

# October 24, 2022

## building

### *focus:*

Finishing touches on first robot

### *summary:*

Reprinted a new version of the servo mount/claw and attached it to the lift. Also attached the mount for hubs to the back of the robot.

### *challenges:*

The screws holes were not aligned perfectly to the wood, so we had to drill more. We also had to cut the wood in the scene shop because of its width.

### *next steps:*

Add something silicon-like to the claws and send the robot off to coding for wiring and testing code