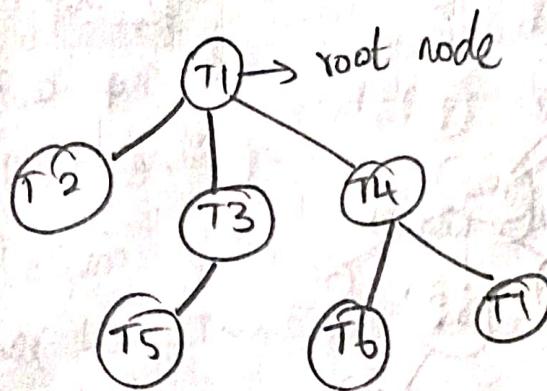


Unit 4

Tree Structure

1) Tree ADT

A tree is a finite set of one or more nodes such that i) There is a specially designed node called root. * The remaining nodes are partitioned into no disjoint sets T_1, T_2, \dots, T_n and this are called subtrees of root.



various operation performed on tree

1. creation of a tree
2. insertion of node in the tree as a child of desired node
3. deletion of any node from the tree
4. modification of node value of the tree
5. searching particular node from the tree

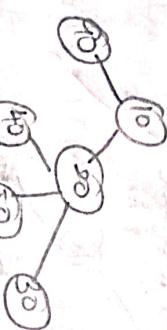
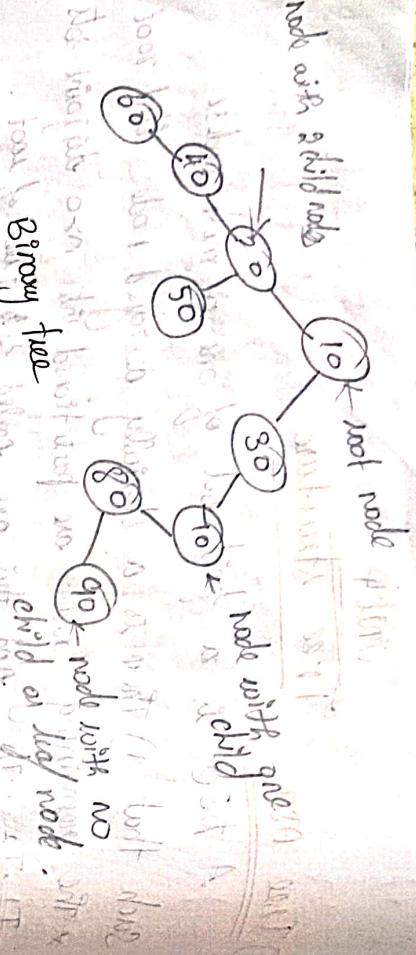
2) Binary tree ADT:

Binary tree is a finite set of nodes which is either empty or consists of a root & two disjoint binary tree called left subtree and right subtree.

③ Tree traversals

The traversal means visiting each node exactly one.

* There are six ways to traverse a tree. For traversals we will use following notations:



Not a binary tree

Abstract Data Type BinT (root)

of instances: Binary tree is a nonlinear data structure which contains every node except the leaf node at most two child nodes.

Operations

- Inception: This operation is used to insert the node in the binary tree. By inserting desired no. of nodes, the binary tree gets created.
- Deletion: This operation is used to remove any node from the tree. Note that if root node is removed the tree becomes empty

Inorder traversal: The left node is visited, then parent node & then right node is visited.

Ex: Step 1: C Step 2: B Step 3: E Inorder traversal is C B D A E

Alg.: 1. If tree is not empty, then a) Traverse the left subtree in inorder. b) Visit the root node. c) Traverse the right subtree in inorder.

Tree traversals means visiting each node exactly one. * There are six ways to traverse a tree. For traversals we will use following notations:
* we will use following notations:
1) for moving to left child. 2) for moving to right child. 3) for parent node.
R for moving to right child. L for moving to left child. P for parent node.
Thus with LRD, we will have six combination such as LDR, LRD, DLR, DRD, RDL, RLD.

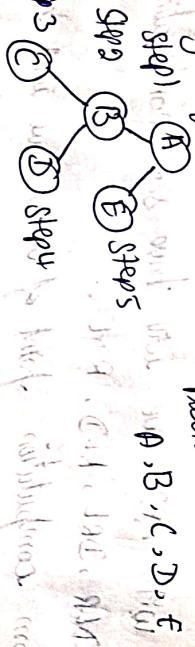
Recursive Routine

1) root :-
 inorder(root.left)
 print(root.val, end = "")

inorder(root.right)

2) preorder Traversal:
 The parent node is visited first, then left node and finally right node will be visited.

eg:-
 Preorder traversal
 A, B, C, D, E, F.



Alg :-

- If the tree is not empty then,

- visit the root node
- traverse the left subtree in preorder
- traverse the right subtree in preorder

Recursive routine

if root :-
 print(root.val, end = "")

preorder(root.left)
 preorder(root.right)

3) postorder Traversal:

The left node is visited first, then right node & finally parent node is visited. If the left subtree is not empty then, traverse the left subtree in postorder.

a) Traverse the left "

b) Traverse the right "

- visit the root node

Postorder Traversal
 C D B E A.

