

numerical approximation for image reconstruction in the 'Spectrometer/Telescope for Imaging X-rays (STIX)' mission on-board 'Solar Orbiter'

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6th IM-workshop on applied approximation, signals, and images

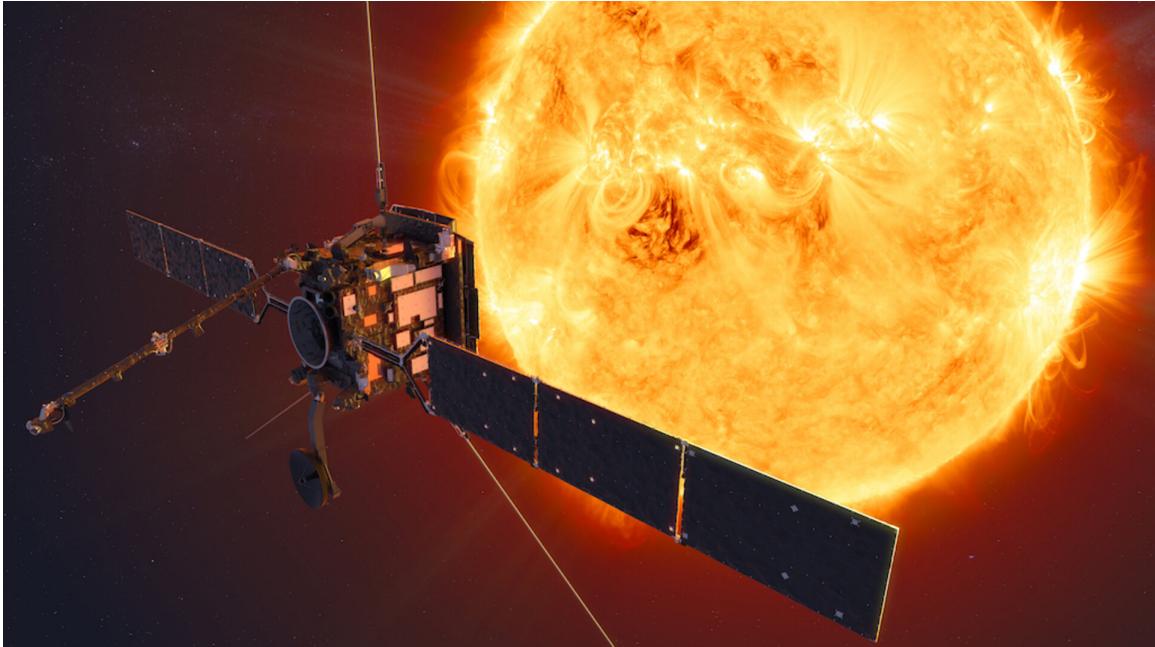
bernried, february 20–24 2023



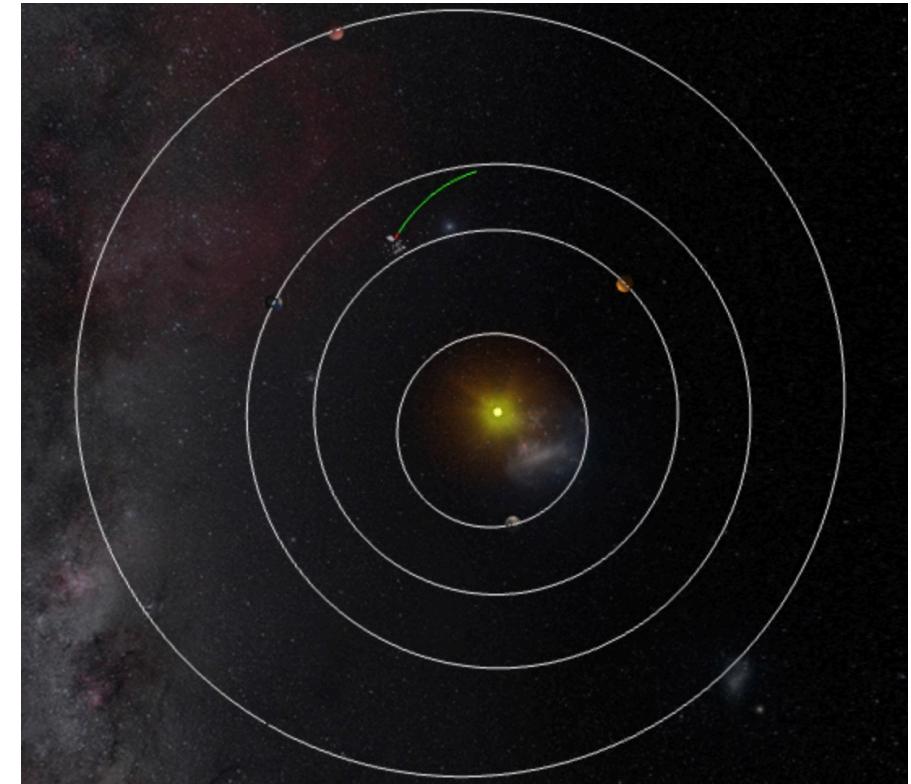
STIX in solar orbiter

solar orbiter: ESA mission launched on February 10, 2020

STIX: one of the four remote sensing instruments on-board solar orbiter

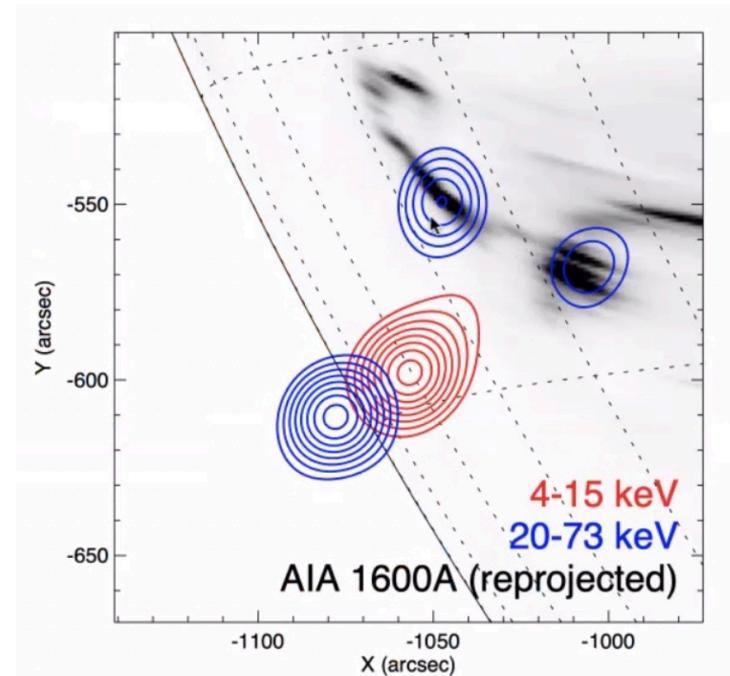
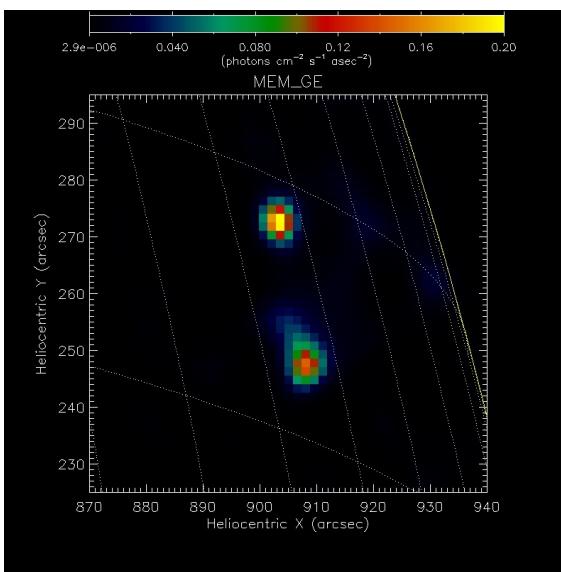
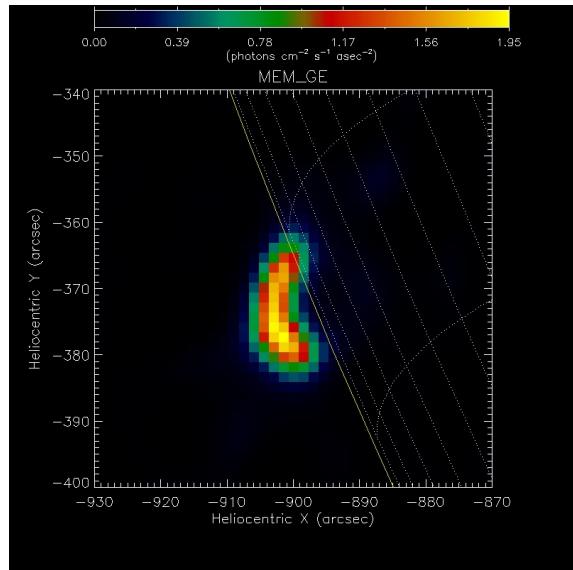
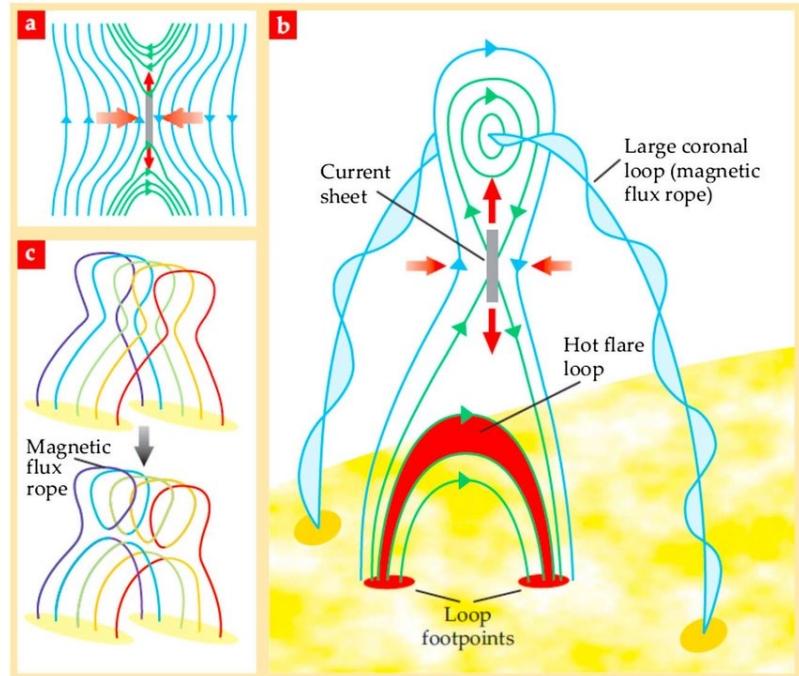


(credits: ESA website)



(<https://solarorbiter.esac.esa.int/where/>)

STIX scientific objective: how about solar flares at high energy?



