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## Telecommunication Systems I

Report of the first project

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Th.1

$$\phi(t) = \begin{cases} \frac{1}{\sqrt{T}}, & \text{if } |t| \leq \frac{T}{2} \\ 0, & \text{else.} \end{cases}$$

1. For:

$$t + \frac{T}{2} < -\frac{T}{2} \Rightarrow t < -T$$

Then the convolution is equal to zero:

$$R\phi\phi(t) = 0$$

2. For:

$$-\frac{T}{2} \leq t + \frac{T}{2} \leq \frac{T}{2} \Rightarrow -T \leq t \leq 0$$

$$R\phi\phi(t) = \int_{-\frac{T}{2}}^{t+\frac{T}{2}} \phi(\tau) \cdot \phi(\tau+t) d\tau = \int_{-\frac{T}{2}}^{t+\frac{T}{2}} \frac{1}{\sqrt{T}} \cdot \frac{1}{\sqrt{T}} d\tau = \frac{1}{T} \cdot (t+T) = \boxed{\frac{t}{T} + 1}$$

3. For:

$$-\frac{T}{2} \leq t - \frac{T}{2} \leq \frac{T}{2} \Rightarrow 0 \leq t \leq T$$

$$R\phi\phi(t) = \int_{t-\frac{T}{2}}^{\frac{T}{2}} \phi(\tau) \cdot \phi(\tau+t) d\tau = \frac{1}{T} \cdot (-t+T) = \boxed{1 - \frac{t}{T}}$$

4. For:

$$t - \frac{T}{2} > \frac{T}{2} \Rightarrow t > T$$

The convolution is equal to zero:

$$R\phi\phi(t) = 0$$

$$R\phi\phi(t) = \begin{cases} 1 + \frac{t}{T}, & -T \leq t \leq 0 \\ 1 - \frac{t}{T}, & 0 \leq t \leq T \\ 0, & \text{else.} \end{cases}$$


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Th.2

$$\phi(t - 10) = \begin{cases} \frac{1}{\sqrt{T}}, & \text{if } -\frac{T}{2} + 10 \leq t \leq \frac{T}{2} + 10 \\ 0, & \text{else.} \end{cases}$$

1.

$$t + \frac{T}{2} + 10 < -\frac{T}{2} + 10 \Rightarrow t < -T$$

Then the convolution is equal to zero:

$$R\phi\phi(t) = 0$$

2.

$$-\frac{T}{2} + 10 \leq t + \frac{T}{2} + 10 \leq \frac{T}{2} + 10 \Rightarrow -T \leq t \leq 0$$

$$R\phi\phi(t) = \int_{-\frac{T}{2}+10}^{t+\frac{T}{2}+10} \phi(\tau) \cdot \phi(\tau + t) d\tau = \frac{1}{T} \cdot (t + T) = \boxed{\frac{t}{T} + 1}$$

3.

$$-\frac{T}{2} + 10 \leq t - \frac{T}{2} + 10 \leq \frac{T}{2} + 10 \Rightarrow 0 \leq t \leq T$$

$$R\phi\phi(t) = \int_{t-\frac{T}{2}+10}^{\frac{T}{2}+10} \phi(\tau) \cdot \phi(\tau + t) d\tau = \frac{1}{T} \cdot (-t + T) = \boxed{1 - \frac{t}{T}}$$

4.

$$t - \frac{T}{2} + 10 > \frac{T}{2} + 10 \Rightarrow t > T$$

The convolution is equal to zero:

$$R\phi\phi(t) = 0$$

$$R\phi\phi(t-10) = \begin{cases} 1 + \frac{t}{T}, & -T \leq t \leq 0 \\ 1 - \frac{t}{T}, & 0 \leq t \leq T \\ 0, & \text{else.} \end{cases}$$


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Th.3

$$\phi(t) = \begin{cases} \frac{1}{\sqrt{T}}, & \text{if } 0 \leq t < \frac{T}{2}, \\ -\frac{1}{\sqrt{T}}, & \text{if } \frac{T}{2} \leq t \leq T, \\ 0, & \text{else.} \end{cases}$$

1.

$$T + t < 0 \Rightarrow t < -T$$

The convolution is equal to zero:

$$R\phi\phi(t) = 0$$

2.

$$t < T$$

The convolution is equal to zero:

$$R\phi\phi(t) = 0$$

3.

$$0 \leq T + t \leq \frac{T}{2} \Rightarrow -T \leq t \leq -\frac{T}{2}$$

$$R\phi\phi(t) = \int_0^{T+t} \phi(\tau) \cdot \phi(\tau+t) d\tau = \int_0^{T+t} \frac{1}{\sqrt{T}} \cdot -\frac{1}{\sqrt{T}} d\tau = -\frac{1}{T}(T+t) = \boxed{-1 - \frac{t}{T}}$$

4.

