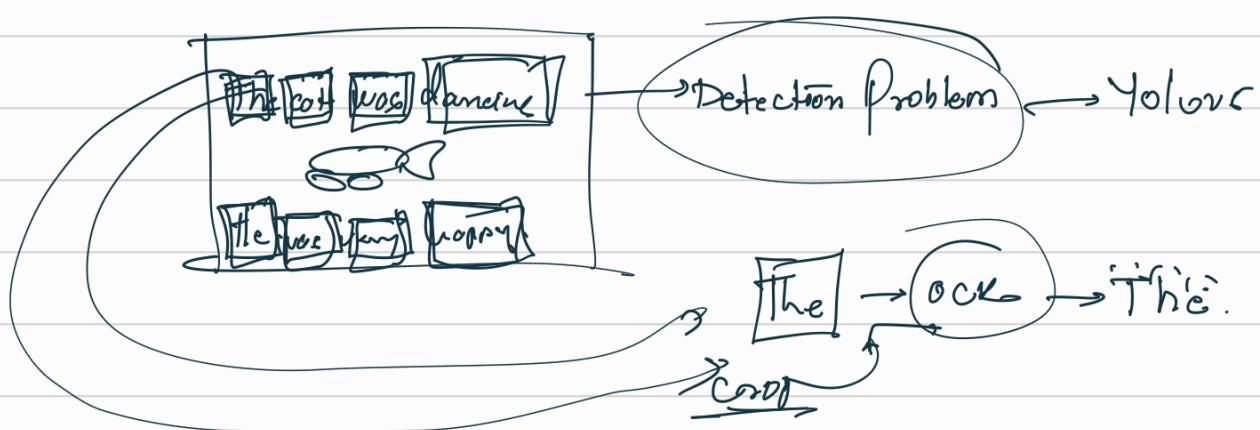




OGR → Optical character Recognition

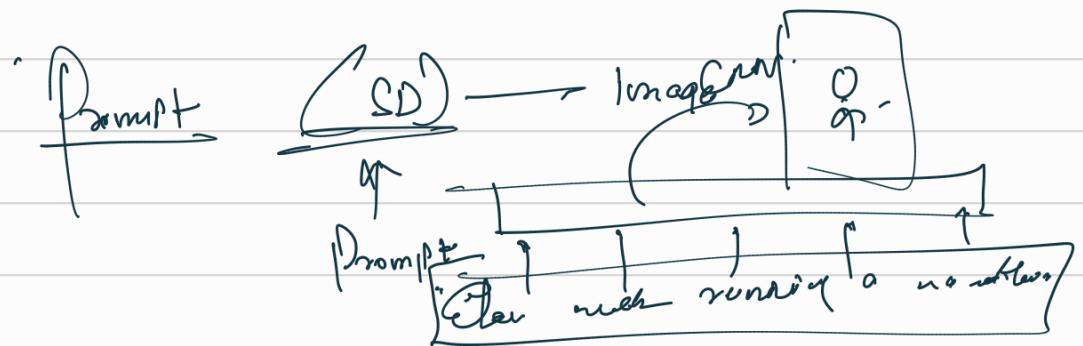
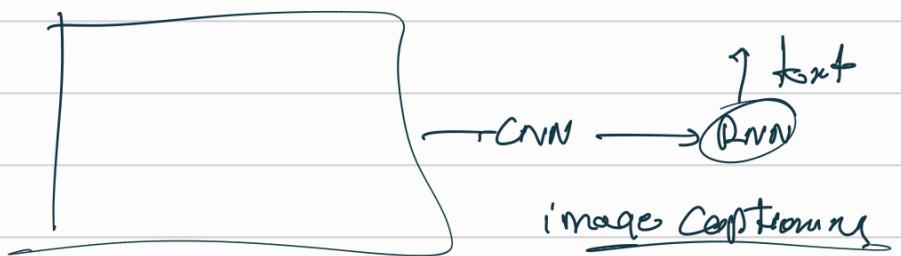
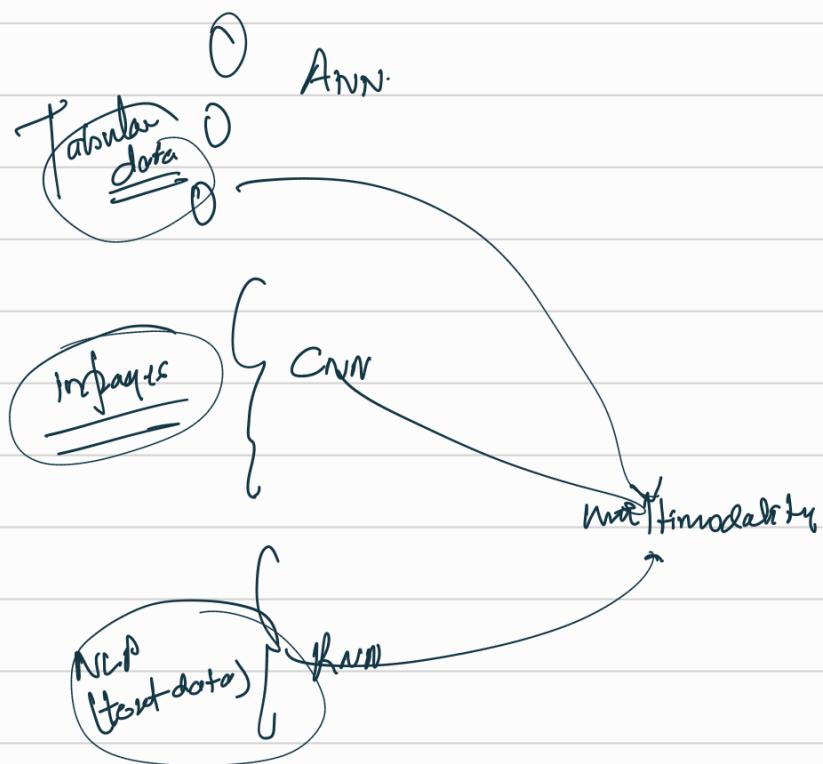


