#### **Recurrent and Generative Artificial Neural Networks**

<b>Exercise Sheet</b>	02	1. Team Partner:	Lennart Slusny
Task	01	2. Team Partner:	Joschka Strüber

(a) How can LSTMs and other gated memory units learn to count and solve other discrete tasks? What is expected to happen during training?

#### **Answer:**

- time steps of calculations act as natural source of discreteness
- (b) Consider a single LSTM unit with D memory cells. Starting with

$$\delta_{\phi}^{t} = \frac{\partial E}{\partial \operatorname{net}_{\phi}^{t}} \tag{1}$$

derive the forget gate gradient of the LSTM:

 $\delta_{\phi}^{t} = \varphi_{\phi}'(\operatorname{net}_{\phi}^{t}) \sum_{c=1}^{D} \zeta_{c}^{t} s_{t}^{t-1}$ (2)

**Answer:** 

(c) Can bidirectional RNNs be effectively used for online classification, that is generating a classification label for every new input immediately? Explain briefly.

**Answer:** No, that is in general not possible. To make inference, a bidirectional RNN needs both pretemporal and posttemporal context to compute an output. However, in online classification, only the pretemporal context is available. To get the posttemporal context, we would have to get to the end of a timeseries and compute the recurrence back in time, which is impossible in this context.

**Task** 02

(a) Name three forms of commonly applied regularization techniques for neural networks and describe their effects.

**Answer:** 

(b) Explain the internal covariate shift and how it has been addressed in the literature.

**Answer:** 

**(c)** Consider the following statement: The more parameters a neural network has the better it will generalize. Is this statement true?

**Answer:** 

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### **Recurrent and Generative Artificial Neural Networks**

(d) What is the effect of residual blocks on the gradient flow in deep networks?

#### **Answer:**

Task 03

(a) What is the general purpose of autoencoders (AEs) and what are their main components? Give an illustration.

**Answer:** 

(b) Briefly explain the purpose of the KL divergence.

**Answer:** 

(c) Given two discrete probability distributions Q, P. Show that KL(Q||P) = KL(P||Q) does not hold in general.

**Answer:** 

(d) Briefly describe the re-parametrization trick and explain why it is necessary to train a VAE.

**Answer:** 

(e) Name a frequently mentioned drawback of VAEs and give one example from the literature that addresses this issue.

**Answer:** 

**(f)** What are the major differences of the variational autoencoders (VAEs) in comparison with standard autoencoders? Relate your answer to the two sub-losses that are optimized during VAE training.

**Answer:** 

**(g) Bonus:** Show that the KL-divergence between two Gaussian distributions simplifies in the following form, if the reference distribution is the standard normal:

$$KL(N(\mu, \Sigma)||N(\mathbf{0}, \mathbf{I})$$
(3)

Task 03

(a) Illustrate the major structure of GANs and name the essential components. Briefly describe the principle.

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# **Answer:**

**(b)** Elaborate on why the training of GANs is considered as particularly difficult/challenging and how it is addressed. Comment on what happens if the discriminator dominates the generator and vice versa.

#### **Answer:**

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