1

Digital Signal Processing Assignment 1

Syed Saqib Habeeb BM20BTECH11015

CONTENTS

1	Software Installation	1
2	Digital Filter	1
3	Difference Equation	2
4	Z-transform	3
5	Impulse Response	6
6	DFT	10
7	FFT	13
8	Exercises	16

Abstract—This manual is the soution of the assignment of the course EE3900 assignment 1.

1 Software Installation

Run the following commands

sudo apt-get update sudo apt-get install libffi-dev libsndfile1 python3 -scipy python3-numpy python3-matplotlib sudo pip install cffi pysoundfile

2 DIGITAL FILTER

2.1 Download the sound file from

wget https://raw.githubusercontent.com/ gadepall/ EE1310/master/filter/codes/Sound_Noise.wav

2.2 You will find a spectrogram at https: //academo.org/demos/spectrum-analyzer. Upload the sound file that you downloaded in

Problem 2.1 in the spectrogram and play. Observe the spectrogram. What do you find? **Solution:** There are a lot of yellow lines between 440 Hz to 5.1 KHz. These represent the synthesizer key tones. Also, the key strokes are audible along with background noise.

2.3 Write the python code for removal of out of band noise and execute the code.

Solution:

```
import soundfile as sf
from scipy import signal
#read .wav file
input signal,fs = sf.read('Sound Noise.wav
#sampling frequency of Input signal
sampl freq=fs
#order of the filter
order=4
#cutoff frquency 4kHz
cutoff freq=4000.0
#digital frequency
Wn=2*cutoff freq/sampl freq
# b and a are numerator and denominator
   polynomials respectively
b, a = signal.butter(order, Wn, 'low')
#filter the input signal with butterworth filter
output signal = signal.filtfilt(b, a,
   input signal)
#output signal = signal.lfilter(b, a,
   input signal)
#write the output signal into .wav file
```

- sf.write('Sound_With_ReducedNoise.wav', output signal, fs)
- 2.4 The the script output of python audio Problem 2.3 is the file in Sound With ReducedNoise.wav. Play the file in the spectrogram in Problem 2.2. What do you observe?

Solution: The key strokes as well as background noise is subdued in the audio. Also, the signal is blank for frequencies above 5.1 kHz.

3 DIFFERENCE EQUATION

3.1 Let

$$x(n) = \left\{ 1, 2, 3, 4, 2, 1 \right\} \tag{3.1}$$

Sketch x(n).

Solution:

import numpy as np import matplotlib.pyplot as plt #If using termux import subprocess import shlex #end if

x=np.array([1.0,2.0,3.0,4.0,2.0,1.0])
k = 20
y = np.zeros(20)

#subplots
plt.subplot(2, 1, 1)
plt.stem(range(0,6),x)
plt.title('Digital Filter Input-Output')
plt.ylabel('\$x(n)\$')
plt.grid()# minor

3.2 Let

$$y(n) + \frac{1}{2}y(n-1) = x(n) + x(n-2),$$

$$y(n) = 0, n < 0 \quad (3.2)$$

Sketch y(n).

for termux

Solution: The following code yields Fig. 5.3.

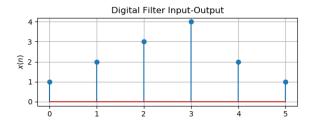


Fig. 3.1

```
import numpy as np
import matplotlib.pyplot as plt
#If using termux
#import subprocess
#import shlex
#end if
x=np.array([1.0,2.0,3.0,4.0,2.0,1.0])
k = 20
y = np.zeros(20)
y[0] = x[0]
y[1] = -0.5*y[0]+x[1]
for n in range(2,k-1):
        if n < 6:
                 y[n] = -0.5*y[n-1]+x[n]+x
                     [n-2]
        elif n > 5 and n < 8:
                 y[n] = -0.5*y[n-1]+x[n-2]
        else:
                 y[n] = -0.5*y[n-1]
print(y)
#subplots
plt.subplot(2, 1, 1)
plt.stem(range(0,6),x)
plt.title('Digital Filter Input-Output')
plt.ylabel('$x(n)$')
```

```
plt.grid()# minor

plt.subplot(2, 1, 2)
plt.stem(range(0,k),y)
plt.xlabel('$n$')
plt.ylabel('$y(n)$')
plt.grid()# minor

#If using termux

#else
```

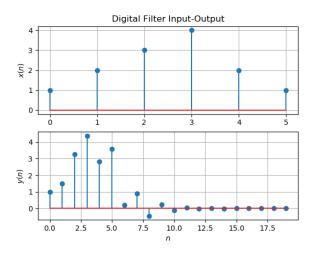


Fig. 3.2

3.3 Repeat the above exercise using a C code. **Solution:**

```
#include <stdio.h>

// A function which calculates y[i] takings
    array x and and i as parameters
float calculatey(int* p1,int n){
        int y=0;
        if(n==0){y =*p1;}
        else if(n==1){y=*(p1+1)+calculatey(
            p1,0);}
        else if(n<6){y = *(p1+n-1) + *(p1+
            n-3) - calculatey(p1,n-1)/2.0;}
        else {y = -calculatey(p1,n-1)/2.0;}
        return y;
}

int main(){
        FILE* fp;</pre>
```

For plotting the data we can use the python code below

```
import matplotlib.pyplot as plt
import numpy as np
y = np.loadtxt("y(n).dat",dtype = "double")
x = np.array([1,2,3,4,2,1])
# ploting graphs
plt.subplot(211)
plt.stem(np.arange(len(x)),x)
plt.xlabel("n")
plt.ylabel("$x(n)$")
plt.grid()
plt.subplot(212)
plt.stem(np.arange(len(y)),y)
plt.xlabel("n")
plt.ylabel("$y(n)$")
plt.grid()
plt.show()
```

4 Z-TRANSFORM

4.1 The Z-transform of x(n) is defined as

$$X(z) = \mathbb{Z}\{x(n)\} = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$
 (4.1)

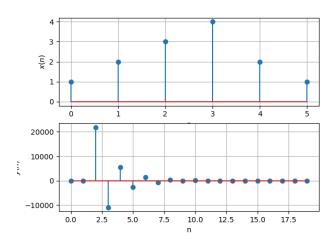


Fig. 3.3

Show that

$$Z{x(n-1)} = z^{-1}X(z)$$
 (4.2)

and find

$$\mathcal{Z}\{x(n-k)\}\tag{4.3}$$

Solution: From (4.1),

$$Z\{x(n-k)\} = \sum_{n=-\infty}^{\infty} x(n-1)z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} x(n)z^{-n-1} = z^{-1} \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$
(4.4)

resulting in (4.2). Similarly, it can be shown that

$$\mathcal{Z}\{x(n-k)\} = z^{-k}X(z) \tag{4.6}$$

4.2 Obtain X(z) for x(n) defined in problem 3.1. **Solution:**

Given that

$$x(n) = \left\{ 1, 2, 3, 4, 2, 1 \right\} \tag{4.7}$$

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$

$$= z^{-0} + 2z^{-1} + 3z^{-2} + 4z^{-3} + 2z^{-4} + 1z^{-5}$$

$$= 1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + 2z^{-4} + 1z^{-5}$$

$$(4.10)$$

4.3 Find

$$H(z) = \frac{Y(z)}{X(z)} \tag{4.11}$$

from (3.2) assuming that the Z-transform is a linear operation.