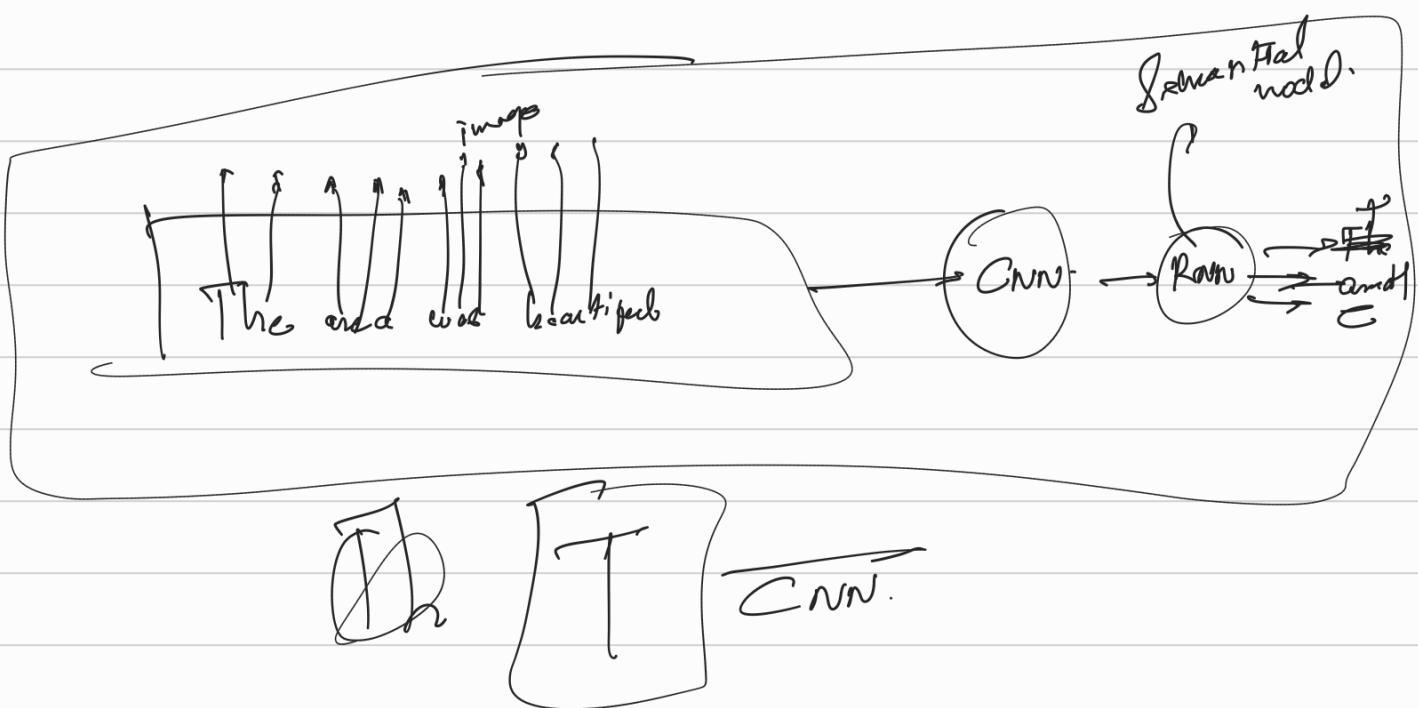
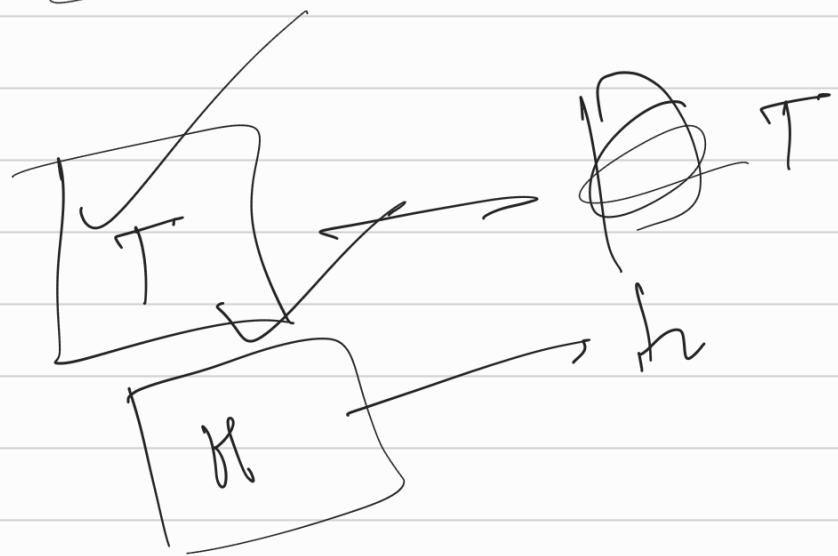
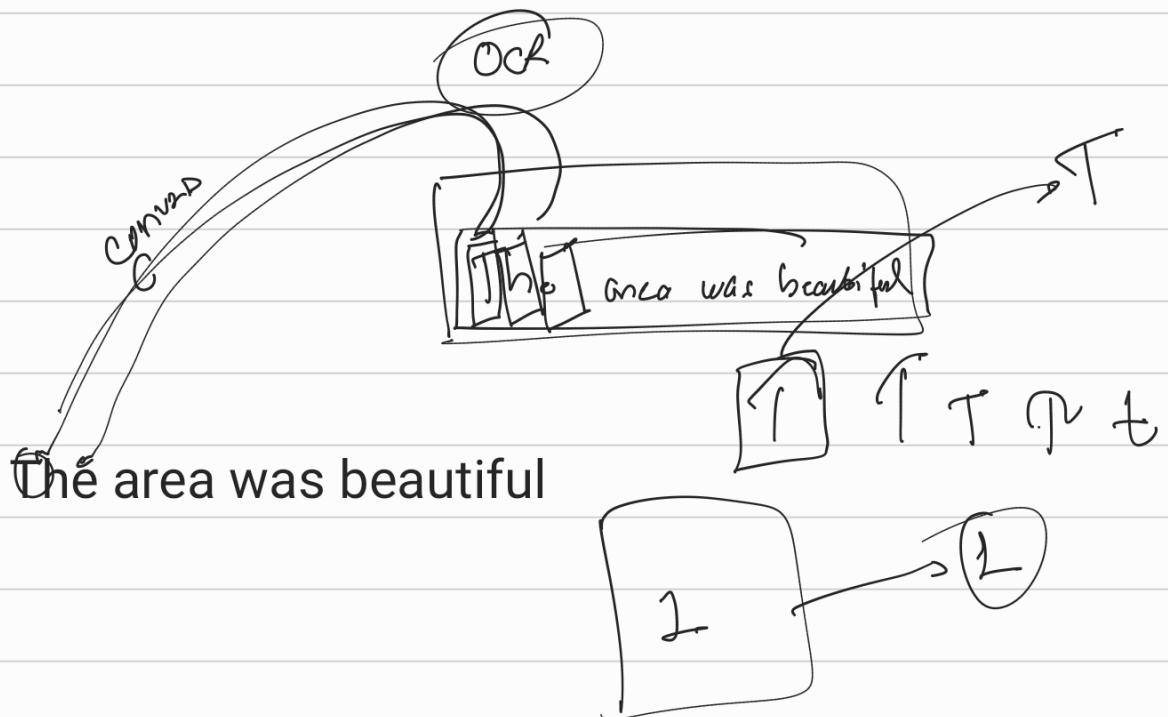
The class is going to be very interesting The class is going to  
be very interesting we will be great