$$\frac{T}{2} \leq T + t \leq T \Rightarrow -\frac{T}{2} \leq t \leq 0$$

$$R\phi\phi(t) = \int_0^{T+t} \phi(\tau) \cdot \phi(\tau+t) d\tau$$

$$\begin{aligned}
&= \int_0^{\frac{T}{2}+t} \phi(\tau) \cdot \phi(\tau+t) d\tau + \int_{\frac{T}{2}+t}^{\frac{T}{2}} \phi(\tau) \cdot \phi(\tau+t) d\tau + \int_{\frac{T}{2}}^{T+t} \phi(\tau) \cdot \phi(\tau+t) d\tau \\
&= \int_0^{\frac{T}{2}+t} \frac{1}{\sqrt{T}} \cdot \frac{1}{\sqrt{T}} d\tau + \int_{\frac{T}{2}+t}^{\frac{T}{2}} -\frac{1}{\sqrt{T}} \cdot \frac{1}{\sqrt{T}} d\tau + \int_{\frac{T}{2}}^{T+t} -\frac{1}{\sqrt{T}} \cdot -(\frac{1}{\sqrt{T}}) d\tau \\
&= \frac{1}{T} \cdot (\frac{T}{2} + t) + \frac{t}{T} + \frac{1}{T} \cdot (\frac{T}{2} + t) \\
&= \frac{1}{T} \cdot (T + 3t) = \boxed{1 + \frac{3t}{T}}
\end{aligned}$$

5.

$$\begin{aligned}
&0 \leq t \leq \frac{T}{2} \\
R\phi\phi(t) &= \int_t^{\frac{T}{2}} \phi(\tau) \cdot \phi(\tau+t) d\tau + \int_{\frac{T}{2}}^{\frac{T}{2}+t} \phi(\tau) \cdot \phi(\tau+t) d\tau + \int_{\frac{T}{2}+t}^T \phi(\tau) \cdot \phi(\tau+t) d\tau \\
&= \int_t^{\frac{T}{2}} \frac{1}{\sqrt{T}} \cdot \frac{1}{\sqrt{T}} d\tau + \int_{\frac{T}{2}}^{\frac{T}{2}+t} -\frac{1}{\sqrt{T}} \cdot \frac{1}{\sqrt{T}} d\tau + \int_{\frac{T}{2}+t}^T -\frac{1}{\sqrt{T}} \cdot -(\frac{1}{\sqrt{T}}) d\tau \\
&= \frac{1}{T} \cdot (\frac{T}{2} - t) - \frac{t}{T} + \frac{1}{T} \cdot (\frac{T}{2} - t) \\
&= \frac{1}{T} \cdot (T - 3t) = \boxed{1 - \frac{3t}{T}}
\end{aligned}$$

6.

$$\begin{aligned}
&\frac{T}{2} \leq t \leq T \\
R\phi\phi(t) &= \int_t^T \phi(\tau) \cdot \phi(\tau+t) d\tau = \int_t^T -\frac{1}{\sqrt{T}} \cdot \frac{1}{\sqrt{T}} d\tau = -\frac{1}{T}(T - t) = \boxed{-1 + \frac{t}{T}} \\
R\phi\phi(t) &= \begin{cases} -1 - \frac{t}{T}, & -T \leq t < -\frac{T}{2}, \\ 1 + \frac{3t}{T}, & -\frac{T}{2} \leq t < 0, \\ 1 - \frac{3t}{T}, & 0 \leq t < \frac{T}{2}, \\ -1 + \frac{t}{T}, & \frac{T}{2} \leq t < T, \\ 0, & \text{else.} \end{cases}
\end{aligned}$$

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By observing each  $\phi$  function convoluted with its mirrored self, we can conclude that the more overlapped area they share with each other the higher the value of the self-similarity function  $R\phi\phi$  with a maximum value of 1.

Transposing  $\phi$ , and then finding its  $R\phi\phi$  results in the same output function.

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A.1 By increasing the roll-off value ( $a$ ), the further away the signal travels from its center, the more the amplitude is attenuated. Also, the higher the roll-off value the larger the maximum amplitude at the center of the pulse.

A.2 Plotting all 3 of them on the same plot was simple enough with the use of a 2D Matrix "phi", and a simple for loop:

```
for i=1:3
    PHI_f(i,:) = fftshift(fft(phi(i,:),N));
    PHI_F(i,:) = PHI_f(i,:).*Ts;
    plot(f_axis,(abs(PHI_F)).^2);
hold on;
end
```

A.3 a. For each roll-off value, the theoretical Bandwidth ( $= \frac{1+a}{2T}$ ) is:

- i.  $BW = 500$ , for  $\phi$  with  $a = 0$
- ii.  $BW = 750$ , for  $\phi$  with  $a = 0.5$
- iii.  $BW = 1000$ , for  $\phi$  with  $a = 1.0$

b. The most efficient pulse is the one with the shortest Bandwidth, in this case the pulse with the roll-off value of 0. It is worth noting that we define the cut-off point of each pulse.

