

Data sampling for surrogate modeling and optimization

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(and others)

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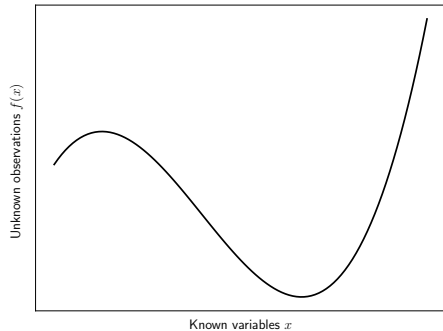
Outlines

Inference problems and high-dimensional modeling

Modeling for high-dimensional optimization

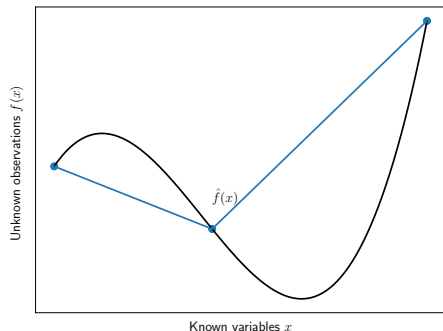
The fundamental machine learning problem

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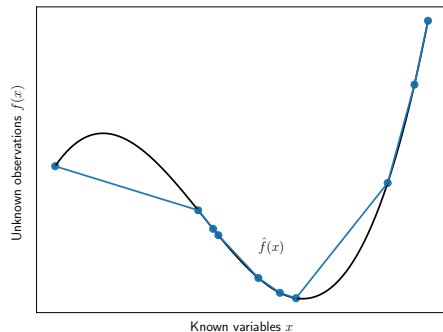
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The fundamental machine learning problem



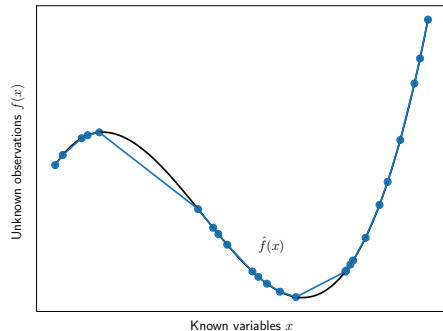
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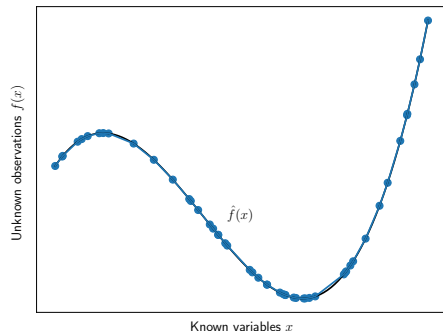
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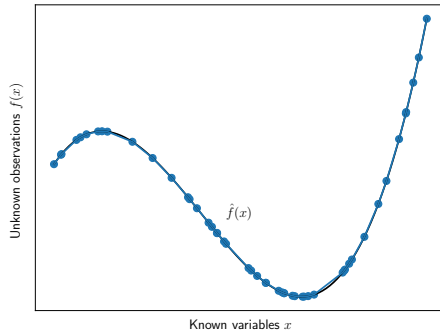
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- ▶ If we have enough data, it doesn't matter

Some basic numerical analysis results

When \hat{f} is a piecewise linear spline:

For h “small enough” – let q be the query point

$$|f(q) - \hat{f}(q)| \sim \mathcal{O}(h^2)$$



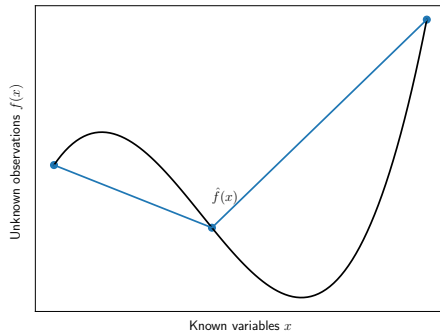
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- ▶ For irregular \mathcal{X} , h could be the distance from q to the nearest neighbor in \mathcal{X}
- ▶ Constants proportional to the Lip constant of ∇f

