

Inter-Process Communication (IPC)

Instructor: Limei Peng
Dept. of CSE, KNU

Outlines

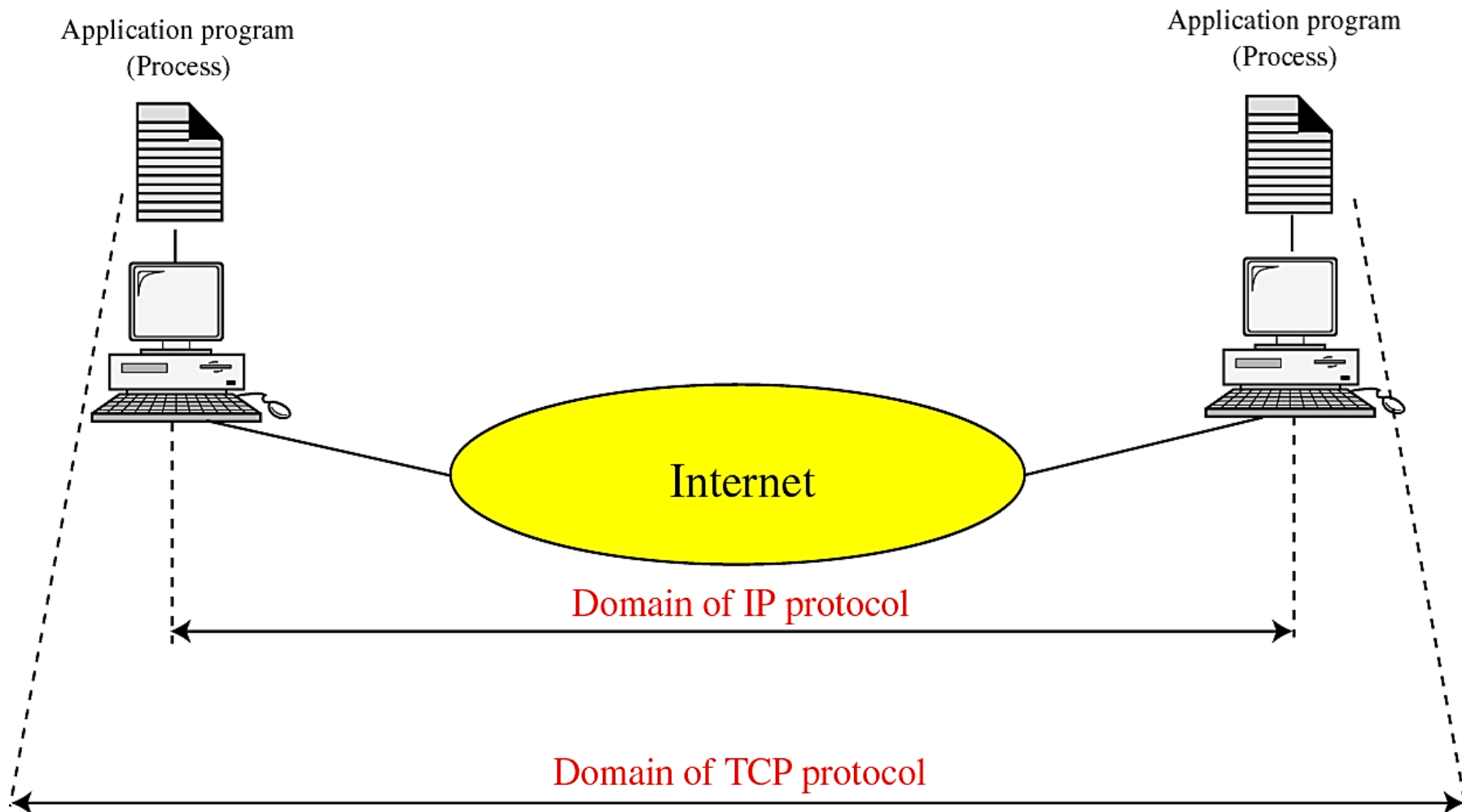
- ❑ What is inter-process communication?
- ❑ **pipe()**

프로세스는 프로세스의 경계를 가진다.