Solution: Applying (4.6) in (3.2),

$$Y(z) + \frac{1}{2}z^{-1}Y(z) = X(z) + z^{-2}X(z)$$
 (4.12)

$$\implies \frac{Y(z)}{X(z)} = \frac{1+z^{-2}}{1+\frac{1}{2}z^{-1}} \tag{4.13}$$

4.4 Find the Z transform of

$$\delta(n) = \begin{cases} 1 & n = 0 \\ 0 & \text{otherwise} \end{cases}$$
 (4.14)

and show that the Z-transform of

$$u(n) = \begin{cases} 1 & n \ge 0 \\ 0 & \text{otherwise} \end{cases}$$
 (4.15)

is

$$U(z) = \frac{1}{1 - z^{-1}}, \quad |z| > 1 \tag{4.16}$$

Solution: It is easy to show that

$$\delta(n) \stackrel{\mathcal{Z}}{\rightleftharpoons} 1 \tag{4.17}$$

and from (4.15),

$$U(z) = \sum_{n=0}^{\infty} z^{-n}$$
 (4.18)

$$= \frac{1}{1 - z^{-1}}, \quad |z| > 1 \tag{4.19}$$

using the fomula for the sum of an infinite geometric progression.

4.5 Show that

$$a^n u(n) \stackrel{\mathcal{Z}}{\rightleftharpoons} \frac{1}{1 - az^{-1}} \quad |z| > |a|$$
 (4.20)

Solution:

Given that,

$$f(n) = a^n u(n) \tag{4.21}$$

and u(n) is a unit step function.

Taking the Z transform of f(n) we get,

$$U(z) = \sum_{n = -\infty}^{\infty} a^n u(n) z^{-n}$$
 (4.22)

$$=\sum_{n=-\infty}^{\infty} a^n z^{-n} \tag{4.23}$$

$$= 1 + az^{-1} + a^2z^{-2} + \dots (4.24)$$

$$= \frac{1}{1 - az^{-1}}, \quad \left| az^{-1} \right| < 1 \tag{4.25}$$

$$= \frac{1}{1 - az^{-1}}, \quad |a| < |z| \tag{4.26}$$

4.6 Let

$$H(e^{j\omega}) = H(z = e^{j\omega}).$$
 (4.27)

Plot $|H(e^{j\omega})|$. Is it periodic? If so, find the period. $H(e^{j\omega})$ is known as the *Discret Time Fourier Transform* (DTFT) of x(n).

Solution: The following code plots Fig. 4.6.

import numpy as np import matplotlib.pyplot as plt

#DTFT

def H(z):

 $\begin{array}{l} num = np.polyval([1,0,1],z**(-1))\\ den = np.polyval([0.5,1],z**(-1))\\ H = num/den\\ return\ H \end{array}$

#Input and Output

omega = np.linspace(-3*np.pi,3*np.pi,1e2)

#subplots

plt.plot(omega, abs(H(np.exp(1j*omega))))
plt.title('Filter Frequency Response')
plt.xlabel('\$\omega\$')
plt.ylabel('\$|H(e^{\jmath\omega})| \$')
plt.grid()

plt.show()

We know that

$$H(z) = \frac{1 + z^{-2}}{1 + \frac{1}{2}z^{-1}}$$
 (4.28)

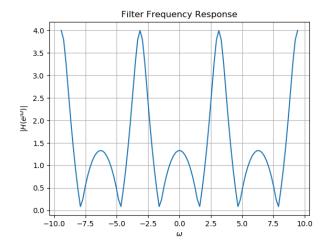


Fig. 4.6: $|H(e^{j\omega})|$

then,

$$H(e^{jw}) = \frac{1 + e^{-2jw}}{1 + \frac{1}{2}e^{-jw}}$$
(4.29)

$$=\frac{1+e^{2jw}}{e^{2jw}+\frac{1}{2}e^{jw}}\tag{4.30}$$

$$\implies \left| H(e^{jw}) \right| = \left| \frac{1 + e^{2jw}}{e^{2jw} + \frac{1}{2}e^{jw}} \right| \tag{4.31}$$

$$= \frac{\left|1 + e^{2jw}\right|}{\left|e^{2jw} + \frac{1}{2}e^{jw}\right|}$$
(4.32)
$$= \frac{\left|\cos 2w + 1 + 2j\sin w\right| * 2}{\left|e^{jw} + 1\right|}$$
(4.33)

$$=\frac{|cosw + jsinw| * 4cosw}{|2cosw + 1 + 2jsinw|}$$
(4.34)

$$= \frac{4\cos w}{\sqrt{(2\cos w + 1)^2 + 4\sin^2 w}}$$
(4.35)

$$=\frac{4\cos w}{\sqrt{5+4\cos w}}\tag{4.36}$$

Therefore

$$H(e^{jw}) = \frac{4\cos w}{\sqrt{5 + 4\cos w}} \tag{4.37}$$

Consider

$$f(x) = \frac{4\cos x}{\sqrt{5 + 4\cos x}} \tag{4.38}$$

then

$$f(x+t) = \frac{4\cos(x+t)}{\sqrt{5+4\cos(x+t)}}$$
 (4.39)

$$f(x+t) = \frac{4\cos(x+t)}{\sqrt{5+4\cos(x+t)}}$$
 (4.40)

$$f(x+t) = \frac{4\cos(x+t)}{\sqrt{5+4\cos(x+t)}}$$
(4.40)
=
$$\frac{4(\cos x \cos t - \sin x \sin t)}{\sqrt{5+4(\cos x \cos t - \sin x \sin t)}}$$
(4.41)

By comparing (4.38) and (4.39), we get cost=1 and sint=0

This is true for $t = 2k\pi$. This implies that the principal period of this function is 2π .

4.7 Express h(n) in terms of $H(e^{j\omega})$.

Solution: We know that

$$H(e^{j\omega}) = \sum_{n=-\infty}^{\infty} h(n) e^{-jn\omega}$$

$$\Rightarrow (e^{j\omega}) * e^{jk\omega} = \sum_{n=-\infty}^{\infty} h(n) e^{-jn\omega} e^{jk\omega}$$

$$(4.43)$$

$$\Rightarrow \int_{-\pi}^{\pi} H(e^{j\omega}) * e^{jk\omega} d\omega = \int_{-\pi}^{\pi} \sum_{n=-\infty}^{\infty} h(n) e^{-jn\omega} e^{jk\omega}$$

$$(4.44)$$

$$\Rightarrow \int_{-\pi}^{\pi} H(e^{j\omega}) * e^{jk\omega} d\omega = \sum_{n=-\infty}^{\infty} h(n) \int_{-\pi}^{\pi} e^{-jn\omega} e^{jk\omega}$$

$$(4.45)$$

NOTE: We know that,

$$\int_{-\pi}^{\pi} e^{-jn\omega} e^{jk\omega} = \begin{cases} 2\pi & n = k \\ 0 & \text{otherwise} \end{cases}$$
 (4.46)

Hence,

$$\int_{-\pi}^{\pi} H\left(e^{j\omega}\right) * e^{jk\omega} d\omega = \int_{-\pi}^{\pi} \sum_{n=-\infty}^{\infty} h\left(n\right) e^{-jn\omega} e^{jk\omega}$$

$$\iff \int_{-\pi}^{\pi} H\left(e^{j\omega}\right) * e^{jk\omega} d\omega = 2\pi h\left(n\right)$$

$$\iff \frac{1}{2\pi} \int_{-\pi}^{\pi} H\left(e^{j\omega}\right) * e^{jk\omega} d\omega = h\left(n\right)$$

$$\tag{4.48}$$

$$\iff \frac{1}{2\pi} \int_{-\pi}^{\pi} H\left(e^{j\omega}\right) * e^{jk\omega} d\omega = h\left(n\right)$$

$$\tag{4.49}$$

Therefore,

$$h(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H\left(e^{j\omega}\right) e^{j\omega n} d\omega \qquad (4.50)$$

5 IMPULSE RESPONSE

5.1 Using long division, find

$$h(n), \quad n < 5$$
 (5.1)

for H(z) in (4.13).