For cut-off at  $c_1 = \frac{T}{10^{-3}}$

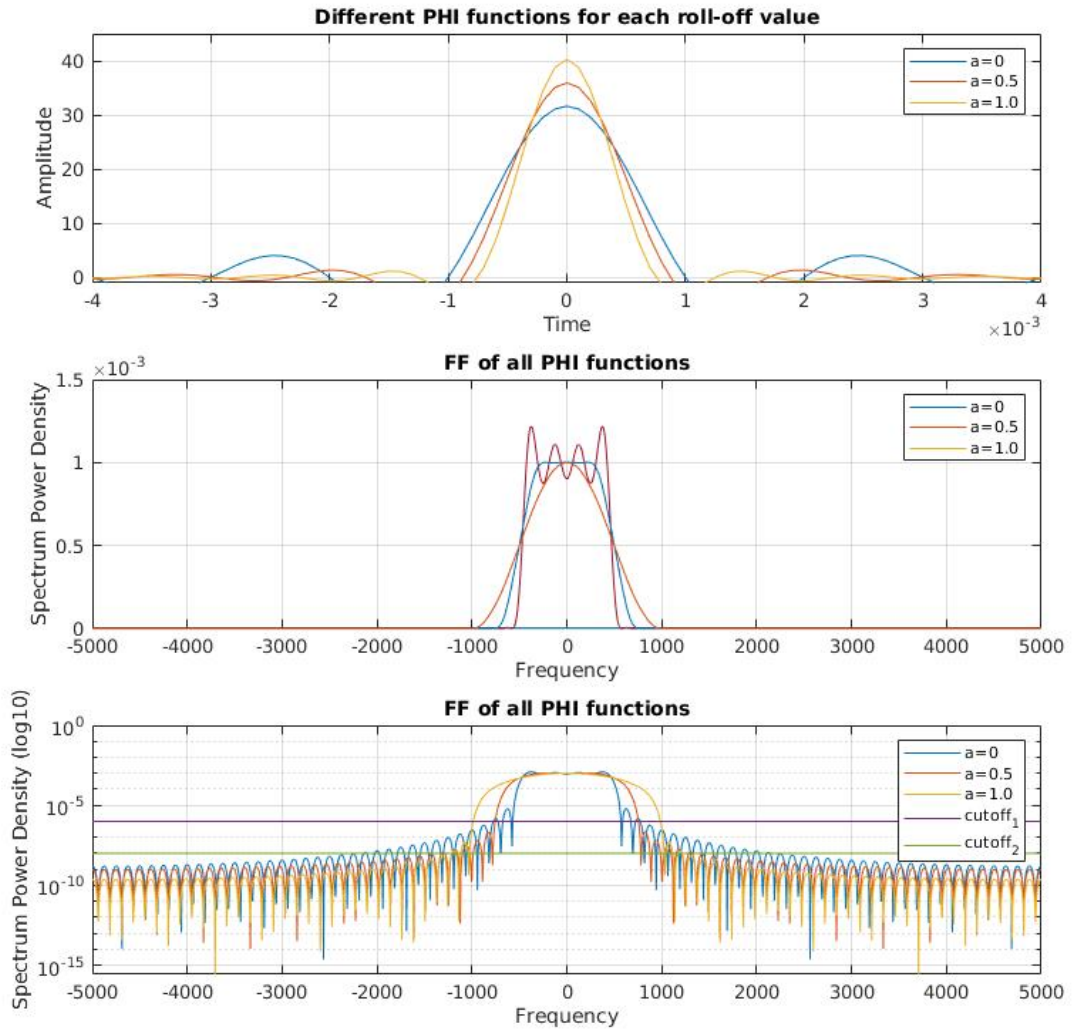
- i.  $BW = 569.2$ , for  $\phi$  with  $a = 0$
- ii.  $BW = 754.6$ , for  $\phi$  with  $a = 0.5$
- iii.  $BW = 986.2$ , for  $\phi$  with  $a = 1.0$

