### **RGB Image Manipulation Using CUDA: Practice**

To process an image in RGB, we just need to apply what we did for a grayscale image but three times, each for an RGB channel: have a matrix (vector) of data for channel R, G and B.

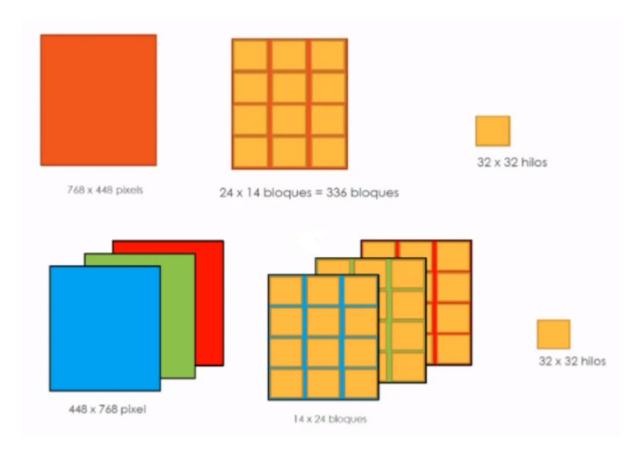


Figure 1: image

#### **Lab 11**

Write a program in c/c++ using CUDA in which you implement a kernel to modify the contrast of an RGB image, and another to modify the brightness, considering the following requirements:

- Blocks of 32 x 32 threads
- The kernel for complement, contrast and brightness should be:

```
- __global__ void complement(uchar* R, uchar* G, uchar* B)
- __global__ void contrast(uchar* R, uchar* G, uchar* B, float fc)
- __global__ void brightness(uchar* R, uchar* G, uchar* B, float fb)
```

• Include error management with a function:

```
- __host__ void checkCUDAError(const char* msg)
```

