## Lab\_02\_output1

June 4, 2025

```
import time
import random
import xml.etree.ElementTree as ET
from glob import glob
from PIL import Image
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt

import tensorflow as tf
from tensorflow.keras import layers, models, applications
from tensorflow.keras.losses import MeanSquaredError
from tensorflow.keras.optimizers import Adam
from tensorflow.keras.callbacks import EarlyStopping, ReduceLROnPlateau
from tensorflow.keras.models import load_model
```

```
[2]: # ===========
    # Task 1: Dataset Exploration and Preprocessing
    # ==============
    # Step 1: Extract Manually Downloaded Data
    # Define paths
    data_root = './data'
    images_tar_path = os.path.join(data_root, 'images.tar.gz')
    annotations_tar_path = os.path.join(data_root, 'annotations.tar.gz')
    images_folder = os.path.join(data_root, 'images')
    annotations_folder = os.path.join(data_root, 'annotations')
    trimaps_folder = os.path.join(annotations_folder, 'trimaps')
    # Create data root directory if it doesn't exist
    if not os.path.exists(data_root):
       os.makedirs(data_root)
    # Extract tar.gz files if necessary
```

```
def extract_if_needed(tar_path, extract_to):
    if not os.path.exists(extract_to):
        print(f"Extracting {tar_path} to {extract_to}...")
        with tarfile.open(tar_path, 'r:gz') as tar:
            tar.extractall(path=data_root)
        print("Done.")
    else:
        print(f"{extract_to} already exists. Skipping extraction.")

# Ensure tar.gz files exist
assert os.path.exists(images_tar_path), f"{images_tar_path} not found"
assert os.path.exists(annotations_tar_path), f"{annotations_tar_path} not found"

# Extract
extract_if_needed(images_tar_path, images_folder)
extract_if_needed(annotations_tar_path, annotations_folder)
```

./data\images already exists. Skipping extraction. ./data\annotations already exists. Skipping extraction.

```
# Step 2: Load Filepaths and Split Dataset
    # -----
    # List all image filenames (without extension)
    image_paths = sorted(glob(os.path.join(images_folder, '*.jpg')))
    all_ids = [os.path.splitext(os.path.basename(p))[0] for p in image_paths]
    # Filter out IDs without corresponding XML
    valid_ids = [id_ for id_ in all_ids if os.path.exists(os.path.
     →join(annotations_folder, 'xmls', id_ + '.xml'))]
    # Shuffle and split
    random.seed(42)
    random.shuffle(valid ids)
    val_ratio = 0.2 # 20% for validation
    split idx = int(len(valid ids) * (1 - val ratio))
    train_ids = valid_ids[:split_idx]
    val_ids = valid_ids[split_idx:]
    # Print dataset sizes
    print("Total valid images with XML:", len(valid_ids))
    print("Train:", len(train_ids))
    print("Val:", len(val_ids))
```

Total valid images with XML: 3686

Train: 2948 Val: 738

```
# Step 3: Define Preprocessing Function
    IMG_SIZE = (224, 224)
    def load_and_preprocess(id_):
        # Load image
        img_path = os.path.join(images_folder, id_ + '.jpg')
        img = tf.io.read_file(img_path)
        img = tf.image.decode_jpeg(img, channels=3)
        img = tf.image.resize(img, IMG_SIZE)
        img = tf.cast(img, tf.float32) / 255.0
        # Load segmentation mask
        mask_path = os.path.join(trimaps_folder, id_ + '.png')
        mask = tf.io.read_file(mask_path)
        mask = tf.image.decode_png(mask, channels=1)
        mask = tf.image.resize(mask, IMG_SIZE, method='nearest')
        mask = tf.cast(mask > 1, tf.float32) # Convert trimap to binary mask_
     \hookrightarrow (foreground = 1)
        return img, mask
```

```
# Step 4: Create tf.data.Datasets
    def load_and_preprocess_py(id_):
        # Convert bytes tensor to string
        id_str = id_.numpy().decode('utf-8')
        # Load image
        img_path = os.path.join(images_folder, id_str + '.jpg')
        img = tf.io.read_file(img_path)
        img = tf.image.decode_jpeg(img, channels=3)
        img = tf.image.resize(img, IMG_SIZE)
        img = tf.cast(img, tf.float32) / 255.0
        # Load mask
        mask_path = os.path.join(trimaps_folder, id_str + '.png')
        mask = tf.io.read_file(mask_path)
        mask = tf.image.decode_png(mask, channels=1)
        mask = tf.image.resize(mask, IMG_SIZE, method='nearest')
        mask = tf.cast(mask > 1, tf.float32)
        return img, mask
```

```
def tf_wrapper(id_):
    img, mask = tf.py_function(
        func=load_and_preprocess_py,
        inp=[id_],
        Tout=[tf.float32, tf.float32]
)
    img.set_shape([*IMG_SIZE, 3])
    mask.set_shape([*IMG_SIZE, 1])
    return img, mask

def create_dataset(id_list):
    dataset = tf.data.Dataset.from_tensor_slices(id_list)
    dataset = dataset.map(tf_wrapper, num_parallel_calls=tf.data.AUTOTUNE)
    dataset = dataset.batch(32).prefetch(tf.data.AUTOTUNE)
    return dataset

train_ds = create_dataset(train_ids)
val_ds = create_dataset(val_ids)
```

```
# Step 5: Visualization
    def visualize_batch(dataset, n=5):
       for images, masks in dataset.take(1):
           plt.figure(figsize=(15, 5))
           for i in range(n):
              ax1 = plt.subplot(2, n, i + 1)
              plt.imshow(images[i])
              plt.title("Image")
              plt.axis("off")
              ax2 = plt.subplot(2, n, n + i + 1)
              plt.imshow(masks[i, :, :, 0], cmap='gray')
              plt.title("Segmentation")
              plt.axis("off")
           plt.tight_layout()
           plt.show()
    visualize_batch(train_ds)
```







Segmentation

















```
# Task 2: Object Detection
    # =============
    # Step 1: Read bounding boxes from XML files
    # Parse XML annotation to extract bounding box in [cx, cy, w, h] format, \Box
     ⇔normalized to image size.