Solution:

$$H(z) = \frac{1 + z^{-2}}{1 + \frac{1}{2}z^{-1}}$$
 (5.2)

Let $z^{-1} = x$, then, by polynomial long division

$$\frac{2x-4}{x^2+1}$$

$$\frac{-x^2-2x}{-2x+1}$$

$$\frac{2x+4}{5}$$

$$\implies (1+z^{-2}) = (\frac{1}{2}z^{-1}+1)(2z^{-1}-4)+5$$

$$\implies \frac{(1+z^{-2})}{\frac{1}{2}z^{-1}+1} = (2z^{-1}-4)+\frac{5}{\frac{1}{2}z^{-1}+1}$$

$$(5.4)$$

$$\implies H(z) = (2z^{-1}-4)+\frac{5}{\frac{1}{2}z^{-1}+1}$$

$$(5.5)$$

Now, consider $\frac{5}{\frac{1}{2}z^{-1}+1}$

The denominator $\frac{1}{2}z^{-1} + 1$ can be expressed as sum of an infinite geometric progression, which as its first term equal to 1 and common ratio $\frac{-1}{2}z^{-1}$

we can write $\frac{5}{\frac{1}{3}z^{-1}+1}$ $5\left(1+\left(\frac{-1}{2}z^{-1}\right)+\left(\frac{-1}{2}z^{-1}\right)^{2}+\left(\frac{-1}{2}z^{-1}\right)^{3}+\left(\frac{-1}{2}z^{-1}\right)^{4}+\ldots\right)$ herefore, H(z) can be given by

$$H(z) = (2z^{-1} - 4) + \frac{5}{\frac{1}{2}z^{-1} + 1}$$
 (5.6)

$$= 2z^{-1} - 4 + 5 + \frac{-5}{2}z^{-1} + \frac{5}{4}z^{-2} + \frac{-5}{8}z^{-3} + \frac{5}{16}z^{-4} + .$$

$$\implies H(z) = 1z^{0} + \frac{-1}{2}z^{-1} + \frac{5}{4}z^{-2} + \frac{-5}{8}z^{-3} + \frac{5}{16}z^{-4} + .$$
(5.9)

Comparing the above expression to (4.1) we get h(n) for n<5 as,

$$h(0) = 1 (5.10)$$

$$h(1) = \frac{-1}{2} \tag{5.11}$$

$$h(2) = \frac{5}{4} \tag{5.12}$$

$$h(3) = \frac{-5}{8} \tag{5.13}$$

$$h(4) = \frac{5}{16} \tag{5.14}$$

5.2 Find an expression for h(n) using H(z), given that

$$h(n) \stackrel{\mathcal{Z}}{\rightleftharpoons} H(z) \tag{5.15}$$

and there is a one to one relationship between h(n) and H(z). h(n) is known as the *impulse response* of the system defined by (3.2).

Solution: From (4.13),

$$H(z) = \frac{1}{1 + \frac{1}{2}z^{-1}} + \frac{z^{-2}}{1 + \frac{1}{2}z^{-1}}$$
 (5.16)

$$\implies h(n) = \left(-\frac{1}{2}\right)^{n} u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2)$$
(5.17)

using (4.20) and (4.6).

5.3 Sketch h(n). Is it bounded? Justify theoretically.

Solution: The following code plots Fig. 5.3.

import numpy as np import matplotlib.pyplot as plt

n = np.arange(10)

fn=(-1/2)**n

hn1=np.pad(fn, (0,2), 'constant', constant values=(0))

hn2=np.pad(fn, (2,0), 'constant',

constant_values=(0))
plt.stem(np.arange(12), hn1+hn2)

plt.title('Filter Impulse Response')
plt.xlabel('\$n\$')
plt.ylabel('\$h(n)\$')

plt.grid()# minor

plt.show()

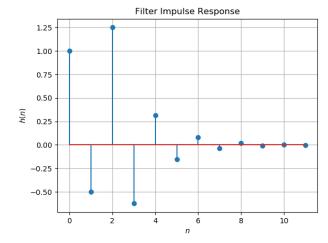


Fig. 5.3

From (5.17) we know that

$$h(n) = \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (5.18)$$

Implies we can write that

$$h(n) = \begin{cases} 0 & , n < 0 \\ \left(\frac{-1}{2}\right)^n & , 0 \le n < 2 \\ 5\left(\frac{-1}{2}\right)^n & , n \ge 2 \end{cases}$$
 (5.19)

A sequence is said to be bounded when

$$|x_n| \le M, \forall n \in \mathcal{N} \tag{5.20}$$

Now consider (5.19),

For n < 0,

$$|h(n)| \le 0 \tag{5.21}$$

For $0 \le n < 2$,

$$|h(n)| = (\frac{1}{2})^n$$
 (5.22)

$$\implies |h(n)| \le 1 \tag{5.23}$$

For $n \geq 2$,

$$|h(n)| = 5(\frac{1}{2})^n$$
 (5.24)

$$\implies |h(n)| \le 5 \tag{5.25}$$

From above we can say that,

$$M = \max\{0, 1, 5\} \tag{5.26}$$

$$= 5 \tag{5.27}$$

Therefore since M exists and is a real value, we can say that h(n) is bounded.

5.4 Convergent? Justify using the ratio test.

Solution:

We can check if a sequence os convergent by ratio test. From the defination of ratio test we can say that a sequence is convergent if

$$\lim_{n \to \infty} \left| \frac{x_{n+1}}{x_n} \right| < 1 \tag{5.28}$$

Here, applying ratio test on (5.17) is same as applying ratio test on (5.19)

$$\lim_{n \to \infty} \left| \frac{h(n+1)}{h(n)} \right| = \lim_{n \to \infty} \left| \frac{5(\frac{-1}{2})^{n+1}}{5(\frac{-1}{2})^n} \right|$$
 (5.29)

$$= \left| \frac{-1}{2} \right| \tag{5.30}$$

$$=\frac{1}{2}$$
 (5.31)

From (5.31) we can clearly say that the sequence h(n) is convergent.

5.5 The system with h(n) is defined to be stable if

$$\sum_{n=-\infty}^{\infty} h(n) < \infty \tag{5.32}$$

Is the system defined by (3.2) stable for the impulse response in (5.15)?

Solution:

From (5.17) we know that,

$$h(n) = \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (5.33)$$

Given that, a system is stable when

$$\sum_{n=-\infty}^{\infty} h(n) < \infty \tag{5.34}$$

$$\implies \sum_{n=-\infty}^{\infty} h(n) = \sum_{n=-\infty}^{\infty} \left(\left(-\frac{1}{2} \right)^n u(n) + \left(-\frac{1}{2} \right)^{n-2} u(n-2) \right)$$

$$= 2 * \sum_{n=-\infty}^{\infty} \left(-\frac{1}{2} \right)^n u(n)$$
(5.36)

$$\implies \sum_{n=-\infty}^{\infty} h(n) = 2 * \left(\frac{1}{1 + \frac{1}{2}}\right)$$
 (5.37)
$$= \frac{4}{2} < \infty$$
 (5.38)

Hence, the system is stable.

5.6 Verify the above result using a python code. **Solution:**

5.7 Compute and sketch h(n) using

$$h(n) + \frac{1}{2}h(n-1) = \delta(n) + \delta(n-2), \quad (5.39)$$

This is the definition of h(n).

Solution: The following code plots Fig. 5.7. Note that this is the same as Fig. ??.

import numpy as np import matplotlib.pyplot as plt k = 12h = np.zeros(k)

$$h[0] = 1$$

 $h[1] = -0.5*h[0]$
 $h[2] = -0.5*h[1] + 1$

for n in range(3,k-1): h[n] = -0.5*h[n-1]

```
#subplots
plt.stem(range(0,k),h)
plt.title('Impulse Response Definition')
plt.xlabel('$n$')
plt.ylabel('$h(n)$')
plt.grid()# minor

plt.show()
```

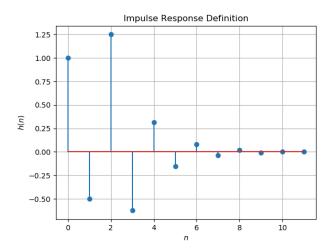


Fig. 5.7: h(n) from the definition

5.8 Compute

$$y(n) = x(n) * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k)$$
 (5.40)

Comment. The operation in (5.40) is known as *convolution*.