For cut-off at  $c_2 = \frac{T}{10^{-5}}$

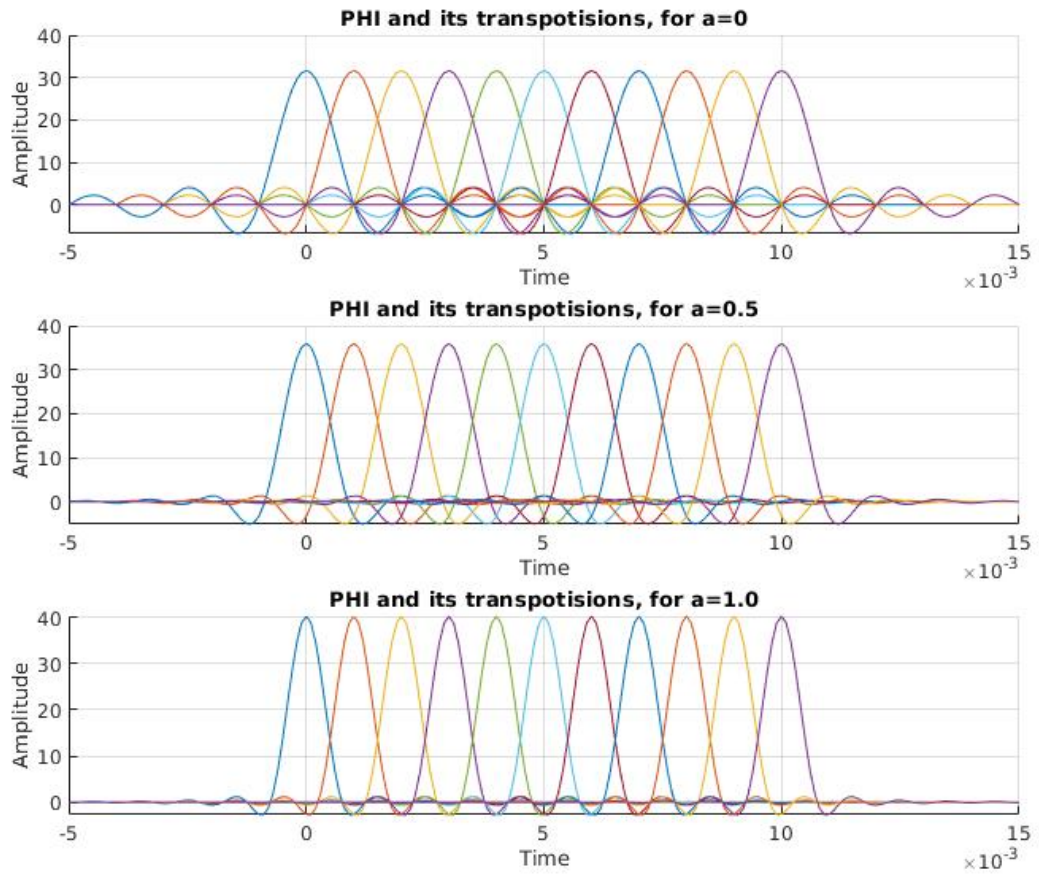
- i.  $BW = 2110$ , for  $\phi$  with  $a = 0$

- ii.  $BW = 1285$ , for  $\phi$  with  $a = 0.5$
- iii.  $BW = 1168.5$ , for  $\phi$  with  $a = 1.0$

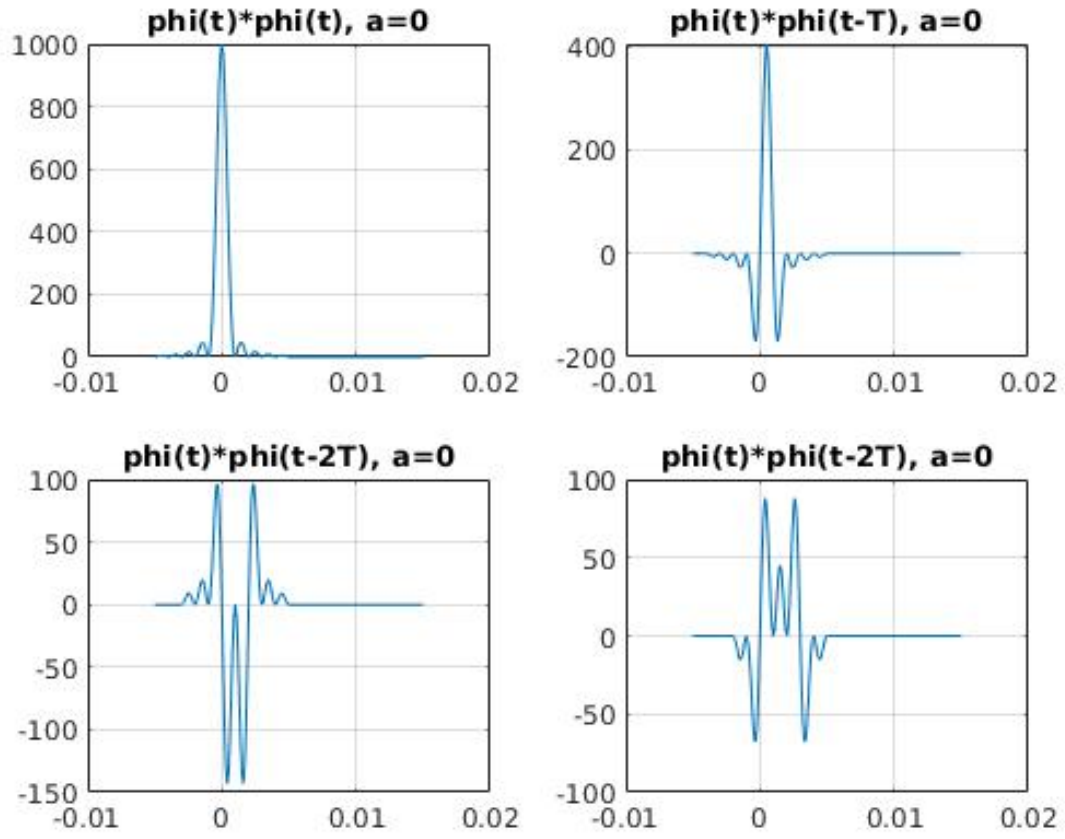
After defining a second cutoff point the most efficient pulse become the one with roll-off  $a = 1$ , due to its steepest decent.