the STIX instrument

A&A 642, A15 (2020)
<https://doi.org/10.1051/0004-6361/201937362>
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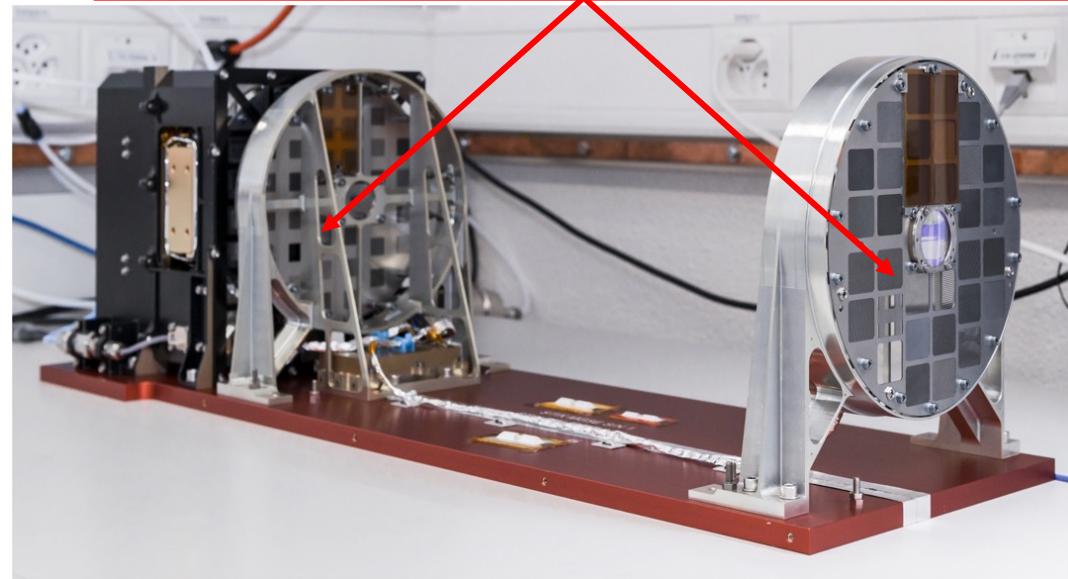
The Solar Orbiter mission

**Astronomy
&
Astrophysics**
Special issue

The Spectrometer/Telescope for Imaging X-rays (STIX)

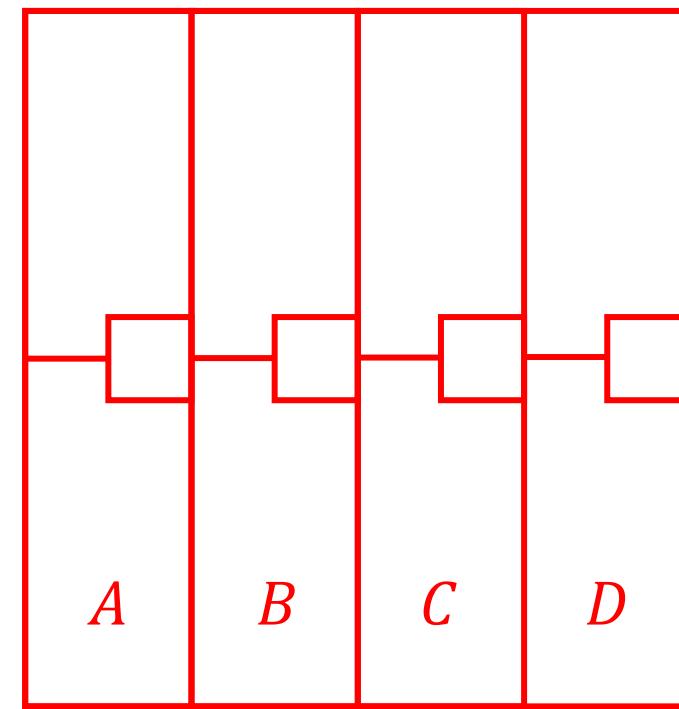
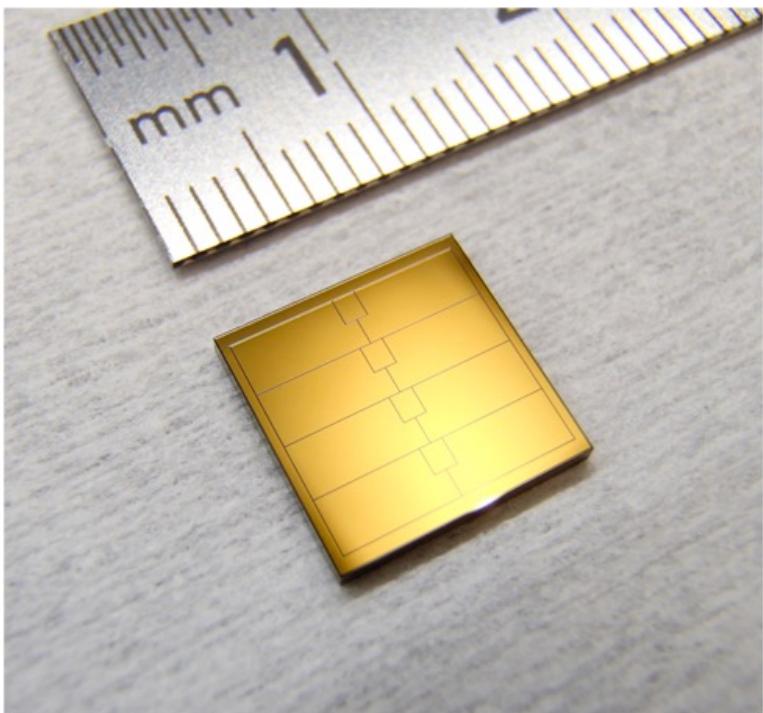
Säm Krucker^{1,2}, G. J. Hurford^{1,2}, O. Grimm^{1,3}, S. Kögl¹, H.-P Gröbelbauer¹, L. Etesi¹, D. Casadei¹, A. Csillaghy¹, A. O. Benz¹, N. G. Arnold¹, F. Molendini¹, P. Orleanski¹, D. Schori¹, H. Xiao¹, M. Kuhar¹, N. Hochmuth¹, S. Felix¹, F. Schramka¹, S. Marcin¹, S. Kobler¹, L. Iseli¹, M. Dreier¹, H. J. Wiehl¹, L. Kleint¹, M. Battaglia¹, E. Lastufka^{1,3}, H. Sathiapal¹, K. Lapadula¹, M. Bednarzik⁴, G. Birrer⁴, St. Stutz⁴, Ch. Wild⁴, F. Marone⁴, K. R. Skup⁵, A. Cichocki⁵, K. Ber⁵, K. Rutkowski⁵, W. Bujwan⁵, G. Juchnikowski⁵, M. Winkler⁵, M. Darmetko⁵, M. Michalska⁵, K. Seweryn⁵, A. Bialek⁵, P. Osica⁵, J. Sylwester⁵, M. Kowalinski⁵, D. Scisłowski⁵, M. Siarkowski⁵, M. Stęslicki⁵, T. Mrozek^{6,5}, P. Podgócki⁵, A. Meuris⁷, O. Limousin⁷, O. Gevin⁸, I. Le Mer⁷, S. Brun⁷, A. Strugarek⁷, N. Vilmer⁹, S. Musset^{9,10}, M. Maksimović⁹, F. Fárník¹¹, Z. Kozáček¹¹, J. Kašparová¹¹, G. Mann¹², H. Önel¹², A. Warmuth¹², J. Rendtel¹², J. Anderson¹², S. Bauer¹², F. Dionies¹², J. Paschke¹², D. Plüschke¹², M. Woche¹², F. Schuller¹², A. M. Veronig¹³, E. C. M. Dickson¹³, P. T. Gallagher^{14,15}, S. A. Maloney^{15,14}, D. S. Bloomfield^{14,16}, M. Piana¹⁷, A. M. Massone¹⁷, F. Benvenuto¹⁷, P. Massa¹⁷, R. A. Schwartz^{13,14,18}, B. R. Dennis¹⁹, H. F. van Beek²⁰, J. Rodríguez-Pacheco²¹, and R. P. Lin²

sub-collimator = front grid + rear grid + detector



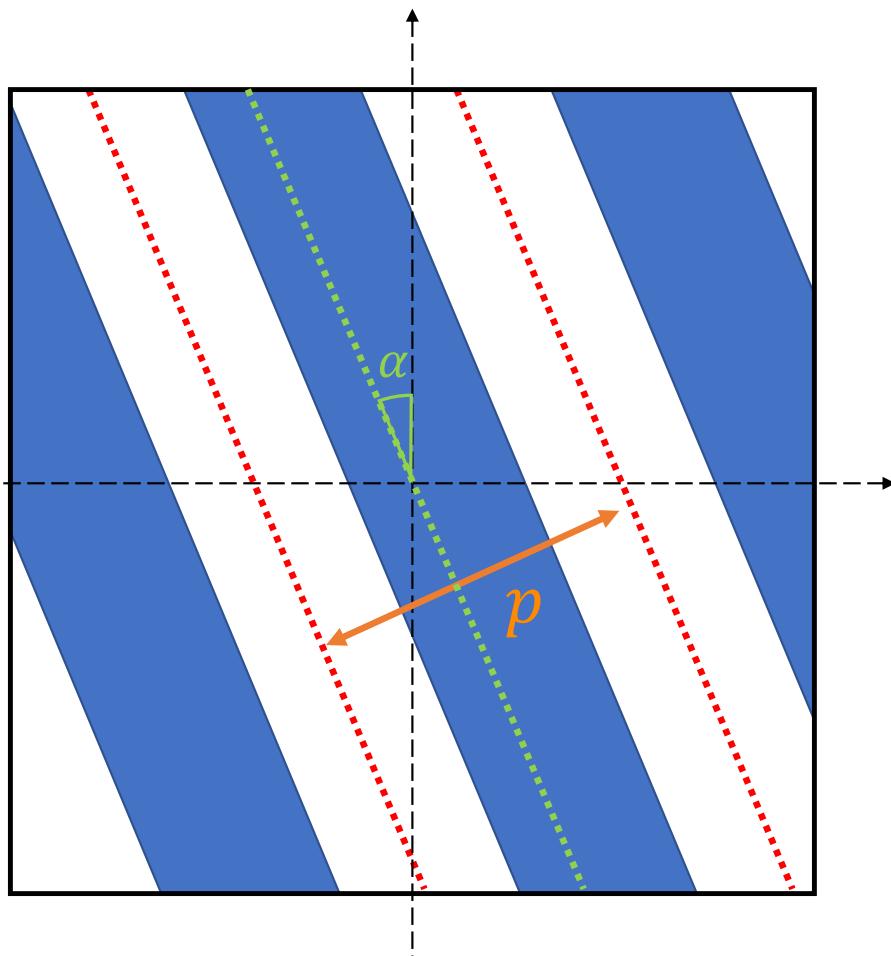
- bi-grid imaging system
- STIX consists of 32 subcollimators:
 - 30 are used for imaging
 - coarse Flare Locator
 - background monitor