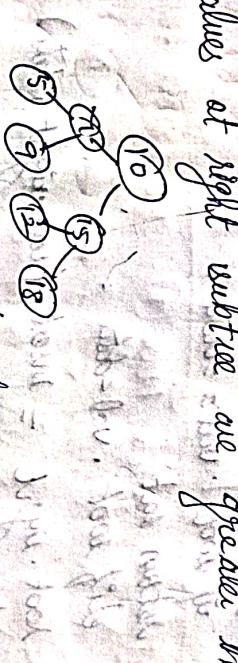
Recursive routine

def postorder(root):

if not postorder(root.left):
 postorder(root.right)
 print(root.val, end = "")

① Binary search tree:

Binary search tree is a binary tree in which nodes are arranged in specific order:
 * The values at left subtree are less than root node
 * The values at right subtree are greater than root node.



* Its based on binary search alg in root operation on Binary search tree.

1. Insertion of a node in a binary Tree:

- Create a new BST node & assign values to it
- Insert (root, data)
- if root == None, return the new node to calling fun.

ii) If $\text{root}.\text{val} == \text{data}$ then

return the root node

iii) If $\text{root} \Rightarrow \text{val} > \text{data}$.

call the insert fun with $\text{root} \Rightarrow \text{right}$ & assign the

return value in $\text{root} \Rightarrow \text{right}$

return value in $\text{root} \Rightarrow \text{right}$

iv) If $\text{root} \Rightarrow \text{data} > \text{data}$.

call the insert fun with $\text{root} \Rightarrow \text{left}$ & assign the

return value in $\text{root} \Rightarrow \text{left}$.

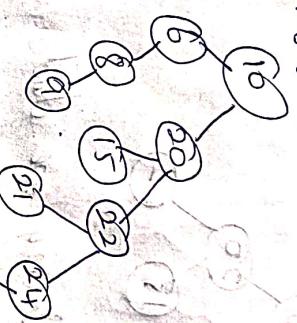
3) Finally, return the original root pointer to the calling fun.

python code:

```
def insert(root, data):  
    if root is None:  
        return Node(data)  
    else:  
        if root.val == data:  
            return root  
        elif root.val < data:  
            root.right = insert(root.right, data)  
        else:  
            root.left = insert(root.left, data)  
    return root
```

subproblem

* we want to insert 23



tree there are 3 cases.

i) Deletion of leaf node

ii) Deletion of node having one child.

iii) Deletion of node having two children.

② Deleting of element from the binary tree:

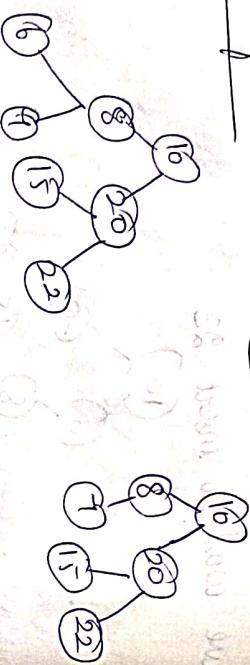
deletion of any nodes from binary search

* Start comparing new node with each node of the tree

* The node which is to be inserted is greater than

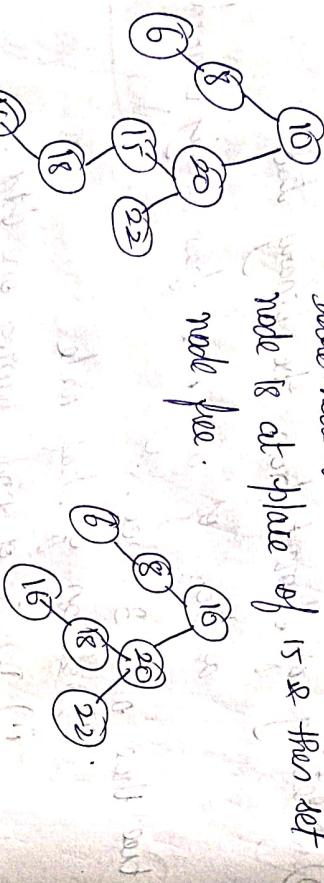
the value of current node we move on to the right

i) Deletion of leaf node.



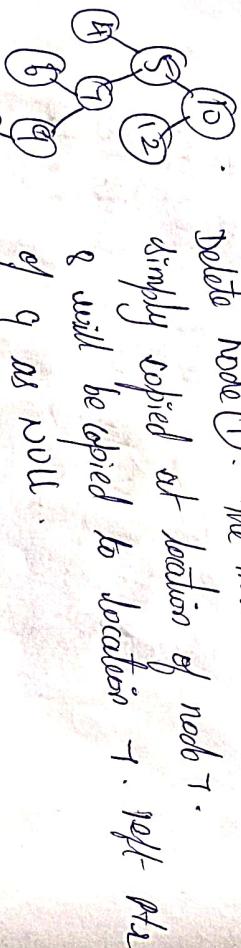
ii) Deletion of a node having one child.

Delete node 15, then we will simply copy node 18 at place of 15 & then set root.free.



iii) The node having two children.

Delete node 7. The inorder successor will be



Deleting a node with two children
temp = inOrderSuccessor (root.right)

root.val = temp.val
root.right = delete (root.right, temp.val)

return temp.

Python code:

```
def delete (root, key):
```

```
    if root is None:
```

```
        return root
```

```
    if key < root.val:
```

```
        root.left = delete (root.left, key)
```

```
    elif (key > root.val):
```

```
        root.right = delete (root.right, key)
```

```
    else:
```

```
        if root.left is None:
```

```
            temp = root.right
```

```
            root = None
```

```
            return temp
```

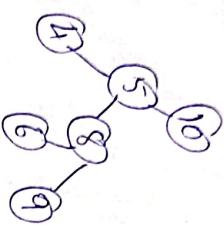
```
        elif root.right is None:
```

```
            temp = root.left
```

```
            root = None
```

```
            return temp
```

3. Searching a node from binary search tree:



- * The search start from root node, if the value of key node is greater than current node, then search on right subbranch otherwise search on left subbranch.
- * In the above example search 9. compare with 10. 9 is lesser so search on left subbranch. compared with 5, greater than 5, so go to right subbranch. compared with 8, greater than 8. so search on right subbranch. finally 9 is on right of 8.