Solution: The following code plots Fig. 5.8. Note that this is the same as y(n) in Fig. 5.3.

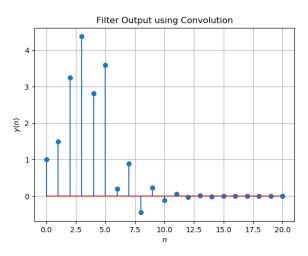


Fig. 5.8: y(n) from the definition of convolution

5.9 Express the above convolution using a Teoplitz matrix.

Solution:

We know that from, (5.40),

$$y(n) = x(n) * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k)$$
 (5.41)

This can also be wrtten as a matrix-vector multiplication given by the expression,

$$y = T(h) * x \tag{5.42}$$

In the equation (5.42), T(h) is a Teoplitz matrix.

The equation (5.42) can be expanded as,

$$\mathbf{y} = \mathbf{x} \otimes \mathbf{h}$$

$$\mathbf{y} = \begin{pmatrix} h_1 & 0 & . & . & . & 0 \\ h_2 & h_1 & . & . & . & 0 \\ h_3 & h_2 & h_1 & . & . & 0 \\ . & . & . & . & . & . & . \\ h_{n-1} & h_{n-2} & h_{n-3} & . & . & 0 \\ h_n & h_{n-1} & h_{n-2} & . & . & h_1 \\ 0 & h_n & h_{n-1} & h_{n-2} & . & h_2 \\ . & . & . & . & . & . & . \\ 0 & . & . & . & 0 & h_{n-1} \\ 0 & . & . & . & 0 & h_n \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ . \\ . \\ x_n \end{pmatrix}$$

$$(5.44)$$

5.10 Show that

$$y(n) = \sum_{n = -\infty}^{\infty} x(n - k)h(k)$$
 (5.45)

Solution:

From the defination of convolution given in (5.40), we know that,

$$y(n) = x(n) * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k)$$
 (5.46)

$$\implies y(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k) \qquad (5.47)$$

Replace k with n-k. Now since n varies from $n=-\infty$ to $n=\infty$, n-k will also vary from $-\infty$ to ∞ . Therefore, we get,

$$y(n) = \sum_{n-k=-\infty}^{\infty} x(n-k)h(k)$$
 (5.48)

$$=\sum_{k=-\infty}^{\infty}x(n-k)h(k)$$
 (5.49)

6 DFT

6.1 Compute

$$X(k) \stackrel{\triangle}{=} \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1$$
(6.1)

and H(k) using h(n).

Solution:

From 3.1, we know that,

$$x(n) = \left\{ 1, 2, 3, 4, 2, 1 \right\} \tag{6.2}$$

Here, let, $\omega = e^{-j2\pi k}$. Then,

$$X(k) = 1 + 2\omega^{\frac{1}{5}} + 3\omega^{\frac{2}{5}} + 4\omega^{\frac{3}{5}} + 2\omega^{\frac{4}{5}} + \omega$$
(6.3)

Similarly, we know from (5.19),

$$h(n) = \begin{cases} 0 & , n < 0 \\ \left(\frac{-1}{2}\right)^n & , 0 \le n < 2 \\ 5\left(\frac{-1}{2}\right)^n & , n \ge 2 \end{cases}$$
 (6.4)

Now, again let, $\omega = e^{-j2\pi k}$. Then,

$$H(k) = 1 + \frac{-1}{2}\omega^{\frac{1}{5}} + \frac{5}{4}\omega^{\frac{2}{5}} + \frac{-5}{8}\omega^{\frac{3}{5}} + \frac{5}{16}\omega^{\frac{4}{5}} + \frac{-5}{32}\omega$$
(6.5)

6.2 Compute

$$Y(k) = X(k)H(k) \tag{6.6}$$

Solution:

Now, from (6.3) and (6.5), we know X(k) and H(k). Now, given that,

$$Y(k) = X(k) * H(k)$$
 (6.7)

$$Y(k) = (1 + 2\omega^{\frac{1}{5}} + 3\omega^{\frac{2}{5}} + 4\omega^{\frac{3}{5}} + 2\omega^{\frac{4}{5}} + \omega)*$$

$$(1 + \frac{-1}{2}\omega^{\frac{1}{5}} + \frac{5}{4}\omega^{\frac{2}{5}} + \frac{-5}{8}\omega^{\frac{3}{5}} + \frac{5}{16}\omega^{\frac{4}{5}} + \frac{-5}{32}\omega)$$
(6.8)

$$Y(k) = 1 + \frac{3}{2}\omega^{\frac{1}{5}} + \frac{13}{4}\omega^{\frac{2}{5}} + \frac{35}{8}\omega^{\frac{3}{5}} + \frac{45}{16}\omega^{\frac{4}{5}}$$
$$\frac{115}{32}\omega^{\frac{5}{5}} + \frac{1}{8}\omega^{\frac{6}{5}} + \frac{25}{32}\omega^{\frac{7}{5}} - \frac{5}{8}\omega^{\frac{8}{5}}$$
$$-\frac{5}{32}\omega^{2} \quad (6.9)$$

where, $\omega = e^{-j2k\pi}$

6.3 Compute

$$y(n) = \frac{1}{N} \sum_{k=0}^{N-1} Y(k) \cdot e^{j2\pi kn/N}, \quad n = 0, 1, \dots, N-1$$
(6.10)

Solution: The following code plots Fig. 5.8. Note that this is the same as y(n) in Fig. 5.3.

import numpy as np import matplotlib.pyplot as plt import scipy

```
N = 11
def x(n):
    if n < 0 or n > 5:
        return 0
    elif n < 4:
        return n + 1
    else:
        return 6 – n
def y(n):
    if n < 0:
        return 0
    else:
        return x(n) + x(n-2) - 0.5 * y(n-1)
def delta(n):
    if n == 0:
        return 1
    else:
        return 0
def h(n):
    if n == 0:
        return 1
    elif n > 0:
        return delta(n) + delta(n-2) - 0.5*h(
            n-1
    else:
        return 2*(delta(n+1) + delta(n-1) -
            h(n+1)
def DFT(k, inp):
    ksum = 0
    for n in range(N):
        ksum += inp(n) * np.exp(-2j * np.
            pi * k * n / N
    return ksum
def Y(k):
    return DFT(k, x) * DFT(k, h)
def IDFT(n, inp):
    nsum = 0
    for k in range(N):
        nsum += inp(k) * np.exp(2j * np.pi
            * k * n / N
    return nsum / N
vec y = scipy.vectorize(y)
```

