

# **GLM Library**

The OpenGL Mathematics (GLM) library is a convenient C++ library for developing graphics applications.

Header only library

```
#include <glm/glm.hpp>
#include <glm/gtc/matrix transform.hpp>
```

 Several functions and variables use similar naming convention as OpenGL and GLSL

```
glm::vec4 point(2, -3, 4, 1);
glm::mat4 viewMat = glm::lookAt(eye, look, up);
glm::mat4 rotnMat = glm::rotate(inMat, angle, axis);
```

 Particularly useful for matrix operations, lighting computations, ray tracing and OpenGL-4 shader development.

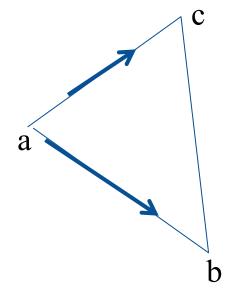
## **GLM Vector Operations: Example**

```
glm::vec3 u, v, w;
u = glm::vec3(3, 0, 4);
v = glm::vec3(-2, -4, 3);
float u len = glm::length(u);
cout << u len << endl;</pre>
                                         //Prints 5
w = glm::cross(u, v);
cout << glm::to string(w) << endl; //Prints vec3(16, -17, -12)
glm::vec3 wn = glm::normalize(w);
cout << glm::to string(wn) << endl; //Prints vec3(0.609, -0.647, -0.457)
float dotprod = glm::dot(u, w);
cout << dotprod << endl;</pre>
                                          //Prints 0
glm::vec4 pt(-5, 2, 9, 1);
     glBegin(GL POINTS);
         glVertex3fv(glm::value ptr(pt));
     glEnd();
```

# Normal Vector of a Triangle

```
glm::vec3 a, b, c;
a = glm::vec3(-2, 1, 1);
b = glm::vec3(0, -5, 3);
C = glm::vec3(3, 2, -7);

glm::vec3 norm;
norm = glm::cross(b-a, c-a);
norm = glm::normalize(norm);
```



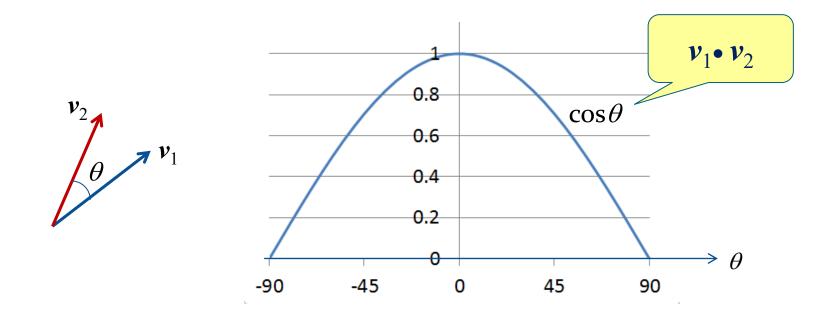
# **GLM Matrix Operations: Example**

```
glm::mat4 im, am, bm, cm;
glm::vec4 p(2, -1, 3, 1), q;
im = glm::mat4(1.0f);
                      //Identity matrix
am = glm::scale(im, glm::vec3(sx, sy, sz));
                          In Radians
bm = glm::rotate(am, theta, glm::vec3(0.f, 1.f, 0.f));
cm = glm::translate(bm, glm::vec3(tx, ty, tz));
q = cm * p;
                         (S = scale transformation matrix)
  am = I * S = S
  bm = am * R = S * R (R = rotation matrix)
  cm = bm * T = S*R*T (T = translation matrix)
   q = cm * p = S*R*T*p
```

#### **Cosine Variation**

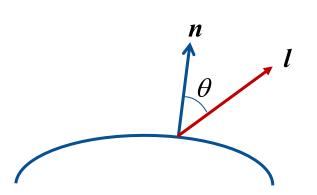
Several values in a lighting computation vary based on the cosine of the angle between two unit vectors:

