

A BRIEF INTRODUCTION TO COQ

The Coq Proof Assistant

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THE COQ PROOF ASSISTANT

usage and applicability of the Coq-proof-assistant

- → developed since 1983
- → community in the industry and research https://coq.inria.fr/community https://github.com/coq-community
- → basic concepts of logic
- → functional programming



Figure: The Rooster.
Source:[2]

OTHER PROOF ASSISTANTS

There are numerous proof assistants.

- → Isabelle https://isabelle.in.tum.de
- → HOL https://hol-theorem-prover.org

LOGIC

"As as matter of fact, logic has turned out to be significantly more effective in computer science then it has been in mathematics." [1]

LOGIC

Reliability in software is amplified by the costs of bugs by insecurity up to multiple levels.

- → basic tools from logic
- → precise claims about programs
- → functional programming methods of programming and logical reasoning about programs



SYSTEM REQUIREMENTS

Coq runs on Linux, Mac OS and Windows. There are a lot of development environments available.

- → Proof General an Emacs based IDE
- → CoqIDE is a simple stand-alone IDE
- → coquille a vim plug-in
- → and others

SYSTEM REQUIREMENTS

Coq runs on Linux, Mac OS and Windows. There are a lot of development environments.

→ Proof General

an Emacs based IDE generic interface for proof assistants developed by multiple universities

→ CoqIDE

is a simple stand-alone IDE user-friendly, included in the official Coq-installation

→ coquille

a vim plug-in an open-source project

PROOF GENERAL

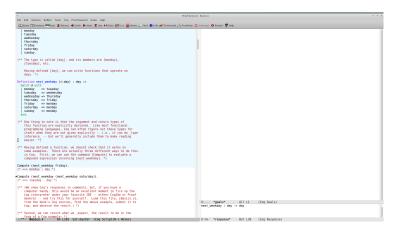


Figure: Coq interface in proof general.

COQIDE

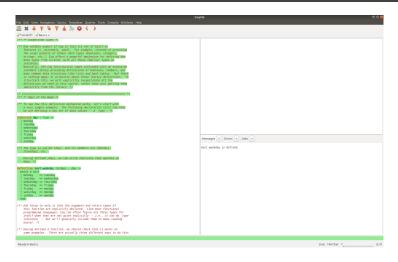


Figure: Coq interface in CoqIDE.

COQUILLE

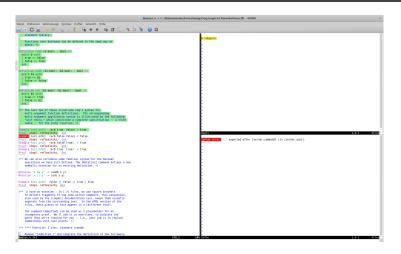
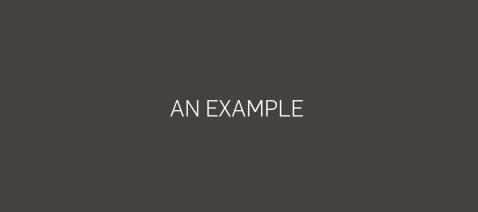


Figure: Coq interface in gvim using coquille.

FUNCTIONAL PROGRAMMING

Coq's functional programming language *Gallina's* sub-types

- 1. vernacular language (top-level interaction):
 - e.g.: Theorem, Proof, Qed.
- 2. tactics language:
 - e.q.: intros, exact
- 3. the language of Cog-terms:
 - $\mathsf{e.g.}$ for all A: Prop, A ightarrow A.



AN EXAMPLE

Listing 1: definition of a datatype called day

AN EXAMPLE

```
Definition next_weekday (d:day) : day :=
 23456789
                     match d with
                        monday
                                      \Rightarrow tuesday
                        tuesday
                                      \Rightarrow wednesday
                        wednesday \Rightarrow thursday
                        thursday
                                      \Rightarrowfriday
                        friday
                                      \Rightarrow monday
                        saturday
                                      \Rightarrowmonday
                        sunday
                                      \Rightarrowmonday
10
                     end.
```

Listing 2: declaration of a function on day

AN EXAMPLE

```
1 Compute (next_weekday friday).
```

Listing 3: call Compute

1 = monday: day

Listing 4: output



APPLICATIONS

A platform for *modeling programming languages* and an environment for *formally certifying software and hardware*

- → PROSA a felxible open-source foundation for formally proven schedulability analysis. PROSA uses the Coq proof assistant and the SSREFLECT extension library [1]
- → Jasmin: High-Assurance and High-Speed Cryptography [1]



PROSA - A COQ LIBRARY



Figure: RT-proofs-logo. Source: [3].

- 1. Formal Proofs for real-time systems (RT-Proofs)
- 2. project running between multiple research faculties (DFG project between INRIA, MPI-SWS, Onera, TU Braunschweig and Verimag, running from 2018 until 2020)
- 3. The PROSA library is where this development takes place.