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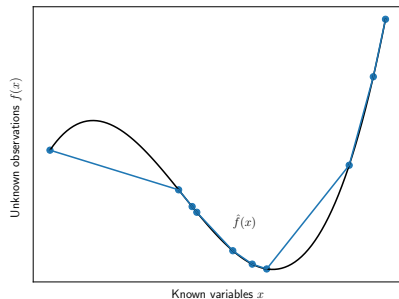
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Some basic deep learning

- ▶ Train a fully-connected multi-layer perceptron (MLP) using \mathcal{X}
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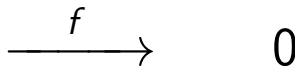
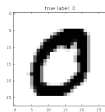
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“There’s more to machine learning than function approximation”

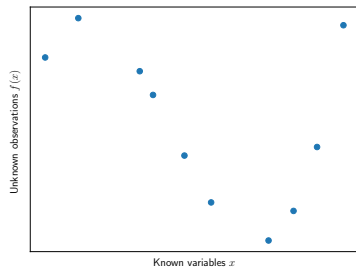
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- ▶ f is often highly *structured* – MLPs with nothing else are from the 60s

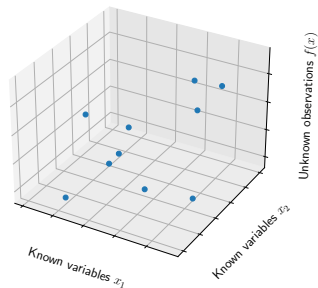


28×28 pixels \neq 784 dimensions...

The curse of dimensionality

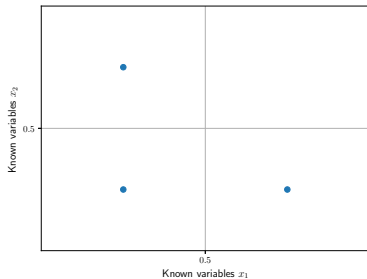


10 training points in 1D



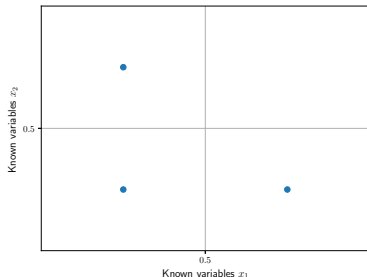
10 training points in 2D

The curse of dimensionality no data



Need data in all quadrants?

The curse of dimensionality no data



Need data in all quadrants?

- ▶ Inference in 2D : $2^2 = 4$
- ▶ Inference in 10D : $2^{10} \approx 1000$
- ▶ Inference in 100D : $2^{100} \approx 10^{30}$ (orders of magnitude bigger than exascale)
- ▶ Many ML problems : inference in 1000+ dimensions

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We measure where we *might* have enough data to make a prediction using the “convex hull” of the training data $CH(\mathcal{X})$

If \mathcal{X} are sampled from *any* distribution, $\mu(CH(\mathcal{X})) \rightarrow 0$ *exponentially* as d grows

This is called a *concentration of measure*

Gorban and Tyukin, Stochastic separation theorems. *Neural Networks* 94, pp. 255-259 (2017).