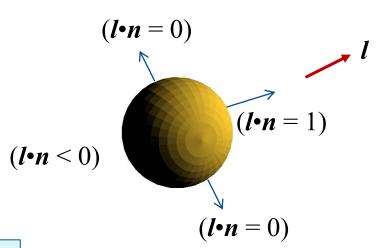
- Max value when angle = 0 (vectors parallel)
- Min value when angle = 90 degs (vectors perpendicular)



#### **Diffuse Reflections**

The diffuse reflection from a surface varies as the cosine of the angle between the **normal vector** *n* and the **light source vector** *l* (Lambert's law)



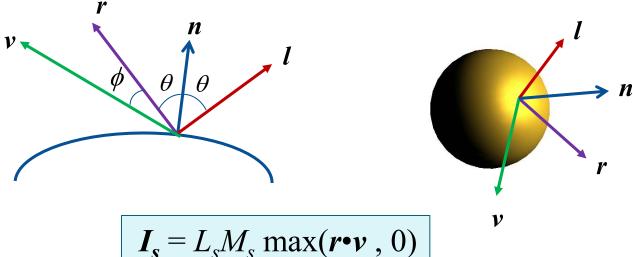


$$I_d = L_d M_d \max(l \cdot n, 0)$$

Note: l, n must be normalized to unit vectors. Usually,  $L_d = (1, 1, 1)$ . Then,  $I_d = M_d \max(l.n, 0)$ 

# **Specular Reflections**

The specular reflection from a surface varies as the cosine of the angle between the **reflection vector** r and the **view vector** r.

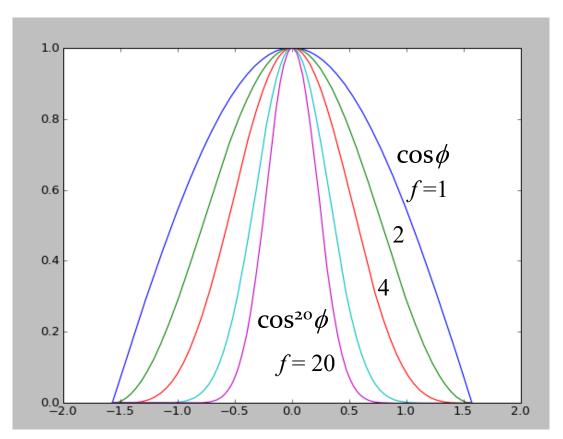


We also include the Phong's constant (shininess term) f to control the diameter of the specular highlight

$$I_s = L_s M_s \{ \max(r \cdot v, 0) \}^f$$

Note: r, v are unit vectors.

# Phong's Constant

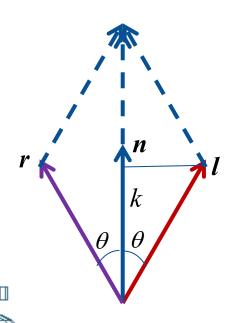


Large values of the exponent f gives highly concentrated highlights.

## Computation of Reflection Vector

The computation of the specular component of lighting requires the reflection vector. It has the following properties:

- ullet Vectors  $oldsymbol{l}$  and  $oldsymbol{v}$  make equal angles with the normal vector  $oldsymbol{n}$
- Vectors *l*, *v* and *n* are on the same plane.



Let k be the length of projection of the vector l on the unit vector n.

$$k = (l \cdot n)$$
 see Slide [7]-18

The projection of r on the unit vector n also has the same length k.

$$r+l=2kn$$

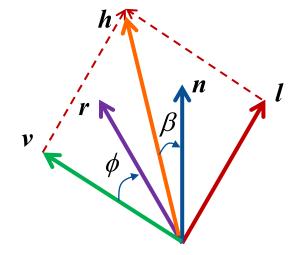
Therefore,

$$r = 2 (l \cdot n) n - l$$

# Half-way Vector

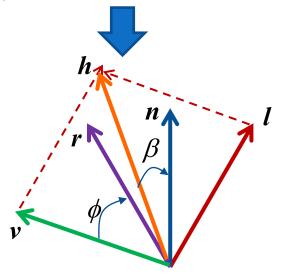
Consider the vector  $\mathbf{h} = (\mathbf{l} + \mathbf{v})$  normalized. Let  $\boldsymbol{\beta}$  be the angle between  $\mathbf{h}$  and  $\mathbf{n}$ . We observe the following facts:

- When  $\phi$  increases,  $\beta$  also increases.
- When  $\phi = 0$ ,  $\beta$  also becomes 0.