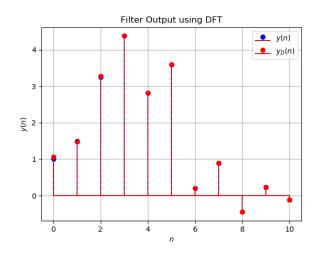


Fig. 6.3: y(n) from the DFT

6.4 Repeat the previous exercise by computing X(k), H(k) and y(n) through FFT and IFFT. **Solution:**

```
import numpy as np
import matplotlib.pyplot as plt
import scipy

N = 11

def x(n):
    if n < 0 or n > 5:
        return 0
    elif n < 4:
        return n + 1
    else:
        return 6 - n

def y(n):</pre>
```

```
if n < 0:
         return 0
    else:
         return x(n) + x(n-2) - 0.5 * y(n-1)
vec y = scipy.vectorize(y, otypes=[float])
def delta(n):
    if n == 0:
         return 1
    else:
         return 0
def h(n):
    if n == 0:
         return 1
    elif n > 0:
         return delta(n) + delta(n-2) - 0.5*h(
             n-1
    else:
         return 2*(delta(n+1) + delta(n-1) -
             h(n+1)
x vec = scipy.vectorize(x, otypes=[float])
h vec = scipy.vectorize(h, otypes=[float])
n \text{ arr} = np.linspace(0, N-1, N)
x 	ext{ arr} = x 	ext{ vec(n arr)}
h \ arr = h \ vec(n \ arr)
# FFT
X 	ext{ arr} = np.fft.fft(x 	ext{ arr})
H arr = np.fft.fft(h arr)
Y \text{ arr} = X \text{ arr} * H \text{ arr}
y = np.fft.ifft(Y = arr)
# DFT
def DFT(k, inp):
    ksum = 0
    for n in range(N):
         ksum += inp(n) * np.exp(-2j * np.
             pi * k * n / N
    return ksum
def Y(k):
    return DFT(k, x) * DFT(k, h)
def IDFT(n, inp):
    nsum = 0
    for k in range(N):
```

```
nsum \mathrel{+=} inp(k) * np.exp(2j * np.pi \\ * k * n / N) \\ return nsum / N \\ \\ plt.stem(n\_arr, vec\_y(n\_arr), markerfmt=' \\ bo', label='$y(n)$') \\ plt.stem(n\_arr, np.real(IDFT(n\_arr, Y)), \\ markerfmt='go', label='$y\_D(n)$') \\ plt.stem(n\_arr, np.real(y\_arr), markerfmt='ro \\ ', label='$y\_F(n)$') \\ plt.title('Filter Output using FFT') \\ plt.ylabel('$y(n)$') \\ plt.xlabel('$n$') \\ plt.grid() \\ plt.legend() \\ plt.show() \\ \\ }
```

This code gives the below figure

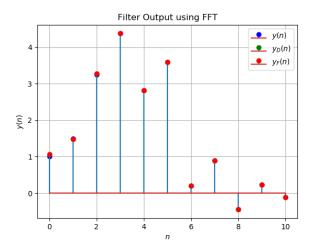


Fig. 6.4: y(n) from different techniques

6.5 Wherever possible, express all the above equations as matrix equations.

Solution:

We use the DFT Matrix, where $\omega = e^{-\frac{j2k\pi}{N}}$, which is given by

$$\mathbf{W} = \begin{pmatrix} \omega^0 & \omega^0 & \dots & \omega^0 \\ \omega^0 & \omega^1 & \dots & \omega^{N-1} \\ \vdots & \vdots & \ddots & \vdots \\ \omega^0 & \omega^{N-1} & \dots & \omega^{(N-1)(N-1)} \end{pmatrix}$$
(6.11)

i.e. $W_{jk} = \omega^{jk}$, $0 \le j, k < N$. Hence, we can write any DFT equation as

$$\mathbf{X} = \mathbf{W}\mathbf{x} = \mathbf{x}\mathbf{W} \tag{6.12}$$

where

$$\mathbf{x} = \begin{pmatrix} x(0) \\ x(1) \\ \vdots \\ x(n-1) \end{pmatrix}$$
 (6.13)

The inverse Fourier Transform is given by

$$\mathbf{x} = \mathcal{F}^{-1}(\mathbf{X}) = \mathbf{W}^{-1}\mathbf{X} = \frac{1}{N}\mathbf{W}^{\mathbf{H}}\mathbf{X} = \frac{1}{N}\mathbf{X}\mathbf{W}^{\mathbf{H}}$$
(6.14)

$$\implies \mathbf{W}^{-1} = \frac{1}{N} \mathbf{W}^{\mathbf{H}} \tag{6.15}$$

where H denotes hermitian operator. We can rewrite (6.6) using the element-wise multiplication operator as

$$\mathbf{Y} = \mathbf{H} \cdot \mathbf{X} = (\mathbf{W}\mathbf{h}) \cdot (\mathbf{W}\mathbf{x}) \tag{6.16}$$

6.6 Verify the above equations by generating the DFT matrix in python.

Solution:

The following code gives the figure

import numpy as np from numpy.fft import fft, ifft import matplotlib.pyplot as plt

N = 14

n = np.arange(N)

fn=(-1/2)**n

hn1=np.pad(fn, (0,2), 'constant',

 $constant_values=(0,0))$

hn2=np.pad(fn, (2,0), 'constant',

 $constant_values=(0,0)$

h = hn1 + hn2

xtemp=np.array([1.0,2.0,3.0,4.0,2.0,1.0])

x=np.pad(xtemp, (0,10), 'constant',

constant values=(0)

dftmtx = fft(np.eye(len(x)))

X = x@dftmtx

H = h@dftmtx

Y = H*X

invmtx = np.linalg.inv(dftmtx)

y = (Y@invmtx).real

#plots

plt.stem(range(0,16),y)

plt.title('\$y(n)\$ from DFT Matrix')

plt.xlabel('\$n\$')

plt.ylabel('\$y(n)\$')

plt.grid() plt.show()

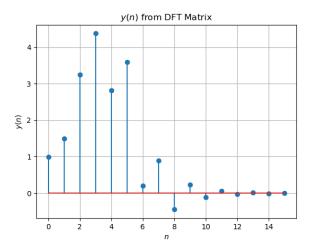


Fig. 6.6: y(n) from DFT Matrix

We can see that the Fig. 6.6 is same as in Fig 5.3 i am here

7 FFT

1. The DFT of x(n) is given by

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1$$
(7.1)

2. Let

$$W_N = e^{-j2\pi/N} \tag{7.2}$$

Then the N-point DFT matrix is defined as

$$\mathbf{F}_N = [W_N^{mn}], \quad 0 \le m, n \le N - 1$$
 (7.3)

where W_N^{mn} are the elements of \mathbf{F}_N .

3. Let

$$\mathbf{I}_4 = \begin{pmatrix} \mathbf{e}_4^1 & \mathbf{e}_4^2 & \mathbf{e}_4^3 & \mathbf{e}_4^4 \end{pmatrix} \tag{7.4}$$

be the 4×4 identity matrix. Then the 4 point *DFT permutation matrix* is defined as

$$\mathbf{P}_4 = \begin{pmatrix} \mathbf{e}_4^1 & \mathbf{e}_4^3 & \mathbf{e}_4^2 & \mathbf{e}_4^4 \end{pmatrix} \tag{7.5}$$

4. The 4 point *DFT diagonal matrix* is defined as

$$\mathbf{D}_4 = diag \begin{pmatrix} W_4^0 & W_N^1 & W_N^2 & W_N^3 \end{pmatrix}$$
 (7.6)

5. Show that

$$W_N^2 = W_{N/2} (7.7)$$

Solution: We write

$$W_N^2 = \left(e^{-\frac{j2\pi}{N}}\right)^2 = e^{-\frac{j2\pi}{N/2}} = W_{N/2}$$
 (7.8)

6. Show that

$$\mathbf{F}_4 = \begin{bmatrix} \mathbf{I}_2 & \mathbf{D}_2 \\ \mathbf{I}_2 & -\mathbf{D}_2 \end{bmatrix} \begin{bmatrix} \mathbf{F}_2 & 0 \\ 0 & \mathbf{F}_2 \end{bmatrix} \mathbf{P}_4 \tag{7.9}$$