B.1 The orthocanonical function  $\phi$  has some special properties. Mainly the integral with its transpositions of integer multiples of  $T$  is 0! It is observed that the approximation of the integral gets better for  $a > 0$ .



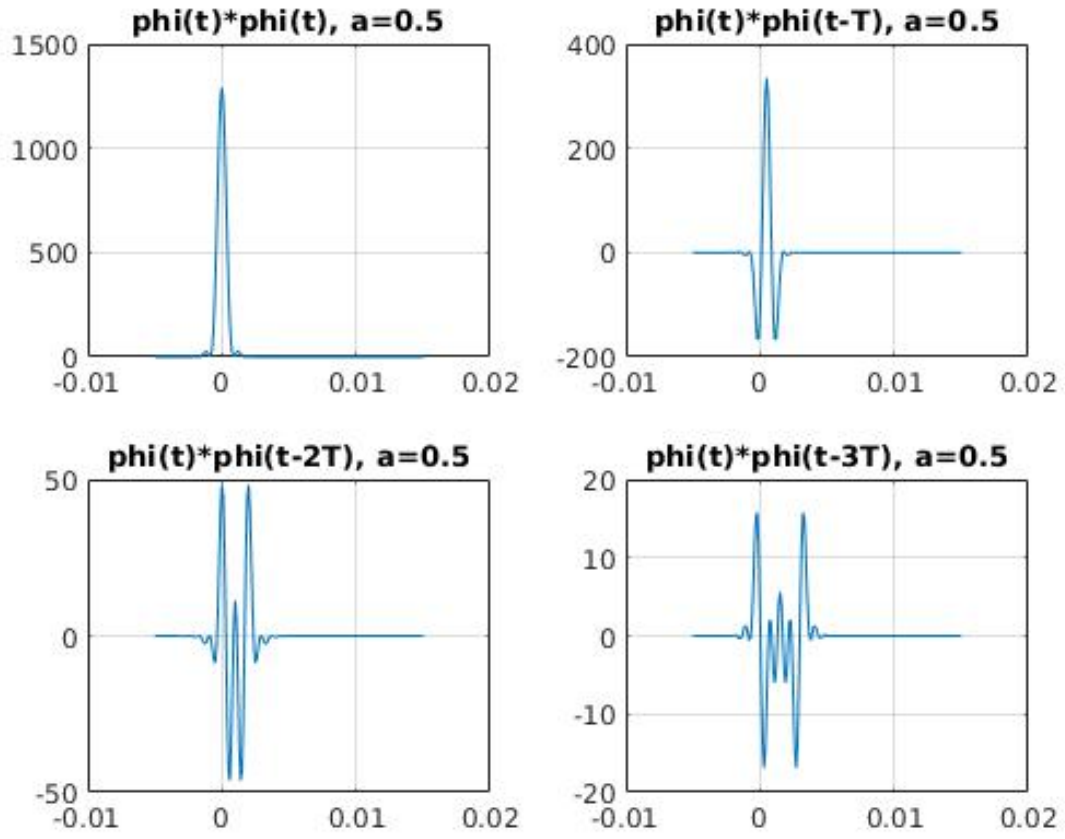
For  $a = 0$



- i.  $\int_{-\infty}^{\infty} \phi(t)\phi(t) dt = 0.98$
- ii.  $\int_{-\infty}^{\infty} \phi(t)\phi(t-T) dt = 0.02$
- iii.  $\int_{-\infty}^{\infty} \phi(t)\phi(t-2T) dt = -0.03$
- iv.  $\int_{-\infty}^{\infty} \phi(t)\phi(t-3T) dt = 0.03$

