

# Computing Sparse Subsets of the Delaunay Triangulation in High-Dimensions for Interpolation and Graph Problems

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# Outlines

## Delaunay Interpolation

- Introduction and Motivation

- Algorithm Description

- Implementation

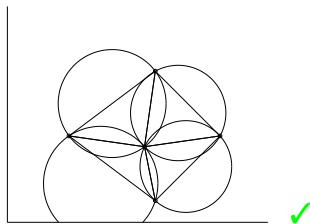
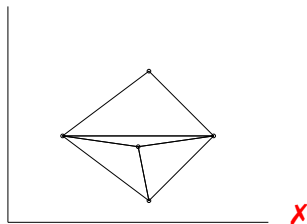
## Application for Computing the Delaunay Graph

- About the Delaunay Graph

- Algorithm using DELAUNAYSPARSE

## About Delaunay Triangulations

- ▶ The *Delaunay triangulation* is an unstructured simplicial mesh defined by an arbitrary vertex set  $P = \{x^{(1)}, \dots, x^{(n)}\} \subset \mathbb{R}^d$
- ▶ The defining property of the Delaunay triangulation  $DT(P)$  is that for every simplex  $S \in DT(P)$ , the circumball  $B^{(S)}$  must have empty intersection with  $P$ :  $B^{(S)} \cap P = \emptyset$ .



- ▶  $DT(P)$  exists and is unique when  $P$  is in *general position*.

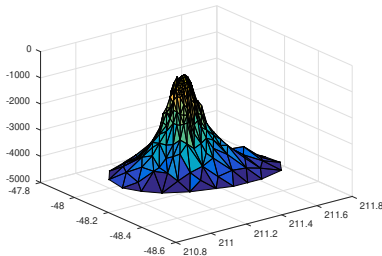
# Delaunay Interpolation

Let  $y \in S \in DT(P)$ .  $S$  has vertex set  $\{s^{(1)}, \dots, s^{(d+1)}\}$  and there exist convex weights  $\{w_1, \dots, w_{d+1}\}$  such that  $y = \sum_{i=1}^{d+1} w_i s^{(i)}$ .

$$\hat{F}_{DT}(y) = \sum_{i=1}^{d+1} w_i F(s^{(i)}).$$

Advantages in data science/ML settings

- ▶ Interpolates data (when that is a desirable property)
- ▶ Like a feed-forward fully-connected ReLU net, this is a piecewise linear model. But this model is provably considered “optimal” (in a sense) for interpolation w.r.t. other piecewise linear models.
- ▶ Can be used to interpolate functional response variables, e.g., PDFs.



## Scalability Issues

- ▶ Owing to Klee, the size of the Delaunay triangulation is

$$\mathcal{O}\left(n^{\lceil d/2 \rceil}\right)$$

- ▶ For  $d > 4$ , this is expensive!
- ▶ For  $d > 8$ , this is not scalable!

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**Observation:** For interpolation at a single point  $y$ , we only need the vertices  $(\{s^{(1)}, \dots, s^{(d+1)}\})$  of  $S \in DT(P)$  such that  $y \in S$

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**Question:** Can we find  $S$  containing  $y$  in polynomial time?

# Algorithm outline

Algorithm to locate Delaunay simplex containing  $y$ :

- ▶ Grow an initial Delaunay simplex (greedy algorithm) that is “nearby” to  $y$
- ▶ “Flip” across facets from which  $y$  is visible to a new Delaunay simplex (closer to  $y$ )
- ▶ This “visibility walk” converges to  $y$  in finite steps (Edelsbrunner’s acyclicity theorem)

*Chang, Watson, Lux, Li, Xu, Butt, Cameron, and Hong. “A polynomial time algorithm for multivariate interpolation in arbitrary dimension via the Delaunay triangulation.” In Proc. 2018 ACMSE Conf.*



# Growing the First Simplex

$\phi$  is the vertex set for the initial Delaunay simplex:

- ▶ Start with  $\phi$  containing just the nearest neighbor to  $y$  in  $P$ ;
- ▶ For all  $x \in P \setminus \phi$ , compute the radius  $r_{min}$  of the smallest circumball about  $\{x\} \cup \phi$  and select the  $x^*$  that minimizes  $r_{min}$ ;
- ▶  $\phi \leftarrow \phi \cup \{x^*\}$ ;
- ▶ Repeat until  $|\phi| = d + 1$ ;