the STIX detectors



A, B, C and D: number of counts
recorded by the detector pixels

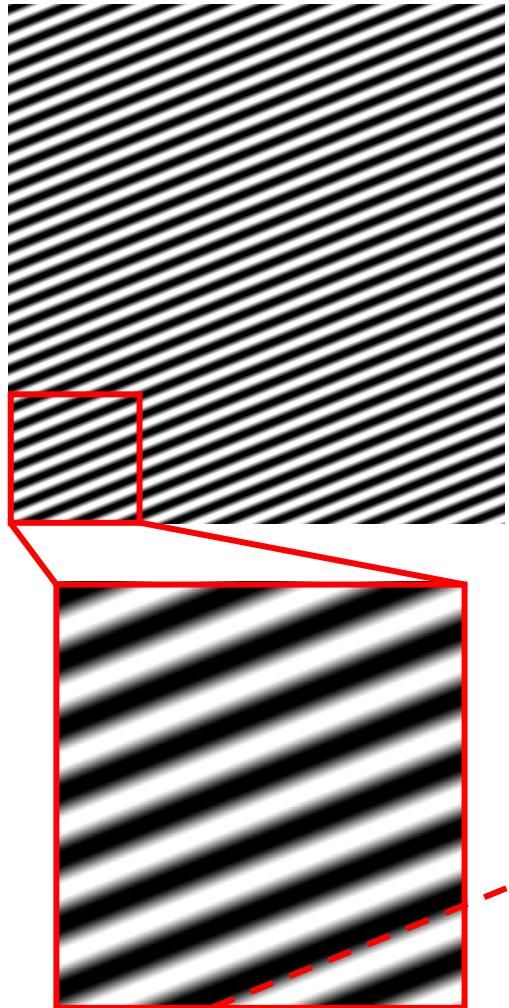
the STIX grid parameters



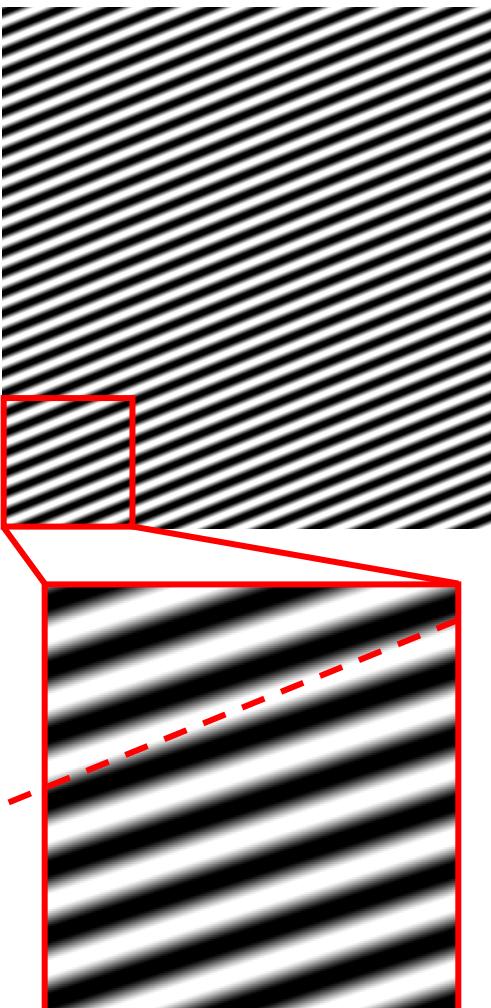
- α : orientation angle
- p : pitch = distance between two consecutive slit centers

the STIX imaging concept

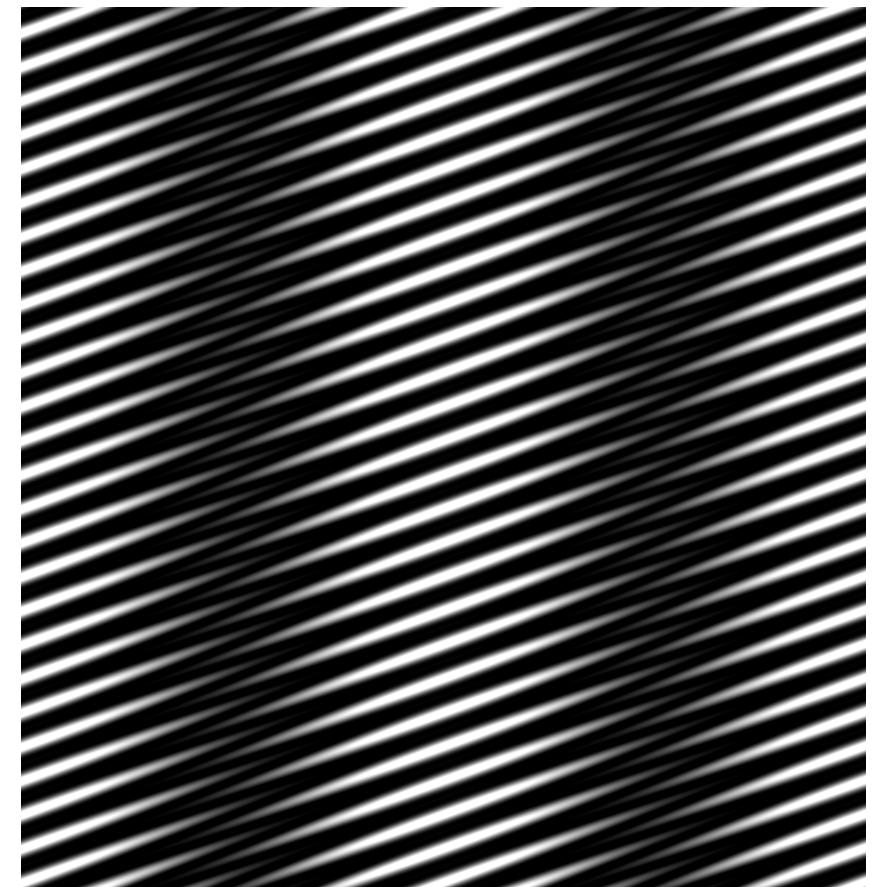
front grid



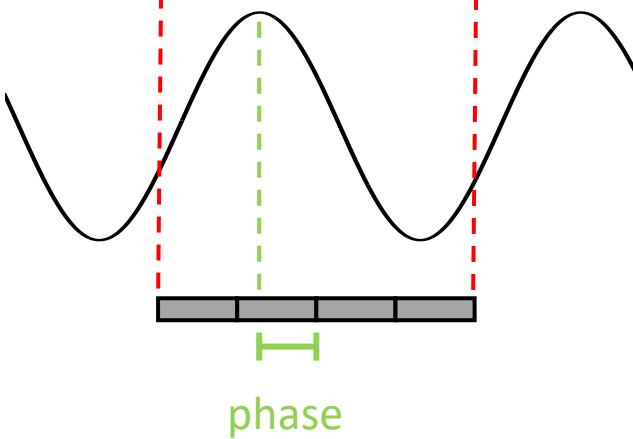
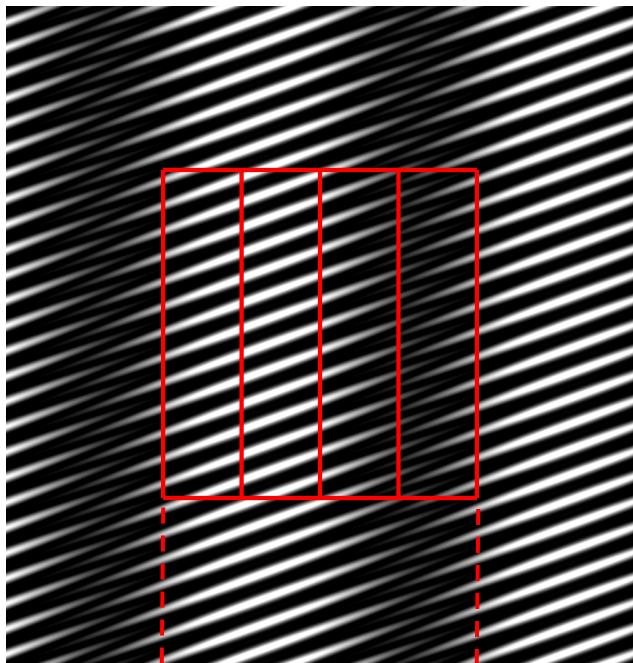
rear grid



moiré pattern



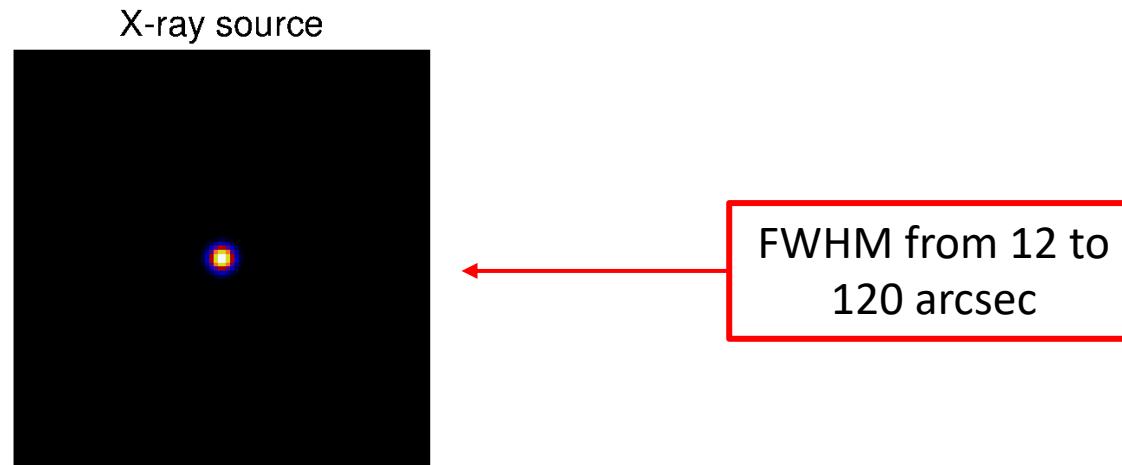
moiré pattern - 1



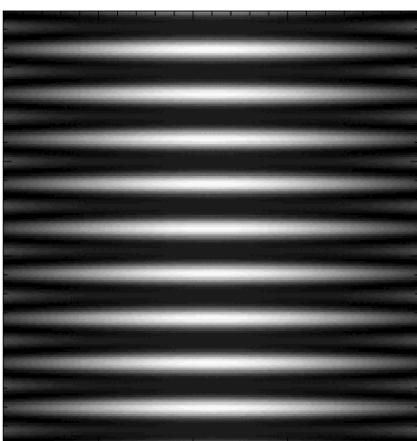
- moiré pattern: sinusoidal wave with period equal to the detector width
- **amplitude** and **phase** of the pattern → amplitude and phase of a Fourier component of the photon flux (**visibility**)

moiré pattern - 2

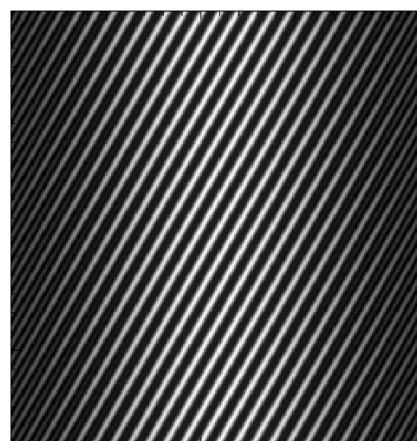
the amplitude of a moiré pattern is sensitive to the source size and shape