    def parse_bounding_box(xml_path, image_width, image_height):
       tree = ET.parse(xml_path)
       root = tree.getroot()
       obj = root.find("object")
       bbox = obj.find("bndbox")
       xmin = int(bbox.find("xmin").text)
       ymin = int(bbox.find("ymin").text)
       xmax = int(bbox.find("xmax").text)
       ymax = int(bbox.find("ymax").text)
       cx = (xmin + xmax) / 2 / image_width
       cy = (ymin + ymax) / 2 / image_height
       w = (xmax - xmin) / image_width
       h = (ymax - ymin) / image_height
       return [cx, cy, w, h]
```

```
# Step 2: Load and preprocess image with bounding box
   # Read image and its corresponding bounding box, resize image and normalize _{f L}
    ⇔bbox coordinates.
```

```
def load_and_preprocess_detection_py(id_):
        try:
            id_str = id_.numpy().decode('utf-8')
            img_path = os.path.join(images_folder, id_str + '.jpg')
            xml_path = os.path.join(annotations_folder, 'xmls', id_str + '.xml')
            if not os.path.exists(img path):
                raise FileNotFoundError(f"Image file not found: {img_path}")
            if not os.path.exists(xml path):
                raise FileNotFoundError(f"XML file not found: {xml_path}")
            # Use PIL to get original image size
            with Image.open(img_path) as img_pil:
                orig_width, orig_height = img_pil.size
            # Load image with TensorFlow
            img_raw = tf.io.read_file(img_path)
            img = tf.image.decode_jpeg(img_raw, channels=3)
            img = tf.image.resize(img, IMG_SIZE)
            img = tf.cast(img, tf.float32) / 255.0
            # Parse bbox based on original image size
            bbox = parse_bounding_box(xml_path, orig_width, orig_height)
            bbox = tf.convert to tensor(bbox, dtype=tf.float32)
            return img, bbox
        except Exception as e:
            print(f"Error processing ID: {id_str}")
            raise e
# Step 3: Create tf.data.Dataset for object detection
    # Build a dataset pipeline using tf.py_function to map image IDs to image and_
     ⇔bbox pairs.
```

```
return img, bbox
     def create_detection_dataset(id_list):
        dataset = tf.data.Dataset.from_tensor_slices(id_list)
        dataset = dataset.map(tf_wrapper_detection, num_parallel_calls=tf.data.
      →AUTOTUNE)
        dataset = dataset.batch(32).prefetch(tf.data.AUTOTUNE)
        return dataset
     train_det_ds = create_detection_dataset(train_ids)
     val_det_ds = create_detection_dataset(val_ids)
# Step 4: Build detection model with backbone
     # -----
     # Build a CNN model with a backbone (e.g., MobileNetV2) and a dense regression \Box
      ⇔head for bounding boxes.
     def build_detection_model(pretrained=True):
        base_model = applications.MobileNetV2(
            input_shape=(*IMG_SIZE, 3),
            include_top=False,
            weights='imagenet' if pretrained else None
        base_model.trainable = True
        x = layers.GlobalAveragePooling2D()(base_model.output)
        x = layers.Dense(128, activation='relu')(x)
        bbox_output = layers.Dense(4, activation='sigmoid')(x)
        model = models.Model(inputs=base_model.input, outputs=bbox_output)
        return model
[]:  # -----
     # Step 4.1: Show sample shape
     # -----
     for img, bbox in train_det_ds.take(1):
        print("Sample shape:", img.shape, bbox.shape)
    Sample shape: (32, 224, 224, 3) (32, 4)
[]: # -----
     # Step 5: Train the object detection model
     # -----
     # Compile and train the model with Mean Squared Error loss and early stopping_
      ⇔callbacks.