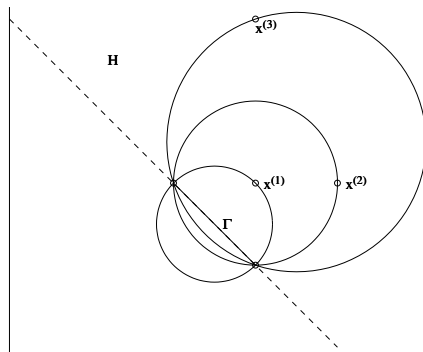
## Lemma

*Let  $P$  be in general position, and let  $\Gamma$  be a Delaunay  $j$ -face with vertices  $\phi \subset P$  where  $j < d$ . Let  $x^* \in P \setminus \phi$  minimize the radius of the smallest  $(d-1)$ -sphere through the points in  $\phi \cup \{x\}$ , over all  $x \in P \setminus \phi$ . Then  $\Gamma^* = \text{ConvexHull}(\phi \cup \{x^*\})$  is a Delaunay  $(j+1)$ -face. **Proof in Paper.***

# Flipping

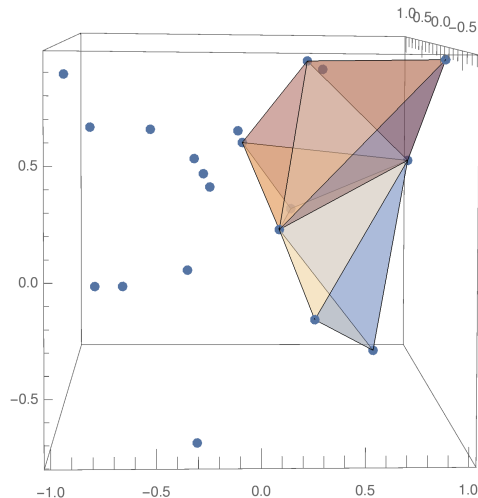
- ▶ Let  $\phi$  be the vertices for a facet of a Delaunay simplex;
- ▶ Let  $\Gamma$  be the facet with vertices in  $\phi$ ;
- ▶ Let  $H$  be the halfspace containing  $y$ , w.r.t. the hyperplane containing  $\Gamma$
- ▶ Unless  $\Gamma$  is a facet of the convex hull, there exists  $x^* \in P \setminus \phi$  such that  $\phi \cup \{x^*\}$  is the vertex set for a Delaunay simplex;

**Proof in Paper.**



# Visibility walk

- ▶ Grow an initial simplex  $S^{(0)}$ ;
- ▶ While  $y \notin S^{(k)}$ , generate  $S^{(k+1)}$  by flipping across a facet of  $S^{(k)}$  from which  $y$  is “visible”;
- ▶ Terminate when  $y \in S^{(k)}$ , otherwise,  $k \leftarrow k + 1$ ;



Converges in finite flips by *Edelsbrunner's Acyclicity Theorem*.

# Algorithm Complexity

- ▶ To grow the first simplex:  $\mathcal{O}(nd^3)$  to apply  $n$  rank-1 updates to the QR factorization of  $d \times j$  matrix for  $j = 1, \dots, d$
- ▶ To compute a flip:  $\mathcal{O}(nd^2)$  to apply  $n$  rank-1 updates to the QR factorization of a  $d \times d$  matrix
- ▶  $\ell$  total flips

|          | $n = 2K$ | $n = 8K$ | $n = 16K$ | $n = 32K$ |
|----------|----------|----------|-----------|-----------|
| $d = 2$  | 3.05     | 2.90     | 3.25      | 3.10      |
| $d = 8$  | 23.75    | 24.75    | 24.30     | 23.10     |
| $d = 32$ | 95.25    | 125.60   | 131.85    | 150.10    |
| $d = 64$ | 171.95   | 221.85   | 248.35    | 280.60    |

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**Overall complexity:**  $\mathcal{O}(nd^2\ell)$

**Unresolved question:**  $\ell \approx d$ ?  $\ell$  independent of  $n$ ?

## Linear programming interpretation

$$\tilde{A} = \begin{bmatrix} (-x^{(1)})^T & 1 \\ (-x^{(2)})^T & 1 \\ \vdots & \vdots \\ (-x^{(n)})^T & 1 \end{bmatrix}, \tilde{b} = \begin{bmatrix} \|x^{(1)}\|_2^2 \\ \|x^{(2)}\|_2^2 \\ \vdots \\ \|x^{(n)}\|_2^2 \end{bmatrix}, \text{ and } \tilde{c} = \begin{bmatrix} -y \\ 1 \end{bmatrix}.$$

