

Data sampling for surrogate modeling and optimization

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Outlines

Problem Setting and Some Background

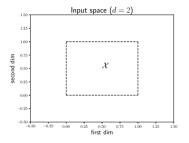
My Story with Interpolation Methods

The Geometry of Bad Data

A Proposed Solution

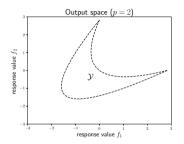


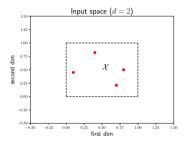
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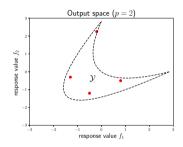


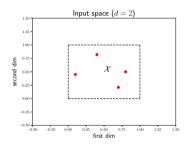






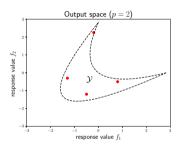
 $F: \mathcal{X} \to \mathcal{Y}$





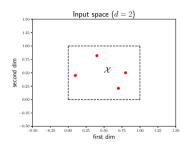




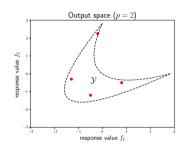


Given a set of n points \mathcal{P} in \mathcal{X} , find $\hat{F} \approx F$ such that $\hat{F}(x) = F(x)$ for all $x \in \mathcal{P}$





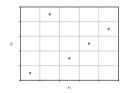


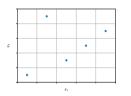


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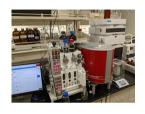
Suppose $\mathcal{X} \subset \mathbb{R}^d$ and $\mathcal{Y} \subset \mathbb{R}^p$, and F is continuous

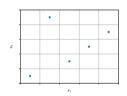




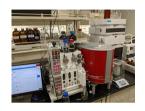


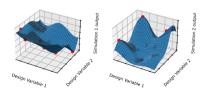


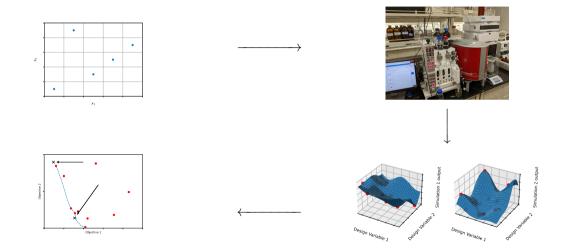


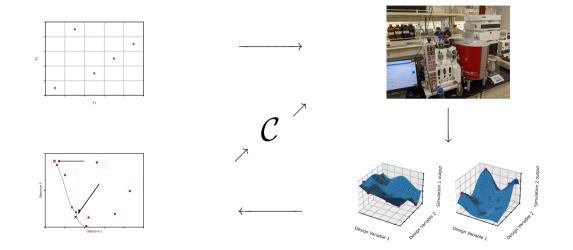


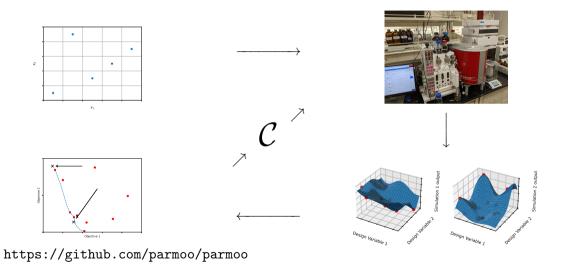












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- "Classical" interpolation techniques
 - Polynomial interpolation
 - B-spline interpolation
 - RBF interpolants
 - generalized Shepard's methods
 - ► Piecewise linear interpolation



My Story with Interpolation Methods

Piecewise Linear Interpolation

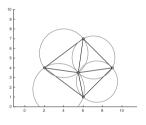
- ▶ Let $\mathcal{T}(\mathcal{P})$ be a *d*-dimensional triangulation of \mathcal{P} .
- ▶ Given an interpolation point $q \in \mathcal{CH}(\mathcal{P})$, let \mathcal{S} be a simplex in $\mathcal{T}(\mathcal{P})$ with vertices s_1, \ldots, s_{d+1} such that $q \in \mathcal{S}$.
- Then there exist unique convex weights w_1, \ldots, w_{d+1} such that $q = \sum_{i=1}^{d+1} w_i s_i$.

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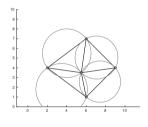
Define:

$$\hat{F}_{\mathcal{T}}(q) = F(s_1)w_1 + F(s_2)w_2 + \ldots + F(s_{d+1})w_{d+1}$$



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Chang et al. 2020. Algorithm 1012: DELAUNAYSPARSE. ACM TOMS 46(4), Article No. 38.