Process-to-Process Communication

각 ID와 각 메모리 공간을 갖는다.

□ Host-to-host communication and process-to-process communication



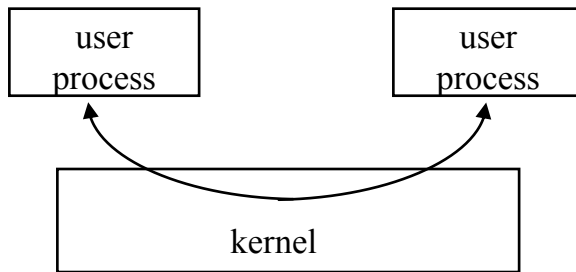
Interprocess Communication (IPC) : 프로세스들 간에 서로 데이터를 주고받는 행위

일반적으로 프로세스들 서로 영향을 주지 않

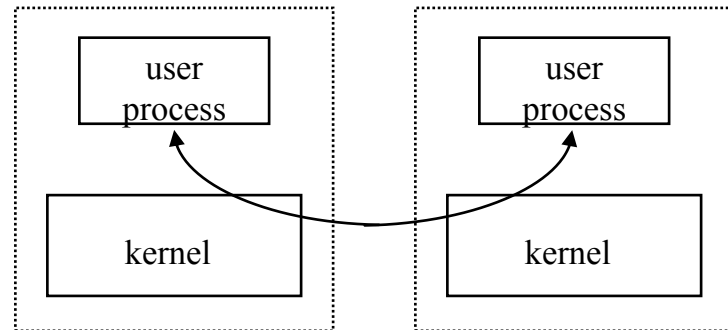
- In general, processes cannot influence each other
 - Each process is executed in isolation from the others (isolated memory) : 각각의 프로세스는 서로 독립되어 실행
 - For example, one process cannot write into the memory of another (한 프로세스는 다른 프로세스의 메모리에 쓸 수 없음)

□ IPC between Two Processes

at the same system



□ IPC between Two Systems



Classifications of IPC

- But you can let ^{여러 프로세스가 서로 통신할 수 있게 만들어 줌} several processes communicate with each other via the following methods:
 - Signals: Send a signal (**SIGHUP**, **SIGINT**, **SIGKILL**, etc.) to another process
 - **PIPE**: ^{데이터를 보내 (data 전송)} a communication channel to transfer data
 - FIFOs, Message Queues, Shared memory (the same memory area is accessible to multiple processes), Semaphores (e.g., to regulate access to shared memory)
- Generally, all these IPCs work only between processes of the same computer

PIPE

CH11

PIPE

- ❑ A specific type of file that IPC is supported by OS
 - Temporal file that is managed by OS, unlike general file
 - It's used to transfer data between **processes** not to store data
- ❑ IPC using a **PIPE**
 - Sender writes to a **PIPE** and receiver reads from that
 - Supports a stream channel
 - Sent data has a sending order

→ 보내는 쪽은 PIPE에 write하고
받는 쪽은 꼭 읽어야.

PIPE

❑ Acts as a conduit/channel allowing two processes to communicate : 두 프로세스가 통할 수 있는 도관/채널 역할

❑ Some questions?