Python code:

```
def search (root, key):
    if root is None or root.val == key:
        return root
    if root.val < key:
        return search (root.right, key)
    else:
        return search (root.left, key)
```

AVL Tree

An empty tree is height balanced if T is a non empty binary tree with T_L & T_R as its left & right subtrees.

* The T is height balanced if and only if

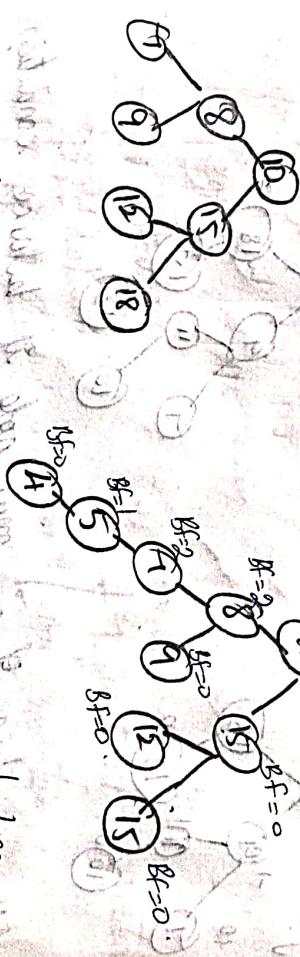
- i) $|T_L - T_R| \leq 1$ where H_L & H_R are height of T_L & T_R .
- ii) $H_L - H_R \leq -1$ where H_L & H_R are height of T_L & T_R .

Balancing of tree

Definition of Balance factor: A binary tree is defined to be

The $BF(T)$ of a node is height of left subtree - height of right subtree when h_L is a height of left subtree & h_R is height of right subtree.

- * $BF(T)$ is $-1, 0$ or $+1$.



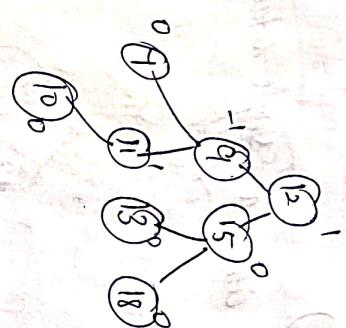
Difference between AVL Tree & Binary search tree

AVL Tree

- AVL tree is height balanced search. It's not a balanced tree.
- There is no concept of balanced factor.

node in an AVL tree

- 3) Searching of any desired node is further due to rebalancing of height of tree more complex to implement.
- 4) AVL property



Representation of AVL Tree:

- * AVL tree follows the property of binary search tree.
- * After insertion of any node in an AVL tree if the balance factor of any node becomes other than -1, 0 or 1 then it said that AVL property is violated.
- * Then we have to restore the destroyed balance condition.

insert 13



After insertion of a new node if balance condition gets destroyed, then the nodes on that path needs to be rebalanced. That is only affected subtree is to be rebalanced.

* The rebalancing should be in the way it should satisfy -

AVL property

Searching is not efficient when there are large number of node in the tree.

Simple to implement.

Insertion:

There are four different cases when rebalancing is required after insertion of new node.

- 1) An insertion of new node into left subtree of left child (LL)
- 2) An insertion of new node into right subtree of left child (LR)
- 3) An insertion of new node into left subtree of right child (RL)
- 4) An insertion of new node into right subtree of right child (RR)

The modification done on AVL tree in order to rebalance it

is called rotation of AVL tree.

Single rotation

LL rotation

RR rotation

Double rotation

→ Left-Right (LR rotation)

→ Right-Left (RL rotation)

Insertion alg:

- 1) Insert a new node as new leaf just as in ordinary binary search tree.
- 2) Now trace the path from insertion pt towards root for each node 'n' encountered, check if height of left(n) & right(n) diff by at most 1.

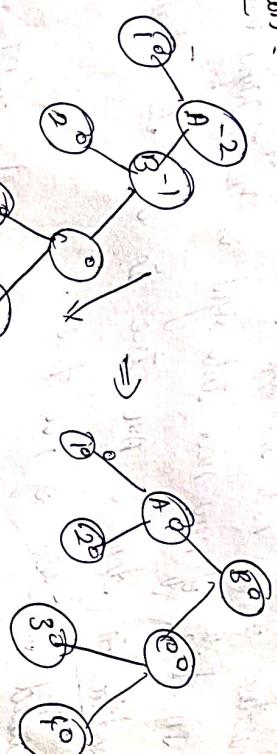
a) if yes, move towards $\text{parent}(v)$
 b) otherwise instructive by doing either a single rotation or double rotation

Different rotation in AVL Tree:

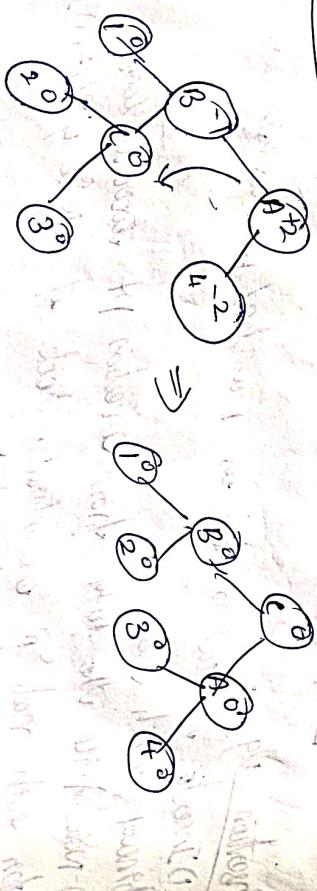
DLR rotation



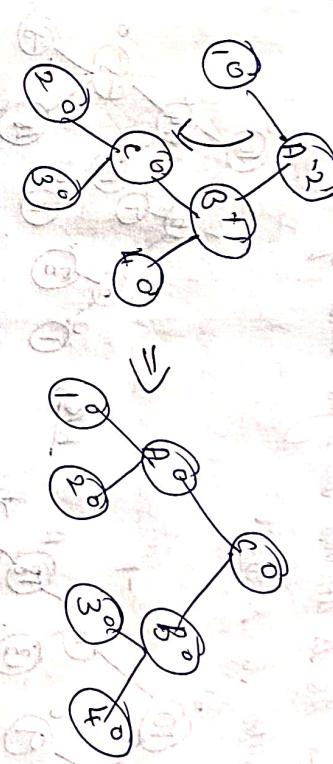
RR rotation:



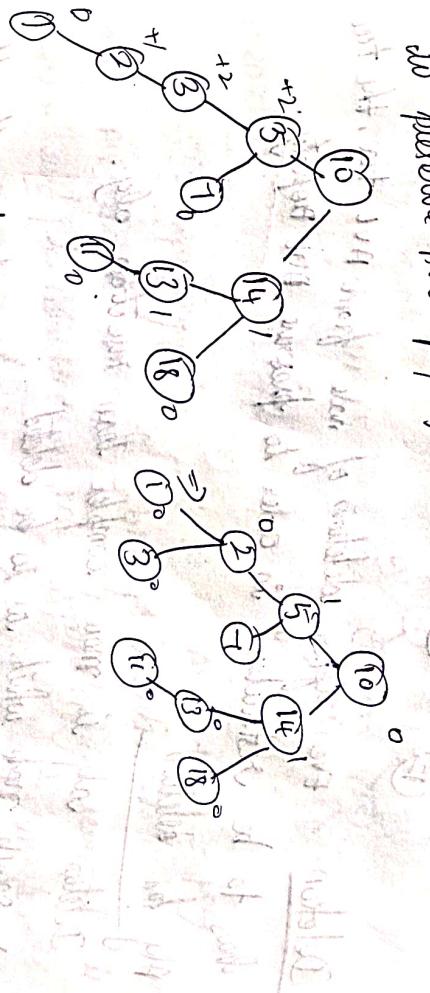
LR rotation:



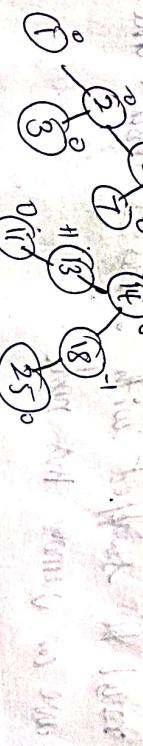
RL rotation:



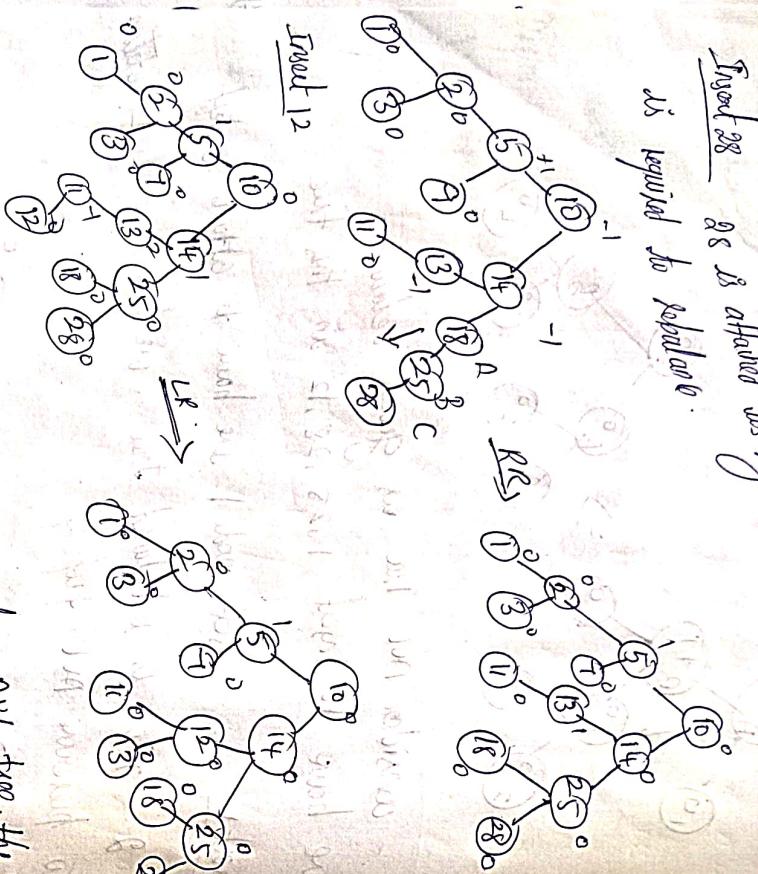
Insert 1: To insert node 1 we have to attach to left of 2. This is unbalanced tree. We have to apply LR rotation to preserve AVL property.