```

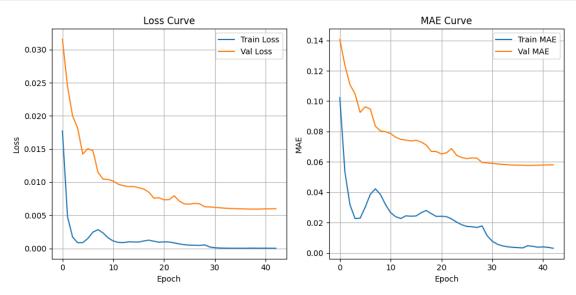
```
model = build_detection_model(pretrained=True)
model.compile(
   optimizer=Adam(learning_rate=1e-4),
   loss=MeanSquaredError(),
   metrics=['mae']
)
callbacks = \Gamma
   EarlyStopping(patience=5, restore_best_weights=True),
   ReduceLROnPlateau(patience=3, factor=0.5)
]
history = model.fit(
   train_det_ds,
   validation_data=val_det_ds,
   epochs=50,
   callbacks=callbacks
)
Epoch 1/50
0.1022 - val_loss: 0.0315 - val_mae: 0.1407 - lr: 1.0000e-04
Epoch 2/50
0.0534 - val_loss: 0.0244 - val_mae: 0.1236 - lr: 1.0000e-04
Epoch 3/50
0.0317 - val_loss: 0.0200 - val_mae: 0.1108 - lr: 1.0000e-04
Epoch 4/50
93/93 [=========== ] - 16s 171ms/step - loss: 8.5466e-04 -
mae: 0.0226 - val_loss: 0.0181 - val_mae: 0.1047 - lr: 1.0000e-04
Epoch 5/50
mae: 0.0229 - val_loss: 0.0142 - val_mae: 0.0926 - lr: 1.0000e-04
Epoch 6/50
93/93 [============= ] - 15s 163ms/step - loss: 0.0015 - mae:
0.0301 - val_loss: 0.0151 - val_mae: 0.0963 - lr: 1.0000e-04
Epoch 7/50
93/93 [============ ] - 15s 164ms/step - loss: 0.0024 - mae:
0.0386 - val_loss: 0.0147 - val_mae: 0.0948 - lr: 1.0000e-04
Epoch 8/50
93/93 [============= ] - 15s 164ms/step - loss: 0.0028 - mae:
0.0423 - val_loss: 0.0115 - val_mae: 0.0835 - lr: 1.0000e-04
Epoch 9/50
93/93 [============== ] - 16s 167ms/step - loss: 0.0023 - mae:
0.0385 - val_loss: 0.0104 - val_mae: 0.0803 - lr: 1.0000e-04
```

```
Epoch 10/50
93/93 [============= ] - 16s 171ms/step - loss: 0.0016 - mae:
0.0318 - val_loss: 0.0104 - val_mae: 0.0798 - lr: 1.0000e-04
Epoch 11/50
0.0265 - val_loss: 0.0101 - val_mae: 0.0786 - lr: 1.0000e-04
Epoch 12/50
mae: 0.0238 - val_loss: 0.0097 - val_mae: 0.0762 - lr: 1.0000e-04
Epoch 13/50
mae: 0.0227 - val_loss: 0.0095 - val_mae: 0.0748 - lr: 1.0000e-04
Epoch 14/50
mae: 0.0244 - val_loss: 0.0093 - val_mae: 0.0743 - lr: 1.0000e-04
Epoch 15/50
93/93 [============ ] - 16s 169ms/step - loss: 9.6446e-04 -
mae: 0.0242 - val_loss: 0.0093 - val_mae: 0.0738 - lr: 1.0000e-04
Epoch 16/50
mae: 0.0243 - val_loss: 0.0092 - val_mae: 0.0742 - lr: 1.0000e-04
Epoch 17/50
93/93 [=============== ] - 16s 167ms/step - loss: 0.0011 - mae:
0.0264 - val_loss: 0.0090 - val_mae: 0.0731 - lr: 1.0000e-04
Epoch 18/50
0.0280 - val_loss: 0.0085 - val_mae: 0.0711 - lr: 1.0000e-04
Epoch 19/50
93/93 [============== ] - 16s 177ms/step - loss: 0.0011 - mae:
0.0259 - val_loss: 0.0076 - val_mae: 0.0669 - lr: 1.0000e-04
Epoch 20/50
mae: 0.0241 - val_loss: 0.0076 - val_mae: 0.0668 - lr: 1.0000e-04
Epoch 21/50
mae: 0.0242 - val_loss: 0.0073 - val_mae: 0.0652 - lr: 1.0000e-04
Epoch 22/50
mae: 0.0239 - val_loss: 0.0074 - val_mae: 0.0660 - lr: 1.0000e-04
Epoch 23/50
mae: 0.0224 - val_loss: 0.0079 - val_mae: 0.0687 - lr: 1.0000e-04
mae: 0.0203 - val_loss: 0.0071 - val_mae: 0.0643 - lr: 1.0000e-04
Epoch 25/50
mae: 0.0186 - val_loss: 0.0067 - val_mae: 0.0629 - lr: 1.0000e-04
```

```
Epoch 26/50
93/93 [============ ] - 16s 169ms/step - loss: 4.8712e-04 -
mae: 0.0174 - val_loss: 0.0067 - val_mae: 0.0621 - lr: 1.0000e-04
Epoch 27/50
mae: 0.0173 - val_loss: 0.0068 - val_mae: 0.0626 - lr: 1.0000e-04