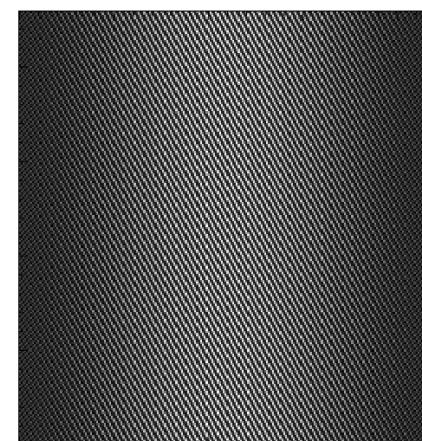
Resolution: 178.6 arcsec



Resolution: 61.0 arcsec



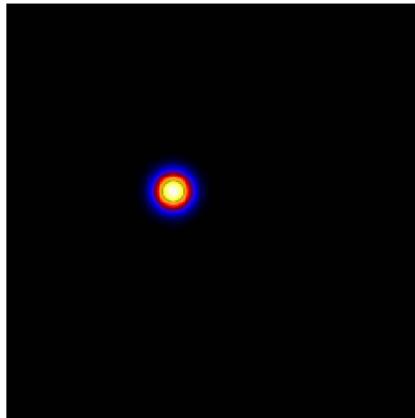
Resolution: 20.9 arcsec



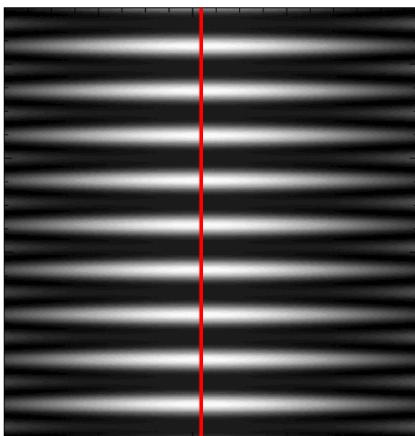
moiré pattern - 3

the phase of a moiré pattern is sensitive to the source location

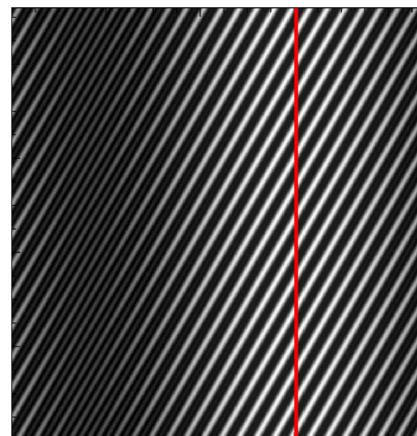
X-ray source



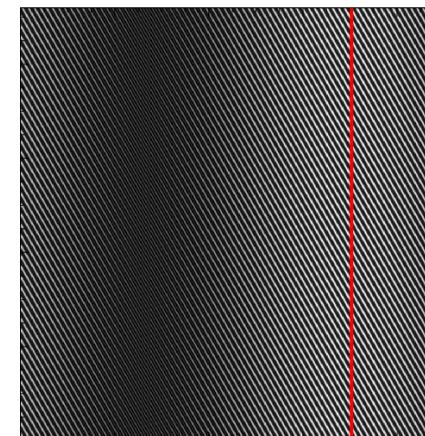
Resolution: 178.6 arcsec



Resolution: 61.0 arcsec



Resolution: 20.9 arcsec



visibilities

each sub-collimator measures a visibility value, i.e. a fourier sample

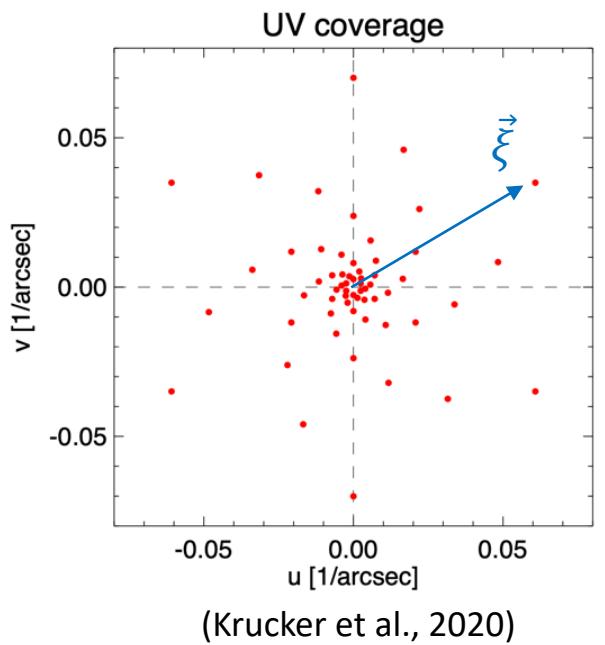
visibilities

each sub-collimator measures a visibility value

grid pitch and orientation



norm and orientation of the sampling frequency ξ



10 different angular resolutions,
logarithmically spaced
between 7.1 and 179 arcsec in steps of 1.43

visibilities

each sub-collimator measures a visibility value

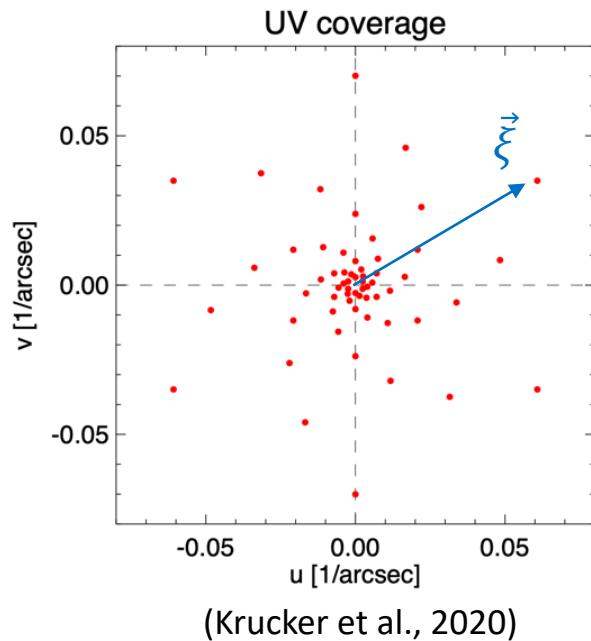
grid pitch and orientation

count measurements A, B, C, D

norm and orientation of the sampling frequency ξ

amplitude and phase of the visibility:

- $|V| \propto \sqrt{(C - A)^2 + (D - B)^2}$
- $\phi = \text{atan} \left(\frac{D-B}{C-A} \right) + 45^\circ + \phi_{calib}$



10 different angular resolutions,
logarithmically spaced
between 7.1 and 179 arcsec in steps of 1.43

visibilities

each sub-collimator measures a visibility value

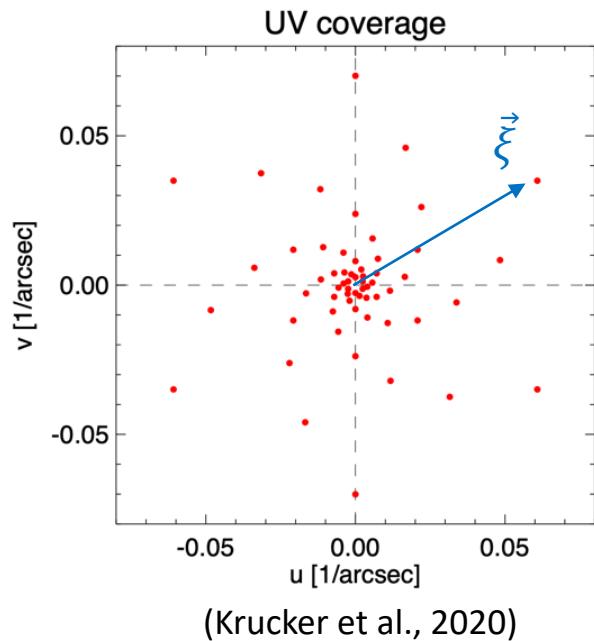
grid pitch and orientation

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10 different angular resolutions,
logarithmically spaced
between 7.1 and 179 arcsec in steps of 1.43

the data measured by STIX are 30 visibilities

STIX image reconstruction problem

image reconstruction problem for STIX:

$$F\phi = V$$

where:

- ϕ is the image to reconstruct
- F is the fourier transform sampled at STIX frequencies
- V is the complex array of observed visibilities

**the STIX image reconstruction problem is an
inverse fourier transform problem with limited data**

imaging methods

state-of-the-art

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<https://doi.org/10.3847/1538-4357/ab8637>



CrossMark

MEM GE: A New Maximum Entropy Method for Image Reconstruction from Solar X-Ray Visibilities

Paolo Massa¹, Richard Schwartz², A Kim Tolbert², Anna Maria Massone^{1,3}, Brian R. Dennis², Michele Piana^{1,3}, and Federico Benvenuto¹

¹ Dip A&A 656, A25 (2021)

² N_z https://doi.org/10.1051/0004-6361/202140946
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Solar Orbiter First Results (Cruise Phase)

Astronomy & Astrophysics
Special issue

ige.it,
.gov

Imaging from STIX visibility amplitudes

A & A 668, A145 (2022)

https://doi.org/10.1051/0004-6361/202243907
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Astronomy & Astrophysics

Forward fitting STIX visibilities

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under construction:

- multi-scale CLEAN
- neural network
- pixon
- uv_smooth

MEM_GE

solves the maximum-entropy regularized problem

$$\arg \min_{\phi \geq 0} \chi^2(\phi) - \lambda H(\phi)$$

$$\text{with } \sum_j \phi_j = f$$

where

$$\chi^2(\phi) = \sum_i \frac{|(\mathcal{F}\phi)_i - V_i|^2}{\sigma_i^2} \quad H(\phi) = - \sum_j \phi_j \log \left(\frac{\phi_j}{me} \right)$$

MEM_GE

solves the maximum-entropy regularized problem

$$\arg \min_{\phi \geq 0} \chi^2(\phi) - \lambda H(\phi)$$

$$\text{with } \sum_j \phi_j = f$$

where

$$\chi^2(\phi) = \sum_i \frac{|(\mathcal{F}\phi)_i - V_i|^2}{\sigma_i^2}$$

data fitting

$$H(\phi) = - \sum_j \phi_j \log \left(\frac{\phi_j}{me} \right)$$

MEM_GE

Solves the maximum-entropy regularized problem

$$\arg \min_{\phi \geq 0} \chi^2(\phi) - \lambda H(\phi)$$

$$\text{with } \sum_j \phi_j = f$$

where

$$\chi^2(\phi) = \sum_i \frac{|(\mathcal{F}\phi)_i - V_i|^2}{\sigma_i^2}$$

$$H(\phi) = - \sum_j \phi_j \log \left(\frac{\phi_j}{me} \right)$$

regularization

MEM_GE

solves the maximum-entropy regularized problem

$$\arg \min_{\phi \geq 0} \chi^2(\phi) - \lambda H(\phi)$$

with $\sum_j \phi_j = f$

regularization parameter

where

$$\chi^2(\phi) = \sum_i \frac{|(\mathcal{F}\phi)_i - V_i|^2}{\sigma_i^2} \quad H(\phi) = - \sum_j \phi_j \log \left(\frac{\phi_j}{me} \right)$$

MEM_GE

solves the maximum-entropy regularized problem

positivity constraint $\longrightarrow \boxed{\phi \geq 0}$

$$\arg \min \chi^2(\phi) - \lambda H(\phi)$$
$$\text{with } \sum_j \phi_j = f$$

where

$$\chi^2(\phi) = \sum_i \frac{|(\mathcal{F}\phi)_i - V_i|^2}{\sigma_i^2} \quad H(\phi) = - \sum_j \phi_j \log \left(\frac{\phi_j}{me} \right)$$

