

# CS898AW Spring 2025 Assignment 2: Modeling Tool Affordances PDDL

## Objective

The objective of this assignment is to integrate tool affordances from the AffordPose dataset with planning using the Planning Domain Definition Language (PDDL). Students will interpret real-world tool definitions, extract affordances, and design PDDL domain and problem files to model tool usage in goal-oriented tasks.

## Background

You are provided with a filtered dataset of tools whose definitions align with affordances described in the AffordPose dataset. These affordances include:

- `handle-grasp`
- `press`
- `lift`
- `pull`
- `twist`
- `wrap-grasp`
- `support`
- `lever`

Each tool in the dataset implies one or more of these hand-object interaction affordances.

## Instructions

### Part 1: Tool Selection and Affordance Mapping (10)

- 1.1. Five tools are assigned to you based on your WSUID. Please refer to **Student\_Tool\_Assignment** and **tool\_list**.

- 1.2. Based on your knowledge, please assign each tool a type (e.g., `cutting_tool`, `fastening_tool`, `lifting_tool`, `music_instrument` etc.).

## Part 2: PDDL Domain Modeling (30)

- 2.1. Create a PDDL domain file (`tools-domain.pddl`) that includes:

- Tool and affordance. The affordance should only select from the provided list in the **Background** section. If more than two words in your assigned tool lists cannot find suitable affordances from the affordance list, please let the instructor and the TA know.
- Predicates such as:
  - `(has ?agent ?tool)`
  - `(affords ?tool ?affordance)`
  - `(used-for ?affordance ?action)`
  - `(at ?agent ?location)`
- Actions based on affordances, e.g., `use-scissors`, `pull-handle`, etc.

## Part 3: PDDL Problem Definition (30)

- 3.1. Define a problem file (`tools-problem.pddl`) where a robot agent utilizes one or more tools to achieve a specified goal. You should define a reasonable goal that is suitable for the given tools.
- 3.2. Please generate a `ReadMe.md` file that describes the goals in natural language.
- 3.3. Include:
  - Initial state: tool affordances, possession, and locations
  - Goal state: desired condition (e.g., `cut object`, `twist lid`)

## Part 4: WSUID\_student\_assignment\_2.csv (30)

- 4.1. Discussed in the class.

## Deliverables

If any of the following files are missing, the grade will be zero.

- `WSUID_tools_domain.pddl`
- `WSUID_tools_problem.pddl`
- `WSUID_student_assignment_2.csv`
- `ReadMe.md`

## Submission Deadline

Submit all files to the Blackboard by **[May 11, 2025 EoD]**. May 11, 2025, is the final deadline, and we need time to finish grading. Therefore, extending the deadline is not possible.