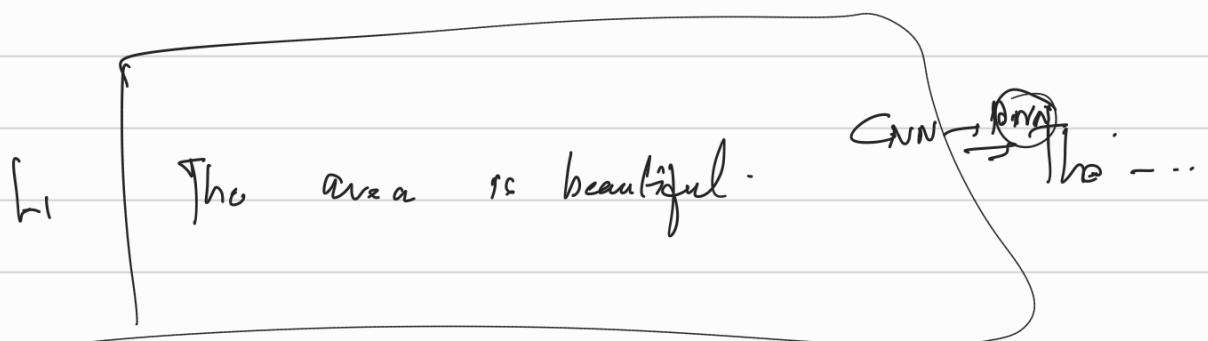
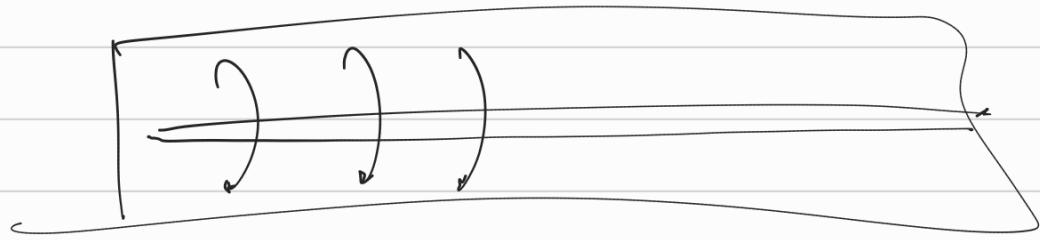


# OCR Problem

Architecture to solve an OCR problem.

