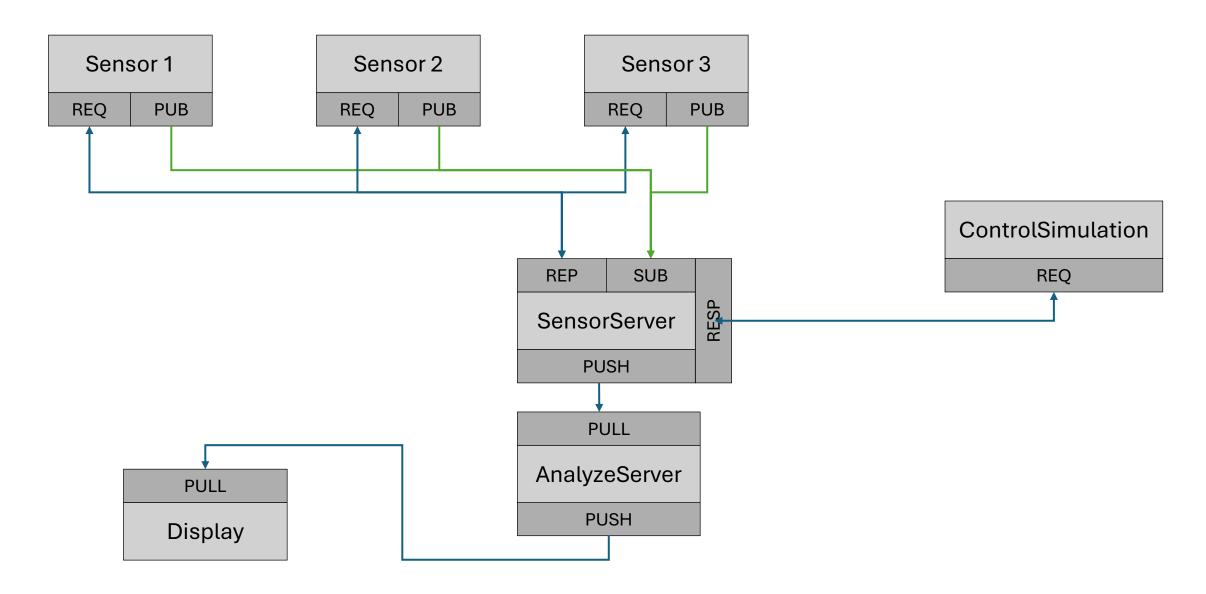
# DISTRIBUTED SYSTEMS LABORATORY

**SENSOR MONITORING UNIT** 

#### **OVERVIEW COMMUNICATION SYSTEM**



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### **ENUMERATION IN COMMUNICATION**

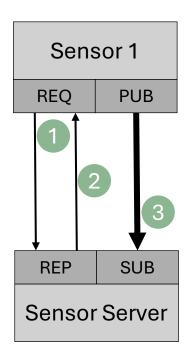
Туре	Enum	Enum			
Name	sens_type	9			
Description	categoris	categorisation or type of trasmitting sensor			
value name	enum id	Description			
TYPE_TEMPERATURE	0	sensor type is temperature sensor			
TYPE_PRESSURE	1	sensor type is pressure sensor			
TYPE_ROTATION	2	sensor type is rotation sensor			
TYPE_ANGLE	3	sensor type is angle sensor			

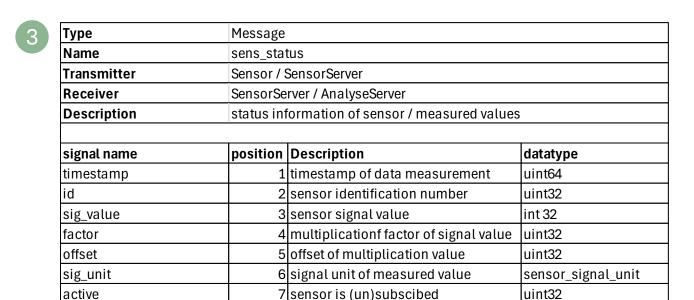
Туре	Enum			
Name	disp_thre	disp_threshold_status		
Description	Status of	Status of Threshold check		
	-			
value name	enum id	Description		
NO_EVALUATION	0	no evaluation run		
VALUE_INSIDE_AREA	1	measured Value is inside the area		
VALUE_TO_HIGH	2	sensor value is over upper theshold		
VALUE_TO_LOW	3	3 sensor value is over lower theshold		

Туре	Enum	Enum		
Name	ctrl_requ	est_id		
Description	ReadSetD	PataByldentifier request identification number		
value name	enum id	Description		
GET_SENSOR_MAX_ID	0	get number of registerd sensors		
UNSUBSCRIBE_SENSOR_ID	1	set Sensor ID to delete from System		
SUBSCRIBE_SENSOR_ID	2	set Sensor ID to delete from System		
SET_LOWER_THRESHOLD	3	set lower threshold of Sensor for Alert		
SET_UPPER_THRESHOLD	4	set upper threshold of Sensor for Alert		
DISPLAY_GRAPH	5	display measured values in seperate window		