Epoch 28/50
mae: 0.0168 - val_loss: 0.0067 - val_mae: 0.0624 - lr: 1.0000e-04
Epoch 29/50
mae: 0.0178 - val_loss: 0.0063 - val_mae: 0.0596 - lr: 5.0000e-05
Epoch 30/50
93/93 [=========== ] - 17s 180ms/step - loss: 2.1098e-04 -
mae: 0.0113 - val_loss: 0.0063 - val_mae: 0.0593 - lr: 5.0000e-05
Epoch 31/50
93/93 [=========== ] - 17s 179ms/step - loss: 9.8553e-05 -
mae: 0.0077 - val_loss: 0.0062 - val_mae: 0.0590 - lr: 5.0000e-05
Epoch 32/50
mae: 0.0057 - val_loss: 0.0061 - val_mae: 0.0586 - lr: 5.0000e-05
Epoch 33/50
mae: 0.0046 - val_loss: 0.0061 - val_mae: 0.0583 - lr: 5.0000e-05
Epoch 34/50
93/93 [============ ] - 16s 177ms/step - loss: 2.8636e-05 -
mae: 0.0040 - val_loss: 0.0060 - val_mae: 0.0581 - lr: 5.0000e-05
Epoch 35/50
93/93 [==========] - 17s 178ms/step - loss: 2.4968e-05 -
mae: 0.0037 - val_loss: 0.0060 - val_mae: 0.0579 - lr: 5.0000e-05
Epoch 36/50
mae: 0.0035 - val_loss: 0.0060 - val_mae: 0.0578 - lr: 5.0000e-05
Epoch 37/50
93/93 [============ ] - 16s 176ms/step - loss: 1.9911e-05 -
mae: 0.0033 - val_loss: 0.0059 - val_mae: 0.0578 - lr: 5.0000e-05
Epoch 38/50
mae: 0.0047 - val_loss: 0.0059 - val_mae: 0.0577 - lr: 2.5000e-05
Epoch 39/50
mae: 0.0043 - val_loss: 0.0059 - val_mae: 0.0577 - lr: 2.5000e-05
mae: 0.0038 - val_loss: 0.0059 - val_mae: 0.0578 - 1r: 2.5000e-05
Epoch 41/50
93/93 [============= ] - 16s 175ms/step - loss: 2.9603e-05 -
mae: 0.0040 - val_loss: 0.0060 - val_mae: 0.0579 - lr: 1.2500e-05
```

```
Epoch 42/50
    93/93 [=========== ] - 16s 175ms/step - loss: 2.4977e-05 -
    mae: 0.0036 - val_loss: 0.0060 - val_mae: 0.0580 - lr: 1.2500e-05
    Epoch 43/50
    mae: 0.0031 - val_loss: 0.0060 - val_mae: 0.0581 - lr: 1.2500e-05
    Model saved to 'object detector.h5'
    Training history saved to 'training_log.csv'
# Step 5.1: Save the trained model to HDF5 (.h5) format in models directory
    # Create models directory if it doesn't exist
    models_dir = "models"
    if not os.path.exists(models_dir):
       os.makedirs(models_dir)
    model.save("models/object_detector.h5")
    print("Model saved to 'models/object_detector.h5'")
    # Step 5.2: Save training history to CSV
    pd.DataFrame(history.history).to csv("models/training log.csv", index=False)
    print("Training history saved to 'models/training_log.csv'")
    Model saved to 'models/object_detector.h5'
    Training history saved to 'models/training_log.csv'
# Step 5.3: Load a trained model from HDF5 file (optional)
    model = load_model("models/object_detector.h5")
    print("Model loaded from 'models/object_detector.h5'")
# Step 5.4: Plot training and validation curves
    plt.figure(figsize=(10, 5))
    # Loss
    plt.subplot(1, 2, 1)
    plt.plot(history.history['loss'], label='Train Loss')
    plt.plot(history.history['val_loss'], label='Val Loss')
```

```
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.title("Loss Curve")
plt.legend()
plt.grid(True)
# MAE
plt.subplot(1, 2, 2)
plt.plot(history.history['mae'], label='Train MAE')
plt.plot(history.history['val_mae'], label='Val MAE')
plt.xlabel("Epoch")
plt.ylabel("MAE")
plt.title("MAE Curve")
plt.legend()