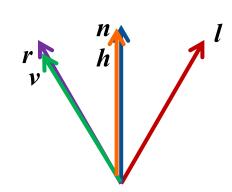


Keeping l, n (and r) fixed, if we move v away from r, then h moves away from n.

If v coincides with r, then h coincides with n.







# Phong-Blinn Model

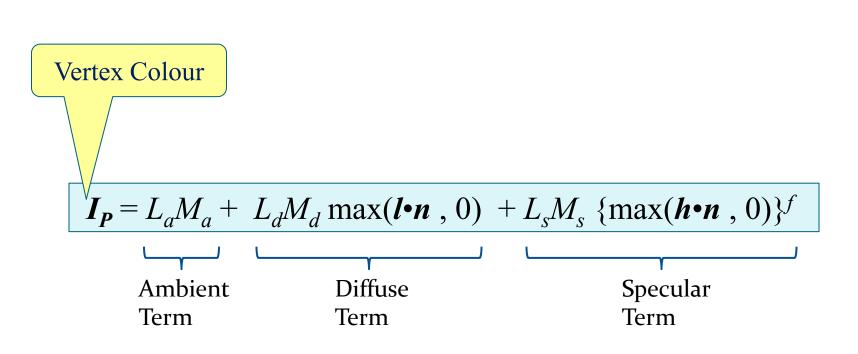
- OpenGL uses an approximation of  $(r \cdot v)$  by the term  $(h \cdot n)$  in the computation of specular reflections.
- The vector h is called the **Half-way Vector**, and is computed as h = (l + v) normalized.
- We can now rewrite the formula for specular reflection:

$$I_s = L_s M_s \{ \max(\boldsymbol{h} \cdot \boldsymbol{n}), 0 \}^f$$

 The lighting equation with the above approximation is called the Phong-Blinn model.

If *l* is a directional source, and the view direction is constant (viewer at infinity), then *h* needs to be computed only once for the whole scene.

# Lighting Equation: Phong-Blinn Model



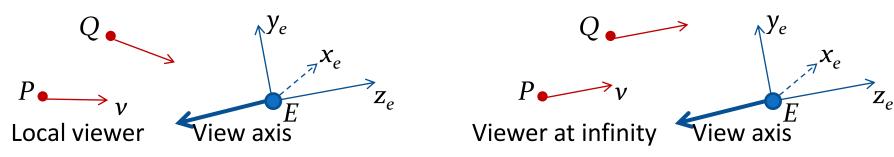
#### **Geometrical Considerations**

• The rendering speed is increased if v is made constant for all vertices (infinite viewpoint). This is the default setting.

```
glLightModeli(GL_LIGHT_MODEL_LOCAL_VIEWER, GL_FALSE);
```

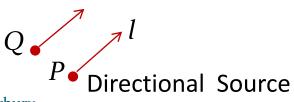
 You can force the computation of the true value of v for each vertex (local viewpoint) for more realistic results:

```
glLightModeli(GL_LIGHT_MODEL_LOCAL_VIEWER, GL_TRUE);
```



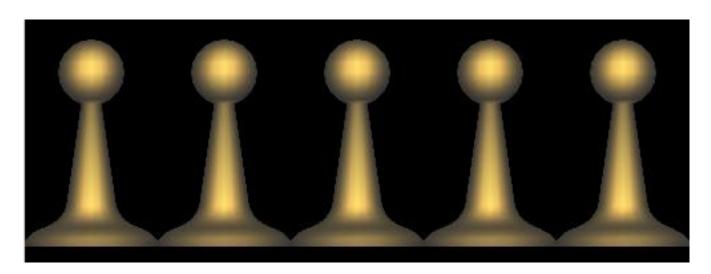
• For a light source at infinity (directional source) the vector *l* is constant for all vertices in the scene.