Туре	Enum		
Name	sens_sigr	nal_unit	
Description	Unit desc	riptin of the sensor signal	
value name	enum id	Description	
UNIT_UNSPECIFIED	0	no unit specified	
UNIT_TEMP_KELVIN	1	Unit of temperature sensor Kelvin	
UNIT_TEMP_CELSIUS	2	Unit of temperature sensor Celsius	
UNIT_PRES_BAR	3	Unit of pressure sensor Bar	
UNIT_PRES_PASCAL	4	Unit of pressure sensor Pascal	
UNIT_ROTA_RPM	5	Unit of rotation sensor round per minute	
UNIT_ROTA_ANGLE	6	Unit of angle sensor in degree	

#### SENSOR TO SENSOR SERVER COMMUNICATION





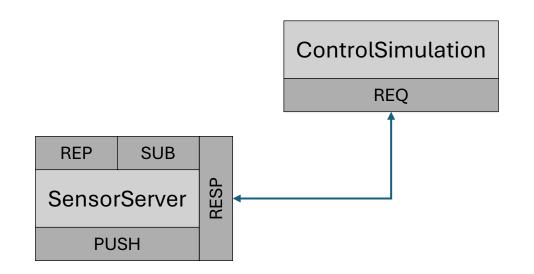


Туре	Message	Message				
Name	sens_cor	sens_com_join				
Transmitter	Sensor					
Receiver	SensorSe	SensorServer				
Description	Connect	Connect new sensors to system				
	-					
signal name	position	Description	datatype			
connect	1	connection request	uint32			
type	2	type of sensor	sensor_type			
sample freq	3	sample frequency of sensor	uint32			



Туре	Message			
Name	sens_con	n_join_resp		
Transmitter	SensorSe	rver		
Receiver	Sensor	Sensor		
Description	Response on ComJoin to handshake the connection			
signal name	position Description datatype			
sensor_id	1	sensor id as handshake	uint32	

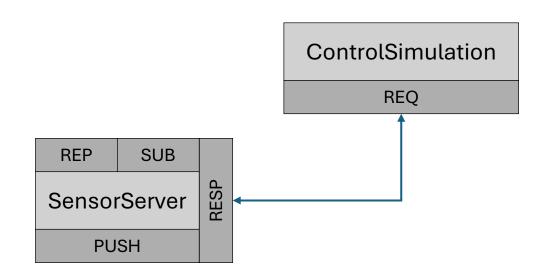
## CONTROL FUNCTIONS BY REMOTE - REQUEST



Туре	Message	Message			
Name	ctrl_RSDE	BI			
Transmitter	SimContr	ol			
Receiver	SensorSe	rver			
Description	ReadSetD	DataByldentifier message			
	-				
signal name	position	Description	datatype		
id	1	requestid	request_id		
value_0	2	buffer for value or parameter	uint32		
value_1	3	buffer for value or parameter	uint32		
value_2	4	buffer for value or parameter	uint32		
value_3	5	buffer for value or parameter	uint32		
value_4	6	buffer for value or parameter	uint32		
value_5	7	buffer for value or parameter	uint32		
value_6	8	buffer for value or parameter	uint32		
value_7	9	buffer for value or parameter	uint32		

	request_id					
signal name	GET_SENSOR_MAX_ID	UNSUBSCRIBE_SENSOR_ID	UNSUBSCRIBE_SENSOR_ID	SET_LOWER_THRESHOLD	SET_UPPER_THRESHOLD	DISPLAY_GRAPH
id	0	1	2	3	4	5
value_0	-	sensor_id	sensor_id	sensor_id	sensor_id	sensor_id
value_1	-	-	-	lower_threshold	upper_threshold	-
value_2	-	-	-	-	-	-
value_3	-	-	-	-	-	-
value_4	-	-	-	-	-	-
value_5	-	-	-	-	-	-
value_6	-	-	-	-	-	-
value_7	-	-	-	-	-	-

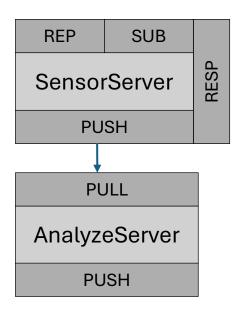
#### CONTROL FUNCTIONS BY REMOTE - RESPONSE