plt.grid(True)
plt.tight_layout()
plt.show()
```



```
cx, cy, bw, bh = bbox
      xmin = int((cx - bw / 2) * w)
      ymin = int((cy - bh / 2) * h)
      xmax = int((cx + bw / 2) * w)
      ymax = int((cy + bh / 2) * h)
      return xmin, ymin, xmax, ymax
  fig, ax = plt.subplots()
  ax.imshow(image)
  xmin, ymin, xmax, ymax = denormalize(true_bbox)
  ax.add_patch(plt.Rectangle((xmin, ymin), xmax - xmin, ymax - ymin, u
⇔edgecolor='green', fill=False, lw=2, label='Ground Truth'))
  xmin, ymin, xmax, ymax = denormalize(pred_bbox)
  ax.add_patch(plt.Rectangle((xmin, ymin), xmax - xmin, ymax - ymin, __

→edgecolor='red', fill=False, lw=2, label='Prediction'))
  plt.legend()
  plt.show()
```

```
# Step 7: Train and compare pretrained vs non-pretrained models
    # Train two versions of the model and compare performance (MAE, loss, training \Box
     ⇔time, early stopping)
    def train_and_evaluate(pretrained=True):
        print(f"Training model with pretrained={pretrained}")
        model = build_detection_model(pretrained=pretrained)
        model.compile(optimizer=Adam(1e-4), loss=MeanSquaredError(),
     →metrics=['mae'])
        callbacks = [
            EarlyStopping(patience=5, restore_best_weights=True),
            ReduceLROnPlateau(patience=3, factor=0.5)
        ]
        start_time = time.time()
        history = model.fit(
           train_det_ds,
           validation_data=val_det_ds,
            epochs=50,
           callbacks=callbacks,
           verbose=1
        duration = time.time() - start_time
        print(f"Training time: {duration:.2f} seconds")
```

```
Epoch 1/50
0.1052 - val_loss: 0.0277 - val_mae: 0.1285 - lr: 1.0000e-04
Epoch 2/50
93/93 [============== ] - 16s 169ms/step - loss: 0.0053 - mae:
0.0562 - val_loss: 0.0207 - val_mae: 0.1102 - lr: 1.0000e-04
Epoch 3/50
0.0349 - val_loss: 0.0178 - val_mae: 0.1027 - lr: 1.0000e-04
Epoch 4/50
93/93 [=============== ] - 16s 169ms/step - loss: 0.0011 - mae:
0.0254 - val_loss: 0.0157 - val_mae: 0.0964 - lr: 1.0000e-04
Epoch 5/50
mae: 0.0228 - val_loss: 0.0151 - val_mae: 0.0942 - lr: 1.0000e-04
Epoch 6/50
93/93 [============== ] - 16s 171ms/step - loss: 0.0013 - mae:
0.0278 - val_loss: 0.0138 - val_mae: 0.0903 - lr: 1.0000e-04
Epoch 7/50
93/93 [============== ] - 16s 171ms/step - loss: 0.0023 - mae:
0.0374 - val_loss: 0.0150 - val_mae: 0.0950 - lr: 1.0000e-04
Epoch 8/50
93/93 [============= ] - 16s 172ms/step - loss: 0.0028 - mae:
0.0415 - val_loss: 0.0143 - val_mae: 0.0928 - lr: 1.0000e-04
Epoch 9/50
93/93 [=============== ] - 16s 171ms/step - loss: 0.0023 - mae:
0.0377 - val_loss: 0.0130 - val_mae: 0.0870 - lr: 1.0000e-04
Epoch 10/50
0.0326 - val_loss: 0.0110 - val_mae: 0.0803 - lr: 1.0000e-04
Epoch 11/50
93/93 [============== ] - 16s 172ms/step - loss: 0.0012 - mae:
0.0274 - val_loss: 0.0107 - val_mae: 0.0792 - lr: 1.0000e-04
Epoch 12/50
mae: 0.0240 - val_loss: 0.0106 - val_mae: 0.0787 - lr: 1.0000e-04
Epoch 13/50
mae: 0.0213 - val_loss: 0.0091 - val_mae: 0.0730 - lr: 1.0000e-04
Epoch 14/50
```

```
mae: 0.0211 - val_loss: 0.0082 - val_mae: 0.0694 - lr: 1.0000e-04