Solution: Observe that for $n \in \mathbb{N}$, $W_4^{4n} = 1$ and $W_4^{4n+2} = -1$. Using (7.7),

$$\mathbf{D}_{2}\mathbf{F}_{2} = \begin{bmatrix} W_{4}^{0} & 0 \\ 0 & W_{4}^{1} \end{bmatrix} \begin{bmatrix} W_{2}^{0} & W_{2}^{0} \\ W_{2}^{0} & W_{2}^{1} \end{bmatrix} \quad (7.10)$$
$$= \begin{bmatrix} W_{4}^{0} & 0 \\ 0 & W_{4}^{1} \end{bmatrix} \begin{bmatrix} W_{4}^{0} & W_{4}^{0} \\ W_{4}^{0} & W_{4}^{2} \end{bmatrix} \quad (7.11)$$

$$= \begin{bmatrix} W_4^0 & W_4^0 \\ W_4^1 & W_4^3 \end{bmatrix} \tag{7.12}$$

$$\Longrightarrow -\mathbf{D}_2 \mathbf{F}_2 = \begin{bmatrix} W_4^2 & W_4^6 \\ W_4^3 & W_4^9 \end{bmatrix} \tag{7.13}$$

and

$$\mathbf{F}_2 = \begin{pmatrix} W_2^0 & W_2^0 \\ W_2^0 & W_2^1 \end{pmatrix} \tag{7.14}$$

$$= \begin{pmatrix} W_4^0 & W_4^0 \\ W_4^0 & W_4^2 \end{pmatrix} \tag{7.15}$$

Hence,

$$\mathbf{W}_{4} = \begin{pmatrix} W_{4}^{0} & W_{4}^{0} & W_{4}^{0} & W_{4}^{0} \\ W_{4}^{0} & W_{4}^{2} & W_{4}^{1} & W_{4}^{3} \\ W_{4}^{0} & W_{4}^{4} & W_{4}^{2} & W_{4}^{6} \\ W_{4}^{0} & W_{4}^{6} & W_{4}^{3} & W_{4}^{9} \end{pmatrix}$$
(7.16)

$$= \begin{bmatrix} \mathbf{I}_2 \mathbf{F}_2 & \mathbf{D}_2 F_2 \\ \mathbf{I}_2 \mathbf{F}_2 & -\mathbf{D}_2 F_2 \end{bmatrix}$$
 (7.17)

$$= \begin{bmatrix} \mathbf{I}_2 & \mathbf{D}_2 \\ \mathbf{I}_2 & \mathbf{D}_2 \end{bmatrix} \begin{bmatrix} \mathbf{F}_2 & 0 \\ 0 & \mathbf{F}_2 \end{bmatrix}$$
 (7.18)

Multiplying (7.18) by \mathbf{P}_4 on both sides, and noting that $\mathbf{W}_4\mathbf{P}_4 = \mathbf{F}_4$ gives us.

7. Show that

$$\mathbf{F}_{N} = \begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix} \mathbf{P}_{N} \quad (7.19)$$

Solution: Observe that for even N and letting \mathbf{f}_N^i denote the i^{th} column of \mathbf{F}_N , from (7.12) and (7.13),

$$\begin{pmatrix} \mathbf{D}_{N/2} \mathbf{F}_{N/2} \\ -\mathbf{D}_{N/2} \mathbf{F}_{N/2} \end{pmatrix} = \begin{pmatrix} \mathbf{f}_{N}^{2} & \mathbf{f}_{N}^{4} & \dots & \mathbf{f}_{N}^{N} \end{pmatrix}$$
(7.20)

and

$$\begin{pmatrix} \mathbf{I}_{N/2} \mathbf{F}_{N/2} \\ \mathbf{I}_{N/2} \mathbf{F}_{N/2} \end{pmatrix} = \begin{pmatrix} \mathbf{f}_{N}^{1} & \mathbf{f}_{N}^{3} & \dots & \mathbf{f}_{N}^{N-1} \end{pmatrix}$$
(7.21)

Thus,

$$\begin{bmatrix} \mathbf{I}_{2}\mathbf{F}_{2} & \mathbf{D}_{2}\mathbf{F}_{2} \\ \mathbf{I}_{2}\mathbf{F}_{2} & -\mathbf{D}_{2}\mathbf{F}_{2} \end{bmatrix} = \begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix}$$
$$= \begin{pmatrix} \mathbf{f}_{N}^{1} & \dots & \mathbf{f}_{N}^{N-1} & \mathbf{f}_{N}^{2} & \dots & \mathbf{f}_{N}^{N} \end{pmatrix}$$
(7.22)

and so,

$$\begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix} \mathbf{P}_{N}$$
$$= \begin{pmatrix} \mathbf{f}_{N}^{1} & \mathbf{f}_{N}^{2} & \dots & \mathbf{f}_{N}^{N} \end{pmatrix} = \mathbf{F}_{N}$$
(7.23)

8. Find

$$\mathbf{P}_4\mathbf{x} \tag{7.24}$$

Solution: We have,

$$\mathbf{P}_{4}\mathbf{x} = \begin{pmatrix} \mathbf{e}_{4}^{1} & \mathbf{e}_{4}^{3} & \mathbf{e}_{4}^{2} & \mathbf{e}_{4}^{4} \end{pmatrix} \begin{pmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \end{pmatrix} = \begin{pmatrix} x(0) \\ x(2) \\ x(1) \\ x(3) \end{pmatrix} (7.25)$$

9. Show that

$$\mathbf{X} = \mathbf{F}_N \mathbf{x} \tag{7.26}$$

where \mathbf{x}, \mathbf{X} are the vector representations of x(n), X(k) respectively.

Solution: Writing the terms of X,

$$X(0) = x(0) + x(1) + \ldots + x(N-1)$$
(7.27)

$$X(1) = x(0) + x(1)e^{-\frac{1^{2\pi}}{N}} + \dots + x(N-1)e^{-\frac{1^{2(N-1)\pi}}{N}}$$
(7.28)

:

$$X(N-1) = x(0) + x(1)e^{-\frac{12(N-1)\pi}{N}} + \dots + x(N-1)e^{-\frac{12(N-1)(N-1)\pi}{N}}$$
(7.29)

Clearly, the term in the m^{th} row and n^{th} column is given by $(0 \le m \le N - 1)$ and $0 \le n \le N - 1)$

$$T_{mn} = x(n)e^{-\frac{12mn\pi}{N}} (7.30)$$

and so, we can represent each of these terms as a matrix product

$$\mathbf{X} = \mathbf{F}_N \mathbf{x} \tag{7.31}$$

where
$$\mathbf{F}_N = \left[e^{-\frac{-j2mn\pi}{N}}\right]_{mn}$$
 for $0 \le m \le N-1$ and $0 \le n \le N-1$.

10. Derive the following Step-by-step visualisation of 8-point FFTs into 4-point FFTs and so on

$$\begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix} = \begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_1(3) \end{bmatrix} + \begin{bmatrix} W_8^0 & 0 & 0 & 0 \\ 0 & W_8^1 & 0 & 0 \\ 0 & 0 & W_8^2 & 0 \\ 0 & 0 & 0 & W_8^3 \end{bmatrix} \begin{bmatrix} X_2(0) \\ X_2(1) \\ X_2(2) \\ X_2(3) \end{bmatrix}$$

$$\begin{bmatrix} X(4) \\ X(5) \\ X(6) \\ X(7) \end{bmatrix} = \begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_1(3) \end{bmatrix} - \begin{bmatrix} W_8^0 & 0 & 0 & 0 \\ 0 & W_8^1 & 0 & 0 \\ 0 & 0 & W_8^2 & 0 \\ 0 & 0 & 0 & W_8^3 \end{bmatrix} \begin{bmatrix} X_2(0) \\ X_2(1) \\ X_2(2) \\ X_2(3) \end{bmatrix}$$

$$(7.32)$$

$$\begin{bmatrix} X(4) \\ X(5) \\ X(7) \end{bmatrix} = \begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_1(3) \end{bmatrix} - \begin{bmatrix} W_8^0 & 0 & 0 & 0 \\ 0 & W_8^1 & 0 & 0 \\ 0 & 0 & W_8^2 & 0 \\ 0 & 0 & 0 & W_8^3 \end{bmatrix} \begin{bmatrix} X_2(0) \\ X_2(1) \\ X_2(2) \\ X_2(3) \end{bmatrix}$$

$$(7.33)$$

4-point FFTs into 2-point FFTs

$$\begin{vmatrix} X_1(0) \\ X_1(1) \end{vmatrix} = \begin{vmatrix} X_3(0) \\ X_3(1) \end{vmatrix} + \begin{vmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{vmatrix} \begin{vmatrix} X_4(0) \\ X_4(1) \end{vmatrix}$$
 (7.34)