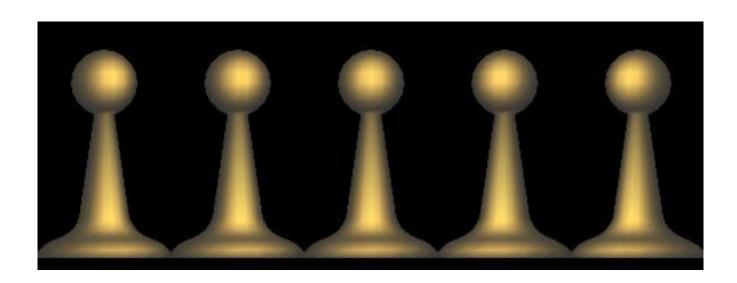


# Infinite viewpoint

# **Local and Infinite Viewpoints**



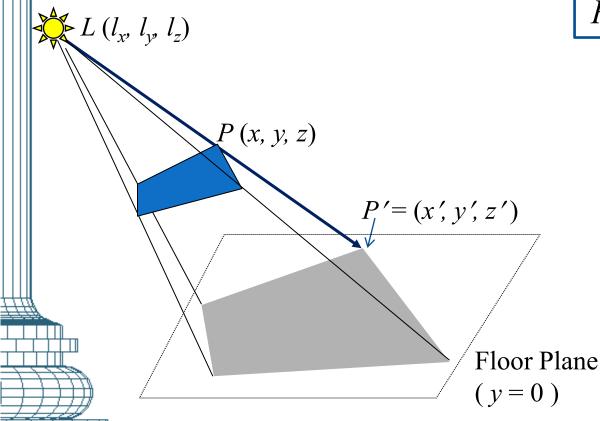
Local viewpoint



### **Planar Shadows**

( See also slides [3]:16-20 )

- Project each of the polygonal faces onto the floor plane, using the light source (L) as the centre of projection.
- Use only the ambient light to draw the projected object.



$$P' = (1-t)L + tP,$$
  $t > 1.$ 

$$x' = (1-t)l_x + tx$$

$$y' = (1-t)l_y + ty = 0$$

$$z' = (1-t)l_z + tz$$

$$\therefore t = \frac{l_y}{l_y - y}$$

#### **Planar Shadows**

The projection P'of the vertex (x, y, z) on the floor- plane is given by the following coordinates:

$$x' = \frac{-l_x y + l_y x}{l_y - y}$$
$$y' = 0$$
$$z' = \frac{-l_z y + l_y z}{l_y - y}$$

Homogeneous Coordinates

$$s_{x} = -l_{x}y + l_{y}x$$

$$s_{y} = 0$$

$$s_{z} = -l_{z}y + l_{y}z$$

$$w = l_{y} - y$$

• The above equations can be written as a transformation:

$$\begin{bmatrix} s_x \\ s_y \\ s_z \\ w \end{bmatrix} = \begin{bmatrix} l_y & -l_x & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -l_z & l_y & 0 \\ 0 & -1 & 0 & l_y \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

# Planar Shadows: Code

( See also slide [3]:20 )

```
// Light source position = (lx, ly, lz)
float shadowMat[16] = \{ ly, 0, 0, 0, -lx, 0, -lz, -1, \}
                        0,0,1y,0,0,0,1y;
// Draw object
glEnable(GL LIGHTING);
glPushMatrix();  //Draw Actual Object
    /* Transformations */
    drawObject();
 qlPopMatrix();
// Draw shadow
 qlDisable(GL LIGHTING);
 glPushMatrix();  //Draw Shadow Object
  qlMultMatrixf(shadowMat);
   /* Transformations */
   glColor4f(0.2, 0.2, 0.2, 1.0);
  drawObject();
 glPopMatrix();
```