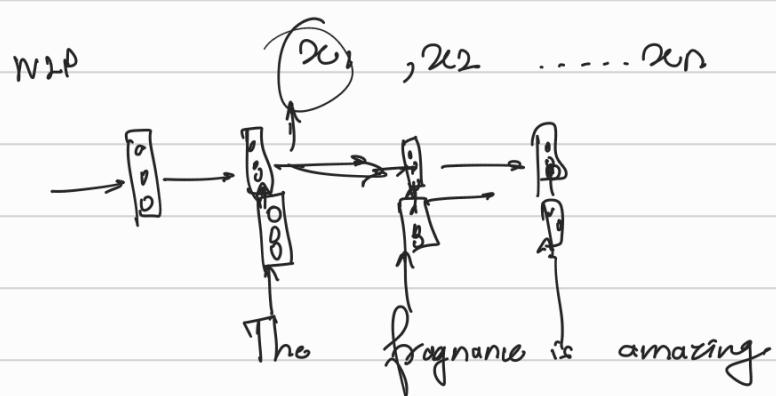


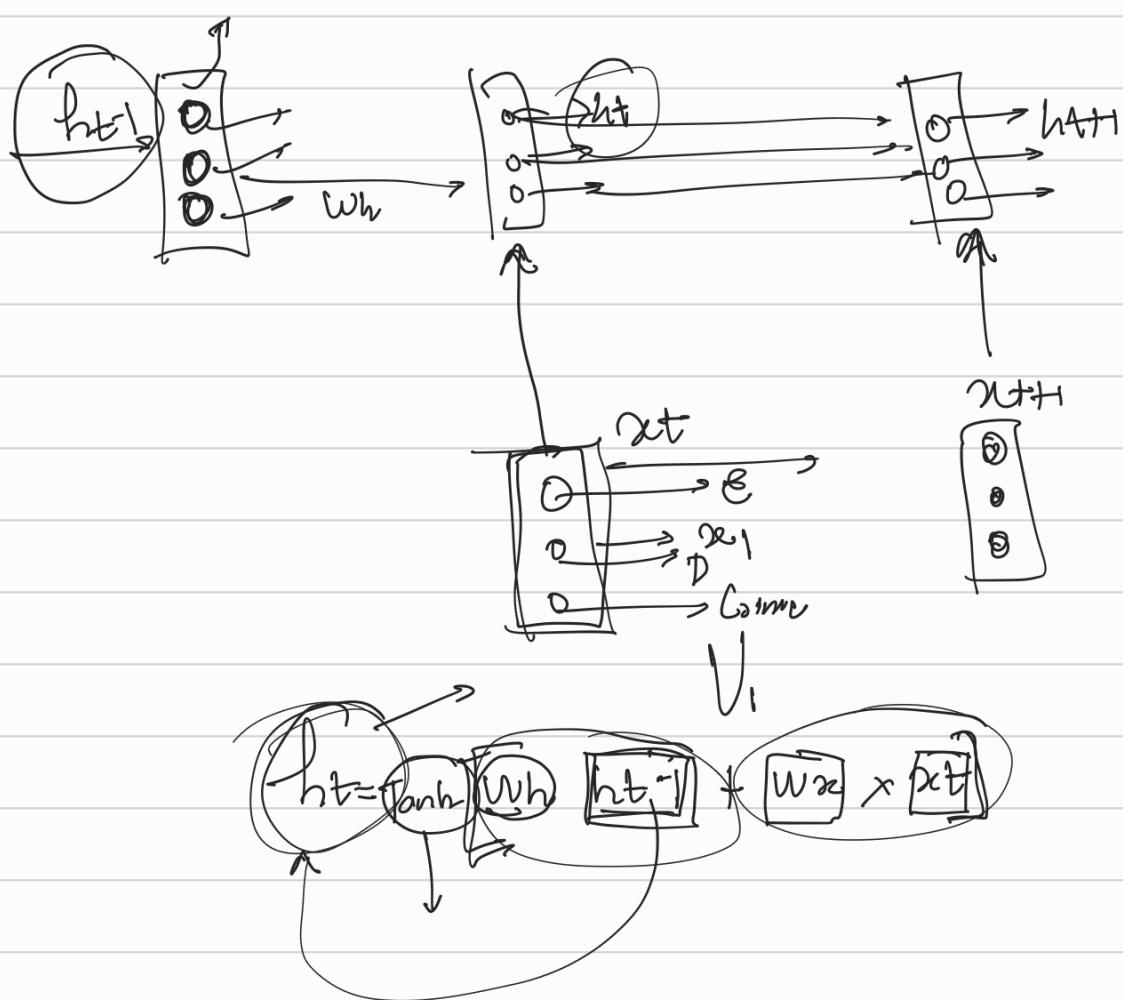
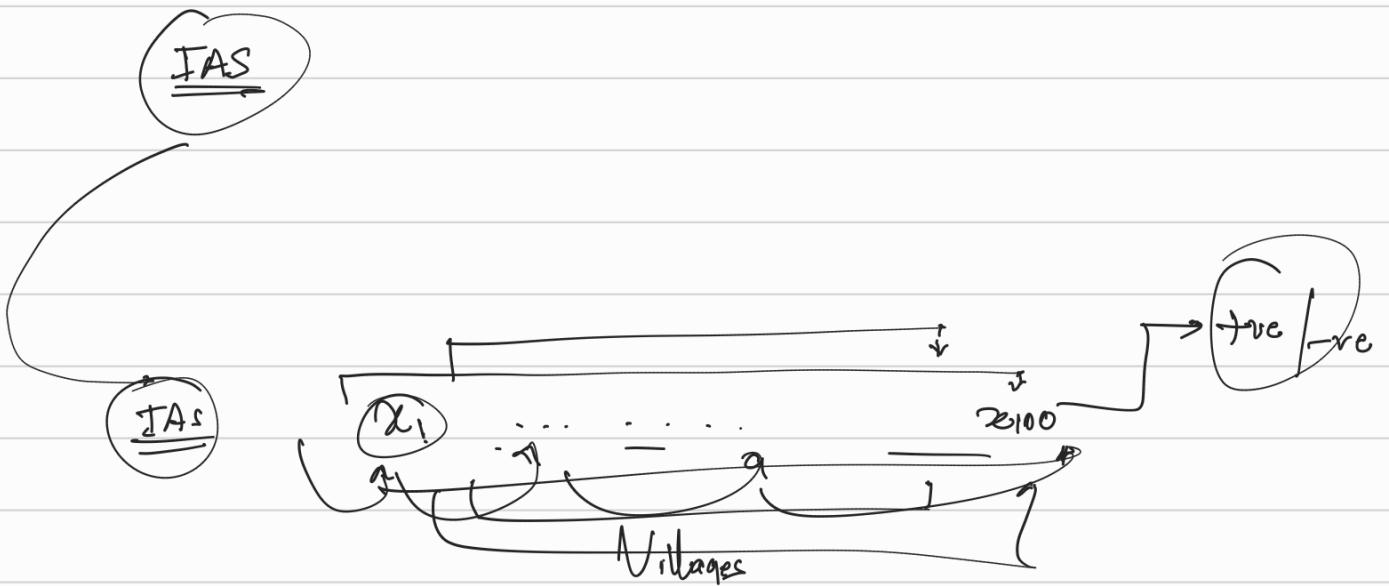




