

# State Space Model (SSM) inversion: Inferring the system dynamics (model parameters)

Given a Set of Data & nonlinear deferential equations (DDEs):

$$\begin{cases} \dot{\mathbf{x}}(t) = \mathbf{f}(\mathbf{x}(t), \mathbf{u}(t), \boldsymbol{\theta}) + \mathbf{w}(t), & \mathbf{x}(0) = \mathbf{x}_{t_0} \\ \mathbf{y}(t) = \mathbf{h}(\mathbf{x}(t)) + \mathbf{v}(t) & \mathbf{w}(t) \sim \mathcal{N}(0, \sigma^2) \text{ and } \mathbf{v}(t) \sim \mathcal{N}(0, \sigma'^2) \end{cases}$$

Aim: identification unknown model parameters  $\boldsymbol{\theta}$ , from the observation in the best possible way.

**Bayesian inference:** uses the language of probability to formalize **model inversion**, as the quantification and propagation of uncertainty, defined via a probability, in the light of observations.

**Bayes' theorem:**

the process of passing from *prior* to *posterior* in the light of data by:

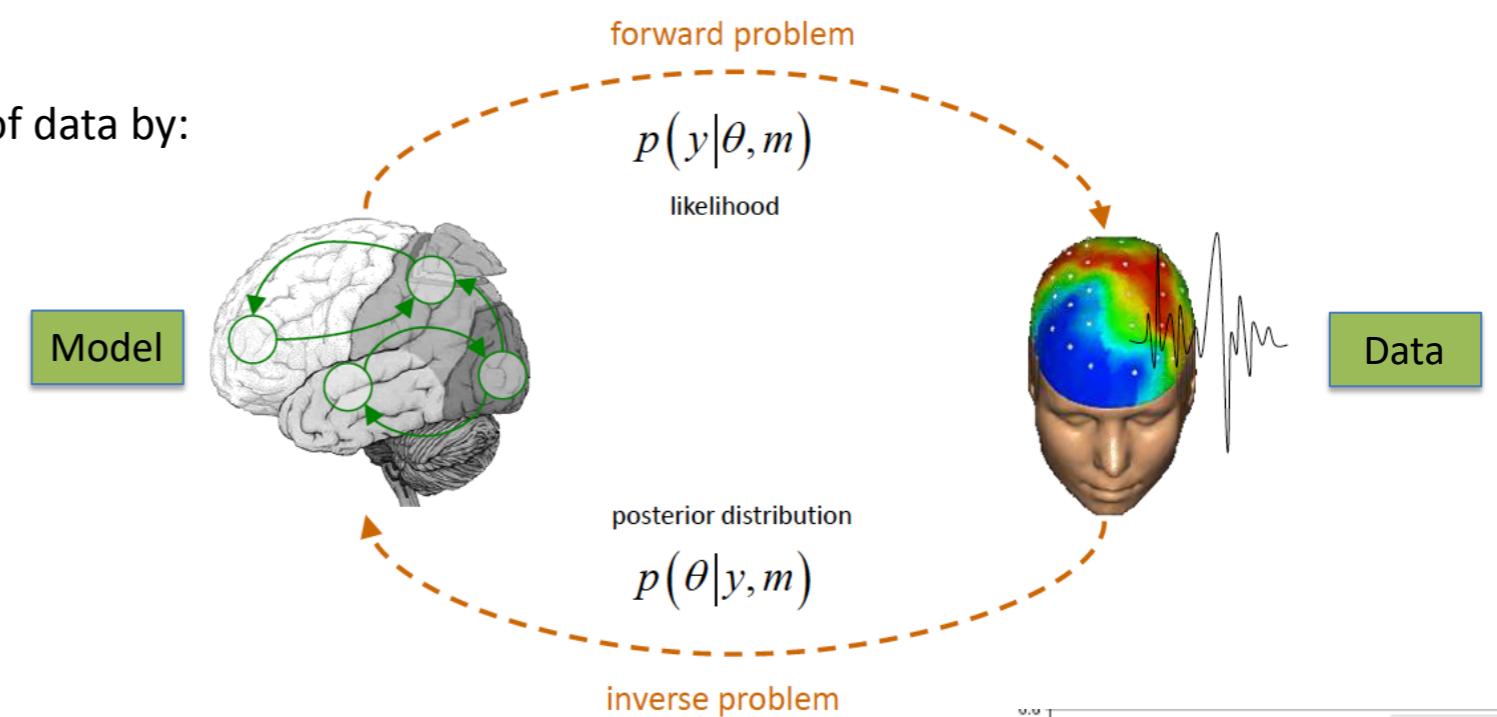


Likelihood      prior

$$p(\theta | y) = \frac{p(y | \theta)p(\theta)}{\int p(y | \theta)p(\theta)d\theta}$$