Now insert 25: inserted at the right of 18. No balancing is required as entire tree is balanced.



Inser₂ as is attached as right child of 25. RR rotation is required to rebalance.



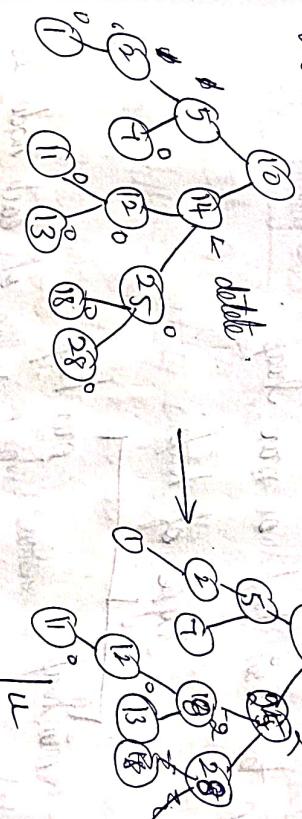
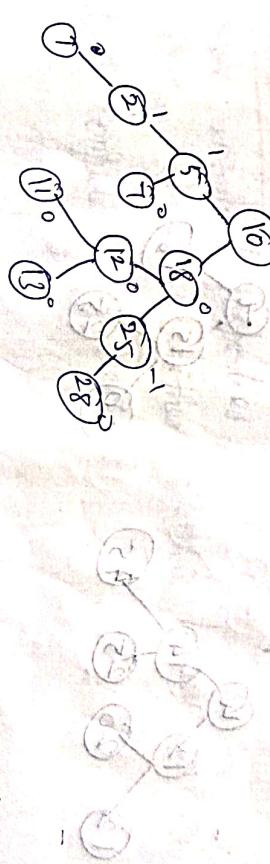
Deletion: even after deletion of node from AVL tree, the tree has to be restructured in order to preserve AVL property.

Alg for deletion:
Deletion alg is more complex than insertion alg.

1. search node which has to be deleted.
2. a) If target node to be deleted simply make it null after delete.
- b) If node to be deleted is not a leaf node, then the node must be swapped with inodes success. one swapped, we can remove this node.

Searching

The searching of a node in an AVL tree is very simple: AVL tree is basically binary search tree, the algorithm used for searching a node from binary search tree is the same one is used to search a node from AVL tree.



3) now we have to traverse back up the path toward root, checking the balance factor of every node along the path. If we encounter rebalancing in some subtree then balance using appropriate single or double rotation. We do this by order on AVL tree.

⑥ Heaps

Heap is a complete binary tree or almost property. Thus heap has two important properties:

- It should be complete binary tree.
- It should satisfy parental property.

Complete binary tree in which every parent node be either greater or lesser than its child nodes.

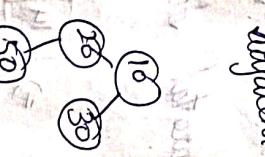
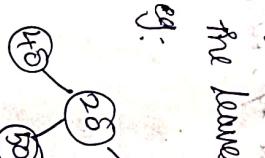
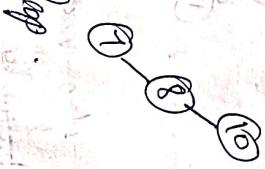
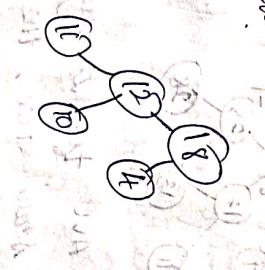
Heap can be min heap or max heap.

Type of heap

min heap

max heap

is a tree in which value of each node is more than or equal to the value of its children nodes.



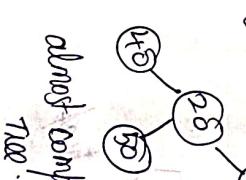
Complete binary tree:

It's a binary tree in which all the levels of binary tree are filled completely except the lowest level nodes.

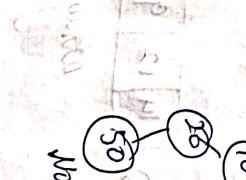
Almost complete binary tree:

- Each node has a left child whenever it has a right child.
- For left child there may not be a right child.
- The leaf in a tree must be present at height height.
- The leaves are on two adjacent levels.

eg:



almost complete binary tree.



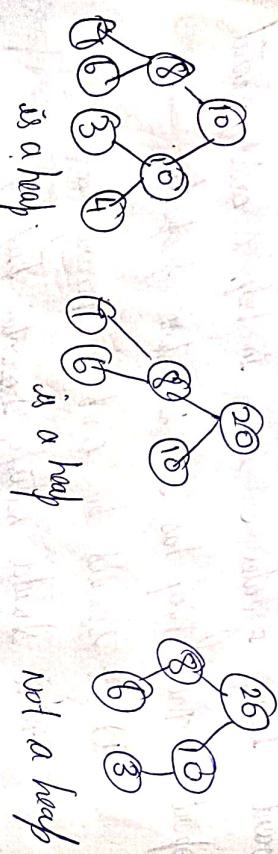
not almost binary tree.

Operations on Heap:

Some important properties.

- There should be either complete binary tree or almost complete binary tree.

parent dominance property is violated ($q < p$) we swap two values.