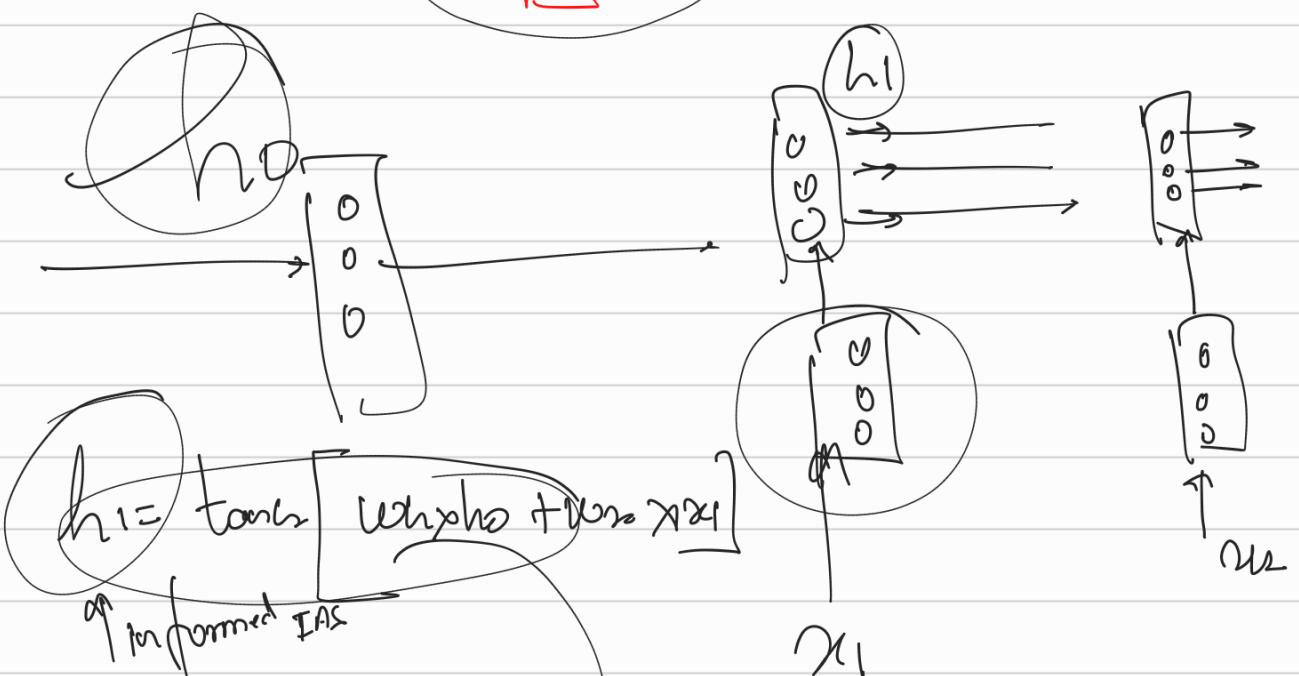
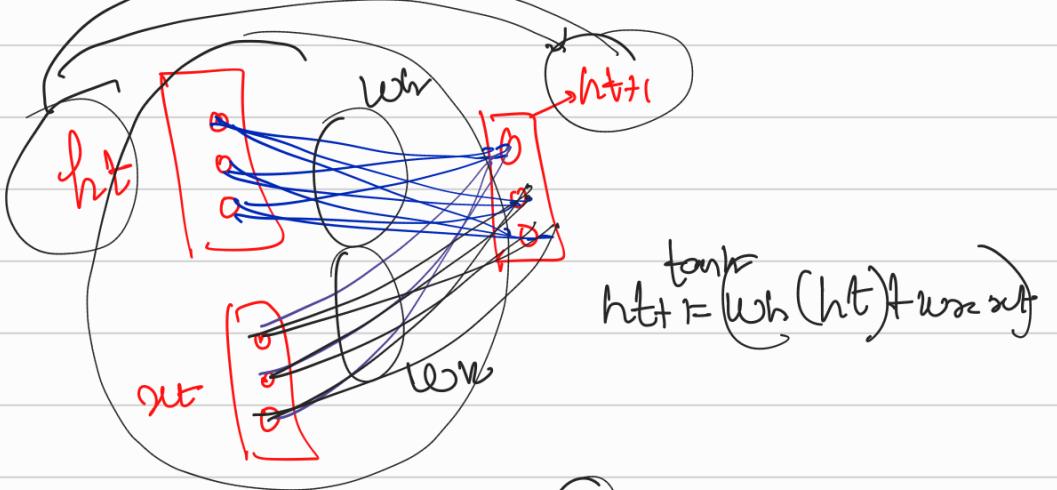
Recurrent neural network

→ Sequential model





$$h_{t+1} = \tanh \left[ w_h h_t + w_x x_{t+1} \right]$$



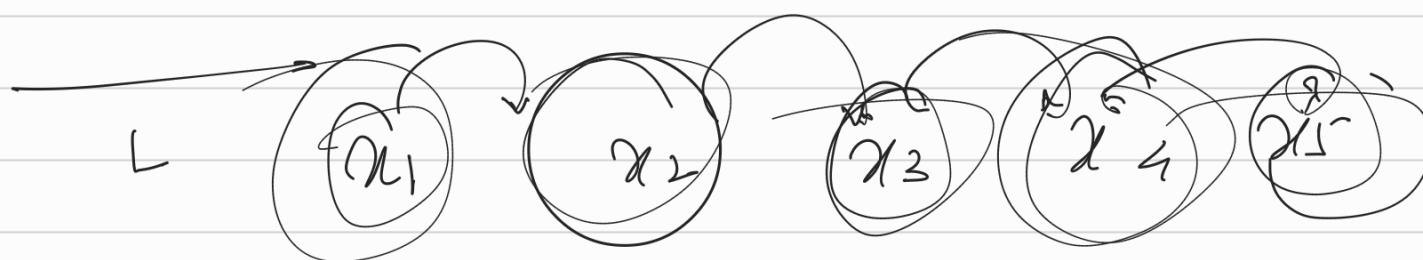
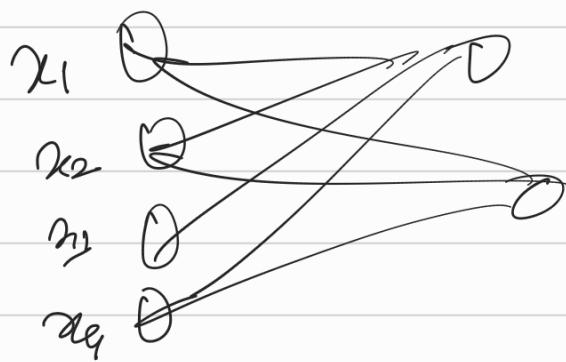
$$h_1 = \tanh [w_h x_0 + w_0 x_1]$$

$$h_2 = w_h h_1 + w_0 x_2$$

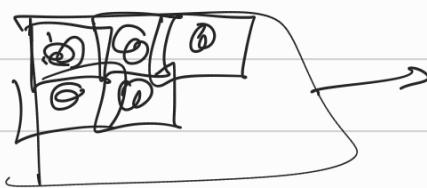
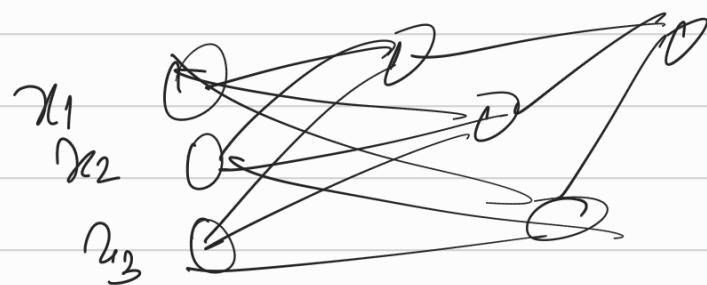
$$h_2 = w_h [w_h x_0 + w_0 x_1] + w_0 x_2$$

