

Forecast the future

Measure the present state

$\vec{p}(0), \dots, \vec{p}(N-1)$

$\vec{x}(0)$

Solve the scheduling MILP

$\delta_{HP}(0), \dots, \delta_{HP}(N-1)$

Solve the MINLP by fixing the binary variables with the schedule

$\vec{u}(0), \dots, \vec{u}(N-1)$

Implement inputs for the length of the first MILP time step

$\vec{u}(0), \dots, \vec{u}(S_1)$

System