posterior

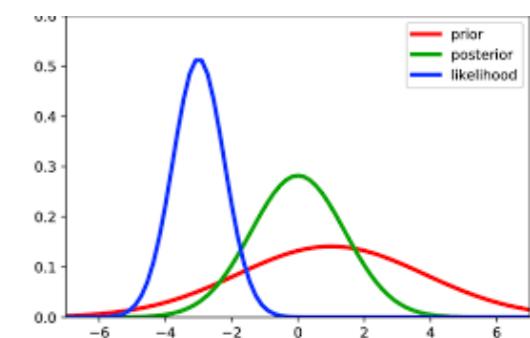
Marginal likelihood  $p(y)$  (model evidence)



**Prior:** encodes what we knew about the model, before the application of the data.

**Likelihood:** is the probability of obtaining the set of observed data, with a given set of parameter values.

**Posterior** : is the conditional probability of of the model parameters (latent variables ) given the data.



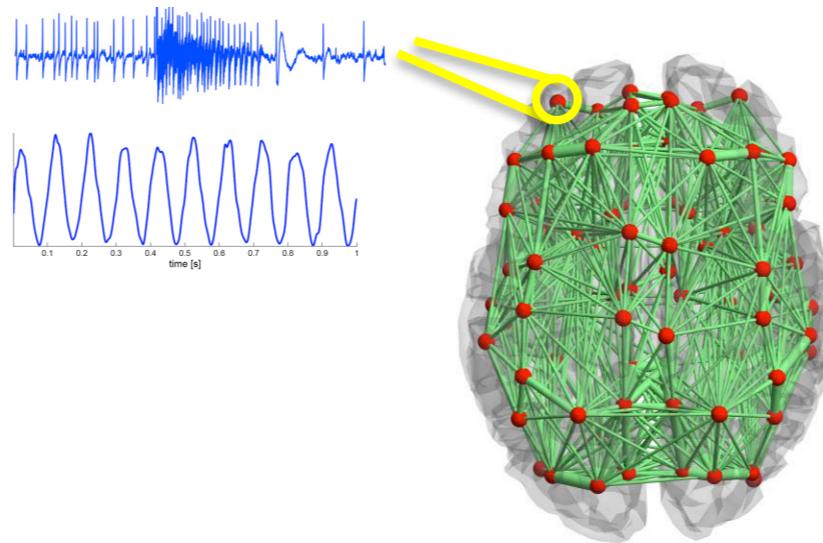
# Bayesian inference

- Integrating patient-specific information through *prior*
- uncertainty (confidence) in the estimations through *posterior*
- out-of-sample prediction for unseen data through *model evidence*
- The relation between parameters (*identifiability/degeneracy*)

## Large-scale brain network modeling

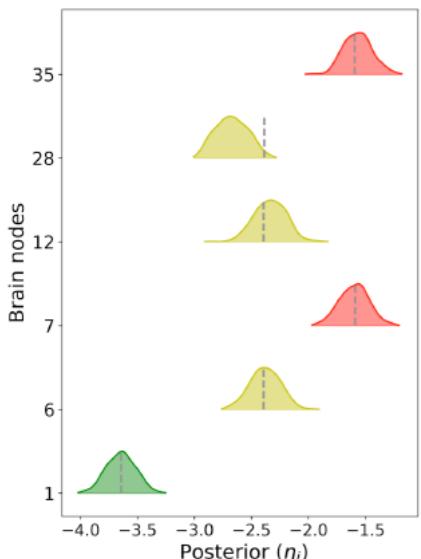
### Neural Mass Models:

- Epileptor (epilepsy)
- Generic Hopf (coupled oscillators)
- Montbrio model (resting-state, ...)
- Neural fields