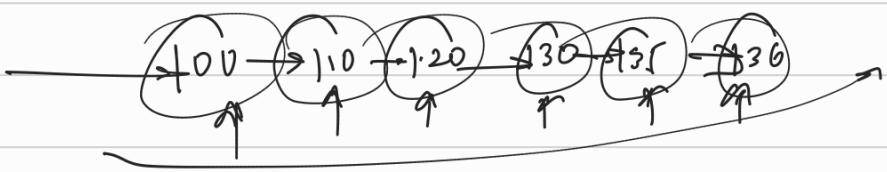
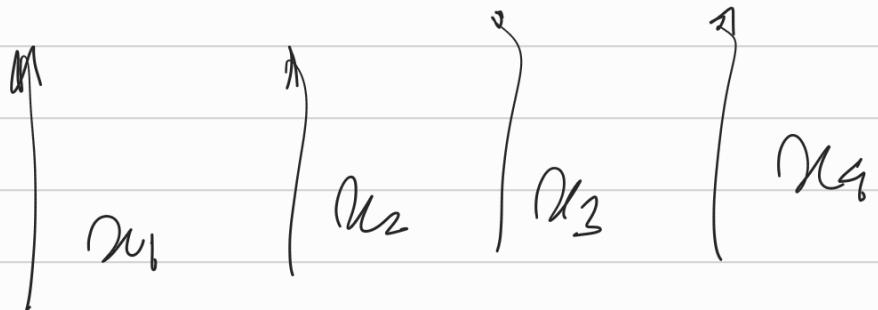
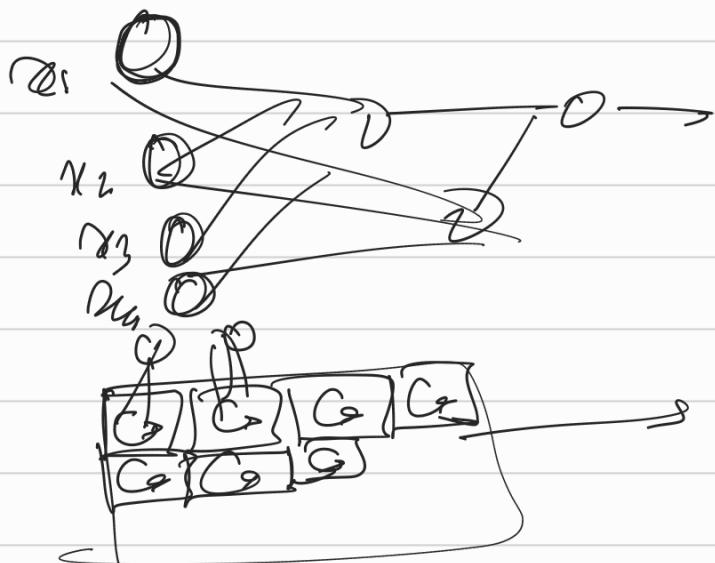
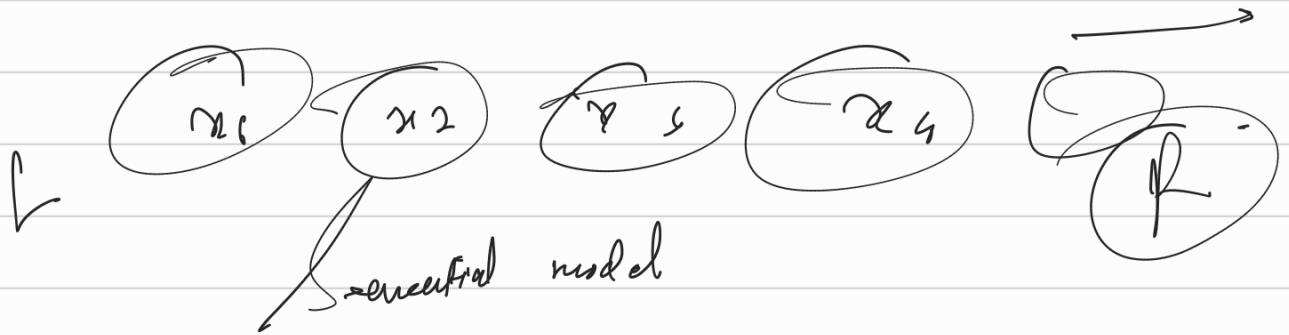
$$h_2 = w_h h_0 + w_0 x_0 + w_0 x_1 + w_0 x_2$$

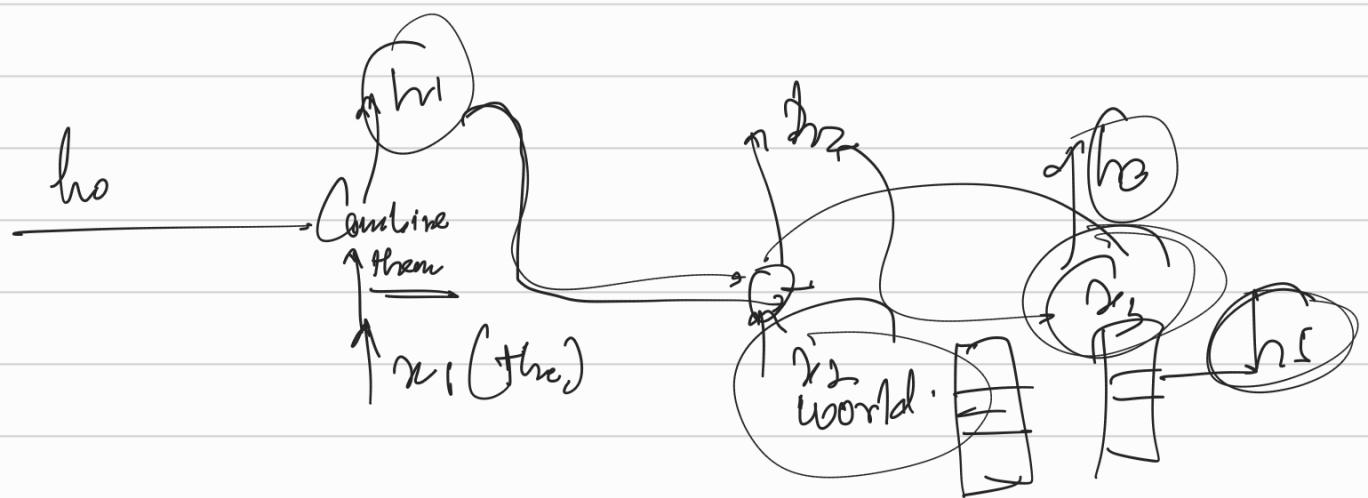
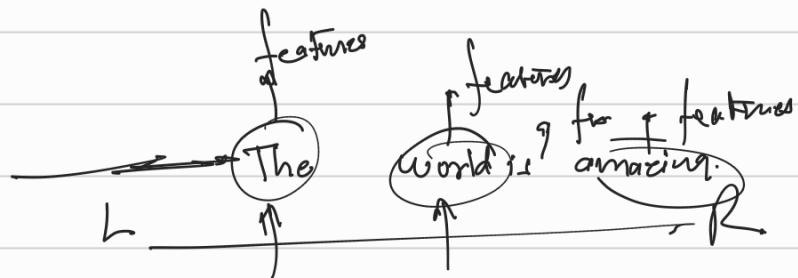
$h_t$  has information for all the villages from  $t+20$