Epoch 15/50
93/93 [============ ] - 16s 175ms/step - loss: 7.2782e-04 -
mae: 0.0215 - val_loss: 0.0085 - val_mae: 0.0708 - lr: 1.0000e-04
Epoch 16/50
93/93 [=========== ] - 17s 178ms/step - loss: 7.7636e-04 -
mae: 0.0218 - val_loss: 0.0083 - val_mae: 0.0691 - lr: 1.0000e-04
Epoch 17/50
93/93 [=========== ] - 17s 179ms/step - loss: 9.3953e-04 -
mae: 0.0241 - val_loss: 0.0079 - val_mae: 0.0671 - lr: 1.0000e-04
mae: 0.0245 - val_loss: 0.0084 - val_mae: 0.0701 - lr: 1.0000e-04
93/93 [============= ] - 17s 182ms/step - loss: 0.0010 - mae:
0.0247 - val_loss: 0.0080 - val_mae: 0.0681 - lr: 1.0000e-04
Epoch 20/50
mae: 0.0242 - val_loss: 0.0071 - val_mae: 0.0641 - lr: 1.0000e-04
93/93 [=========== ] - 16s 177ms/step - loss: 8.9387e-04 -
mae: 0.0232 - val_loss: 0.0078 - val_mae: 0.0674 - lr: 1.0000e-04
Epoch 22/50
mae: 0.0234 - val_loss: 0.0069 - val_mae: 0.0633 - lr: 1.0000e-04
Epoch 23/50
93/93 [=========== ] - 16s 175ms/step - loss: 8.4579e-04 -
mae: 0.0227 - val_loss: 0.0068 - val_mae: 0.0631 - lr: 1.0000e-04
Epoch 24/50
mae: 0.0228 - val_loss: 0.0070 - val_mae: 0.0641 - lr: 1.0000e-04
Epoch 25/50
93/93 [============ ] - 16s 174ms/step - loss: 8.2900e-04 -
mae: 0.0228 - val loss: 0.0065 - val mae: 0.0613 - lr: 1.0000e-04
Epoch 26/50
mae: 0.0217 - val_loss: 0.0064 - val_mae: 0.0601 - lr: 1.0000e-04
Epoch 27/50
93/93 [=========== ] - 16s 173ms/step - loss: 6.9852e-04 -
mae: 0.0207 - val_loss: 0.0063 - val_mae: 0.0597 - lr: 1.0000e-04
Epoch 28/50
mae: 0.0209 - val_loss: 0.0066 - val_mae: 0.0612 - lr: 1.0000e-04
Epoch 29/50
mae: 0.0209 - val_loss: 0.0067 - val_mae: 0.0624 - lr: 1.0000e-04
Epoch 30/50
```

```
mae: 0.0225 - val_loss: 0.0060 - val_mae: 0.0585 - lr: 5.0000e-05
Epoch 31/50
93/93 [============ ] - 16s 172ms/step - loss: 3.7404e-04 -
mae: 0.0152 - val_loss: 0.0058 - val_mae: 0.0572 - lr: 5.0000e-05
Epoch 32/50
93/93 [============ ] - 16s 175ms/step - loss: 1.5306e-04 -
mae: 0.0097 - val_loss: 0.0057 - val_mae: 0.0566 - lr: 5.0000e-05
Epoch 33/50
93/93 [=========== ] - 16s 172ms/step - loss: 7.3780e-05 -
mae: 0.0066 - val_loss: 0.0057 - val_mae: 0.0564 - lr: 5.0000e-05
mae: 0.0050 - val_loss: 0.0056 - val_mae: 0.0563 - lr: 5.0000e-05
Epoch 35/50
mae: 0.0043 - val_loss: 0.0056 - val_mae: 0.0561 - lr: 5.0000e-05
Epoch 36/50
mae: 0.0038 - val_loss: 0.0056 - val_mae: 0.0560 - lr: 5.0000e-05
Epoch 37/50
93/93 [=========== ] - 16s 170ms/step - loss: 4.4209e-05 -
mae: 0.0052 - val_loss: 0.0056 - val_mae: 0.0557 - lr: 2.5000e-05
Epoch 38/50
mae: 0.0050 - val_loss: 0.0056 - val_mae: 0.0556 - lr: 2.5000e-05
Epoch 39/50
93/93 [=========== ] - 16s 169ms/step - loss: 3.3737e-05 -
mae: 0.0045 - val_loss: 0.0056 - val_mae: 0.0556 - lr: 2.5000e-05
Epoch 40/50
mae: 0.0051 - val_loss: 0.0056 - val_mae: 0.0557 - lr: 1.2500e-05
Epoch 41/50
93/93 [============ ] - 16s 171ms/step - loss: 3.6228e-05 -
mae: 0.0048 - val loss: 0.0056 - val mae: 0.0557 - lr: 1.2500e-05
Epoch 42/50
mae: 0.0041 - val_loss: 0.0056 - val_mae: 0.0558 - lr: 1.2500e-05
Epoch 43/50
93/93 [=========== ] - 16s 173ms/step - loss: 2.4289e-05 -
mae: 0.0039 - val_loss: 0.0056 - val_mae: 0.0559 - lr: 6.2500e-06