### Simulated/empirical Data:

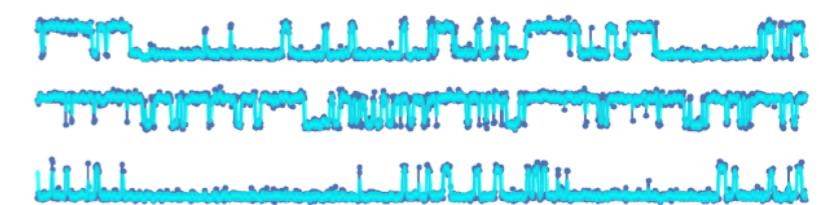
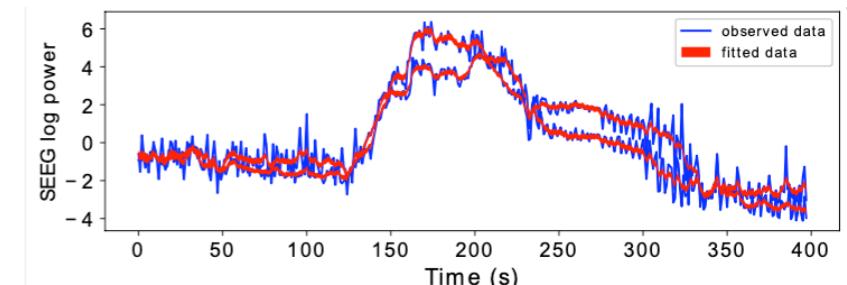
- SEEG (epilepsy)
- Source brain activity
- BOLD fMRI (resting-state)
- EEG/MEG/fMRI,...



Brain region's parameter(s)?

homogeneity/heterogeneity (regional variance)  
(normal/informative/hierarchical prior)

**SC** is fixed but **G** to scale the connectome?



The **likelihood** function is the central ingredient in both frequentist and Bayesian inference

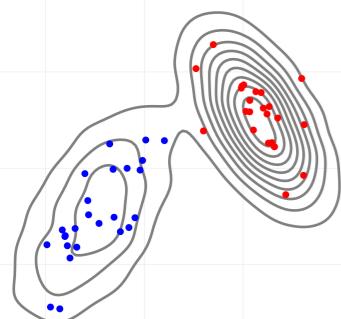
$$p(y \mid \theta) = \int dz \ p(y, z \mid \theta)$$

challenge: likelihood is an integral over all possible trajectories in the latent space

## 1) Likelihood based inference (non-parametric)

PPLs such as Stan/PyMC3:

- Self-tuning Hamiltonian Monte Carlo (NUTS)
- Automatic Differentiation Variational Inference (ADVI)
- Maximum a Posteriori (MAP)



No objective function:  
RMSE, correlation, ...

- probabilistic model in code
- Observed data



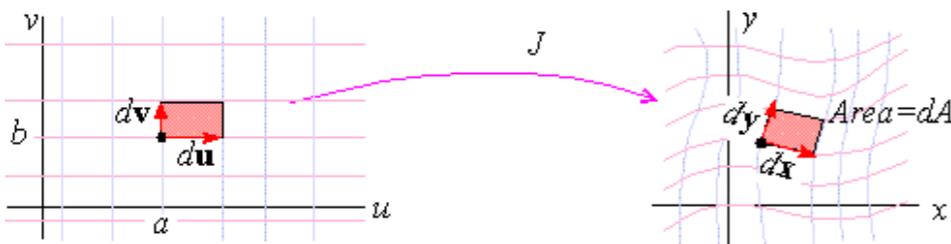
**posterior**

Diagnostics for convergence ( $\hat{R}$ )  
for satisfying detailed balance condition (ergodicity)

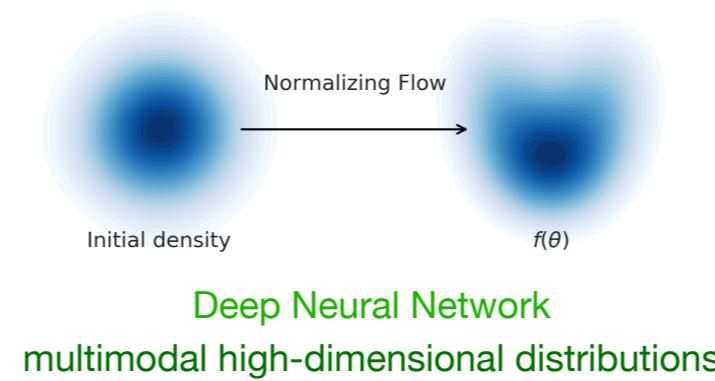
## 2) Approximate Likelihood inference (parametric)

Simulated Based Inference (normalize flow)