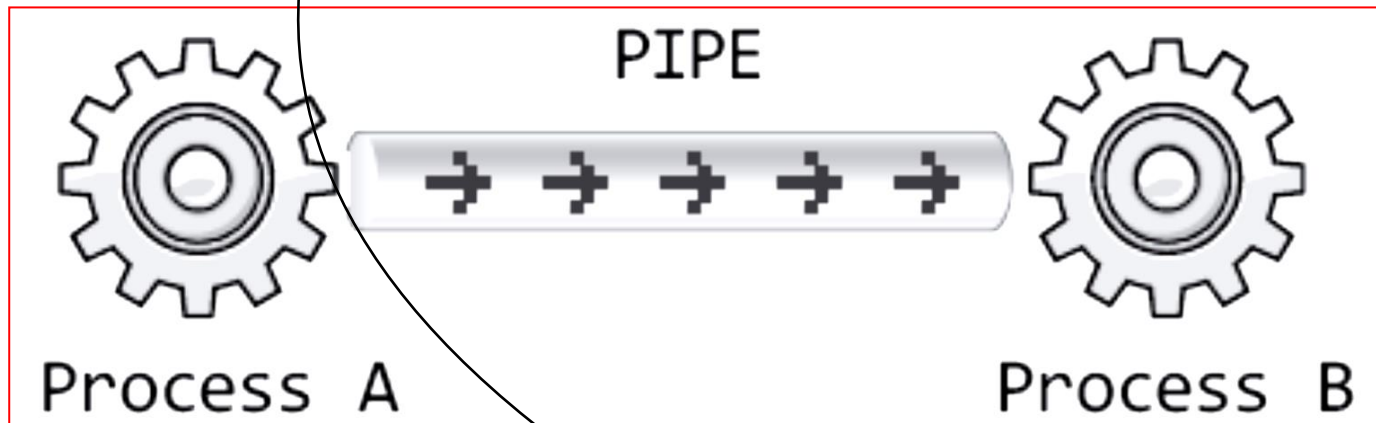
6방향통 vs 양방향통

- Is communication **unidirectional** or **bidirectional**?
- Must there exist a **relationship** (i.e., parent-child) between the communicating processes?
통할 때 관계가 필요하냐?

pipe()-unnamed PIPE

□ A simple, unnamed pipe provides a one-way flow of data : *동일한 부모 프로세스를 가진 프로세스들 간에 '대방향' 자원 (named pipe, any process)*

- Can be thought as a special file that can store a limited amount of data in a first-in-first-out (FIFO) manner, exactly akin to a queue : *(제한 비저장) FIFO 구조 (First in First Out)*



□ Other variations: *→ 제한된 양의 데이터를 FIFO로 저장할 수 있는 특 파일로 생체하임.*

- Stream pipes
- FIFOs

pipe()-unnamed PIPE

- ❑ An unnamed pipe is created by calling **pipe()**, which returns an array of 2 file descriptors (int)
 - The file descriptors (are for reading and writing, respectively)
→ read, write
- ❑ Unnamed pipes can only be used between **related process**, such as parent/child, or child/child processes : parent/child 나 child/child 같이
서로 연결된 프로세스 사이에서만 사용 가능
- ❑ Unnamed pipes can exist only as long as the processes using them : unnamed 파이프는 프로세스가 사용 중일 때만 존재할 수 있음

pipe() System Call (unnamed)

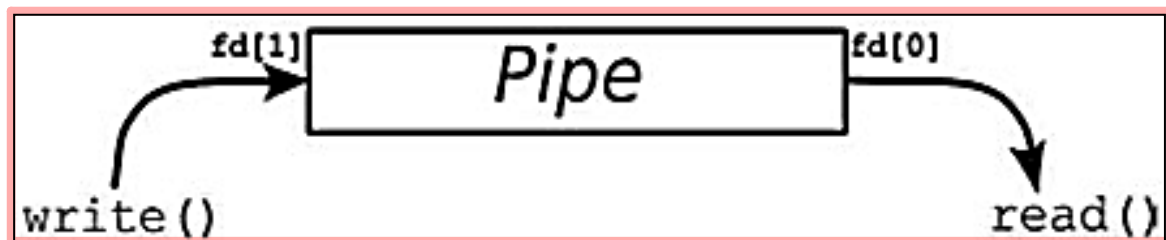
Creates a unidirectional pipe.

```
#include <unistd.h>
```

```
int pipe (int pipefd[2]);
```

Return 0 on Success; -1 on Failure;