Training time: 696.00 seconds
Training model with pretrained=False
Epoch 1/50
0.1222 - val_loss: 0.0287 - val_mae: 0.1394 - lr: 1.0000e-04
Epoch 2/50
93/93 [============== ] - 16s 173ms/step - loss: 0.0217 - mae:
```

```
0.1141 - val_loss: 0.0284 - val_mae: 0.1383 - lr: 1.0000e-04
   Epoch 3/50
   93/93 [=============== ] - 16s 174ms/step - loss: 0.0181 - mae:
   0.1039 - val_loss: 0.0278 - val_mae: 0.1367 - lr: 1.0000e-04
   Epoch 4/50
   0.0948 - val_loss: 0.0273 - val_mae: 0.1352 - lr: 1.0000e-04
   Epoch 5/50
   93/93 [============== ] - 16s 177ms/step - loss: 0.0126 - mae:
   0.0872 - val_loss: 0.0270 - val_mae: 0.1342 - lr: 1.0000e-04
   Epoch 6/50
   0.0814 - val_loss: 0.0264 - val_mae: 0.1323 - lr: 1.0000e-04
   Epoch 7/50
   93/93 [============ ] - 16s 172ms/step - loss: 0.0103 - mae:
   0.0787 - val_loss: 0.0268 - val_mae: 0.1332 - lr: 1.0000e-04
   Epoch 8/50
   93/93 [============ ] - 17s 179ms/step - loss: 0.0086 - mae:
   0.0716 - val_loss: 0.0263 - val_mae: 0.1314 - lr: 1.0000e-04
   Epoch 9/50
   93/93 [============= ] - 16s 174ms/step - loss: 0.0072 - mae:
   0.0662 - val_loss: 0.0265 - val_mae: 0.1314 - lr: 1.0000e-04
   Epoch 10/50
   0.0613 - val_loss: 0.0258 - val_mae: 0.1293 - lr: 1.0000e-04
   Epoch 11/50
   93/93 [============== ] - 16s 171ms/step - loss: 0.0055 - mae:
   0.0580 - val_loss: 0.0264 - val_mae: 0.1308 - lr: 1.0000e-04
   0.0531 - val_loss: 0.0291 - val_mae: 0.1372 - lr: 1.0000e-04
   Epoch 13/50
   0.0510 - val_loss: 0.0291 - val_mae: 0.1375 - lr: 1.0000e-04
   Epoch 14/50
   93/93 [============== ] - 16s 171ms/step - loss: 0.0037 - mae:
   0.0475 - val_loss: 0.0282 - val_mae: 0.1347 - lr: 5.0000e-05
   Epoch 15/50
   0.0384 - val_loss: 0.0294 - val_mae: 0.1372 - lr: 5.0000e-05
   Training time: 246.36 seconds
# Step 7.1: Save both trained models to HDF5 (.h5) format
    # -----
    models_dir = "models"
```

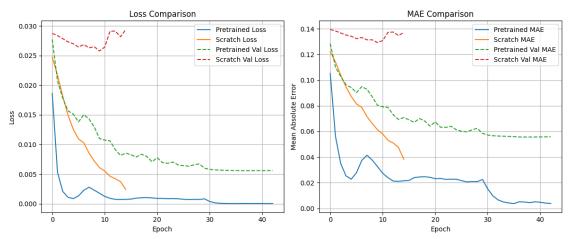
```
if not os.path.exists(models_dir):
        os.makedirs(models dir)
     model_pretrained.save(os.path.join(models_dir, "object_detector_pretrained.h5"))
     print("Saved: models/object_detector_pretrained.h5")
     model_scratch.save(os.path.join(models_dir, "object_detector_scratch.h5"))
     print("Saved: models/object_detector_scratch.h5")
     # Step 7.2: Save training histories to CSV
     import pandas as pd
     pd.DataFrame(history_pre.history).to_csv(os.path.join(models_dir,_
      print("Saved: models/training_log_pretrained.csv")
     pd.DataFrame(history_scratch.history).to_csv(os.path.join(models_dir,_

¬"training_log_scratch.csv"), index=False)
     print("Saved: models/training_log_scratch.csv")
    Saved: models/object_detector_pretrained.h5
    Saved: models/object_detector_scratch.h5
    Saved: models/training_log_pretrained.csv
    Saved: models/training log scratch.csv
# Step 7.3 : Load both trained models from HDF5 files
     # ==============
     model_pretrained = load_model(os.path.join(models_dir,__

¬"object_detector_pretrained.h5"))
     model_scratch = load_model(os.path.join(models_dir, "object_detector_scratch.