MEM_GE

solves the maximum-entropy regularized problem

$$\arg \min_{\phi \geq 0} \chi^2(\phi) - \lambda H(\phi)$$

with $\sum_j \phi_j = f$



flux constraint

where

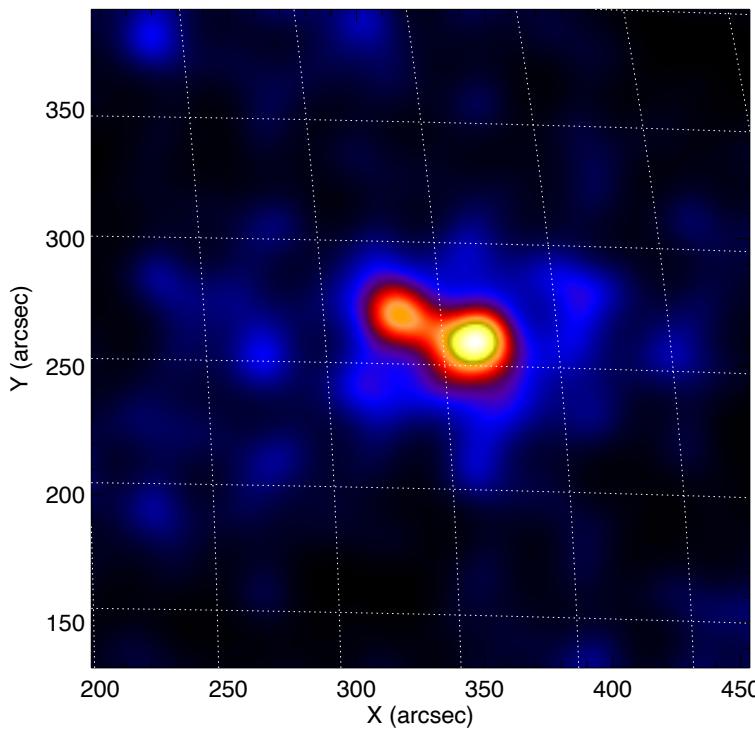
$$\chi^2(\phi) = \sum_i \frac{|(\mathcal{F}\phi)_i - V_i|^2}{\sigma_i^2}$$

$$H(\phi) = - \sum_j \phi_j \log \left(\frac{\phi_j}{m e} \right)$$

MEM_GE

λ : finds a tradeoff between data fitting and regularization

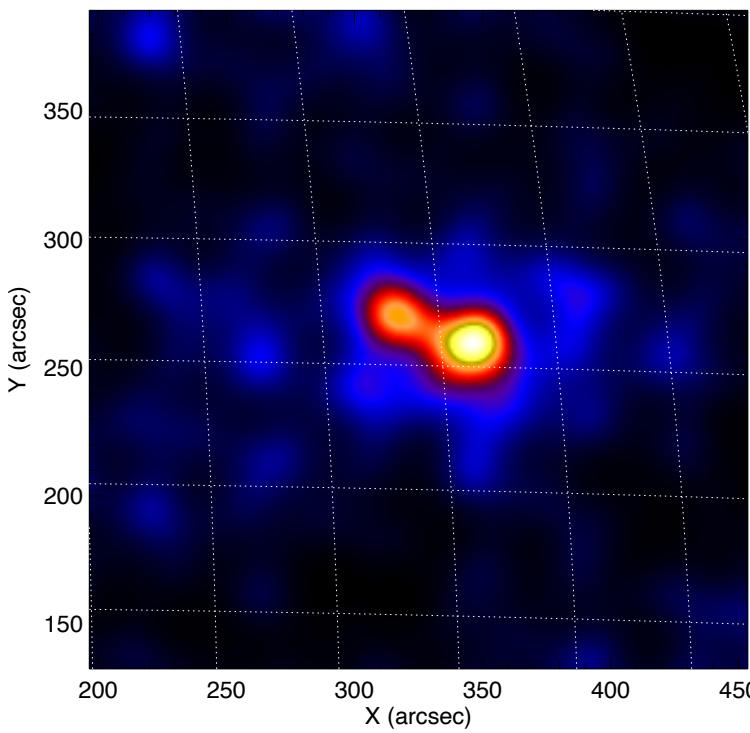
large λ



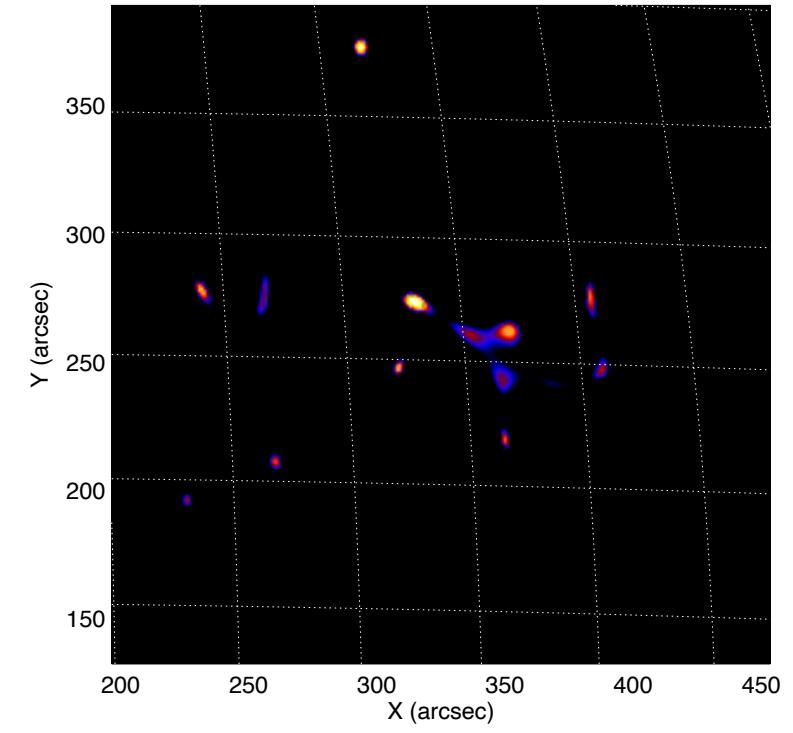
MEM_GE

λ : finds a tradeoff between data fitting and regularization

large λ

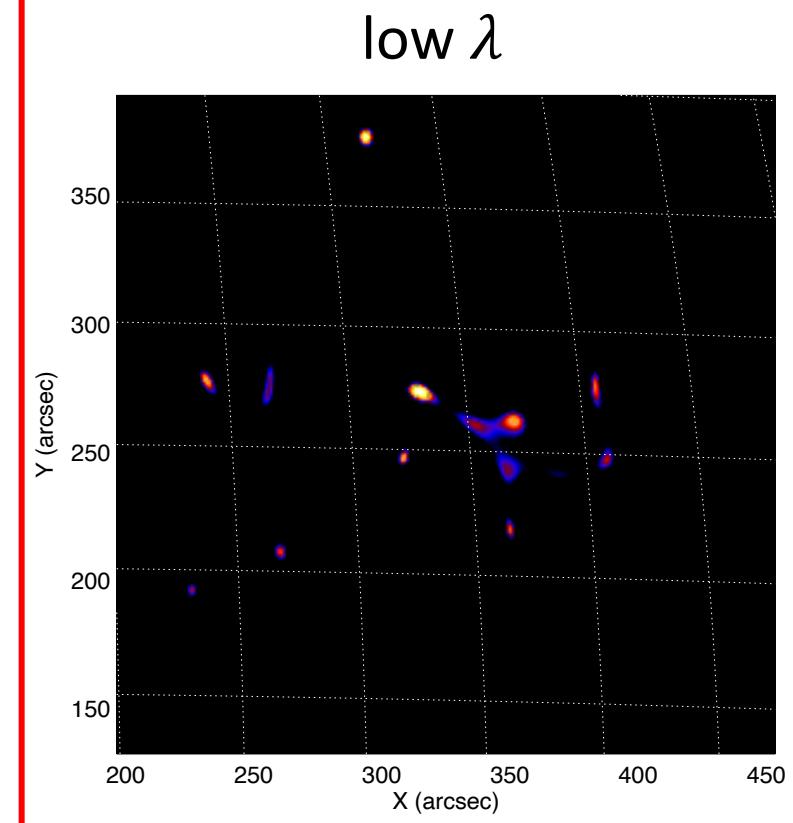
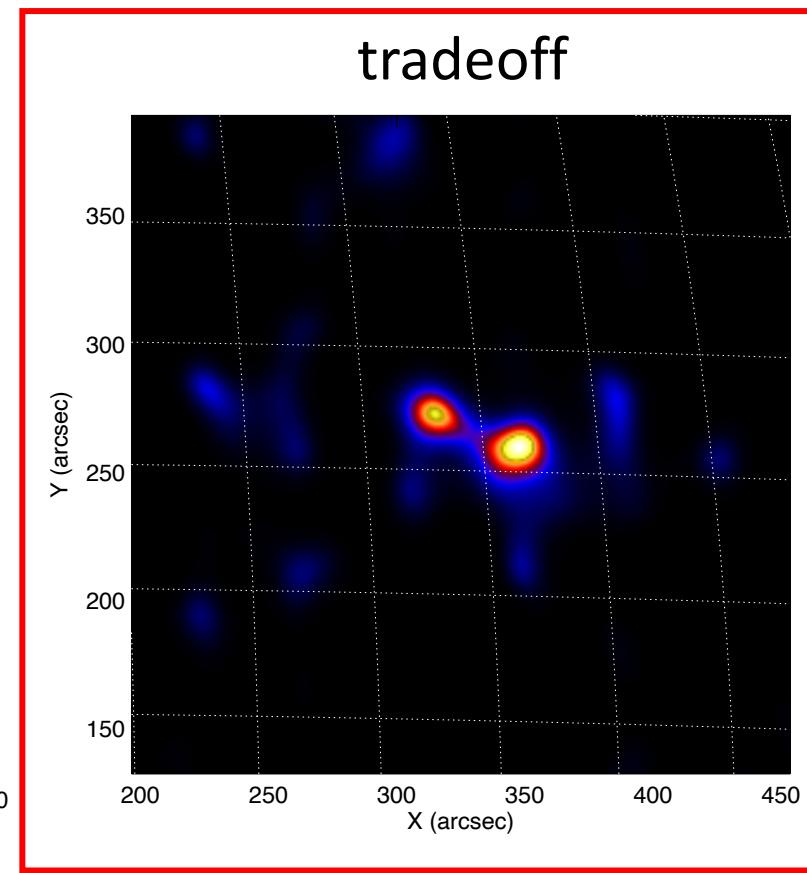
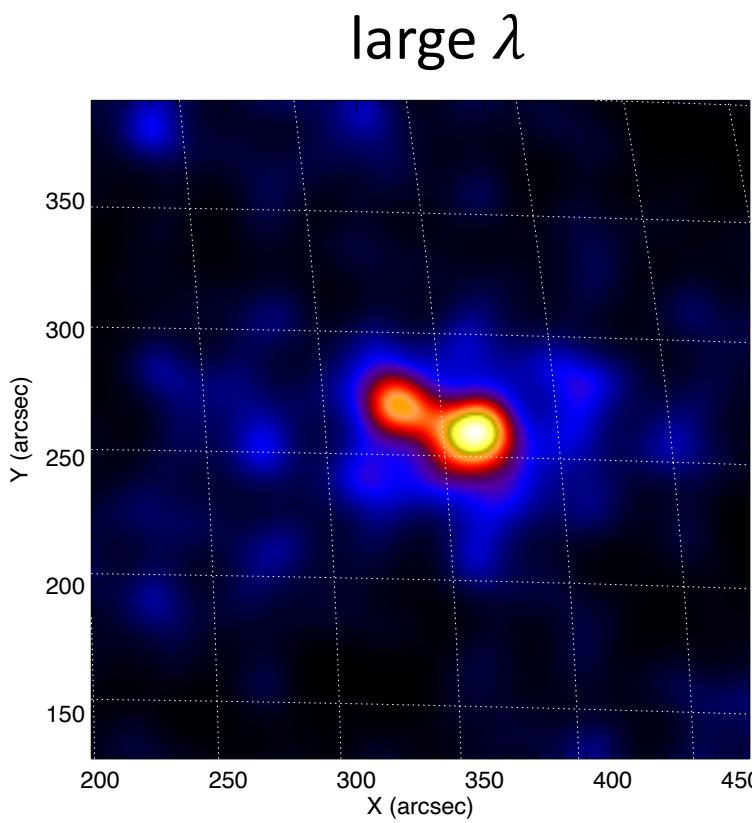


