Types of Schedulers

Thursday, May 19, 2022 6:57 AM

We saw communication $\infty - \infty$, ∞ many times, which is done using Condition variable.
Implementations of this are in two examples:
1) Clock (alarm that wakes up threads)
2) Ping Pong (two threads + main thread)
"ball" < [o←] : receives communication
[→o] : sends communication

x variable is the condition to check for sleep and wait or continue

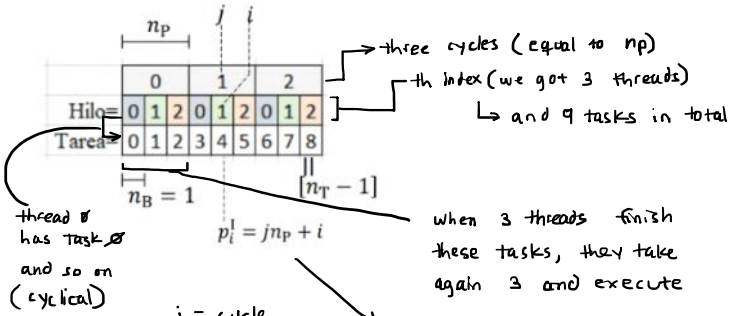
each thread has one unique lock object → they share the mutex anyway
- x = 0 : the thread has no ball → wait for ball
  - enters waiting and frees mutex
  - so that other thread checks x
  - answer : puts back x = 0 after waiting loop
- x = 1 : the other thread waits
  - answer : puts back x = 1 after waiting loop

→ This was an example where threads communicate between each other, many times along time.
→ These are useful when you need threads to wait for other threads to compute something

When we use parallelism, we use the Foster Method:
1) Partitioning
2) Communication
3) Union
4) Mapping (Load Balance) ↓ we need scheduler

A scheduler
↳ they work well when $n_{tasks} < n_{proc}$ (otherwise, a processor has many tasks (sequence))
→ Its function is to manage the unbalance of load (when processors differ in load and threads finish first)
→ Types
1) static: When we know all tasks have the same size → the tasks are assigned $T_i = P_j$ at the beginning of execution. This is never reassigned.
2) Dynamic: When all tasks have a different size (maybe unknown)

Static: 3 ways of scheduling
1) Cyclical Distribution (One extreme)



→ three cycles (equal to np)

→ th index (we got 3 threads)

↳ and 9 tasks in total

thread 0 has task 0 and so on (cyclical)

when 3 threads finish these tasks, they take again 3 and execute

j = cycle

i = thread

the position of a Task

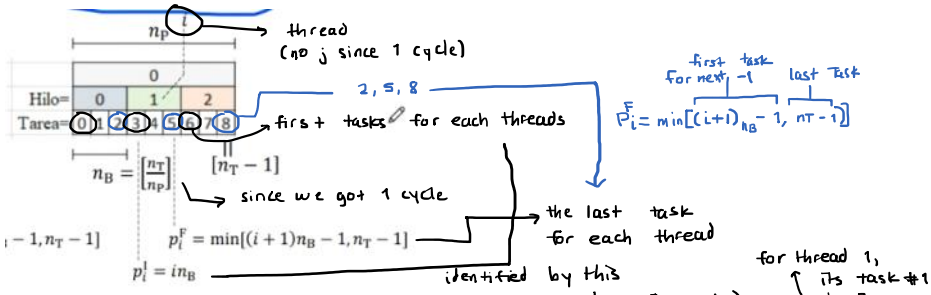
$p_i = j(np) + i$

$p_i = 4$ (id of task)

n_B = num of block

num of Tasks in a processor per cycle

3) Distribution by Block



thread (no j since 1 cycle)

2, 5, 8 → first + tasks for each threads

first task for next -1 | last Task

$P_i^F = \min[(i+1)_{nB} - 1, nT - 1]$

since we got 1 cycle

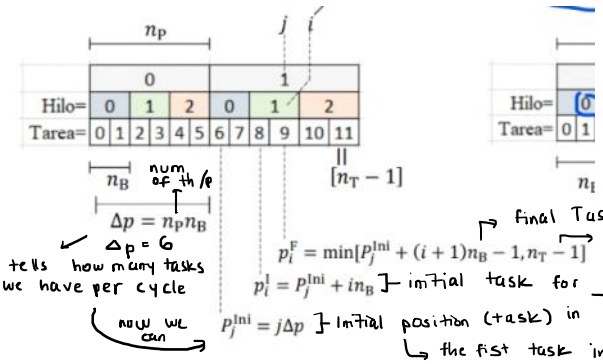
the last task for each thread identified by this

↳ $p_1^F = 1(3) = 3$ → for thread 1, its task #1 is 3

→ Here we assume 1 cycle

↳ the bigger the amount of cycles, the smaller n_B

2) Cyclical Distribution by Blocks: Intermediate case



Hilo= 0

Tarea= 0 1

n_t

Δp tells how many tasks we have per cycle

now we can

final Task for ith thread

this term takes care of the case where n_{Tasks} is not perfectly divisible by n_B

initial task for ith thread

initial position (task) in jth cycle

↳ the fist task in

→ we have cycles back: say two cycles

↳ threads appear twice

→ Here we assign more tasks in a thread per cycle

$n_B = 2$ ↳ 2 in this case

a block is more than one task per thread

→ One cycle: becomes type 3)

Many cycles: becomes type 1)] 2) can become this (✓)

→ n_B Calculation:

7 tasks

9 threads

$n_B = \frac{7}{3} = \lceil 2.\overline{3} \rceil = 3$

$= \lceil 2.1 \rceil = 3$

$n_B = \left\lceil \frac{nT}{np} \right\rceil$

If we assume that task indices are how RAM is organized:

↳ the bigger the cycle, the less false sharing

3) avoids false sharing (faster)

1) May not take care of false sharing (slower)

→ when tasks tends to increase size (or not)

n_B: the bigger n_B, the better behaviour in cache ↳ since false sharing appears

n_B : the bigger n_B, the better behaviour in cache appears
but the worse load Balance (big differences when a thread has diff amount of Tasks)
↳ try to have small n_B (for a good load Balance)
↳ but not too small

2) Dynamic distribution: when the number of sizes in Tasks is different (or unknown)
↳ or the pattern is very complex
↳ we use basically a queue
↳ when a processor finishes, we take the top of the queue and give the task to this processor