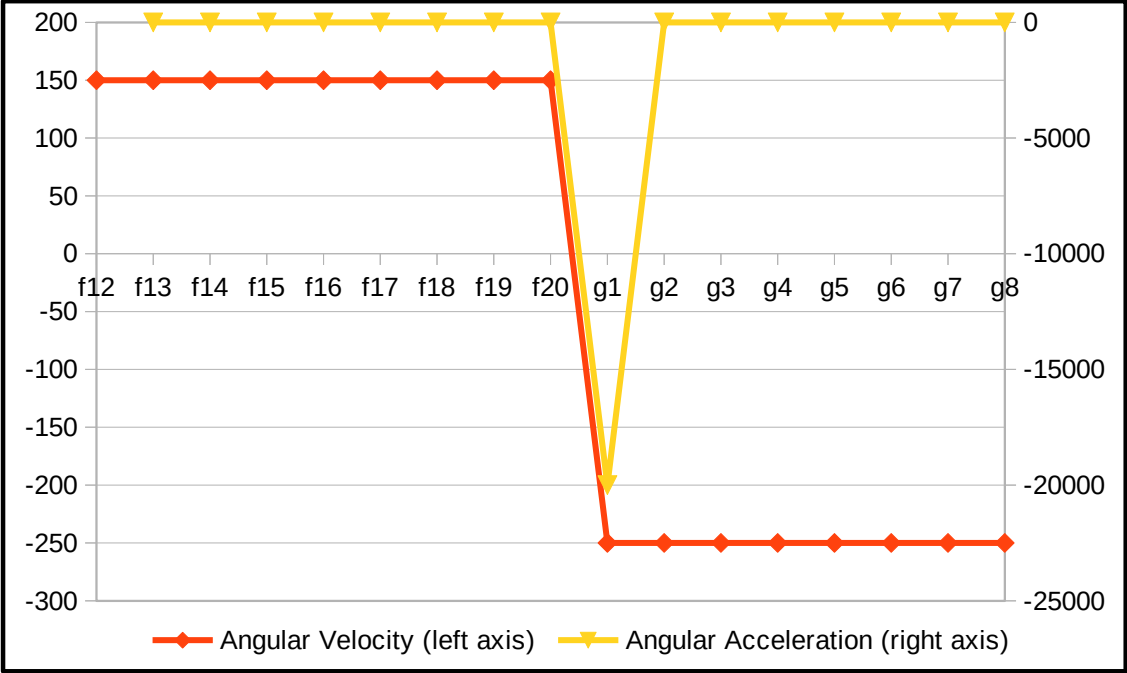
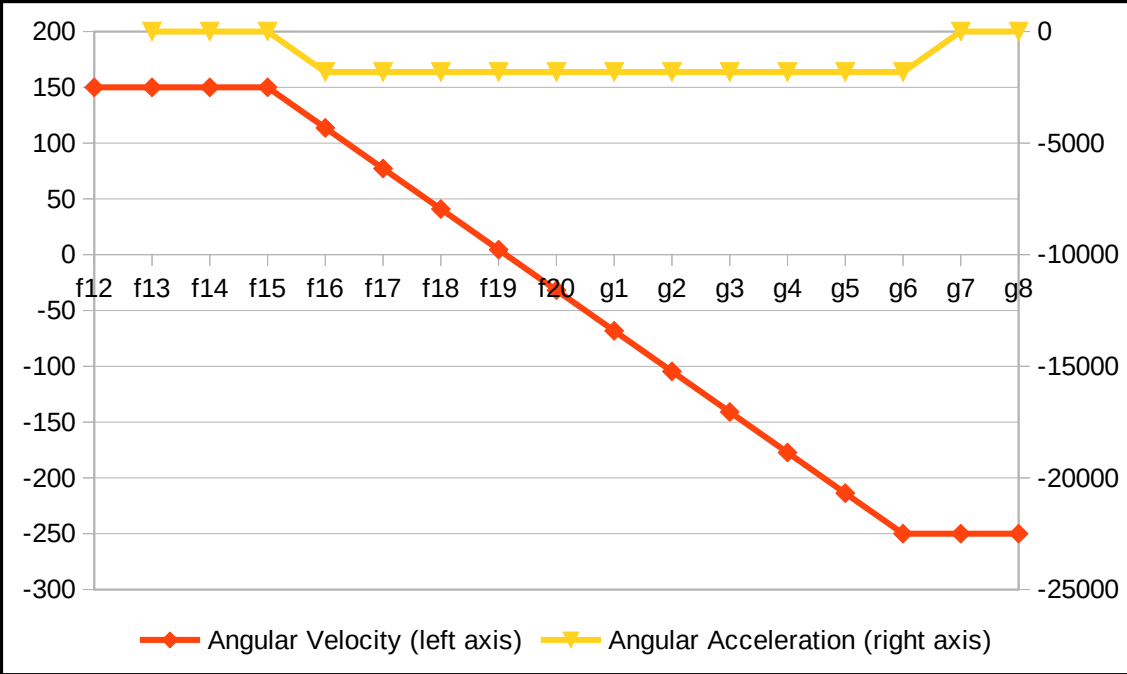


Frame	degrees / frame	Angular Velocity (left axis)	Angular Acceleration (right axis)	Angular Jerk
		Degrees/sec	deg/sec^2	deg/sec^3
f12	3	150		
f13	3	150	0	0
f14	3	150	0	0
f15	3	150	0	0
f16	3	150	0	0
f17	3	150	0	0
f18	3	150	0	0
f19	3	150	0	0
f20	3	150	0	0
g1	-5	-250	-20000	-1000000
g2	-5	-250	0	1000000
g3	-5	-250	0	0
g4	-5	-250	0	0
g5	-5	-250	0	0
g6	-5	-250	0	0
g7	-5	-250	0	0
g8	-5	-250	0	0



Frame	degrees / frame	Angular Velocity (left axis)	Angular Acceleration (right axis)	Angular Jerk
		Degrees/sec	deg/sec^2	deg/sec^3
f12	3	150		
f13	3	150	0	0
f14	3	150	0	0
f15	3	150	0	0
f16	2.27	113.64	-1818.18	-90909.09
f17	1.55	77.27	-1818.18	0.00
f18	0.82	40.91	-1818.18	0.00
f19	0.09	4.55	-1818.18	0.00
f20	-0.64	-31.82	-1818.18	0.00
g1	-1.36	-68.18	-1818.18	0.00
g2	-2.09	-104.55	-1818.18	0.00
g3	-2.82	-140.91	-1818.18	0.00
g4	-3.55	-177.27	-1818.18	0.00
g5	-4.27	-213.64	-1818.18	0.00
g6	-5.00	-250.00	-1818.18	0.00
g7	-5.00	-250.00	0.00	90909.09



g8 -5 -250 0 0