## The Kernel

It is a method executed in the GPU as a mass execution. As seen before, CUDA architecure's Processing flow is done switching between CPU and GPU. The kernel is a function you execute on the Device.

Specifier (Identifier)	Called From	Executed In	Syntax	Description
host	Host	Host	float float name()	CPU functions that are normally used in a program. You can skip the identifier, but it's good pratice.
global	Host	Device	global void name()	This identifier is for the kernel.  Executed in the GPU, in parallel.
device	Device	Device	device float name()	This is executed in the device, but it's not exactly a kernel (parallel), because it could or not be something in parallel.

- If there is no specifier before a function, it is simply taken as a normal function in CPU processing. In this way, \_\_host\_\_ is just a simple CPU function as well.
- \_\_device\_\_ functions are defined throughout your code and then a kernel function calls it. Could be or not a parallel process function, it is just a method the kernel might need to be done.
- A **kernel** return value type is always void. If you want to return something, you do it by a reference pass using the kernel parameters.

- The specifier \_\_global\_\_ creates a kernel.
- To call a kernel is to execute code in the GPU.
- **Synchronization**: when you want to wait for an action in parallel in order to begin another sequentially or viceversa.

### **The Kernel Syntax**

The kernel call is done in the CPU, the execution is in GPU.

```
1 __global__ void myKernel(arg_1, arg_2, ..., arg_n) {
2    // code to be executed in the GPU
3 }
4    
5  // from CPU you call the kernel
6 myKernel <<<blocks, threads>>>(arg_1, arg_2, ..., arg_n);
```

### **Launching a Kernel**

Basic Sequence:

- 1. Reserve memory in the host: this memory will be used for storing the info that will be processed in parallel.
- 2. Initialize the data from the host: this reserved memory is initialized with the said info to process in the GPU.
- 3. Data transfer from host to device: all this memory is in the host, and in order to process it in the device, we need to copy it to the device.
- 4. Launch the kernel specifying the number of blocks and threads: give the order of the execution of the function in the GPU, taking the transferred data to be processed.
- 5. Result data transfer from device to host: from the device memory, we copy the info back to the host so that it can be analized.
- 6. Free memory (device and host) from the host.

#### **Exercise 1**

- A function that adds two integer numbers in the host (a simple add function).
- A function that adds two integer numbers in the device through the launch of a kernel.

```
1 #include "cuda_runtime.h"
2 #include "device_launch_parameters.h"
4 #include <stdio.h>
5 #include <stdlib.h>
6
   __host__ int addCPU(int* num1, int* num2) {
8
       return(*num1 + *num2);
9 }
11 // kernel: __global__
12 __global__ void addGPU(int* num1, int* num2, int* res)
13 {
14
       *res = *num1 + *num2;
15 }
17 int main()
18
  {
19
       // reserve mem in host
       int* host_num1 = (int*)malloc(sizeof(int)); // could be a
          simple integer and then you pass as param the &variable
21
       int* host_num2 = (int*)malloc(sizeof(int));
22
       int* host_resCPU = (int*)malloc(sizeof(int));
       int* host_resGPU = (int*)malloc(sizeof(int));
24
25
       // reserve mem in dev
26
       int* dev_num1, * dev_num2, * dev_res;
       cudaMalloc((void**)&dev_num1, sizeof(int)); // &3 error //
27
           &intvar no error but you need pointers with malloc in
          cuda
28
       cudaMalloc((void**)&dev_num2, sizeof(int));
29
       cudaMalloc((void**)&dev_res, sizeof(int)); // this pointer
           points to an address in the device
30
       // init data
32
       *host_num1 = 2;
       *host_num2 = 3;
34
       *host_resCPU = 0;
       *host_resGPU = 0;
36
       // data transfer
38
       cudaMemcpy(dev_num1, host_num1, sizeof(int),
          cudaMemcpyHostToDevice);
       cudaMemcpy(dev_num2, host_num2, sizeof(int),
39
          cudaMemcpyHostToDevice);
40
41
       // CPU call to CPU func
42
       *host_resCPU = addCPU(host_num1, host_num2);
43
       printf("CPU result \n");
       printf("%d + %d = %d \n", *host_num1, *host_num2, *
44
```

```
host_resCPU);
45
       // CPU call to GPU func
47
       addGPU <<< 1, 1 >>> (dev_num1, dev_num2, dev_res);
48
       // dev_res is a pointer made with cudaMalloc (Global
          Memory)
       cudaMemcpy(host_resGPU, dev_res, sizeof(int),
           cudaMemcpyDeviceToHost);
       printf("GPU result \n");
       // dev_num1 is án address in GPU, you cannot access it
           from CPU
52
       printf("d + d = d \setminus n", *host_num1, *host_num2, *
          host_resGPU);
54
       // free memory
       free(host_num1);
56
       free(host_num2);
       free(host_resCPU);
       free(host_resGPU);
58
       cudaFree(dev_num1);
60
61
       cudaFree(dev_num2);
62
       cudaFree(dev_res);
64
       return 0;
   }
```

At the line int\* host\_num1 = (int\*)malloc(sizeof(int));, Visual Studio makes a suggestion, which is the same I put in the comment on that line.

### **Output Example 01**

My machine produces the following output.

```
Microsoft Visual Studio Debug Console

CPU result
2 + 3 = 5
GPU result
2 + 3 = 5

C:\Users\mariana\Documents\github-mariana\parallel-computing-cuda\08162021\ex01\x64\Debug\ex01.exe (process 7512) exited with code 0.
To automatically close the console when debugging stops, enable Tools→Options→Debugging→Automatically close the conso le when debugging stops.

Press any key to close this window . . .

✓
```

# **Code Alternatives**

```
1 __global__ void addGPU(int num1, int num2, int* res)
2 {
3     *res = num1 + num2;
4 }
5 int main(){
6     addGPU <<< 1, 1 >>> (2, 3, dev_res);
7 }
```