#### Input



Figure 2: img

#### **Solution**

```
1 #include "cuda_runtime.h"
2 #include "device_launch_parameters.h"
4 #include <stdio.h>
5 #include <stdlib.h>
6 #include <opencv2/opencv.hpp>
8 __host__ void checkCUDAError(const char* msg) {
9
      cudaError_t error;
       cudaDeviceSynchronize();
       error = cudaGetLastError();
       if (error != cudaSuccess) {
12
           printf("ERROR %d: %s (%s)\n", error,
              cudaGetErrorString(error), msg);
14
       }
15 }
17 __global__ void complement(uchar* R, uchar* G, uchar* B) {
      // locate my current block row
int threads_per_block = blockDim.x * blockDim.y;
```

```
20
       int threads_per_row = threads_per_block * gridDim.x;
21
       int row_offset = threads_per_row * blockIdx.y;
       // locate my current block column
24
       int block_offset = blockIdx.x * threads_per_block;
       int threadId_inside = blockDim.x * threadIdx.y + threadIdx
          .x;
26
27
       int gId = row_offset + block_offset + threadId_inside;
28
       R[gId] = 255 - R[gId];
29
       G[gId] = 255 - G[gId];
       B[gId] = 255 - B[gId];
31 }
32
   __global__ void contrast(uchar* R, uchar* G, uchar* B, float
34
       // locate my current block row
       int threads_per_block = blockDim.x * blockDim.y;
       int threads_per_row = threads_per_block * gridDim.x;
37
       int row_offset = threads_per_row * blockIdx.y;
38
       // locate my current block column
       int block_offset = blockIdx.x * threads_per_block;
41
       int threadId_inside = blockDim.x * threadIdx.y + threadIdx
          .х;
42
43
       int gId = row_offset + block_offset + threadId_inside;
44
       if (fc * R[gId] > 255) { R[gId] = 255; } else { R[gId] =
          fc * R[gId]; }
       if (fc * G[gId] > 255) { G[gId] = 255; } else { G[gId] =
45
          fc * G[gId]; }
       if (fc * B[gId] > 255) { B[gId] = 255; } else { B[gId] =
          fc * B[gId]; }
47 }
48
49 __global__ void brightness(uchar* R, uchar* G, uchar* B, float
       fb) {
       // locate my current block row
       int threads_per_block = blockDim.x * blockDim.y;
       int threads_per_row = threads_per_block * gridDim.x;
       int row_offset = threads_per_row * blockIdx.y;
54
       // locate my current block column
56
       int block_offset = blockIdx.x * threads_per_block;
       int threadId_inside = blockDim.x * threadIdx.y + threadIdx
          . X ;
58
59
       int gId = row_offset + block_offset + threadId_inside;
60
       if (fb >= 0){
61
       if (fb + R[gId] > 255) { R[gId] = 255; } else { R[gId] =
         fb + R[gId]; }
```

```
if (fb + G[gId] > 255) { G[gId] = 255; } else { G[gId] =
62
           fb + G[gId]; }
        if (fb + B[gId] > 255) { B[gId] = 255; } else { B[gId] =
           fb + B[gId]; }
        }
        if (fb < 0) {
        if (fb + R[gId] < 0) { R[gId] = 0; } else { R[gId] = fb +
67
           R[gId]; }
68
        if (fb + G[gId] < 0) { G[gId] = 0; } else { G[gId] = fb +
           G[gId]; }
        if (fb + B[gId] < 0) { B[gId] = 0; } else { B[gId] = fb +
           B[gId]; }
        }
71
   }
72
73 using namespace cv;
74
   int main() {
75
        Mat img = imread("antenaRGB.jpg");
78
        const int R = img.rows;
79
        const int C = img.cols;
80
81
        Mat imgComp(img.rows, img.cols, img.type());
82
        Mat imgCont(img.rows, img.cols, img.type());
83
        Mat imgBright(img.rows, img.cols, img.type());
84
        uchar* host_r, * host_g, * host_b, * dev_r1, * dev_g1, *
           dev_b1, * dev_r2, * dev_g2, * dev_b2, * dev_r3, *
           dev_g3, * dev_b3;
        host_r = (uchar*)malloc(sizeof(uchar) * R * C);
85
        host_g = (uchar*)malloc(sizeof(uchar) * R * C);
86
        host_b = (uchar*)malloc(sizeof(uchar) * R * C);
87
88
89
        cudaMalloc((void**)&dev_r1, sizeof(uchar) * R * C);
90
        checkCUDAError("Error at malloc dev_r1");
        cudaMalloc((void**)&dev_g1, sizeof(uchar) * R * C);
92
        checkCUDAError("Error at malloc dev_g1");
        cudaMalloc((void**)&dev_b1, sizeof(uchar) * R * C);
94
        checkCUDAError("Error at malloc dev_b1");
96
        cudaMalloc((void**)&dev_r2, sizeof(uchar) * R * C);
        checkCUDAError("Error at malloc dev_r2");
        cudaMalloc((void**)&dev_g2, sizeof(uchar) * R * C);
98
99
        checkCUDAError("Error at malloc dev_g2");
        cudaMalloc((void**)&dev_b2, sizeof(uchar) * R * C);
100
        checkCUDAError("Error at malloc dev_b2");
102
        cudaMalloc((void**)&dev_r3, sizeof(uchar) * R * C);
        checkCUDAError("Error at malloc dev_r3");
104
        cudaMalloc((void**)&dev_g3, sizeof(uchar) * R * C);
```

```
106
        checkCUDAError("Error at malloc dev_g3");
107
        cudaMalloc((void**)&dev_b3, sizeof(uchar) * R * C);
108
        checkCUDAError("Error at malloc dev_b3");
109
        // matrix as vector
        for (int i = 0; i < R; i++) {
            for (int j = 0; j < C; j++) {
112
                Vec3b pix = img.at < Vec3b > (i, j);
114
                host_r[i * C + j] = pix[2];
                host_g[i * C + j] = pix[1];
                host_b[i * C + j] = pix[0];
117
            }
118
        }
119