low λ



MEM_GE

λ : finds a tradeoff between data fitting and regularization



may 2021 events

angle relative to Earth-Sun (in may 2021): $97.4^\circ - 98.2^\circ$

Solar Physics (2022) 297:93
<https://doi.org/10.1007/s11207-022-02029-x>

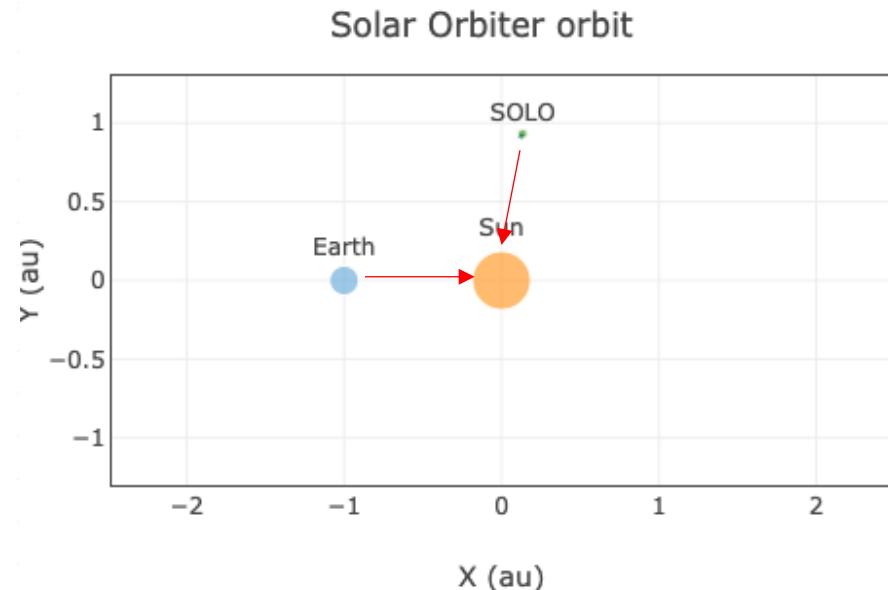


First Hard X-Ray Imaging Results by Solar Orbiter STIX

Paolo Massa¹ · Andrea F. Battaglia^{2,3} · Anna Volpara¹ · Hannah Collier^{2,3} ·
Gordon J. Hurford² · Matej Kuhar² · Emma Perracchione⁴ · Sara Garbarino¹ ·
Anna Maria Massone^{1,5} · Federico Benvenuto¹ · Frederic Schuller⁶ ·
Alexander Warmuth⁶ · Ewan C.M. Dickson⁷ · Hualin Xiao² · Shane A. Maloney^{8,9} ·
Daniel F. Ryan² · Michele Piana^{1,5} · Säm Krucker^{2,10}

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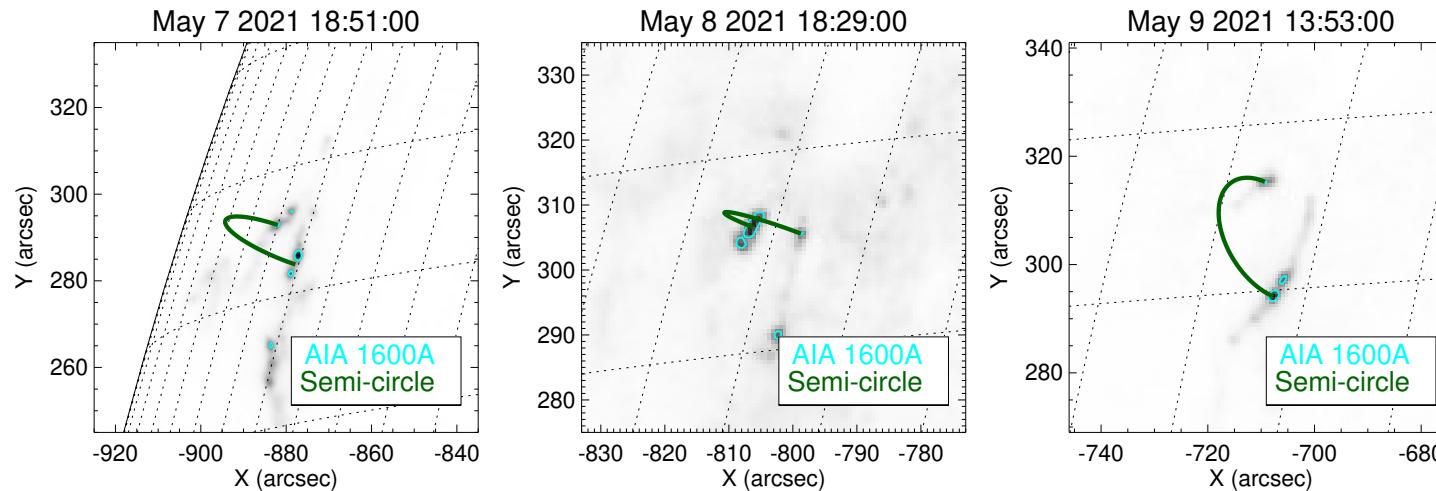
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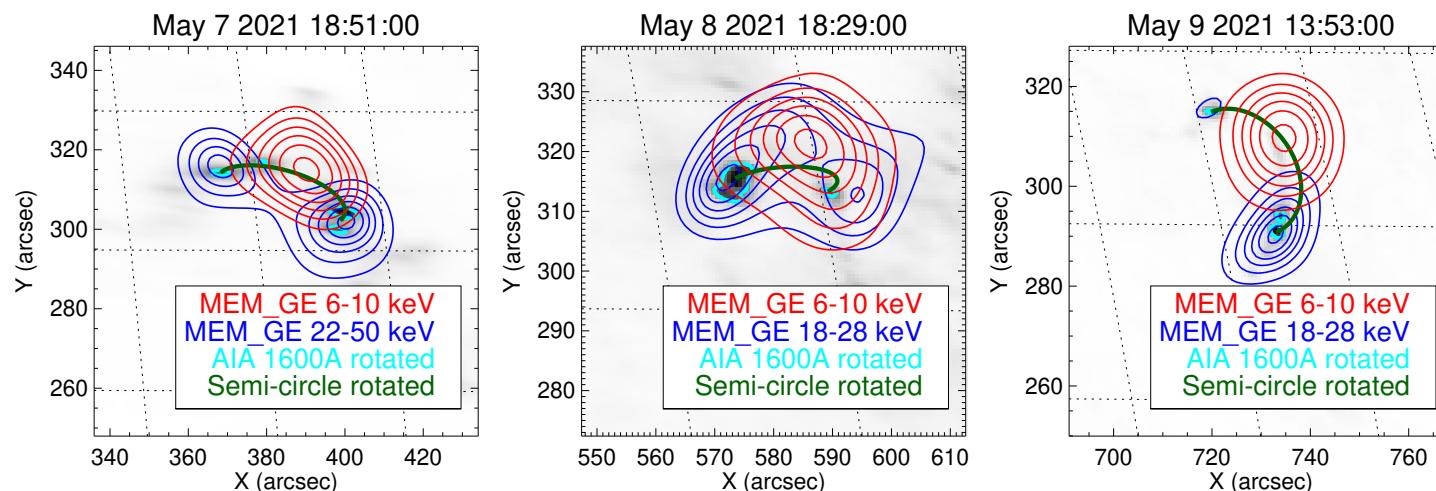
AIA images rotated by means of the
reproject Python package (see
battaglia et al., 2021)

may 2021 events

Earth vantage point



Solar Orbiter vantage point



active region AR2822

- may 7: GOES M3.9
- may 8: GOES C8.6
- may 9: GOES C4.0

manual shift STIX reconstructions

event	Δx (arcsec)	Δy (arcsec)
may 7	44	54
may 8	45	57
may 9	47.5	53

STIX and numerical approximation

interpolation/extrapolation: general scheme

1. interpolation of the scattered observations of the fourier transform to generate a uniform sampling in the spatial frequency domain

$$P(\mathbf{u}_i) = \mathbf{V}_i, \quad i = 1, \dots, n.$$

$$P(\mathbf{u}) = \sum_{k=1}^n a_k b_k(\mathbf{u}),$$

2. extrapolation/inversion of the generated interpolants (possibly via FFT) to perform (super-resolved) image reconstruction

$$\bar{\mathbf{I}}(\mathbf{x}) = (\mathcal{F}^{-1} P_V^D)(\mathbf{x}),$$

+ some constraint to regularize while realizing out-of-band extrapolation and beat the shannon theorem

uv_smooth: first release

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doi:[10.1088/0004-637X/703/2/2004](https://doi.org/10.1088/0004-637X/703/2/2004)

HARD X-RAY IMAGING OF SOLAR FLARES USING INTERPOLATED VISIBILITIES

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⁵ Department of Physics & Astronomy, The University, Glasgow G12 8QQ, UK; eduard@astro.gla.ac.uk

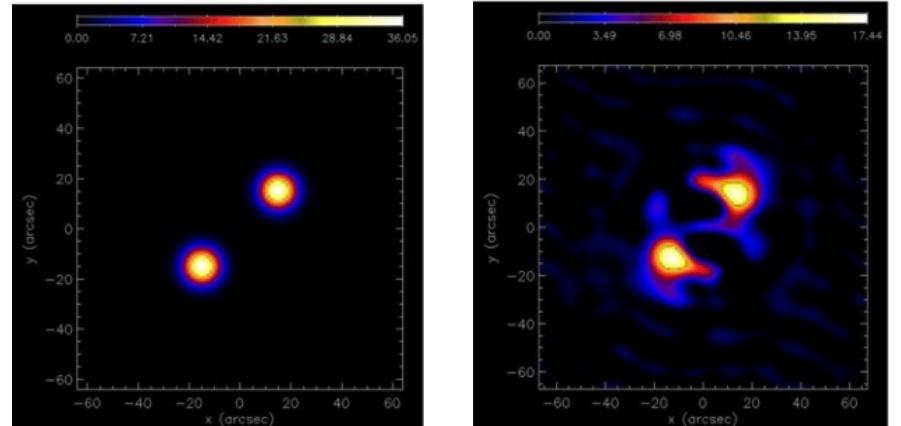
⁶ Dipartimento di Informatica, Università di Verona, Cà Vignal 2, Strada le Grazie 15, I-37134 Verona, Italy; michele.piana@univr.it