$$\begin{bmatrix} X_1(2) \\ X_1(3) \end{bmatrix} = \begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} - \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix}$$
 (7.35)

$$\begin{bmatrix} X_2(0) \\ X_2(1) \end{bmatrix} = \begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} + \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix}$$
 (7.36)

$$\begin{bmatrix} X_2(2) \\ X_2(3) \end{bmatrix} = \begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} - \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix}$$
 (7.37)

$$P_{8} \begin{bmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \\ x(4) \\ x(5) \\ x(6) \\ x(7) \end{bmatrix} = \begin{bmatrix} x(0) \\ x(2) \\ x(4) \\ x(6) \\ x(1) \\ x(3) \\ x(5) \\ x(7) \end{bmatrix}$$
 (7.38)

$$P_{4} \begin{bmatrix} x(0) \\ x(2) \\ x(4) \\ x(6) \end{bmatrix} = \begin{bmatrix} x(0) \\ x(4) \\ x(2) \\ x(6) \end{bmatrix}$$
 (7.39)

$$P_{4} \begin{bmatrix} x(1) \\ x(3) \\ x(5) \\ x(7) \end{bmatrix} = \begin{bmatrix} x(1) \\ x(5) \\ x(3) \\ x(7) \end{bmatrix}$$
 (7.40)

Therefore,

$$\begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} = F_2 \begin{bmatrix} x(0) \\ x(4) \end{bmatrix}$$
 (7.41)

$$\begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} = F_2 \begin{bmatrix} x(2) \\ x(6) \end{bmatrix}$$
 (7.42)

$$\begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} = F_2 \begin{bmatrix} x(1) \\ x(5) \end{bmatrix}$$
 (7.43)

$$\begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} = F_2 \begin{bmatrix} x(3) \\ x(7) \end{bmatrix}$$
 (7.44)

Solution: We write out the values of performing an 8-point FFT on \mathbf{x} as follows.

$$X(k) = \sum_{n=0}^{7} x(n)e^{-\frac{12kn\pi}{8}}$$

$$= \sum_{n=0}^{3} \left(x(2n)e^{-\frac{12kn\pi}{4}} + e^{-\frac{12k\pi}{8}}x(2n+1)e^{-\frac{12kn\pi}{4}} \right)$$
(7.45)

$$= X_1(k) + e^{-\frac{12k\pi}{4}} X_2(k) \tag{7.47}$$

where X_1 is the 4-point FFT of the evennumbered terms and X_2 is the 4-point FFT of the odd numbered terms. Noticing that for $k \ge 4$,

$$X_1(k) = X_1(k-4) \tag{7.48}$$

$$e^{-\frac{j2k\pi}{8}} = -e^{-\frac{j2(k-4)\pi}{8}} \tag{7.49}$$

we can now write out X(k) in matrix form as in (??) and (??). We also need to solve the two 4-point FFT terms so formed.

$$X_{1}(k) = \sum_{n=0}^{3} x_{1}(n)e^{-\frac{12kn\pi}{8}}$$

$$= \sum_{n=0}^{1} \left(x_{1}(2n)e^{-\frac{12kn\pi}{4}} + e^{-\frac{12k\pi}{8}} x_{2}(2n+1)e^{-\frac{12kn\pi}{4}} \right)$$

$$(7.51)$$

$$= X_3(k) + e^{-\frac{12k\pi}{4}} X_4(k) \tag{7.52}$$

using $x_1(n) = x(2n)$ and $x_2(n) = x(2n+1)$. Thus we can write the 2-point FFTs

$$\begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} = F_2 \begin{bmatrix} x(2) \\ x(6) \end{bmatrix}$$
 (7.54)

Using a similar idea for the terms X_2 ,

$$\begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} = F_2 \begin{bmatrix} x(1) \\ x(5) \end{bmatrix}$$
 (7.55)

$$\begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} = F_2 \begin{bmatrix} x(3) \\ x(7) \end{bmatrix}$$
 (7.56)

But observe that from (7.25),

$$\mathbf{P}_{8}\mathbf{x} = \begin{pmatrix} \mathbf{x}_{1} \\ \mathbf{x}_{2} \end{pmatrix} \tag{7.57}$$

$$\mathbf{P}_4 \mathbf{x}_1 = \begin{pmatrix} \mathbf{x}_3 \\ \mathbf{x}_4 \end{pmatrix} \tag{7.58}$$

$$\mathbf{P}_4 \mathbf{x}_2 = \begin{pmatrix} \mathbf{x}_5 \\ \mathbf{x}_6 \end{pmatrix} \tag{7.59}$$

where we define $x_3(k) = x(4k)$, $x_4(k) = x(4k + 2)$, $x_5(k) = x(4k + 1)$, and $x_6(k) = x(4k + 3)$ for k = 0, 1.

11. For

$$\mathbf{x} = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 2 \\ 1 \end{pmatrix} \tag{7.60}$$

compte the DFT using (7.26)

Solution:

The code below gives the answer

import numpy as np from numpy.fft import fft, ifft import matplotlib.pyplot as plt x=np.array([1.0,2.0,3.0,4.0,2.0,1.0])

dftmtx = fft(np.eye(len(x))) X = x@dftmtx print(X)

- 12. Repeat the above exercise using the FFT after zero padding **x**.
- 13. Write a C program to compute the 8-point FFT.

Solution:

```
#include <stdio.h>
#include <stdbool.h>
#include <math.h>
#include <stdlib.h>
#include <complex.h>
```

```
#include <time.h>
#define EPS 1e-6
complex *myfft(int n, complex *a) {
        if (n == 1) return a;
         complex *g = (complex *)malloc(n
             /2*sizeof(complex));
         complex *h = (complex *)malloc(n
             /2*sizeof(complex));
         for (int i = 0; i < n; i++) {
                 if (i\%2) h[i/2] = a[i];
                 else g[i/2] = a[i];
         g = myfft(n/2, g);
         h = myfft(n/2, h);
         for (int i = 0; i < n; i++) a[i] = g[i]
             %(n/2)] + cexp(-I*2*M PI*i/n)
             *h[i\%(n/2)];
         free(g); free(h);
         return a;
int main() {
        int n = 8:
         complex *a = (complex *)malloc(
             sizeof(complex)*n);
         a[0] = 1.0, a[1] = 2.0, a[2] = 3.0, a
             [3] = 4.0, a[4] = 2.0, a[5] = 1.0,
              a[6] = 0.0, a[7] = 0.0;
         a = myfft(n, a);
         for (int i = 0; i < n; i++) printf("X
             (\%d) = \%lf + \%lfj\n", i, creal(a
             [i]), cimag(a[i]));
         free(a);
         return 0;
```

14. Analyze the time complexities of DFT and FFT routines **Solution:**

8 Exercises

Answer the following questions by looking at the python code in Problem 2.3.

