Practice

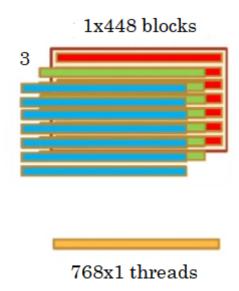


Figure 1: img

Lab 13

Write a program in c/c++ using CUDA in which you implement a kernel to calculate an RGB image complement. The kernel must be verified, consider the requirements:

• The complement of an image is defined as:

```
I(x,y) = 255 - I(x,y)
```

- \bullet Blocks of 768 x 1 threads.
- A grid of 1 x 448 x 3 blocks.
- The kernel signature should be: __global__ void complement(uchar* RGB)
- The CPU complement function signature should be: __host__ void complementCPU (Mat* original, Mat* comp)
- The kernel validation signature should be: __host__ bool validationKernel(Mat img1, Mat img2)

Solution

```
1 #include "cuda_runtime.h"
2 #include "device_launch_parameters.h"
3
4 #include <stdio.h>
```

```
5 #include <stdlib.h>
 6 #include <opencv2/opencv.hpp>
 7
 8 using namespace cv;
 9
10 __host__ void checkCUDAError(const char* msg) {
        cudaError_t error;
12
        cudaDeviceSynchronize();
        error = cudaGetLastError();
14
        if (error != cudaSuccess) {
            printf("ERROR %d: %s (%s)\n", error,
                cudaGetErrorString(error), msg);
        }
17
   }
18
19 __global__ void complement(uchar* RGB) {
21
        // locate my current block row
22
        int threads_per_block = blockDim.x;
23
        int threads_per_row = threads_per_block * gridDim.x;
24
        int row_offset = threads_per_row * blockIdx.y;
25
26
        // locate my current block column
27
        int block_offset = blockIdx.x * threads_per_block;
28
29
        // locate my current grid row
        int thread_per_grid = (gridDim.x * gridDim.y *
           threads_per_block);
        int gridOffset = blockIdx.z * thread_per_grid;
32
        int gId = gridOffset + row_offset + block_offset +
           threadIdx.x;
        RGB[gId] = 255 - RGB[gId];
34
35 }
37
    __host__ void complementCPU(Mat* original, Mat* comp) {
        for (int i = 0; i < original->rows; i++) {
38
            for (int j = 0; j < original -> cols; <math>j++) {
                 comp \rightarrow at < Vec3b > (i, j)[0] = 255 - original \rightarrow at <
40
                    Vec3b>(i, j)[0];
                 comp \rightarrow at < Vec3b > (i, j)[1] = 255 - original \rightarrow at <
41
                    Vec3b>(i, j)[1];
42
                 comp \rightarrow at < Vec3b > (i, j)[2] = 255 - original \rightarrow at <
                    Vec3b>(i, j)[2];
            }
        }
44
45 }
47 __host__ bool validationKernel(Mat img1, Mat img2) {
       Vec3b* pImg1, * pImg2;
     for (int k = 0; k < 3; k++) {
```

```
for (int i = 0; i < img1.rows; i++) {
                pImg1 = img1.ptr<Vec3b>(i);
                pImg2 = img2.ptr<Vec3b>(i);
                for (int j = 0; j < img1.cols; <math>j++) {
54
                    if (pImg1[j][k] != pImg2[j][k]) {
                        printf("Error at kernel validation\n");
56
                        return true;
57
                    }
58
                }
           }
60
       }
61
       printf("Kernel validation successful\n");
62
       return false;
63
   }
64
65
   int main() {
67
       Mat img = imread("antenaRGB.jpg");
68
69
       const int R = img.rows;
       const int C = img.cols;
72
       Mat imgComp(img.rows, img.cols, img.type());
73
       Mat imgCompCPU(img.rows, img.cols, img.type());
74
       uchar* host_rgb, * dev_rgb;
       host_rgb = (uchar*)malloc(sizeof(uchar) * R * C * 3);
       cudaMalloc((void**)&dev_rgb, sizeof(uchar) * R * C * 3);
78
       checkCUDAError("Error at malloc dev_r1");
79
80
       // matrix as vector
81
       for (int k = 0; k < 3; k++) {
           for (int i = 0; i < R; i++) {
82
83
                for (int j = 0; j < C; j++) {
84
                    Vec3b pix = img.at < Vec3b > (i, j);
85
86
                    host_rgb[i * C + j + (k * R * C)] = pix[k];
87
88
                }
89
           }
90
       cudaMemcpy(dev_rgb, host_rgb, sizeof(uchar) * R * C * 3,
           cudaMemcpyHostToDevice);
       checkCUDAError("Error at memcpy host_rgb -> dev_rgb");
       //dim3 block(32, 32);
94
       //dim3 grid(C / 32, R / 32, 3); // 24 14
       dim3 block(C, 1, 1); // 768
96
       dim3 grid(1, R, 3); // 448
98
       complement << < grid, block >> > (dev_rgb);
```

```
100
        cudaDeviceSynchronize();
        checkCUDAError("Error at kernel complement");
        cudaMemcpy(host_rgb, dev_rgb, sizeof(uchar) * R * C * 3,
           cudaMemcpyDeviceToHost);
104
        checkCUDAError("Error at memcpy host_rgb <- dev_rgb");</pre>
        for (int k = 0; k < 3; k++) {
106
            for (int i = 0; i < R; i++) {
                 for (int j = 0; j < C; j++) {
108
109
                     imgComp.at < Vec3b > (i, j)[k] = host_rgb[i * C +
                        j + (k * R * C)];
                }
111
            }
112
        }
113
114
        complementCPU(&img, &imgCompCPU);
        bool error = validationKernel(imgCompCPU, imgComp);
117
        if (error) {
118
            printf("Check kernel operations\n");
119
            return 0;
        }
121
        imshow("Image", img);
124
        imshow("Image Complement CPU", imgCompCPU);
        imshow("Image Complement GPU", imgComp);
126
        waitKey(0);
127
128
        free(host_rgb);
129
        cudaFree(dev_rgb);
        return 0;
132 }
```

Input



Figure 2: img

Output



Figure 3: img



Figure 4: img