        cudaMemcpy(dev_r1, host_r, sizeof(uchar) * R * C,
           cudaMemcpyHostToDevice);
        checkCUDAError("Error at memcpy host_r -> dev_r1");
        cudaMemcpy(dev_g1, host_g, sizeof(uchar) * R * C,
121
           cudaMemcpyHostToDevice);
        checkCUDAError("Error at memcpy host_r -> dev_g1");
        cudaMemcpy(dev_b1, host_b, sizeof(uchar) * R * C,
           cudaMemcpyHostToDevice);
124
        checkCUDAError("Error at memcpy host_r -> dev_b1");
        cudaMemcpy(dev_r2, host_r, sizeof(uchar) * R * C,
           cudaMemcpyHostToDevice);
127
        checkCUDAError("Error at memcpy host_r -> dev_r2");
        cudaMemcpy(dev_g2, host_g, sizeof(uchar) * R * C,
128
           cudaMemcpyHostToDevice);
        checkCUDAError("Error at memcpy host_r -> dev_g2");
        cudaMemcpy(dev_b2, host_b, sizeof(uchar) * R * C,
           cudaMemcpyHostToDevice);
        checkCUDAError("Error at memcpy host_r -> dev_b2");
        cudaMemcpy(dev_r3, host_r, sizeof(uchar) * R * C,
           cudaMemcpyHostToDevice);
        checkCUDAError("Error at memcpy host_r -> dev_r3");
        cudaMemcpy(dev_g3, host_g, sizeof(uchar) * R * C,
           cudaMemcpyHostToDevice);
        checkCUDAError("Error at memcpy host_r -> dev_g3");
        cudaMemcpy(dev_b3, host_b, sizeof(uchar) * R * C,
           cudaMemcpyHostToDevice);
138
        checkCUDAError("Error at memcpy host_r -> dev_b3");
139
140
        dim3 block(32, 32);
141
        dim3 grid(C / 32, R / 32);
142
        complement << < grid, block >> > (dev_r1, dev_g1, dev_b1);
144
        cudaDeviceSynchronize();
145
        checkCUDAError("Error at kernel complement");
```

```
cudaMemcpy(host_r, dev_r1, sizeof(uchar) * R * C,
147
            cudaMemcpyDeviceToHost);
        checkCUDAError("Error at memcpy host_r <- dev_r1");</pre>
148
149
         cudaMemcpy(host_g, dev_g1, sizeof(uchar) * R * C,
            cudaMemcpyDeviceToHost);
        checkCUDAError("Error at memcpy host_r <- dev_g1");</pre>
        cudaMemcpy(host_b, dev_b1, sizeof(uchar) * R * C,
            cudaMemcpyDeviceToHost);
        checkCUDAError("Error at memcpy host_r <- dev_b1");</pre>
152
        for (int i = 0; i < R; i++) {
154
             for (int j = 0; j < C; j++) {
156
                 imgComp.at < Vec3b > (i, j)[0] = host_b[i * C + j];
157
                 imgComp.at < Vec3b > (i, j)[1] = host_g[i * C + j];
158
                 imgComp.at < Vec3b > (i, j)[2] = host_r[i * C + j];
159
             }
        }
162
        contrast << < grid, block >> > (dev_r2, dev_g2, dev_b2,
           0.5);
        cudaDeviceSynchronize();
         checkCUDAError("Error at kernel contrast");
166
        cudaMemcpy(host_r, dev_r2, sizeof(uchar) * R * C,
            cudaMemcpyDeviceToHost);
        checkCUDAError("Error at memcpy host_r <- dev_r2");</pre>
         cudaMemcpy(host_g, dev_g2, sizeof(uchar) * R * C,
168
            cudaMemcpyDeviceToHost);
        checkCUDAError("Error at memcpy host_r <- dev_g2");</pre>
        cudaMemcpy(host_b, dev_b2, sizeof(uchar) * R * C,
            cudaMemcpyDeviceToHost);
        checkCUDAError("Error at memcpy host_r <- dev_b2");</pre>
        for (int i = 0; i < R; i++) {
174
             for (int j = 0; j < C; j++) {
                 imgCont.at < Vec3b > (i, j)[0] = host_b[i * C + j];
                 imgCont.at < Vec3b > (i, j)[1] = host_g[i * C + j];
176
                 imgCont.at < Vec3b > (i, j)[2] = host_r[i * C + j];
178
             }
179
        }
181
        brightness << < grid, block >> > (dev_r3, dev_g3, dev_b3,
            100);
182
        cudaDeviceSynchronize();
183
        checkCUDAError("Error at kernel brightness");
184
185
        cudaMemcpy(host_r, dev_r3, sizeof(uchar) * R * C,
            cudaMemcpyDeviceToHost);
186
        checkCUDAError("Error at memcpy host_r <- dev_r3");</pre>
        cudaMemcpy(host_g, dev_g3, sizeof(uchar) * R * C,
187
            cudaMemcpyDeviceToHost);
```

```
188
        checkCUDAError("Error at memcpy host_r <- dev_g3");</pre>
189
        cudaMemcpy(host_b, dev_b3, sizeof(uchar) * R * C,
            cudaMemcpyDeviceToHost);
190
        checkCUDAError("Error at memcpy host_r <- dev_b3");</pre>
        for (int i = 0; i < R; i++) {
             for (int j = 0; j < C; j++) {
                 imgBright.at < Vec3b > (i, j)[0] = host_b[i * C + j];
                 imgBright.at < Vec3b > (i, j)[1] = host_g[i * C + j];
196
                 imgBright.at < Vec3b > (i, j)[2] = host_r[i * C + j];
             }
        }
198
199
200
        imshow("Image", img);
        imshow("Image Complement", imgComp);
        imshow("Image Contrast", imgCont);
203
        imshow("Image Brightness", imgBright);
204
        waitKey(0);
205
206
        free(host_r);
        free(host_g);
207
208
        free(host_b);
209
        cudaFree(dev_r1);
210
        cudaFree(dev_g1);
        cudaFree(dev_b1);
212
        cudaFree(dev_r2);
        cudaFree(dev_g2);
213
214
        cudaFree(dev_b2);
215
        cudaFree(dev_r3);
216
        cudaFree(dev_g3);
217
        cudaFree(dev_b3);
218
219
        return 0;
220 }
```

# Output

## Complement



Figure 3: img

### Contrast



Figure 4: img

## Brightness



Figure 5: img