- ❑ If successful, the **pipe** system call will return two integer file descriptors, **pipefd[0]** and **pipefd[1]**
 - **pipefd[0]** is the **read** end from the pipe
 - **pipefd[1]** is the **write** end to the pipe
- ❑ Example (pipe1.c)
 - Parent/child processes communicating via unnamed pipe



Example #1-pipe1.c

→ unidirectional communication

```
int main(int argc, char *argv[])
{
```

```
    int fds[2];
```

```
    char str[]="Who are you?";
```

```
    char buf[BUF_SIZE];
```

```
    pid_t pid;
```

```
    pipe(fds);
```

[0]: read
[1]: write

```
    pid=fork();
```

```
    if(pid==0): child process
```

```
    {
```

```
        write(fds[1], str, sizeof(str));
```

```
    }
```

```
    else : parent process
```

```
    {
```

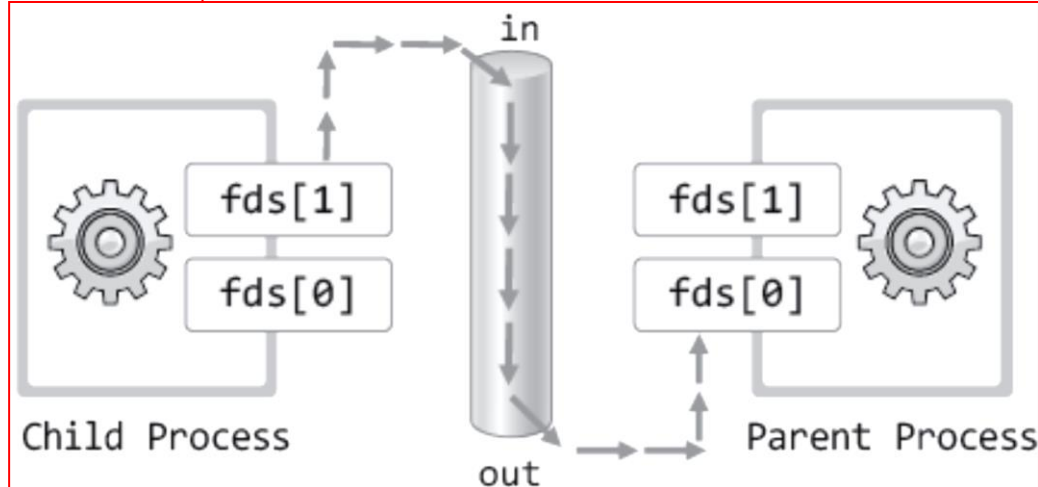
```
        read(fds[0], buf, BUF_SIZE);
```

```
        puts(buf);
```

```
    }
```

```
    return 0;
```

```
}
```



```
root@my_linux:/tcpip# gcc pipe1.c -o pipe1
root@my_linux:/tcpip# ./pipe1
Who are you?
```