A new tool for constructing flexible probability distributions from simple base distributions using DNN



$$\mathbf{x} = f(\mathbf{z}) \rightarrow p(\mathbf{x}) = p(\mathbf{z}) \left| \det \frac{\partial f^{-1}}{\partial \mathbf{z}} \right|$$



Data features

Neural Net minimizes KL divergence

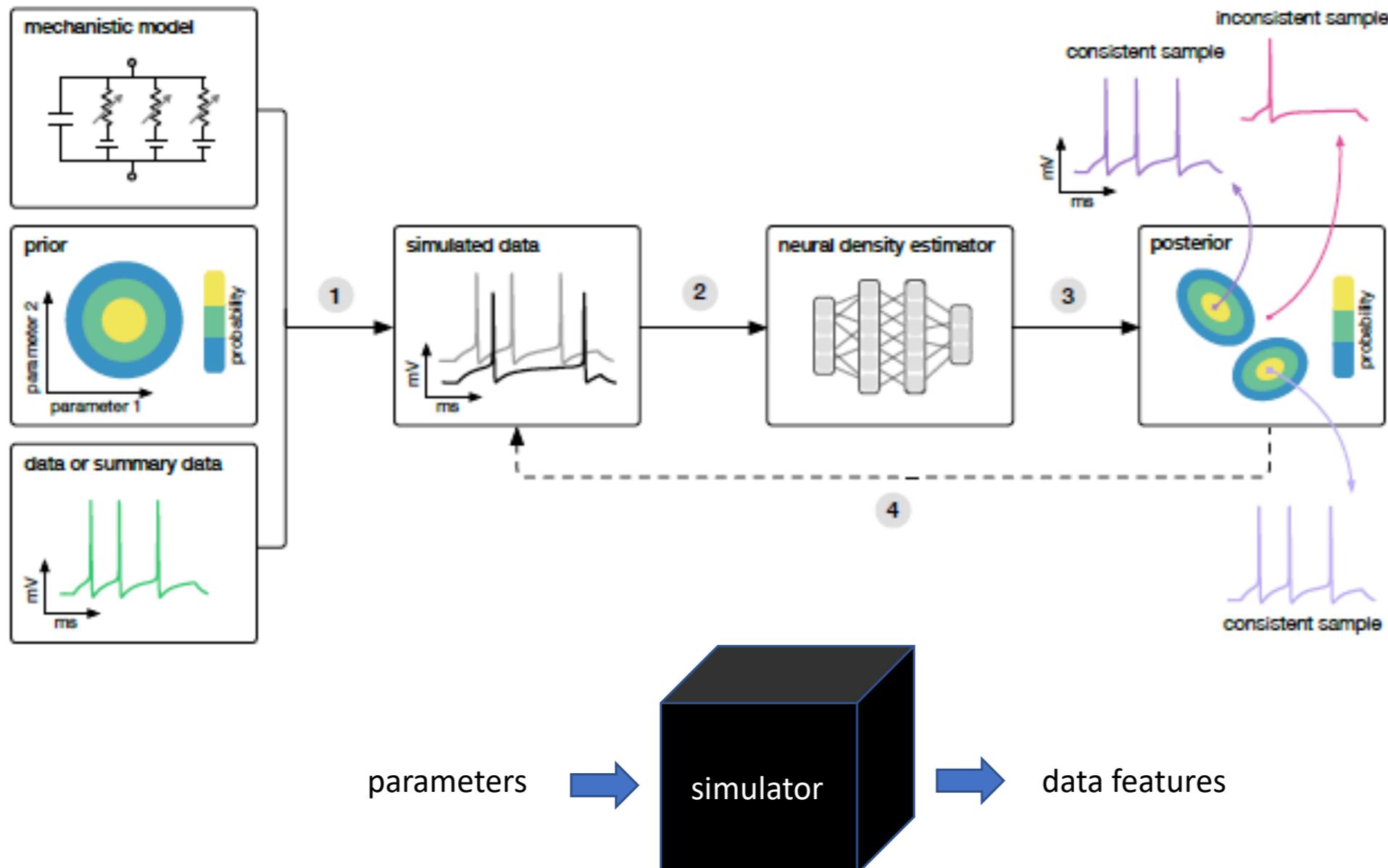
- prior distribution
- simulator (forward model)
- summary statistics



**posterior**

Infer a parameterized (invertible) function that maps between observation space and latent variables to approximate posterior distribution.

# Simulated Based Inference



Gonçalves et al, eLife (2020)

# Amortized Bayesian inference (ABI) of Virtual Epileptic Patient (VEP)

