

Assignment Deep Learning

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Feed Forward Network

$inputs = [1, X_1, X_2, \dots, X_n]$

$weights = [W_0, W_1, W_2, \dots, W_n]$

$Z = X_0W_0 + X_1W_1 + X_2W_2 + \dots + X_nW_n$

Z is summation of product of Input and their Associated weights

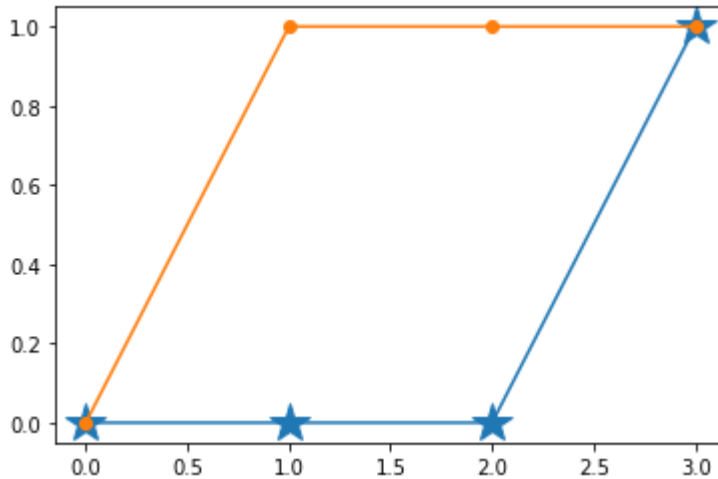
Step Function is used to decide output based on value of Z

```
In [10]: import numpy as np
import matplotlib.pyplot as plt
i_input=np.array([[0,0],[0,1],[1,0],[1,1]]) #input values of AND gate
labels=np.array([0,0,0,1]) #initially labels for each input of i_input set
weights=[0.784,0.897] #associated weights
threshold=0.54 #threshold value
# Defining step function
def step_fun(sum):
    if sum>threshold:
        return 1
    else:
        return 0
#iterating through i_input array to calculate Z
updated_labels=[]
for i in range(0, i_input.shape[0]):
    actual_value=labels[i]
    instances=i_input[i]
    x0=instances[0]
    x1=instances[1]
    z=x0*weights[0]+x1*weights[1] # Z is sum of Product of Inputs and their ass
    fire= step_fun(z)
    updated_labels.append(fire)
    delta=actual_value-fire #delta is Error (When Error is 0 it means predict
    print("Predicted value ", fire, " Whereas Actual Value", labels[i], " Error
```

```
Predicted value 0 Whereas Actual Value 0 Error is 0
Predicted value 1 Whereas Actual Value 0 Error is -1
Predicted value 1 Whereas Actual Value 0 Error is -1
Predicted value 1 Whereas Actual Value 1 Error is 0
```

```
In [2]: plt.plot(labels, marker='*', ms=20)
plt.plot(updated_labels, marker='o')
```

```
Out[2]: [<matplotlib.lines.Line2D at 0x7f72c46b7e48>]
```



SUMMARY

We have a set of input along with actual output. Now this model associates some weights randomly in order to predict the output. We have can track whether our outcome is Correctly predicted or not with the help of Error (delta).

In above graph Orange Circles indicate Actual Value and Blue Stars indicate Predicted Value . We can see that for 3rd input [1,0] Predicted and Actual outcomes vary

This Variation can be solved using Gradient Descent approach by using Learning rate for Weight Updation

Perceptron Training Rule

Learning Problem is to determine Weights that causes perceptron to produce correct output

delta- delta is the difference between Predicted and Actual outputs ¶

We keep on modifying weights whenever it misclassifies an example. Weights are modified at each step iteratively according to perceptron learning rate until it classifies all training examples correctly

$$W_i = W_i + \Delta W$$

$$\Delta W = \eta(t-o)X_i$$

η is positive learning rate. Role of η to moderate degree at which weights are changing

```

In [5]: import numpy as np
import matplotlib.pyplot as plt
i_input=np.array([[0,0],[0,1],[1,0],[1,1]]) #input values of AND gate
y=np.array([0,0,0,1]) #y is target output for each input of i_input set
w=[0.78,0.91] #associated weights
threshold=0.54 #threshold value
iteration=5
eta=0.1 #eta is learning rate

# Defining step function
def step_fun(sum):
    if sum>threshold:
        return 1
    else:
        return 0
print("Initial Weights ", w)

#iterating through i_input array to calculate Z
updated_labels=[]
for j in range(0,iteration):
    print("Iteration ",j)
    print("Actual(y)", " ", "Predicted(y')", " ", "Error")
    for i in range (0, i_input.shape[0]):
        actual_value=y[i]
        instances=i_input[i]
        x0=instances[0]
        x1=instances[1]
        z=x0*w[0]+x1*w[1] # Z is sum of Product of Inputs and their associated
        fire= step_fun(z)
        updated_labels.append(fire)
        delta=actual_value-fire #delta is Error (When Error is 0 it means pre
        print( y[i], " "*12,fire," "*12,delta)
        w[0]=w[0]+delta*eta #Updating Weights
        w[1]=w[1]+delta*eta
    print("_"*35)
print("Updated Weights after Iteration",w) #Updated Weights after learning