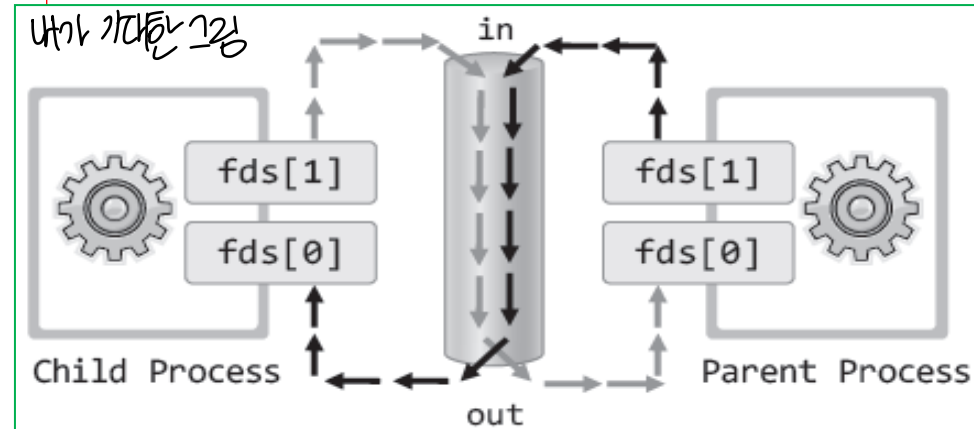
Example #2-pipe2.c (bidirectional)

```
int main(int argc, char *argv[])
{
    int fds[2];
    char str1[]="Who are you?";
    char str2[]="Thank you for your message";
    char buf[BUF_SIZE];
    pid_t pid;

    pipe(fds);
    pid=fork();
    if(pid==0)
    {
        write(fds[1], str1, sizeof(str1));
        sleep(2);
        read(fds[0], buf, BUF_SIZE);
        printf("Child proc output: %s \n", buf);
    }
    else
    {
        read(fds[0], buf, BUF_SIZE);
        printf("Parent proc output: %s \n", buf);
        write(fds[1], str2, sizeof(str2));
        sleep(3);
    }
    return 0;
}
```

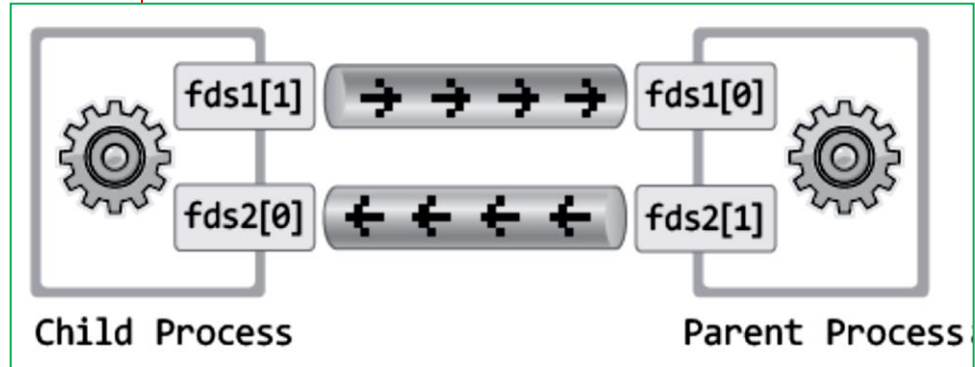
[0]: read
[1]: write

Bad Example!! Why?



Example #3-pipe3.c (bidirectional)-Good!

```
int main(int argc, char *argv[])
{
    int fds1[2], fds2[2];
    char str1[]="Who are you?";
    char str2[]="Thank you for your message";
    char buf[BUF_SIZE];
    pid_t pid;
    pipe(fds1), pipe(fds2);
    pid=fork();
    if(pid==0)
    {
        write(fds1[1], str1, sizeof(str1));
        read(fds2[0], buf, BUF_SIZE);
        printf("Child proc output: %s \n", buf);
    }
    else
    {
        read(fds1[0], buf, BUF_SIZE);
        printf("Parent proc output: %s \n", buf);
        write(fds2[1], str2, sizeof(str2));
        sleep(3);
    }
    return 0;
}
```



```
root@my_linux:/tcpip# gcc pipe3.c -o pipe3
root@my_linux:/tcpip# ./pipe3
Parent proc output: Who are you?
Child proc output: Thank you for your message
```

```

/*echo_store.c*/
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include <signal.h>
#include <sys/wait.h>
#include <arpa/inet.h>
#include <sys/socket.h>

```

```

#define BUFSIZE 100

```

```

void errorHandling(char* msg);
void readChildProc(int sig);

```

```

int main(int argc, char* argv[])
{

```

```

    int servSock, clntSock;
    struct sockaddr_in servAddr, clntAddr;
    int fds[2];

```

```

    pid_t pid;
    struct sigaction act;
    socklen_t addrSz;
    int strLen, state;
    char buf[BUFSIZE];