Insertion of element:

Algorithm for inserting an element :

1. Insert element at last position in heap.
2. Compare with its parent, swap the two nodes if parental dominance condition gets violated.

parental dominance = parent is greater than its children

3. Continue comparing the new element with node up, each time by satisfying parental dominance condition.

e.g. -

```
graph LR; subgraph Initial [Initial]; 14[14] --- 12[12]; 14 --- 9[9]; 14 --- 8[8]; 14 --- 11[11]; 14 --- 10[10]; end; subgraph Final [Final]; 14[14] --- 12[12]; 14 --- 9[9]; 14 --- 18[18]; 14 --- 11[11]; 14 --- 10[10]; end;
```

array rep of heap
array [14, 12, 9, 8, 11, 10]

insert 18

parental dominance property is violated ($q < p$) we swap two values .

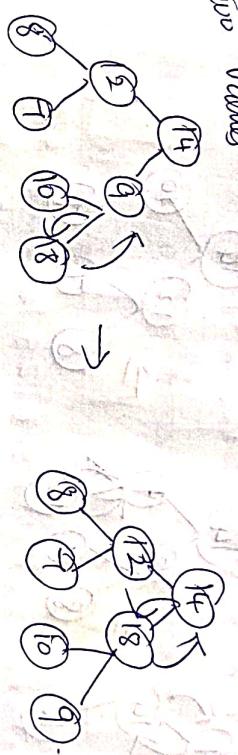
```
graph LR; subgraph Initial [Initial]; 8[8] --- 12[12]; 8 --- 9[9]; 8 --- 10[10]; 8 --- 11[11]; 8 --- 14[14]; 8 --- 15[15]; 8 --- 16[16]; end; subgraph Final [Final]; 18[18] --- 12[12]; 18 --- 9[9]; 18 --- 10[10]; 18 --- 11[11]; 18 --- 14[14]; 18 --- 15[15]; 18 --- 16[16]; end;
```

attach this node at a
last node.

Deletion of Element:

Algorithm for deletion of element from heap

1. Exchange the root with last leaf.
2. Decrease the heap size by 1.
3. Heify the smaller tree using bottom up construction algorithm.

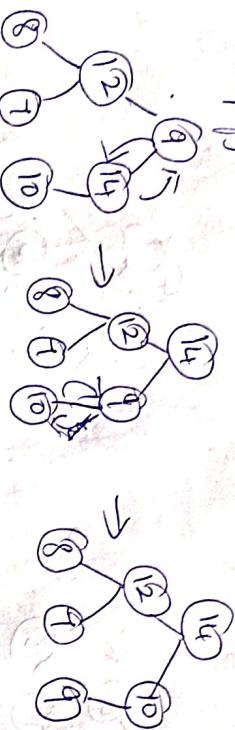


In top down approach the heap is

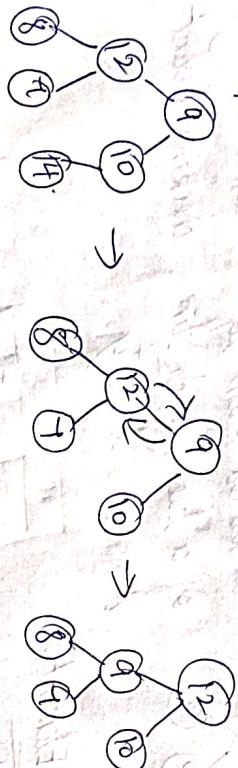
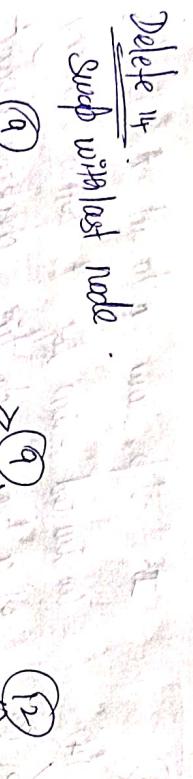
converted from top to bottom sloping

of a tree, each time checking parent dominance property .

Heaps



Delete $\frac{14}{14}$
Swap with last node



Application of Binary Heaps:

1. Binary heaps are useful data structures for sorting.

the elements using heap sort method.

2. Binary heaps are used to find the shortest path using Dijkstra's shortest path alg.

3. For finding kth smallest element binary heaps are used.

① Multi-way search Trees:

B-Tree : B-Tree is a specialized multi-way tree used

to store the records in a disk. There are number of subtrees to each node. So that the height of

the tree is relatively small. So that only small number of nodes must be read from disk to retrieve an item. The goal is to get fast access of the data. multi-way search

B-Tree is a multiway search tree of order m is an

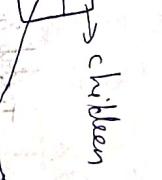
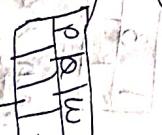
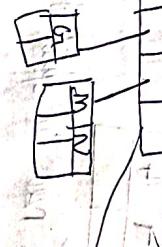
ordered tree where each node has at most m children. If there are n number of children in a node then $(n-1)$ is the number of keys in the node.

e.g. - following is a tree of order 4.

level 1

F | K | O

→ key



From above tree following observation can be made.

1. The node which has n children poses $(n-1)$ keys

2. The keys in each node are in ascending order.

3. For every node $Node.child[i]$ has only keys which are less than $Node.key[i]$. Similarly, $Node.child[i]$ has only keys which are greater than $Node.key[i]$.

Properties :

Rule 1 : All the leaf nodes are on the bottom level.

Rule 2 : The root node should have at least 2 children.

Rule 3 : All the internal node except root node have at

Least ceil ($m/2$) nonempty children.