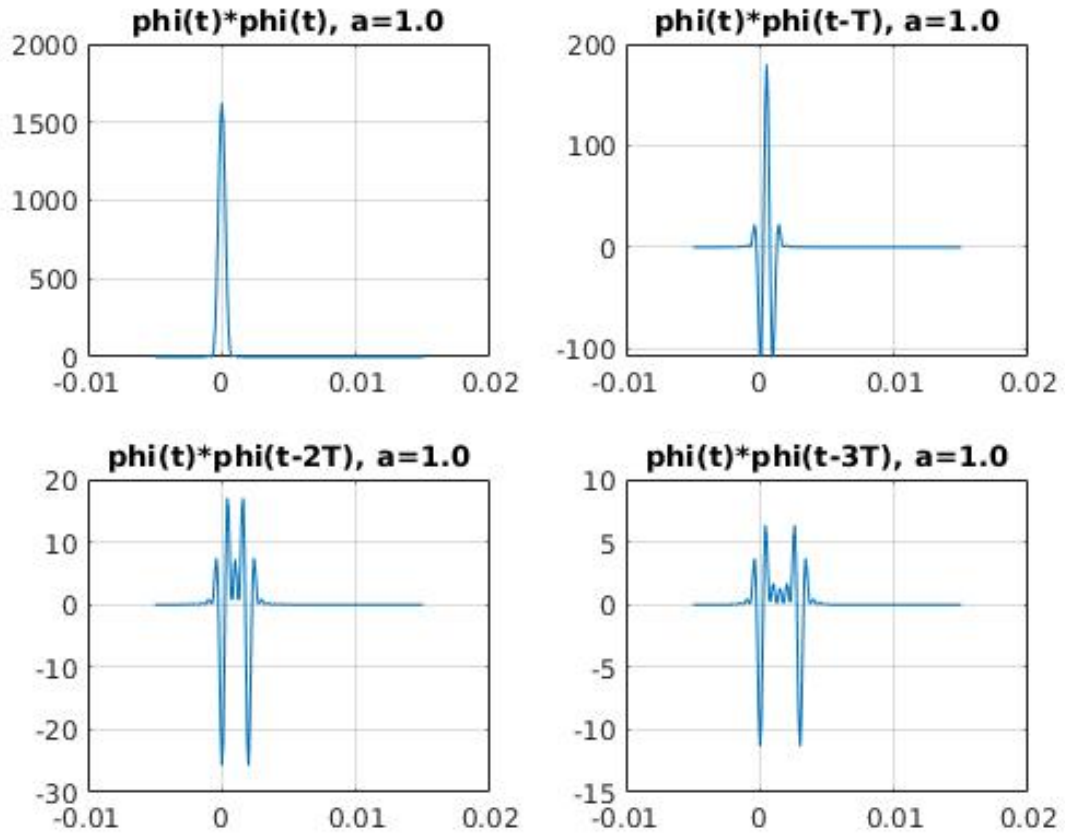


For  $a = 0.5$



- i.  $\int_{-\infty}^{\infty} \phi(t) \phi(t) dt = 1$
- ii.  $\int_{-\infty}^{\infty} \phi(t) \phi(t - T) dt = 0$
- iii.  $\int_{-\infty}^{\infty} \phi(t) \phi(t - 2T) dt = 0$
- iv.  $\int_{-\infty}^{\infty} \phi(t) \phi(t - 3T) dt = 0$

For  $a = 1.0$



- i.  $\int_{-\infty}^{\infty} \phi(t)\phi(t) dt = 1$
- ii.  $\int_{-\infty}^{\infty} \phi(t)\phi(t - T) dt = 0$
- iii.  $\int_{-\infty}^{\infty} \phi(t)\phi(t - 2T) dt = 0$
- iv.  $\int_{-\infty}^{\infty} \phi(t)\phi(t - 3T) dt = 0$

For creating the transpositions of  $\phi(t)$  a new function called **phi\_kT** was created that returns a  $length(k) \times length(time)$  matrix. It (pre)appends zeroes to  $\phi(t - kT)$  so that all  $\phi$ 's have the same time vector. Then the products and integrals can be computed by taking the requested rows from that matrix. Function Code:

```
function [phi_K] = phi_kT(phi, time, T, Ts, A)
    phi_K = zeros(11, length(time));
    for k=0:1:2*A
        offset = uint64(k*T/Ts);
        padL = zeros(1, offset);
        padR = zeros(1, length(time) - offset - length(phi));
        t_phi_k = [padL, phi, padR];
        phi_K(k+1,:)= t_phi_k;
    end
end
```

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C.1 Create N (50) random bits using the function

$$(\mathbf{sign}(\mathbf{randn}(\mathbf{bits}, 1)) + 1)/2$$

C.2 The simple 2-PAM system

- a. The function **bits\_to\_2PAM()** maps the value of each bit to a specific symbol using the following table:

$$0 \longrightarrow +1,$$

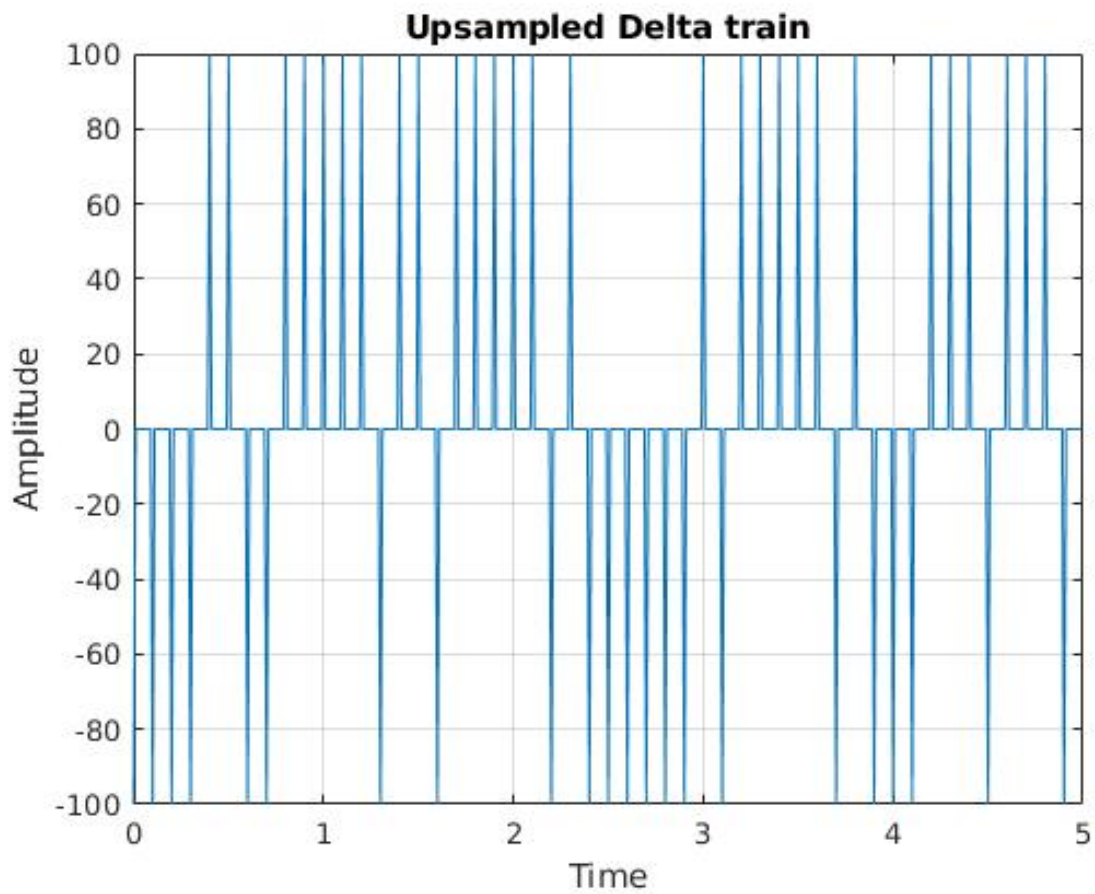
$$1 \longrightarrow -1.$$

Function Code:

```
function X = bits_to_2PAM( bits )  
    X = zeros(1, length( bits ));  
    X( bits==1 ) = -1;  
    X( bits==0 ) = 1;  
end
```

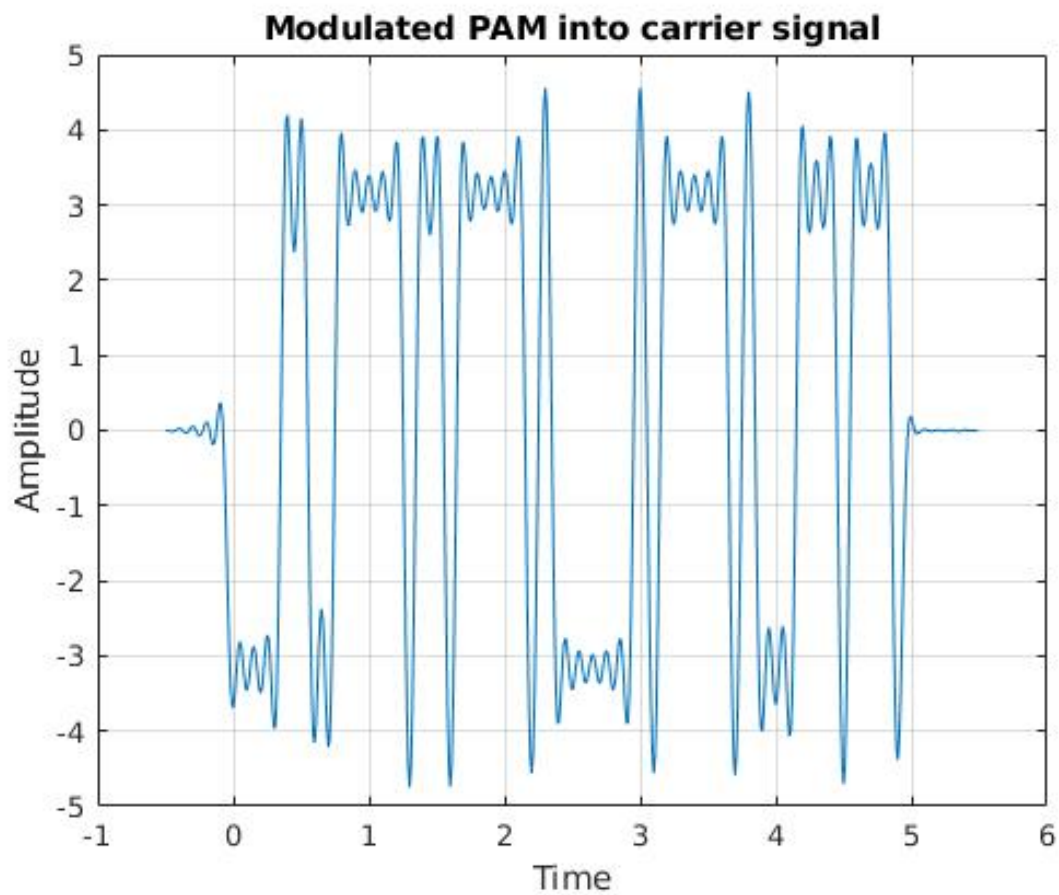
- b. After creating the bit stream, it gets upsampled and multiplied by  $1/T_s$  so that on every sample at  $kT$  a delta pulse is captured (The time vector needs readjustment to accommodate the injected zeroes):

```
X_delta = 1/Ts * upsample(X, over)  
T_delta = 0:Ts: bits/over-Ts;
```