Error Rates for Piecewise Linear Interpolants

For an individual component function F_i :

- ▶ Let ∇F_i be λ -Lipschitz in the 2-norm
- ▶ For $S \in \mathcal{T}$ containing q,
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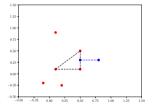
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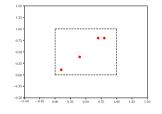
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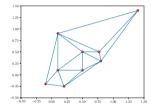
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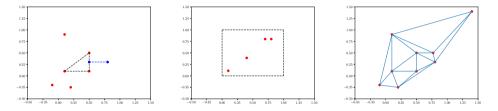
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Lux, Watson, Chang, et al. 2021. Interpolation of sparse high-dimensional data. Numerical Algorithms 88(1), 281–313.



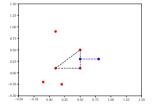


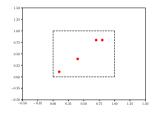


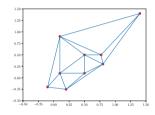


► Too many extrapolation points (information lost in projection)

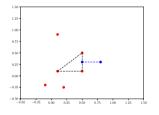


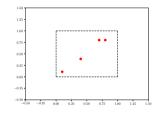


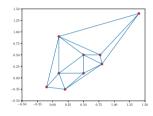




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- "Flat" data set cannot (accurately) triangulate
- Several massive simplices (high error-rate, poor conditioning)



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What does the theory say?

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My take:

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My take:

Yes, it does... and it's bad.

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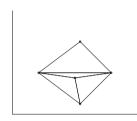
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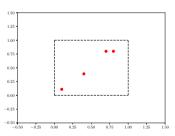
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What Could Go Wrong: Poor data conditioning

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- Simplices are long and narrow
- ightharpoonup $\kappa_{\mathcal{S}}$ term blows up
- $ightharpoonup \hat{F}_{\mathcal{T}}$ is hard to compute and low accuracy
- Ex: data lies close to a lower-dimensional manifold



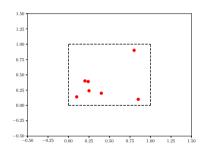




What Could Go Wrong: Data imbalance

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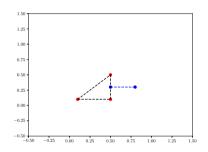
- ightharpoonup Data accumulates in subregions of \mathcal{X}
- \blacktriangleright ξ stays large in less-dense regions of ${\mathcal X}$
- ► Can also result in poor conditioning, but they are not the same
- Called high discepancy



What Could Go Wrong: Extrapolation

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- $ightharpoonup \hat{F}_{\mathcal{T}}$ is only defined in the $\mathcal{CH}(\mathcal{P})$
- ▶ Will have to project q into $\mathcal{CH}(\mathcal{P})$ and interpolate projection
- Low accuracy when residual is large
- ▶ When $\mathcal{CH}(\mathcal{P})$ is a small subset of \mathcal{X} , overall accuracy can be poor



Same Issues for RBFs/GPs

$$\hat{F}_{RBF} = \omega^{ op} \left[egin{array}{c} e^{-\|x_1 - x\|^2/\sigma} \ e^{-\|x_2 - x\|^2/\sigma} \ dots \ e^{-\|x_n - x\|^2/\sigma} \end{array}
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- "Uncertainty principle" for real-world datasets, cannot have accuracy and solvability



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- ightharpoonup When \hat{F} interpolates, conditions for fully linearity reduce to geometric conditions
 - ightharpoonup d+1 model points in ball are affinely independent
- Only accurate within ball
 - no guarantees during extrapolation
 - no convergence in low-density regions

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- Imbalanced
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Real-world datasets have zero-volume in high-dimensions, which leads to all of the properties

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- Latin hypercubes
 - ► Stratifies sample good for linear models
 - No theory for nonlinear models
 - Heuristically good in practice and cheap to calculate

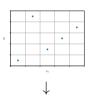


Stochastic Fourier SFD

- Desired sample size
- Performance criertia

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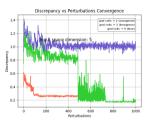


$$\alpha_1 e^{2\pi i x} + \alpha_2 e^{2\pi i (2x)} + \dots$$

Preliminary Results







Resources

E-mail: tchang@anl.gov

Code: github.com/thchang/sf-sfd

This material is based upon work supported by the U.S. Department of Energy, Office of Science, Office of Advanced Scientific Computing Research, SciDAC program under contract number DE-AC02-06CH11357.