Rules : Each leaf node must contain at least ceil ($m/2$) - 1 keys.

Insertion :

Construct B tree with order 5 with following numbers :

3, 14, 7, 1, 8, 5, 11, 11, 13, 6, 23, 12, 20, 26, 4, 16, 18, 24,

25, 19.

The order 5 means at the most 4 keys are allowed.
The internal node should have at least 3 nonempty children
and each leaf node must contain at least 2 keys.

Step 1 insert 3, 14, 7, 1 as follows :

1	3	7	14
---	---	---	----

Step 2 Insert 8, then we need to split the node 1, 3, 7, 8, 14 at medium.

1	3	5	6
8	11	12	

Step 3 : Insert 5, 11, 17 which can be easily inserted in B tree.

1	3	5	6
8	11	14	17

Step 4 Now insert 13 then leaf node will have 5 keys.

which is not allowed. Hence 8, 11, 13, 14, 17 is split & medium node 13 is moved up.

Step 5 Now insert 6, 23, 12, 20 without any split.

1	3	5	6
8	11	12	
14	17	20	

Step 6 : 26 is inserted at rightmost leaf node. Hence 14, 17, 20 & 23, 26 the node is split & 20 will be moved up.

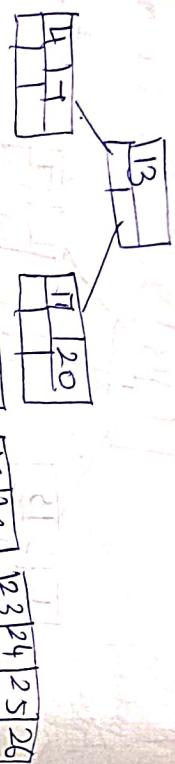
1	3	5	6
8	11	12	
14	17	20	

Step 7 Insertion of 4 causes left most node to split.
The 13, 4, 5, 6 causes key 4 to move up. Then insert 16, 18, 24, 25.

1	3	5	6
8	11	12	
14	17	20	
16	18	24	25

Step 8 Finally insert 19, then 4, 7, 13, 19, 20 needs to be split.
The median (3) will be moved up to form a root node.

The tree will



Alg for insertion in B-tree:

Algorithm insert (root, key)

{
temp \leftarrow root

if $h[\text{temp}] = 2t - 1$ then

S \leftarrow get-node ()

root \leftarrow S

leaf [S] \leftarrow FALSE

h[S] \leftarrow 0

child [S] \leftarrow root

split-child (S,1,root)

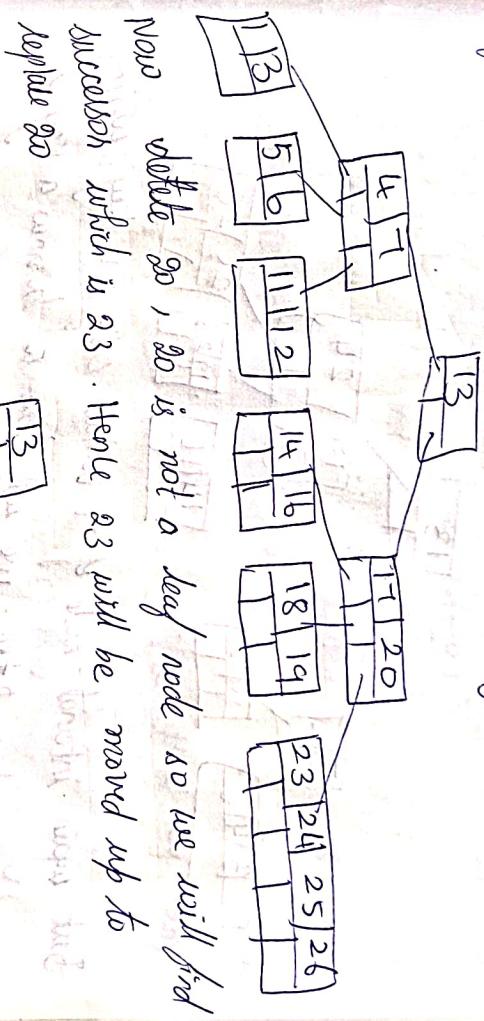
Insert-In (S, key)

} else Insert-In (S, key)

} J

Deletion:

Consider a B tree

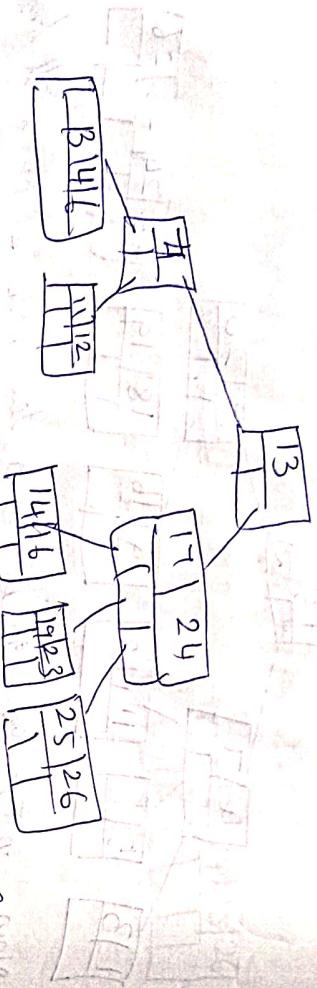


Now delete 18 . will case the node with only one key.
which is not desired in B-tree of order 5 . The sibling node is immediately right has a extra key . so we can borrow a key from parent and move spare key of sibling to up .