no → The child played with the dog but

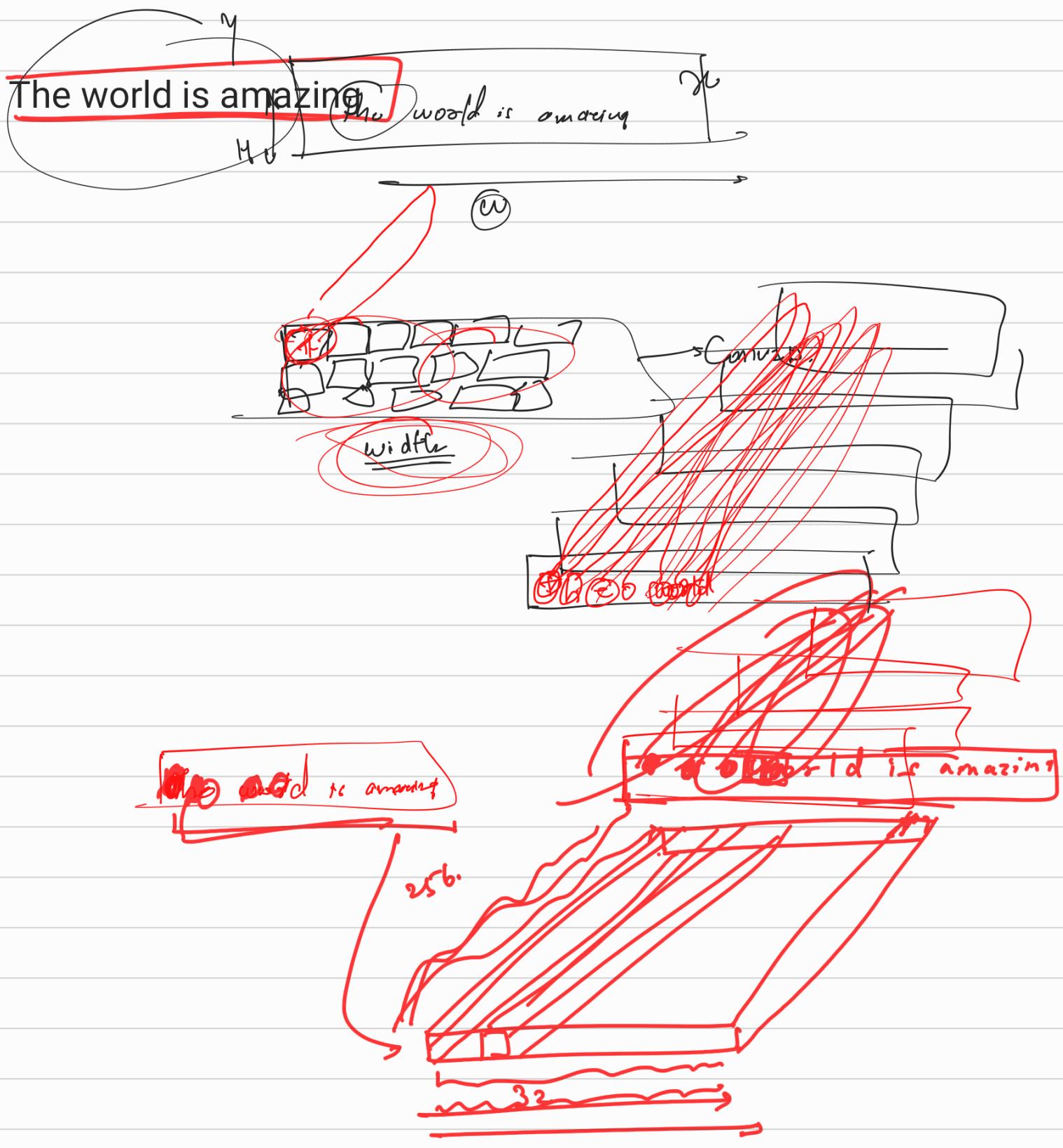






tanh (h<sub>0</sub> x w<sub>1</sub> + b<sub>1</sub>) tanh h<sub>1</sub> What's wrong

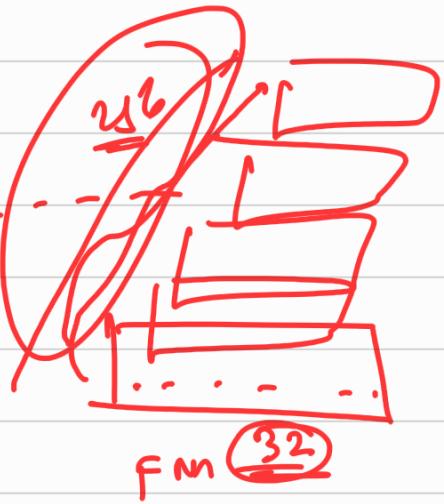
A diagram showing a tanh layer. It consists of two large overlapping circles. The left circle contains "wh<sub>1</sub>" and the right circle contains "wx x h<sub>2</sub>". An arrow points from the left circle to the right circle. Above the right circle is a smaller circle labeled "b<sub>2</sub>". An arrow points from the right circle to the right, labeled "tanh = h<sub>2</sub>".