     print("Loaded pretrained model from 'models/object_detector_pretrained.h5'")
     print("Loaded scratch model from 'models/object_detector_scratch.h5'")
    Loaded pretrained model from 'models/object_detector_pretrained.h5'
    Loaded scratch model from 'models/object_detector_scratch.h5'
# Step 7.4: Visualize training and validation loss and MAE for both models
     import matplotlib.pyplot as plt
```

```
plt.figure(figsize=(12, 5))
# Plot loss
plt.subplot(1, 2, 1)
plt.plot(history_pre.history['loss'], label='Pretrained Loss')
plt.plot(history_scratch.history['loss'], label='Scratch Loss')
plt.plot(history_pre.history['val_loss'], label='Pretrained Val Loss', __
 →linestyle='--')
plt.plot(history_scratch.history['val_loss'], label='Scratch Val Loss',_
 →linestyle='--')
plt.title("Loss Comparison")
plt.xlabel("Epoch")
plt.ylabel("Loss")
plt.legend()
plt.grid(True)
# Plot MAE
plt.subplot(1, 2, 2)
plt.plot(history_pre.history['mae'], label='Pretrained MAE')
plt.plot(history_scratch.history['mae'], label='Scratch MAE')
plt.plot(history_pre.history['val_mae'], label='Pretrained Val MAE',_
 →linestyle='--')
plt.plot(history_scratch.history['val_mae'], label='Scratch Val MAE',_

slinestyle='--')
plt.title("MAE Comparison")
plt.xlabel("Epoch")
plt.ylabel("Mean Absolute Error")
plt.legend()
plt.grid(True)
plt.tight_layout()
plt.show()
```



```
# Step 8: Compute Intersection over Union (IoU)
     # -----
     # Compute IoU between predicted and true bounding boxes for visual examples
     def compute_iou(box1, box2):
         def denorm(bbox):
            cx, cy, w, h = bbox
            xmin = cx - w / 2
            ymin = cy - h / 2
            xmax = cx + w / 2
            ymax = cy + h / 2
            return [xmin, ymin, xmax, ymax]
         box1 = denorm(box1)
         box2 = denorm(box2)
         xA = max(box1[0], box2[0])
         yA = max(box1[1], box2[1])
         xB = min(box1[2], box2[2])
         yB = min(box1[3], box2[3])
         inter_area = max(0, xB - xA) * max(0, yB - yA)
         box1 area = (box1[2] - box1[0]) * (box1[3] - box1[1])
         box2_area = (box2[2] - box2[0]) * (box2[3] - box2[1])
         union_area = box1_area + box2_area - inter_area
         iou = inter_area / union_area if union_area > 0 else 0
         return iou
# Step 9: Visualize predictions and IoU
     # -----
     # Visualize a few predictions from the validation set and display the IoU
     def visualize_predictions(model, dataset, n=3):
         for images, bboxes in dataset.take(1):
            preds = model.predict(images)
            for i in range(n):
                img_np = images[i].numpy()
                true_bbox = bboxes[i].numpy()
                pred_bbox = preds[i]
                iou_score = compute_iou(true_bbox, pred_bbox)
```

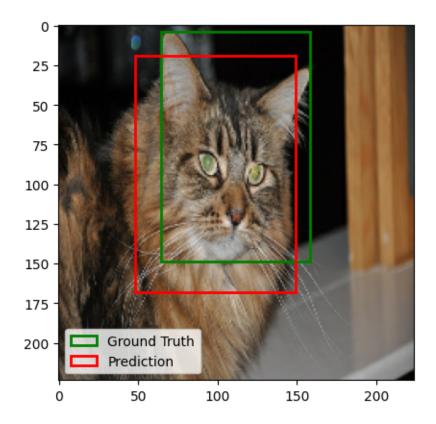
print(f"IoU Score: {iou\_score:.3f}")

display\_bbox(img\_np, true\_bbox, pred\_bbox)

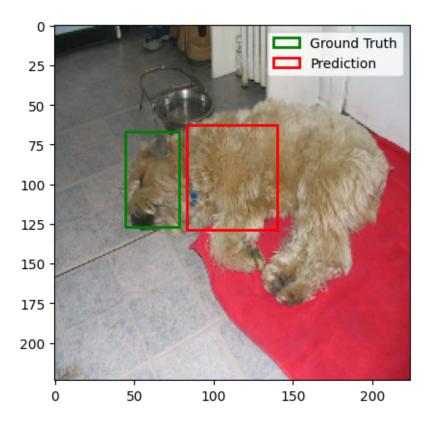
# Show prediction results from pretrained model
visualize\_predictions(model\_pretrained, val\_det\_ds)

1/1 [======] - 1s 571ms/step

IoU Score: 0.622



IoU Score: 0.000



IoU Score: 0.147