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interpolation:
thin-plate spline

$$\mathcal{F}(I^{(k+1)}) = \tau \mathcal{F}(\bar{I}) + (1 - \tau \chi_D) \mathcal{F}(I^{(k)}), \quad k = 1, 2, \dots,$$

$$I^{(k+1)} = \mathcal{P}_+ I^{(k+1)}, \quad (\mathcal{P}_+ I^{(k+1)})(\mathbf{x}) = \begin{cases} 0 & I^{(k+1)}(\mathbf{x}) < 0, \\ I^{(k+1)}(\mathbf{x}) & \text{otherwise.} \end{cases}$$



augmented uv_smooth: theory

IOP Publishing

Inverse Problems 37 (2021) 105001 (21pp)

Inverse Problems

<https://doi.org/10.1088/1361-6420/ac1ad7>

Feature augmentation for the inversion of the Fourier transform with limited data

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Published 27 August 2021



$$P(\mathbf{u}_i) = \mathbf{V}_i, \quad i = 1, \dots, n.$$

$$P(\mathbf{u}) = \sum_{k=1}^n a_k b_k(\mathbf{u}),$$

$$b_k(\mathbf{u}) = \phi(\|(\mathbf{u}, \psi(\mathbf{u})) - (\mathbf{u}_k, \psi(\mathbf{u}_k))\|), \quad k = 1, \dots, n,$$

$$\mathbf{K}\mathbf{a} = \mathbf{V}$$

technical results:

$$\phi(\|\mathbf{u}\|) = e^{-\varepsilon\|\mathbf{u}\|},$$

$$K_\varepsilon(\mathbf{w}, \mathbf{z}) = \varphi_\varepsilon(\|\mathbf{w} - \mathbf{z}\|_2),$$

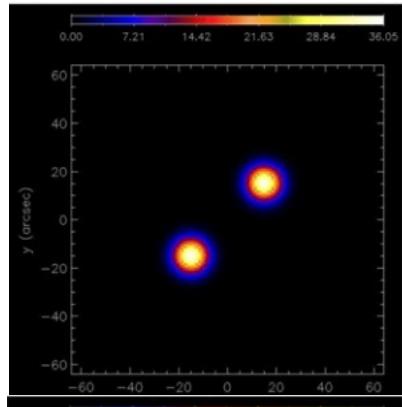
$$K_\varepsilon^\Psi(\mathbf{w}, \mathbf{z}) := K_\varepsilon((\mathbf{w}, \Psi(\mathbf{w})), (\mathbf{z}, \Psi(\mathbf{z}))),$$



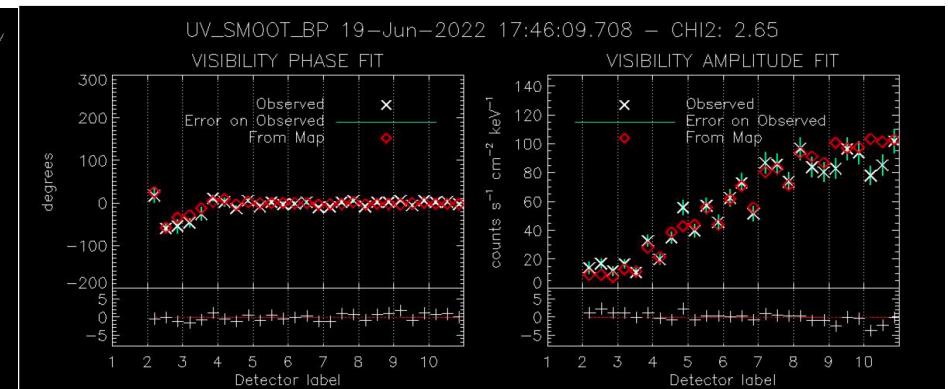
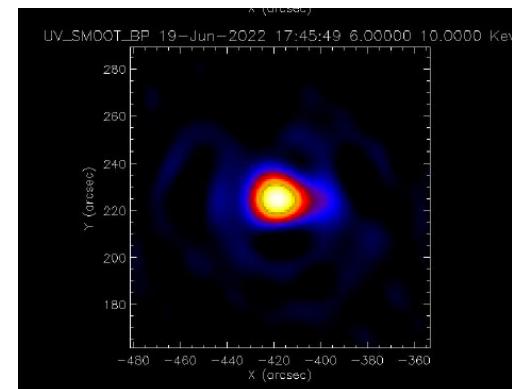
$$S(\mathbf{K}) = \frac{n}{\|\mathbf{K}\|_F} \leqslant \frac{n}{\|\mathbf{K}^\Psi\|_F} = S(\mathbf{K}^\Psi).$$

$$\text{cond}(\mathbf{K}^\Psi) \leqslant \text{cond}(\mathbf{K}).$$

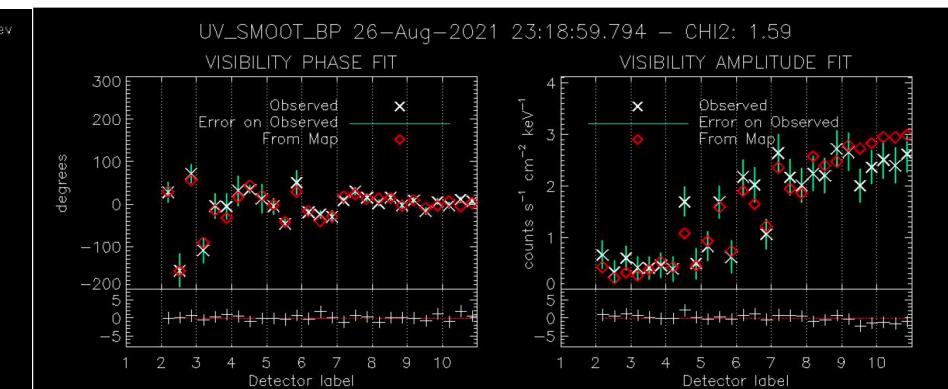
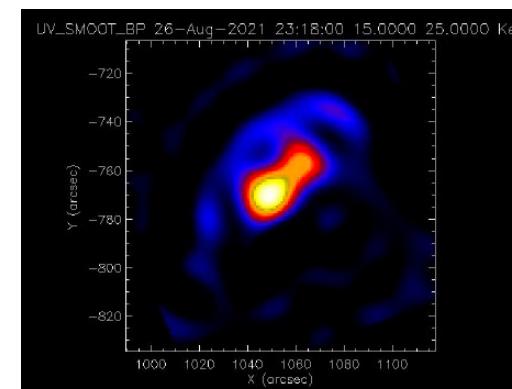
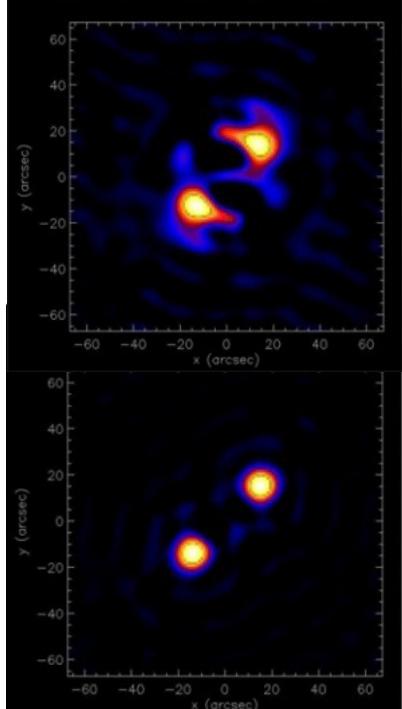
synthetic visibilities



augmented uv_smooth: results



june 19 2022



august 26 2021

credits

from MIDA:

- paolo massa
- anna volpara
- emma perracchione
- sara garbarino
- anna maria massone

from the rest of the STIX crew:

- sam krucker
- gordon hurford
- andrea battaglia
- ewan dickson
- hualin xiao

references

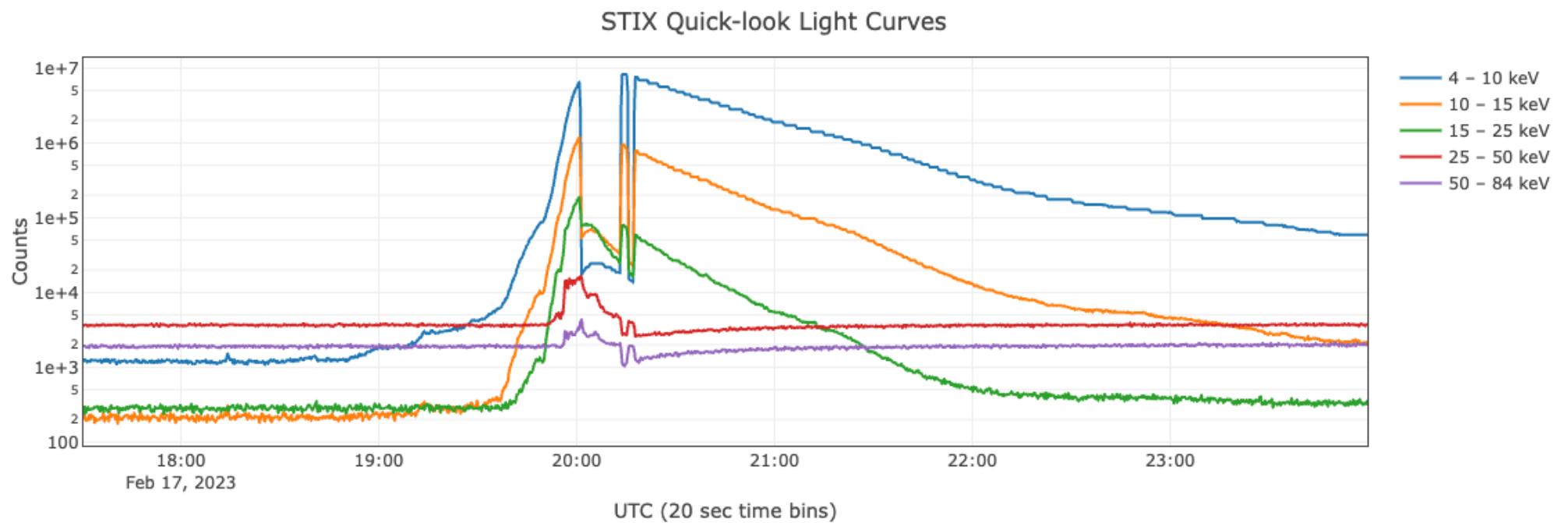
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- massone et al, astrophysical journal, 703, 2, 2004

we are hiring people at MIDA



- junior position: two-year position within the solar orbiter contract (STIX imaging)
- senior position: two-year position within the horizon europe project ARCAFF (flare forecasting)

thank you for the attention



Visibility calibration

Amplitude calibration:

- background subtraction
- grid transmission (including the flare location)
- ELUT
- livetime

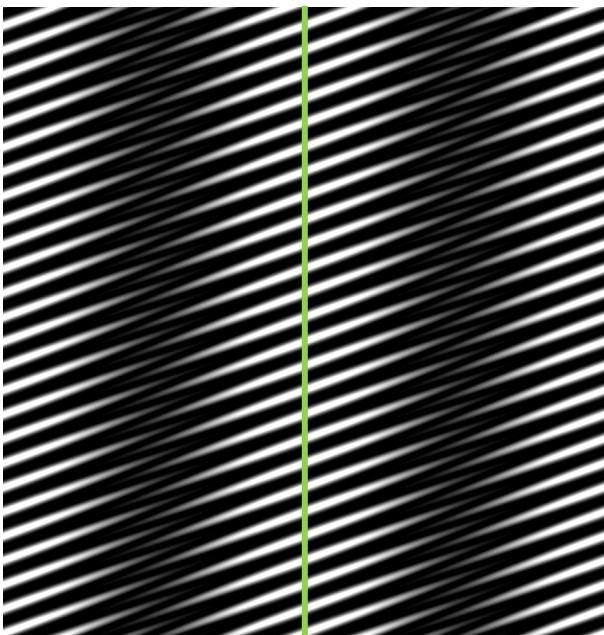
Phase calibration: keeps into account the grid geometry