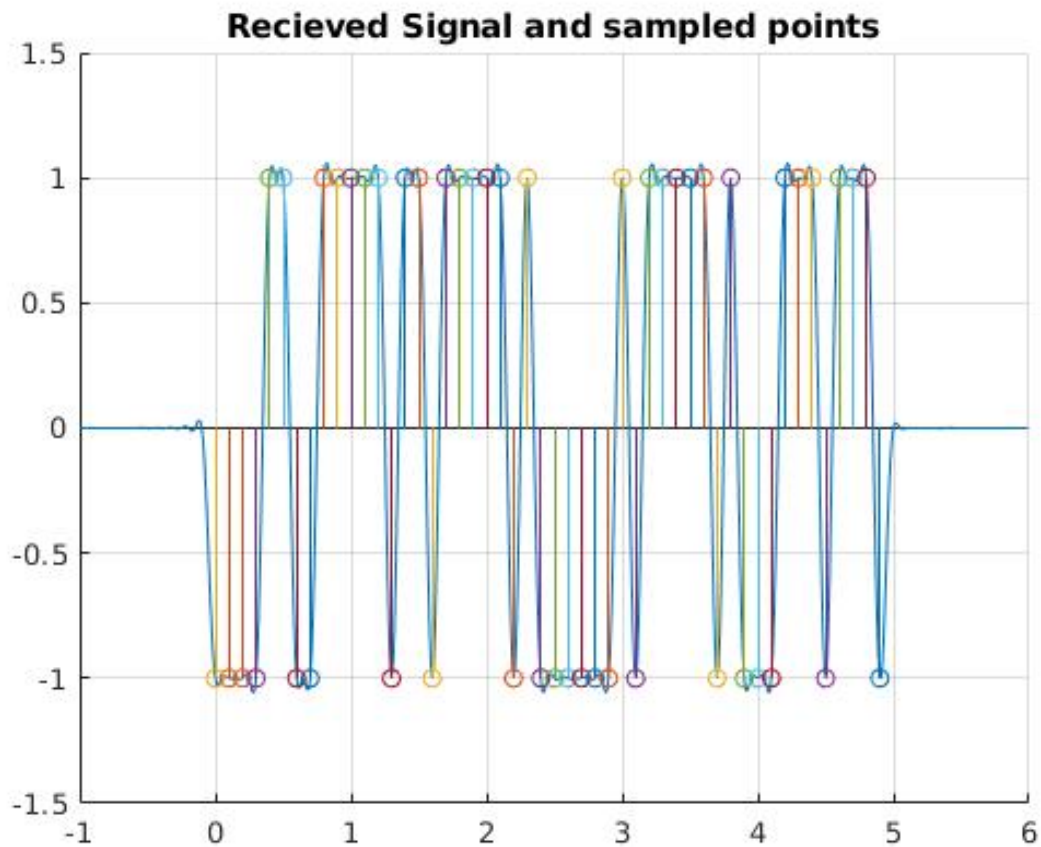
- c. Convoluting the carrier wave  $\phi(t)$  with  $X_{\text{delta}}$  results in the signal to be transmitted,  $X(t)$ :

```
t_phi_conv = (t(1) + T_delta(1):Ts:t(end) + T_delta(end));  
X_t = conv(X_delta, phi)*Ts;  
plot(t_phi_conv, X_t);
```



The receiving end:

- d. Considering an ideal communications channel, the received signal should be the  $X(t)$  without any additional noise. To recreate the sequence that was sent, a convolution with the matched filter  $\phi(-t)$ , needs to be performed. The output of the filter is the integral mentioned in [B.1]. If this output is sampled at specific times it can recreate the original symbol sequence. On  $kT$  multiples of  $T$ ,  $\phi$  should pass from 1 or  $-1$ .



The matched filter is created by mirroring  $\phi$  and its time vector using:

```
t_phi_minus = -fliplr(t);
phi_minus = fliplr(phi);
```

After filtering, the convolution can take place and then the sampling

```
tconv = (t_phi_minus(1) + t_phi_conv(1):Ts:t_phi_minus(end) +
t_phi_conv(end));
X_z = conv(phi_minus, X_t)*Ts;
plot(tconv, X_z);
stem((0:49)*T,X_50);
for t=1:length(tconv)
    if mod(tconv(t), T) == 0 && tconv(t) >= 0
        && tconv(t) <= A(2)-Ts
            stem(tconv(t), X_z(t));
    end
end
```

Looking closely one would observe that there is a slight deviation from the sent symbol and the received one. All sent symbols line up perfectly on  $y = 1$  and  $y = -1$ , however because  $\phi$  is just an approximation a slight deviation is expected.