Example

Suppose that we uniformly sample $x = (x_1, x_2, \dots, x_d)$ from $[0, 1]^d$

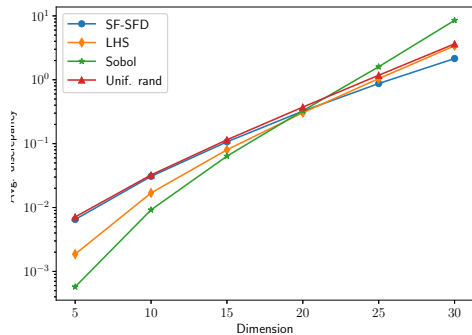
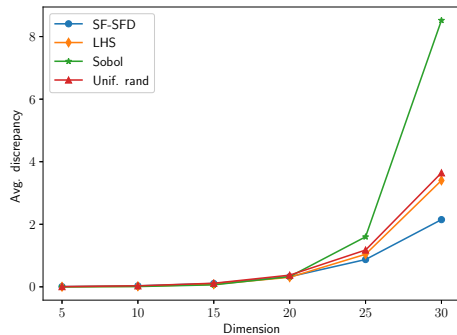
$$\|x - \frac{1}{2}\|_2^2 = \sum_{i=1}^d (x_i - \frac{1}{2})^2.$$

$$\mathbb{E} \left[\left(x_i - \frac{1}{2} \right)^2 \right] = \int_0^1 \left(u - \frac{1}{2} \right)^2 du = \frac{1}{12}$$

with finite variance v

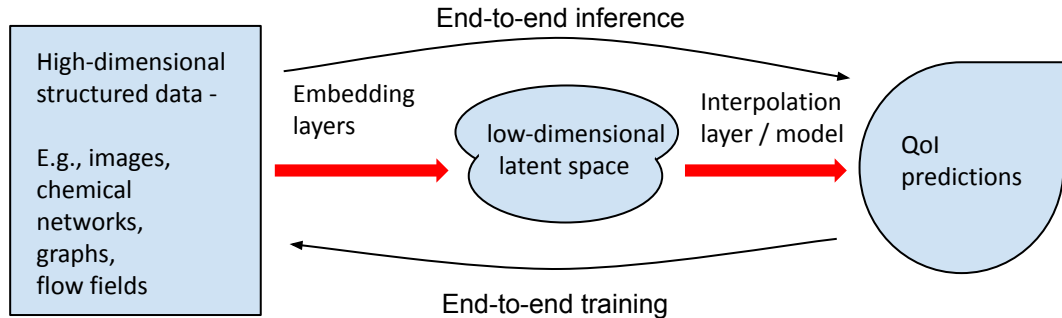
By CLT for all $x \in \mathcal{X}$: $\mathbb{E}[\|x - \frac{1}{2}\|_2^2] = \frac{d}{12}$ with variance $\frac{v}{d} \rightarrow 0$ as $d \rightarrow \infty$.

Collapse of some common distributions

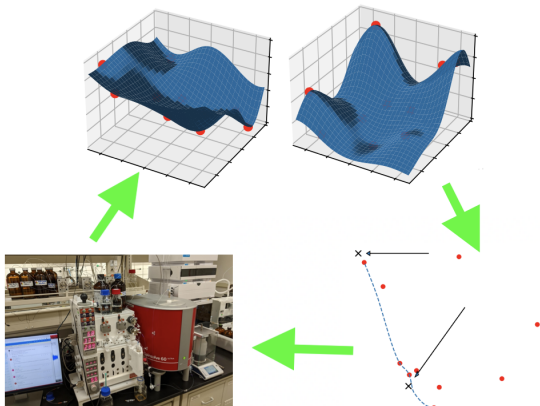


Garg, Chang, and Raghavan, Stochastic optimization of Fourier coefficients to generate space-filling designs. *To appear in Winter Sim 2023.*

Modern deep learning pipeline



Hope in context of optimization



Global modeling is harder than optimization

For optimization, only need model accuracy near the solution...

- ▶ Global modeling is *significantly harder than optimizing*
- ▶ To build a *globally accurate model* over n variables, need $\mathcal{O}(2^n)$ samples
- ▶ To build a *locally accurate model* over n variables, need $\mathcal{O}(n)$ samples

Global optimization

In global optimization literature...

- ▶ Balance exploration vs. exploitation
- ▶ Drive *global model error* to zero
- ▶ Need exponentially many samples to guarantee global convergence

Guarantees convergence for problems with thousands of local minima