```

```

Initial Weights [0.78, 0.91]
Iteration 0
Actual(y)    Predicted(y')    Error
0            0              0
0            1              -1
0            1              -1
1            1              0

```

```

Iteration 1
Actual(y)    Predicted(y')    Error
0            0              0
0            1              -1
0            0              0
1            1              0

```

```

Iteration 2
Actual(y)    Predicted(y')    Error
0            0              0
0            1              -1
0            0              0
1            1              0

```

```

Iteration 3
Actual(y)    Predicted(y')    Error
0            0              0
0            0              0
0            0              0
1            1              0

```

Iteration	4		
Actual(y)	Predicted(y')	Error	
0	0	0	
0	0	0	
0	0	0	
1	1	0	

Updated Weights after Iteration [0.3800000000000001, 0.5100000000000001]

Summary

Initially a random weight was chosen and the Two predicted outputs were misclassified.

After applying Perceptron Training Rule , Weights were Modified till it classified Examples correctly till some iteration

Initially weights was [0.78,0.91] after Updation [0.38, 0.51] and this updated weights predicted output Correctly after few iterations

Gradient Descent

Activation fun $1/(1+e^{-\text{weighted_sum}})$

$\text{weighted_sum} = W_1X_1 + W_2X_2 + \dots W_iX_i + \text{Bias}$

$\text{Loss} = -(\text{target} \log(\text{pred}) + (1 - \text{target}) \log(1 - \text{pred}))$

$W_i = W_i + \Delta W$

$\Delta W = \eta(t - o)X_i$

$\text{New Bias}(b') = \text{Old Bias}(b) + \eta(\text{target} - \text{predicted})$

η is Learning rate which ensures gradual weight update

Bias helps to tune our model .

```
In [ ]: import numpy as np
import matplotlib.pyplot as plt
def Activation_fun(z): #z is weighted sum of input and associated weights
    return 1/(1+np.e**(-z))
def get_prediction(Input,Weights,bias):
    return Activation_fun(np.dot((Input,Weights)+bias))
def Gradient_Descent(Input, Weights, Target, Prediction, eta,bias):
    new_weight=[]
    bias=bias+eta*(Target-Prediction)
    for x,w in zip(Input,Weights):
        new_w=w+eta*(Target-Prediction)*x
        new_weight.append(new_w)
    return new_weight,bias

#DATA
Input=np.array([[0,1,0],[0,1,1],[1,1,0],[1,1,1],[1,0,0]])
Target=np.array([0,1,1,0,1])
Weights=np.array([0.3,0.1,0.5,-0.1,0.45])
bias=0.5
eta=0.01
for i in range(10):
    for x,y in zip(Input, Target):
        pred=get_prediction(x,Weights, bias)
        weights,bias=Gradient_Descent(x,Weights,y,pred,eta,bias)
```

Convolutional Neural network(CNN) ¶

The convolutional layer is the core building block of a CNN, and it is where the majority of computation occurs. It requires a few components, which are input data, a filter, and a feature map. Let's assume that the input will be a color image, which is made up of a matrix of pixels in 3D. This means that the input will have three dimensions—a height, width, and depth—which correspond to RGB in an image. We also have a feature detector, also known as a kernel or a filter, which will move across the receptive fields of the image, checking if the feature is present. This process is known as a convolution.

```
In [1]: import keras
        from keras.datasets import mnist
        from keras.models import Sequential
        from keras.layers import Dense, Dropout, Flatten
        from keras.layers import Conv2D, MaxPooling2D
        from keras import backend as K
        import numpy as np
```

```
In [2]: (x_train, y_train), (x_test, y_test) = mnist.load_data()
```