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**Ext pts:**  $\tilde{u} = (-2\text{circumcenter}, \text{circumradius}^2 - \|\text{circumcenter}\|_2^2)$



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**LP basic solution in polynomial time is an open problem!**

# DELAUNAYSPARSE Package

Standalone software package DELAUNAYSPARSE:

- ▶ Robust against degeneracy
- ▶ Runs in  $\mathcal{O}(mnd^2\ell)$  time
- ▶ Parallel and serial implementations

| Runtime<br>(secs) for<br>interpolating<br>a single<br>point<br>( $m = 1$ ) with<br>$n$ pts in $\mathbb{R}^d$ | $n$    | $d$    |         |         |          |          |
|--|--------|--------|---------|---------|----------|----------|
|  |        | 2      | 8       | 32      | 64       | 128      |
|  | 250    | 0.005  | 0.013   | 0.150   | 3.404    | 27.078   |
|  | 500    | 0.021  | 0.042   | 0.325   | 6.479    | 59.511   |
|  | 1000   | 0.083  | 0.152   | 0.791   | 14.020   | 124.320  |
|  | 2000   | 0.344  | 0.583   | 2.230   | 28.984   | 242.066  |
|  | 4000   | 1.314  | 2.284   | 7.165   | 62.494   | 502.620  |
|  | 8000   | 5.580  | 9.027   | 26.210  | 151.177  | 905.711  |
|  | 16,000 | 22.086 | 35.725  | 109.448 | 386.596  | 2190.362 |
|  | 32,000 | 82.915 | 145.115 | 421.934 | 1097.060 | 5024.675 |

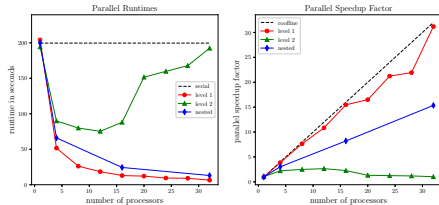
Chang, Watson, Lux, Butt, Cameron, and Hong. 2020. Algorithm 1012: DELAUNAYSPARSE: Interpolation via a sparse subset of the Delaunay triangulation in medium to high dimensions. *ACM Trans. Math. Softw.* 46(4).

# Parallel implementation

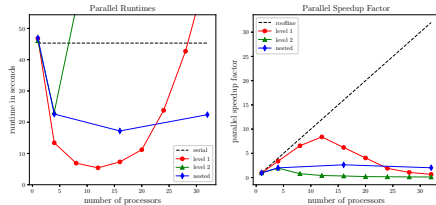
**Distributed memory:** Run the serial algorithm on small batches of interpolation pts

**Shared memory:** Multiple levels

- ▶ Level 1: loop over multiple interpolation points (like distributed case)
- ▶ Level 2: loop(s) over data points – results in additional work; preferable only when  $m$  is small and  $n$  is large



$d = 50, n = 500, m = 64$



$d = 10, n = 1000, m = 1024$

# The Delaunay Graph

- ▶ Delaunay graph of  $P = DG(P)$
- ▶ Connect 2 vertices iff they are shared by a single Delaunay simplex
- ▶ Used for:
  - ▶ Neighbor structure in spatial data
  - ▶ Topological shape analysis
- ▶ There are at most  $n(n-1)/2$  edges
- ▶ Current state-of-the-art implementation in CGAL computes  $DG(P)$  from  $DT(P)$ 
  - scales well for large  $n$ , infeasible for  $d \geq 10$

# Getting the Delaunay Graph

- ▶ The number of connections in  $DG(P)$  is upper bounded by  $n(n-1)/2$
- ▶ Can recover  $DG(P)$  by interpolating the midpoint between each pair of points in  $P$ 
  - ▶ If the simplex containing the midpoint between  $x^{(1)}$  and  $x^{(2)}$  also contains both  $x^{(1)}$  and  $x^{(2)}$ , then they are clearly connected
  - ▶ If not, then it certifies that they are not connected in a Delaunay triangulation (in case degenerate)
- ▶ Using DELAUNAYSPARSE, requires  $\mathcal{O}(n^3 d^2 \ell)$  time — better than current state-of-the-art for  $d$  large, worse for  $n$  large

Implementation currently under review for publication.

Full proof/description in

*T.H. Chang. Mathematical Software for Multiobjective Optimization Problems. Ph.D. Thesis, Virginia Tech, 2020.*

# Questions

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