Delete 5 , but its not easy , because the leaf node has no extra keys to immediate left or right . In such case combine the node with siblings . Remove 5 & combine 6 with node 13 .

To make tree balanced we have to move parent key down.

The running time of search operation depends upon the height of the tree. It is $O(\log n)$.



But again internal node of T contains only one key which
- I - → top : we will try to borrow a key from

is not shown as B has no space key. Hence combine
Sibling But sibling 17,24 has no space key.

With 13 217, 14

The diagram consists of several boxes containing numbers, connected by arrows:

- Box 1:** A 2x2 grid containing 13 and 14.
- Box 2:** A 2x2 grid containing 5 and 6.
- Box 3:** A 2x2 grid containing 8 and 11.
- Box 4:** A 2x2 grid containing 11 and 12.
- Box 5:** A 2x2 grid containing 17 and 20.
- Box 6:** A 2x2 grid containing 14 and 16.
- Box 7:** A 2x2 grid containing 18 and 19.
- Box 8:** A 2x2 grid containing 23 and 24.
- Box 9:** A 2x2 grid containing 24 and 25.
- Box 10:** A 2x2 grid containing 25 and 26.

Arrows indicate connections between the following pairs of boxes:

- Box 1 to Box 2
- Box 2 to Box 3
- Box 3 to Box 4
- Box 4 to Box 5
- Box 5 to Box 6
- Box 6 to Box 7
- Box 7 to Box 8
- Box 8 to Box 9
- Box 9 to Box 10
- Box 10 to Box 5

If we want to find "then"

1) "L13 ~~move~~ right most node
2) "L13 move in second block
3) "L13 move right most node

Alg

Algorithm Search (temp, target)

```

{ 
    i ← 1
    while i ≤ h [temp] AND (target = key [temp])
        return (temp, i)
    if (leaf [temp] == TRUE) then
        return NULL
    else READ (C [temp])
        selfish search (C, [temp], target)
    }

```

B+tree

In B+tree the traversing of nodes is done in inorder manner which is time consuming. we want such a data structure of B-tree which will allow us to access data sequentially, instead of inorder traversing.

Definition: In B+tree from leaf nodes reference to any other node can be possible. The leaves in B+tree form a linked list which is useful in scanning the nodes sequentially. The insertion & deletion operations are similar to B-trees.

e.g.: construct B+tree for F,S,Q,X,C,L,H,I,T,V,W.

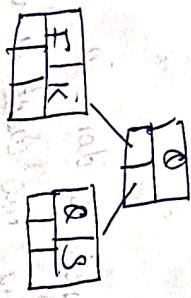
* Constructing B+tree is similar to B tree but the only difference here is that, the parent node also appears in the leaf nodes. we will build B+tree for order 5.

* The order 3 means at the most 2 keys are allowed.

Step 1 Insert F & S



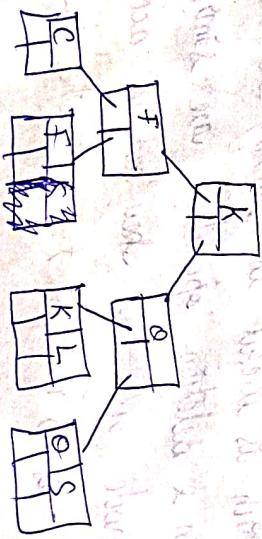
Step 3 insert K



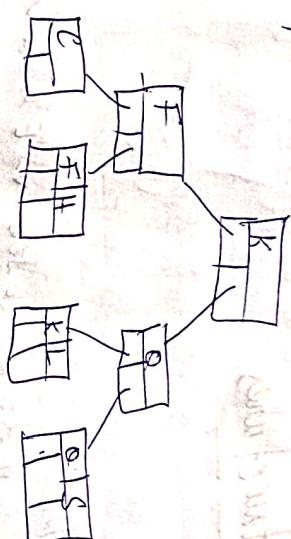
Step 4 Insert L, but this will create a seq C,F,K. This will split F go up.



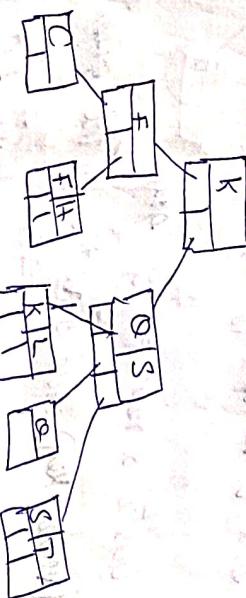
Step 5 Insert L. This will make the seq F,K,L. Again this sequence will split up & K will go up. Then the seq F,K,Q will split up & K goes up.



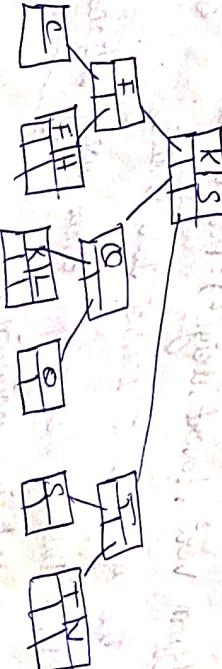
Step 6 Insert H. This will make the seq F,K,K. The seq will split up & H will go up.



Step 7 Insert T. Sequence Q,S,T will split up. The S will go up.



Step 8 Insert V. The sequence S,T,V will split up. T will go up again the seq Q,S,T will split up & S will go up.



Step 9 Insert W. The seq become T,V,W. Then V goes up.