Downloading data from <https://storage.googleapis.com/tensorflow/tf-keras-datasets/mnist.npz> (<https://storage.googleapis.com/tensorflow/tf-keras-datasets/mnist.npz>)
11490434/11490434 [=====] - 2s 0us/step

```
In [3]: img_rows, img_cols = 28, 28

        if K.image_data_format() == 'channels_first':
            x_train = x_train.reshape(x_train.shape[0], 1, img_rows, img_cols)
            x_test = x_test.reshape(x_test.shape[0], 1, img_rows, img_cols)
            input_shape = (1, img_rows, img_cols)
        else:
            x_train = x_train.reshape(x_train.shape[0], img_rows, img_cols, 1)
            x_test = x_test.reshape(x_test.shape[0], img_rows, img_cols, 1)
            input_shape = (img_rows, img_cols, 1)

        x_train = x_train.astype('float32')
        x_test = x_test.astype('float32')
        x_train /= 255
        x_test /= 255

        y_train = keras.utils.to_categorical(y_train, 10)
        y_test = keras.utils.to_categorical(y_test, 10)
```

```
In [5]: model = Sequential()
        model.add(Conv2D(32, kernel_size = (3, 3),
            activation = 'relu', input_shape = input_shape))
        model.add(Conv2D(64, (3, 3), activation = 'relu'))
        model.add(MaxPooling2D(pool_size = (2, 2)))
        model.add(Dropout(0.25)) , model.add(Flatten())
        model.add(Dense(128, activation = 'relu'))
        model.add(Dropout(0.5))
        model.add(Dense(10, activation = 'softmax'))
```

```
In [6]: model.compile(loss = keras.losses.categorical_crossentropy,  
optimizer = keras.optimizers.Adadelta(), metrics = ['accuracy'])
```

```
In [7]: model.fit(  
x_train, y_train,  
batch_size = 128,  
epochs = 12,  
verbose = 1,  
validation_data = (x_test, y_test)  
)
```

Epoch 1/12

469/469 [=====] - 97s 205ms/step - loss: 2.2782 - accuracy: 0.1654 - val_loss: 2.2462 - val_accuracy: 0.3393

Epoch 2/12

469/469 [=====] - 91s 193ms/step - loss: 2.2283 - accuracy: 0.2842 - val_loss: 2.1860 - val_accuracy: 0.5698

Epoch 3/12

469/469 [=====] - 96s 204ms/step - loss: 2.1653 - accuracy: 0.3792 - val_loss: 2.1047 - val_accuracy: 0.6451

Epoch 4/12

469/469 [=====] - 96s 205ms/step - loss: 2.0771 - accuracy: 0.4524 - val_loss: 1.9928 - val_accuracy: 0.6710

Epoch 5/12

469/469 [=====] - 96s 204ms/step - loss: 1.9633 - accuracy: 0.5031 - val_loss: 1.8476 - val_accuracy: 0.7002

Epoch 6/12

469/469 [=====] - 97s 208ms/step - loss: 1.8186 - accuracy: 0.5452 - val_loss: 1.6696 - val_accuracy: 0.7383

Epoch 7/12

469/469 [=====] - 96s 205ms/step - loss: 1.6567 - accuracy: 0.5794 - val_loss: 1.4714 - val_accuracy: 0.7690

Epoch 8/12

469/469 [=====] - 98s 210ms/step - loss: 1.4867 - accuracy: 0.6086 - val_loss: 1.2771 - val_accuracy: 0.7910

Epoch 9/12

469/469 [=====] - 98s 209ms/step - loss: 1.3380 - accuracy: 0.6332 - val_loss: 1.1076 - val_accuracy: 0.8102

Epoch 10/12

469/469 [=====] - 99s 211ms/step - loss: 1.2136 - accuracy: 0.6551 - val_loss: 0.9707 - val_accuracy: 0.8220

Epoch 11/12

469/469 [=====] - 100s 213ms/step - loss: 1.1104 - accuracy: 0.6790 - val_loss: 0.8624 - val_accuracy: 0.8308

Epoch 12/12

469/469 [=====] - 101s 214ms/step - loss: 1.0256 - accuracy: 0.6982 - val_loss: 0.7784 - val_accuracy: 0.8389

Out[7]: <keras.callbacks.History at 0x21d4ce70c40>

```
In [8]: score = model.evaluate(x_test, y_test, verbose = 0)  
  
print('Test loss:', score[0])  
print('Test accuracy:', score[1])
```

Test loss: 0.7784239053726196

Test accuracy: 0.8389000296592712

```
In [9]: pred = model.predict(x_test)
pred = np.argmax(pred, axis = 1)[:5]
label = np.argmax(y_test,axis = 1)[:5]

print(pred)
print(label)
```

```
313/313 [=====] - 4s 12ms/step
[7 2 1 0 4]
[7 2 1 0 4]
```

```
In [ ]:
```