Visibility calibration

Amplitude calibration:

- background subtraction
- grid transmission (including the flare location)
- ELUT
- livetime

Phase calibration: keeps into account the grid geometry

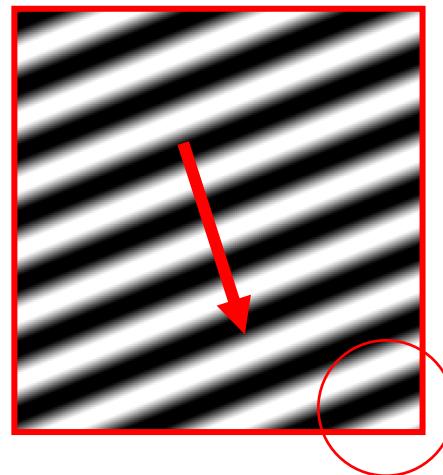
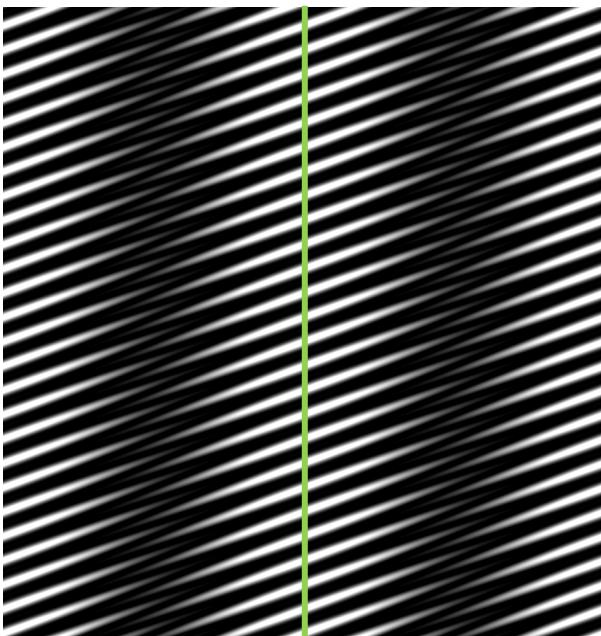


Visibility calibration

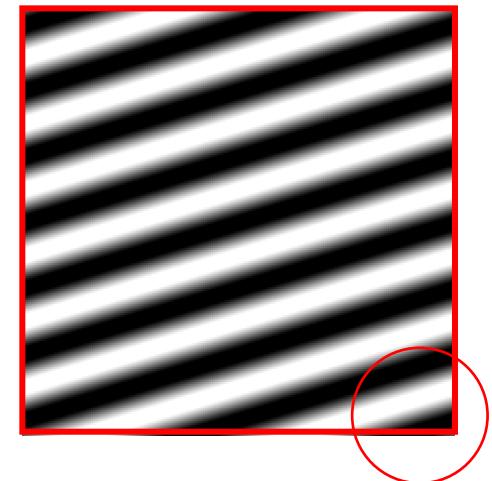
Amplitude calibration:

- background subtraction
- grid transmission (including the flare location)
- ELUT
- livetime

Phase calibration: keeps into account the grid geometry



Shift front grid

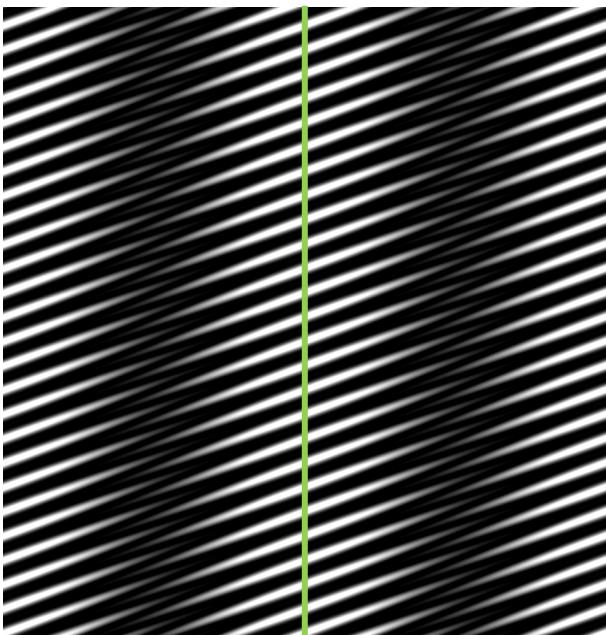


Visibility calibration

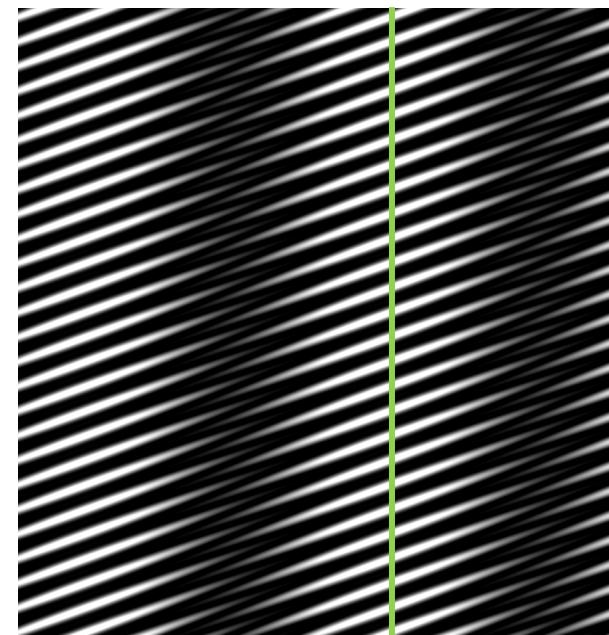
Amplitude calibration:

- background subtraction
- grid transmission (including the flare location)
- ELUT
- livetime

Phase calibration: keeps into account the grid geometry

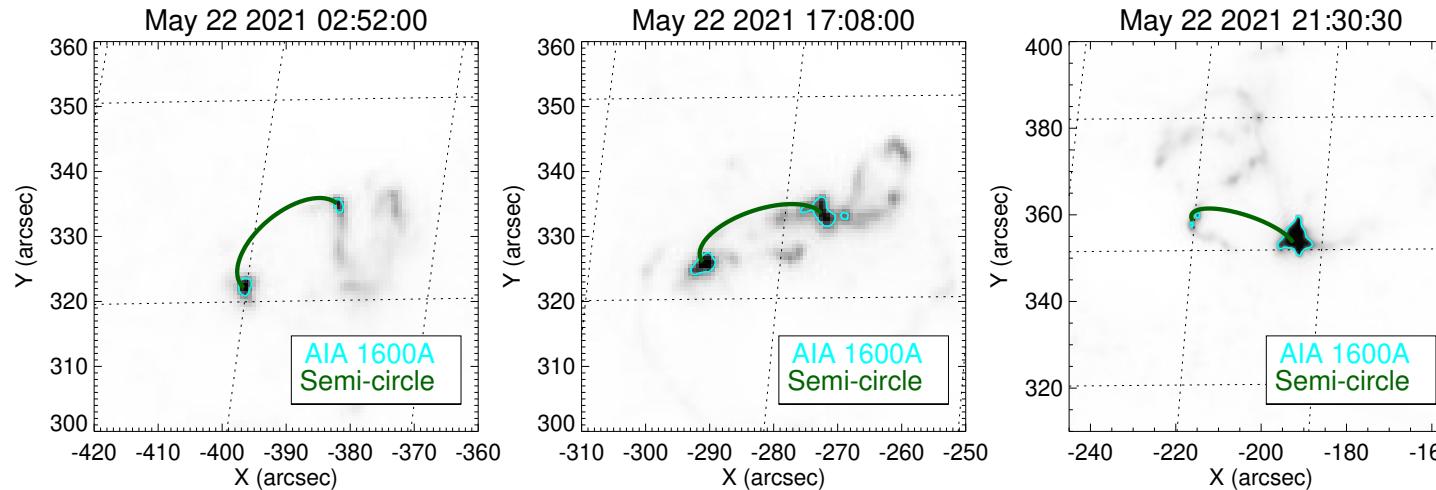


Shift front grid
→

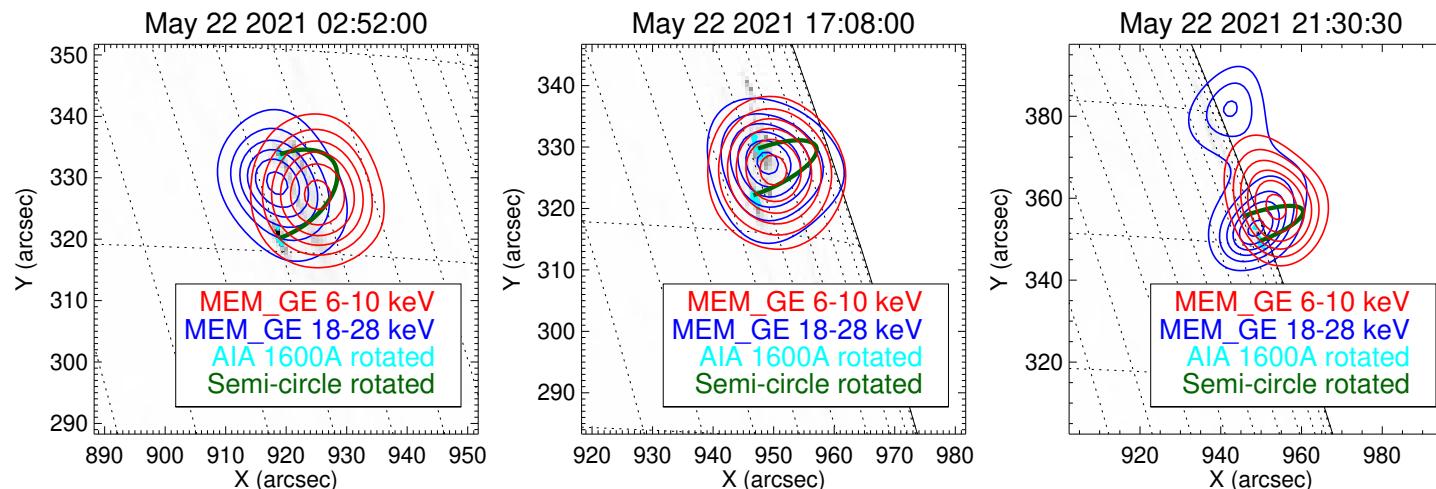


May 2021 events (Massa et al., 2022, in preparation)

Earth vantage point



Solar Orbiter vantage point



Active region AR2824

May 22:

- 02:52:00 UT: GOES C6.1
- 17:08:00 UT: GOES M1.1
- 21:30:30 UT: GOES M1.4

Manual shift STIX reconstructions

Event	Δx (arcsec)	Δy (arcsec)
02:52	47	55
17:08	47	50
21:30	50	50