8.1 The command

```
output_signal = signal.lfilter(b, a,
    input_signal)
```

in Problem 2.3 is executed through the following difference equation

$$\sum_{m=0}^{M} a(m) y(n-m) = \sum_{k=0}^{N} b(k) x(n-k) \quad (8.1)$$

where the input signal is x(n) and the output signal is y(n) with initial values all 0. Replace **signal.filtfilt** with your own routine and verify. **Solution:**

```
import soundfile as sf
from scipy import signal, fft
import numpy as np
from numpy.polynomial import Polynomial
from matplotlib import pyplot as plt
def myfiltfilt(b, a, input signal):
    X = fft.fft(input signal)
    w = np.linspace(0, 1, len(X) + 1)
    W = np.exp(2i*np.pi*w[:-1])
    B = (np.absolute(np.polyval(b,W)))**2
    A = (np.absolute(np.polyval(a,W)))**2
    Y = B*(1/A)*X
    return fft.ifft(Y).real
#read .wav file
input signal,fs = sf.read('Sound Noise.wav
    ')
#sampling frequency of Input signal
sampl freq=fs
#order of the filter
order=4
#cutoff frquency 4kHz
cutoff freq=4000.0
#digital frequency
Wn=2*cutoff freq/sampl freq
# b and a are numerator and denominator
    polynomials respectively
b, a = signal.butter(order, Wn, 'low')
#filter the input signal with butterworth filter
```

output signal = signal.filtfilt(b, a,

input signal)

8.2 Repeat all the exercises in the previous sections for the above *a* and *b*.

Solution:

For the given values, the difference equation is

$$y(n) - (4.44) y(n-1) + (8.78) y(n-2)$$

$$- (9.93) y(n-3) + (6.90) y(n-4)$$

$$- (2.93) y(n-5) + (0.70) y(n-6)$$

$$- (0.07) y(n-7) = (5.02 \times 10^{-5}) x(n)$$

$$+ (3.52 \times 10^{-4}) x(n-1) + (1.05 \times 10^{-3}) x(n-2)$$

$$+ (1.76 \times 10^{-3}) x(n-3) + (1.76 \times 10^{-3}) x(n-4)$$

$$+ (1.05 \times 10^{-3}) x(n-5) + (3.52 \times 10^{-4}) x(n-6)$$

$$+ (5.02 \times 10^{-5}) x(n-7)$$
(8.2)

From (8.1), we see that the transfer function can be written as follows

$$H(z) = \frac{\sum_{k=0}^{N} b(k)z^{-k}}{\sum_{k=0}^{M} a(k)z^{-k}}$$

$$= \sum_{i} \frac{r(i)}{1 - p(i)z^{-1}} + \sum_{j} k(j)z^{-j}$$
 (8.4)

where r(i), p(i), are called residues and poles respectively of the partial fraction expansion of H(z). k(i) are the coefficients of the direct polynomial terms that might be left over. We can now take the inverse z-transform of (8.4) and get using (4.20),

$$h(n) = \sum_{i} r(i)[p(i)]^{n} u(n) + \sum_{j} k(j)\delta(n-j)$$
(8.5)

Substituting the values,

```
h(n) = [(2.76)(0.55)^n]
+(-1.05-1.841)(0.57+0.161)^n
+(-1.05+1.841)(0.57-0.161)^n
+(-0.53+0.081)(0.63+0.321)^n
+(-0.53-0.081)(0.63-0.321)^n
+(0.20+0.004_1)(0.75+0.47_1)^n
+(0.20-0.004_1)(0.75-0.47_1)^n u(n)
+ \left(-6.81 \times 10^{-4}\right) \delta(n)
                                      (8.6)
```

The values r(i), p(i), k(i) and thus the impulse response function are computed and plotted at

```
import soundfile as sf
import matplotlib.pyplot as plt
from scipy import signal
from scipy import vectorize as vec
import numpy as np
#read .wav file
input signal,fs = sf.read('/home/saqib/iith/
    courseWork/sem5/EE3900/filter/codes/
    Sound Noise.wav')
#sampling frequency of Input signal
sampl freq=fs
#order of the filter
order=7
#cutoff frquency 4kHz
cutoff freq=4000.0
#digital frequency
Wn=2*cutoff freq/sampl freq
# b and a are numerator and denominator
    polynomials respectively
b, a = signal.butter(order, Wn, 'low')
# get partial fraction expansion
r, p, k = signal.residuez(b, a)
#number of terms of the impulse response
sz = 50
sz lin = np.arange(sz)
def rp(x):
```

```
return r@(p**x).T
rp vec = vec(rp, otypes=['double'])
h1 = rp \ vec(sz \ lin)
k add = np.pad(k, (0, sz - len(k)), 'constant
    ', constant values=(0,0))
h = h1 + k add
plt.stem(sz lin, h)
plt.xlabel('n')
plt.ylabel('h(n)')
plt.grid()
plt.plot()
plt.show()
```

The filter frequency response is plotted at

```
import numpy as np
import matplotlib.pyplot as plt
from scipy import signal
import soundfile as sf
input signal,fs = sf.read('/home/saqib/iith/
   courseWork/sem5/EE3900/filter/codes/
   Sound Noise.wav')
sampl freq=fs
order=4
cutoff freq=4000.0
Wn=2*cutoff freq/sampl freq
b, a = signal.butter(order, Wn, 'low')
def H(z):
        num = np.polyval(b,z**(-1))
        den = np.polyval(a,z**(-1))
        H = num/den
        return H
omega = np.linspace(0,np.pi,100)
plt.plot(omega, abs(H(np.exp(1j*omega))))
plt.xlabel('$\omega$')
plt.ylabel('$|H(e^{\imath\omega})| $')
plt.grid()
```

plt.show()

Observe that for a series $t_n = r^n$, $\frac{t_{n+1}}{t_n} = r$. By the ratio test, t_n converges if |r| < 1. We note that observe that |p(i)| < 1 and so, as h(n) is the sum of convergent series, we see that h(n) converges. From Fig. (8.2), it is clear that h(n) is bounded. From (4.1),

$$\sum_{n=0}^{\infty} h(n) = H(1) = 1 < \infty$$
 (8.7)

Therefore, the system is stable. From h(n) is negligible after $n \ge 64$, and we can apply a 64-bit FFT to get y(n). The following code uses the DFT matrix to generate y(n).

```
import soundfile as sf
import matplotlib.pyplot as plt
from scipy import signal
from scipy import vectorize as vec
import numpy as np
input signal,fs = sf.read('codes/
    Sound Noise.wav')
sampl freq=fs
order=7
cutoff freq=4000.0
Wn=2*cutoff freq/sampl freq
# b and a are numerator and denominator
    polynomials respectively
b, a = signal.butter(order, Wn, 'low')
output signal = signal.filtfilt(b, a,
    input signal)
# get partial fraction expansion
r, p, k = signal.residuez(b, a)
#number of terms of the impulse response
sz = 64
sz lin = np.arange(sz)
dftmtx = np.fft.fft(np.eye(sz))
```

invmtx = np.linalg.inv(dftmtx)

return r@(p**x).T

def rp(x):

```
rp_vec = vec(rp, otypes=['double'])
h1 = rp_vec(sz_lin)
k_add = np.pad(k, (0, sz - len(k)), 'constant', constant_values=(0,0))
h = h1 + k_add
H = h@dftmtx
X = input_signal[:sz]@dftmtx
Y = H*X
y = (Y@invmtx).real
plt.stem(np.arange(sz), y[:sz])
plt.xlabel('n')
plt.ylabel('y(n)')
plt.grid()
plt.plot()
plt.show()
```

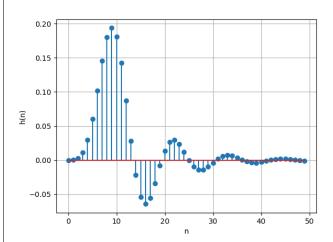


Fig. 8.2: Plot of h(n)

8.3 What is the sampling frequency of the input signal?

Solution:

Sampling frequency(fs)=44.1kHZ.

8.4 What is type, order and cutoff-frequency of the above butterworth filter

Solution:

The given butterworth filter is low pass with order=2 and cutoff-frequency=4kHz.

8.5 Modifying the code with different input parameters and to get the best possible output.

Solution:

A better filtering was found on setting the order of the filter to be 7.

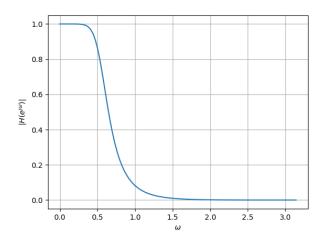


Fig. 8.2: Filter frequency response

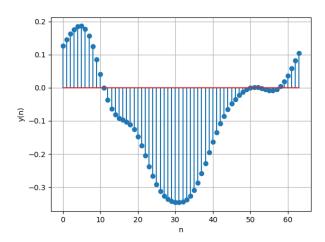


Fig. 8.2: Plot of y(n)