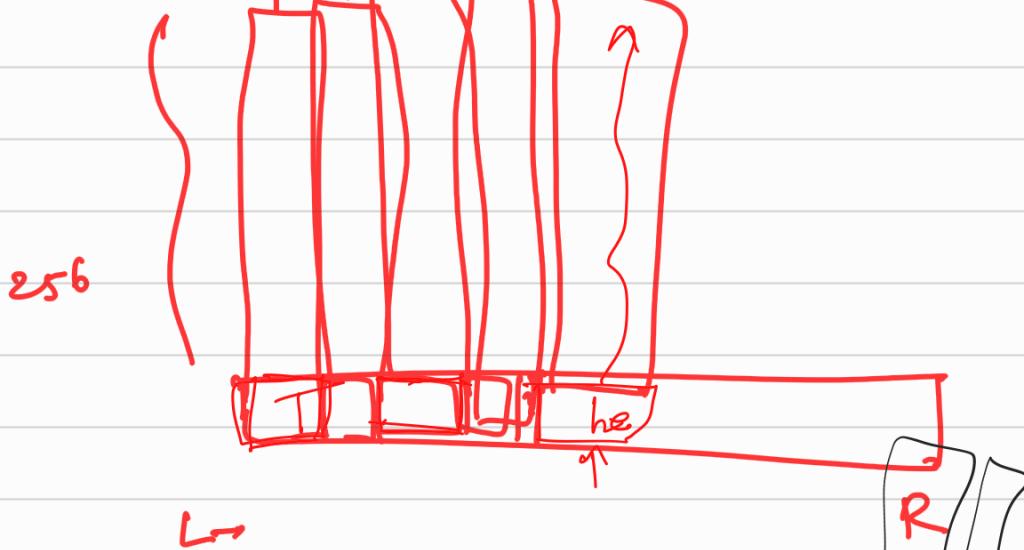
g have 256 features of 32 Characters. (including blank)

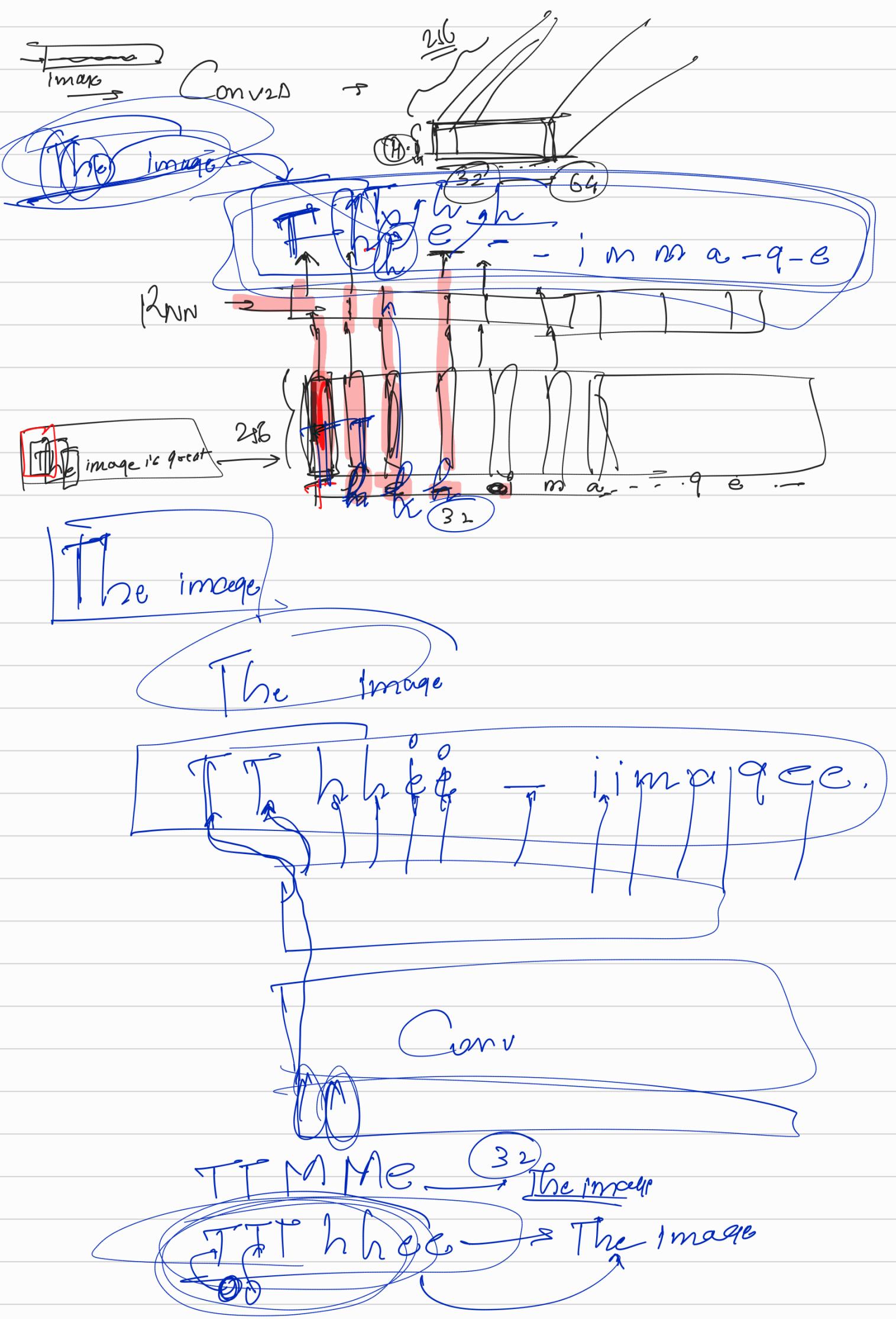
The world is be

Conn



Rnn →





Connectionist temporal loss  
Viterbi Algorithm

9:41 Pm

I am going to eat Burger

I am going to tfalangan o



Jam I am going to Schoo 1 School x... re