```

```

    if( argc != 2 )
    {
        printf("usage : %s <port>\n", argv[0]);
        exit(1);
    }

```

```

    act.sa_handler = readChildProc;
    sigemptyset(&act.sa_mask);
    act.sa_flags = 0;
    state = sigaction(SIGCHLD, &act, 0);

```

```

    servSock = socket(PF_INET, SOCK_STREAM, 0);
    memset(&servAddr, 0, sizeof(servAddr));
    servAddr.sin_family = AF_INET;
    servAddr.sin_addr.s_addr = htonl(INADDR_ANY);
    servAddr.sin_port = htons(atoi(argv[1]));

```

```

    if( bind(servSock, (struct sockaddr*)&servAddr, sizeof(servAddr)) == -1 )
        errorHandling("bind() error");

```

```

    if( listen(servSock, 5) == -1 )
        errorHandling("listen() error");

```

Example#4 Echo server storing message (1/2)

/*Server stores all strings sent by client*/

→ ~~1000~~ ~~0100~~ ~~0000~~


```

pipe(fds);
pid = fork();
if( pid == 0 )
{
    FILE *fp = fopen("echomsg.dat", "wt");
    char msgbuf[BUFSIZE];

    int i, len;
    for( i = 0 ; i < 10 ; i++ )
    {
        len = read(fds[0], msgbuf, BUFSIZE);
        fwrite((void*)msgbuf, 1, len, fp);
    }
    fclose(fp);
    return 0;
}

while(1)
{
    addrSz = sizeof(clntAddr);
    clntSock = accept(servSock, (struct sockaddr*)&clntAddr, &addrSz);
    if( clntSock == -1 )
        continue;
    else
        puts("new client connected...");

    pid = fork();

    if( pid == 0 )
    {
        close(servSock);

        while((strLen = read(clntSock, buf, BUFSIZE)) != 0 )
        {
            write(clntSock, buf, strLen);
            write(fds[1], buf, strLen);
        }

        close(clntSock);
        puts("client disconnected...");
        return 0;
    }

    else
        close(clntSock);
}

close(servSock);
return 0;
}

```

Example#4 Echo server storing message (2/2)

```

void errorHandling(char* msg)
{
    fputs(msg, stderr);
    fputc('\n', stderr);
    exit(1);
}

void readChildProc(int sig)
{
    pid_t pid;
    int status;
    pid = waitpid(-1, &status, WNOHANG);
    printf("removed proc id: %d\n", pid);
}

```


Example#4 Echo server-additional explanations

```
pipe(fds);
pid=fork();
if(pid==0)
{
    FILE * fp=fopen("echomsg.txt", "wt");
    char msgbuf[BUF_SIZE];
    int i, len;

    for(i=0; i<10; i++)
    {
        len=read(fds[0], msgbuf, BUF_SIZE);
        fwrite((void*)msgbuf, 1, len, fp);
    }
    fclose(fp);
    return 0;
}
```

*서버에서 처음으로
생성하는 자식프로세스*

파이프를 생성하고 자식 프로세스를 생성해서,
자식 프로세스가 파이프로부터 데이터를 읽어서
저장하도록 구현되어 있다.

accept 함수 호출 후 fork 함수호출을 통해서 파이
프의 디스크립터를 복사하고, 이를 이용해서 이전에
만들어진 자식 프로세스에게 데이터를 전송한다.

```
clnt_sock=accept(serv_sock, (struct sockaddr*)&clnt_adr, &adr_sz);
. . .
pid=fork();
if(pid==0)
{
    close(serv_sock);
    while((str_len=read(clnt_sock, buf, BUF_SIZE))!=0)
    {
        write(clnt_sock, buf, str_len);
        write(fds[1], buf, str_len);
    }

    close(clnt_sock);
    puts("client disconnected...");
    return 0;
}
else
    close(clnt_sock);
```

*서버에서 연결
허용시마다 생성하는
자식프로세스*