PROSA - A COQ LIBRARY

to reproduce the PROSA - ECRTS'16 Artifact Evaluation by mechanically proofing the case study the following framework is provided online

utility	source
Ubuntu 15.10, wily	VM-Image
Coq Version 8.5pl	VM-Image
Proof General 4.3pre131011	VM-Image
mathcomp-1.6, ssreflect-extension	VM-Image
PROSA v.01	former version of the
	Coq spec and proof
	development of the
	RT-PROOFS project

PROSA - A COQ LIBRARY

to reproduce the PROSA - ECRTS'16 Artifact Evaluation by mechanically proofing the case study the following framework is provided online

my current working directory: https://gitlab.cs.hs-rm.de/almeroth/prosa_working_dir members: Steffen Reith due to documentation including all listings

- → »We conclude that the develop foundations are sufficiently felixble and powerful to support a large fraction of existing literature and real-time scheduling, without compromising readability.« [1]
- → »Mechanized schedulability proofs are feasible, to the point that non-trivial multiprocessor schedulability analyses can be formalized in a reasonable time frame.«[1]
- → case studies

a case study provided: Ciriniei's RTA for EDF [2, p.160, Figure 17.3]

definition and proofs of termination and correctness of Bertonga and Cicerei's RTA for EDF

```
Theorem (Main Theorem)
           Theorem edf_analysis_yields_response_time_bounds :
                tsk R,
               (tsk, R) \\In edf_claimed_bounds ts →
               response_time_bounded_by tsk R.
                Listing 5: theorem_edf_analysis [1]
```

practical specification: correctness of the proof

mechanized proofs available

- → correctness of the work-loaded-based interference bound for work-conserving schedulers
- → EDF-specific interference bound definition and proof of termination and correctness of Bertongna and Cicerei's RTA for FP scheduling
- \rightarrow definition and proof of termination and correctness of Bertongna and Cicerei's RTA for EDF scheduling ($\approx 1'320$ LOC)

 $\approx 13'070 \text{ LOC}$

practical specification: correctness of the proof

mechanized proofs available

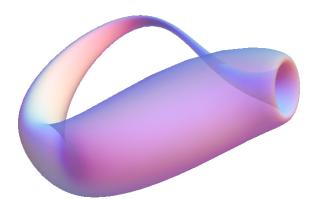
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- → EDF-specific interference bound definition and proof of termination and correctness of Bertongna and Cicerei's RTA for FP scheduling
- ightarrow definition and proof of termination and correctness of Bertongna and Cicerei's RTA for EDF scheduling ($pprox 1'320\ LOC$)

 $\approx 13'070 \text{ LOC}$



BREAK - LET'S TALK ABOUT INSIDE AND OUTSIDE.

https://www.youtube.com/watch?v=SyD4p8_y8Kw



Klein Bottle with slight transparency, rendered with Mathematica 8 using the parameterisation provided by Robert Israel. Copyright by wikipedia, Creative Commons Attribution-Share Alike 3.0 Unported

Kasier's encapsulated EDF-scheduler [3]

- → real-time as in [1]
- → hierarchical (local and global distinction)
- → multi-core (in the real-time-sense)
- → EDF (earlines deadline first on a local level)
- → sporadic
- → disruptive

Main theorem: correctness of analysis although it is a deductive derivation

Definition

The *process* is defined as a sequential execution of a program on a processor. The execution ends after a finite number of steps. Therefore it corresponds to a finite execution of machine commands and is not separable.

Definition

A process is called *periodic* if it should be restated after a certain time called *the period*.

Otherwise a process is called *aperiodic* or *sporadic*. Furthermore, whenever as process is said to be *non-preemptive* the execution may not be interrupted between the beginning and ending of the process.

It is called *preemptive* if it may be interrupted after any instruction.

The **slotted prirority modell** from [1] with sporadic and periodic processes ([3]). Due to [1] the major requirement is said to be as in the following:

»If a system itself the execution of a real-time and non-real-time thread in alternate intervals the intervals in which real-time threads execute are scheduled to be in every l time unit, then it must be ensured that the interval begin at time t where $kl \leq t \leq kl + \epsilon \quad \forall \epsilon \geq 0$.«

Moreover there is this requirement \mathcal{B} .

»For $L>\epsilon$ (for a suitable ϵ) for which the real-time thread schedule has asserted a real-time thread τ to be expected on the CPU, there must be a function of the method by which the minimum number of CPU cycles available to execute the instructions of τ can be determined.«

Definition

$$\delta_p \in \mathbb{N}$$
 be a periodic disruptive process and (1)

$$\delta_s \in \mathbb{N}$$
 be an asporadic disruptive process. (2)

Let
$$P := \{1, \dots, n\} \subset \mathbb{N}^n$$
 be an disruptable process. (3)

Let
$$\delta p_i$$
, for $i = 1, ..., n$ denote the period and (4)

$$\delta e_i$$
 for $i = 1, ..., n$ denote the execution time. (5)

Moreover, we define the slotted priority model by Bollea with Kaiser's sporadic and periodic disruptive process with a discrete time in contrast to these authors. This chioce is due to the real-time model from [?] and the real-time kernel as in [1, chp. 5.3] and the exclusion model [1, p.12].

Definition

Time is \mathbb{N} .

. . .

Admitted.

OUTLOOK

- → lecture notes for Steffen Reith, incorporate review
- → incorporate linear temporal logic
- → Steffen Reith's review
- → incorporate Steffen Reith's review on the PROSA working directory
- → tutorial on Gallina and SSreflect (4 person days)
- ightarrow formally proof the Kaiser's EDF scheduler in PROSA hopefully less then ($\approx 1'320~{\rm LOC}$)
- ightarrow see at what is the best way to approach the complete kernel

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