Туре	Message	Message			
Name	ctrl_RSDE	BI_resp			
Transmitter	SensorSe	rver			
Receiver	SimContr	ol			
Description	ReadSetD	DataByldentifier response message	)		
signal name	position	Description	datatype		
id	1	requestid	request_id		
value_0	2	buffer for value or parameter	uint32		
value_1	3	buffer for value or parameter	uint32		
value_2	4	buffer for value or parameter	uint32		
value_3	5	buffer for value or parameter	uint32		
value_4	6	buffer for value or parameter	uint32		
value_5	7	buffer for value or parameter	uint32		
value_6	8	buffer for value or parameter	uint32		
value_7	9	buffer for value or parameter	uint32		

		request_id				
signal name	GET_SENSOR_MAX_ID	UNSUBSCRIBE_SENSOR_ID	UNSUBSCRIBE_SENSOR_ID	SET_LOWER_THRESHOLD	SET_UPPER_THRESHOLD	DISPLAY_GRAPH
id	0	1	2	3	4	5
value_0	number of sensors	sensor_id	sensor_id	sensor_id	sensor_id	sensor_id
value_1	-	ack=1	ack=1	lower_threshold	upper_threshold	ack=1
value_2	-	-	-	ack=1	ack=1	-
value_3	-	-	-	•	-	-
value_4	•	-	-	-	-	-
value_5	-	-	-	-	-	-
value_6	-	-	-	-	-	-
value_7	-	-	-	-	-	-

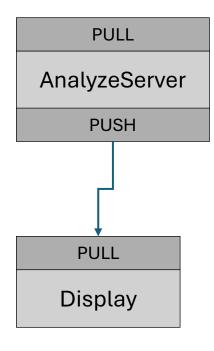
#### CONTROL FUNCTIONS BY REMOTE – TO ANALYZE SERVER



Туре	Message	Message			
Name	ctrl_requ	est_transfert			
Transmitter	SensorSe	rver			
Receiver	AnalyseS	erver			
Description	Transfert	Transfert analyse request			
	-				
signal name	position	Description	datatype		
sensor_id	1	ID of sensor to set treshold	uint32		
request_type	2	2 request_type ctrl_request_id			
value	3	value to set (default -> 0)	uint32		

Туре	Enum		
Name	ctrl_requ	est_id	
Description	ReadSetD	DataByldentifier request identification number	
value name	enum id	Description	
GET_SENSOR_MAX_ID	0	get number of registerd sensors	
UNSUBSCRIBE_SENSOR_ID	1	set Sensor ID to delete from System	
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SET_LOWER_THRESHOLD	3	set lower threshold of Sensor for Alert	
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DISPLAY_GRAPH	5	display measured values in seperate window	

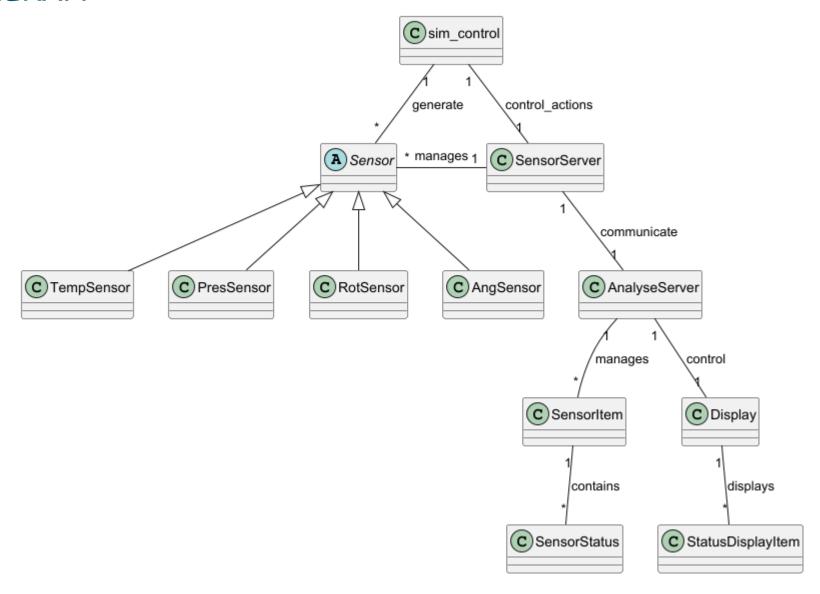
#### **DISPLAY COMMUNICATION**



Туре	Message	Message			
Name	disp_sen	disp_sensor_status			
Description	Status di	Status displayed in the Display			
signal name	position	Description	datatype		
sensor_id	1	sensor id	uint32		
fequency	2	Sensor is (un)subcsibed	uint32		
type	3	timestamp of data measurement	sensor_type		
active	4	sensor signal value	int 32		
timestamp	5	timestamp of data measurement	uint32		
sig_value	6	sensor signal value	uint32		
factor	7	factor of multiplication value	sensor_signal_unit		
offset	8	offset of multiplication value	uint32		
sig_unit	9	signal unit of measured value	uint32		
lower_threshold	10	lower threshold for signal	uint32		
upper_threshold	11	upper threshold for signal	uint32		
threshold_status	12	status of theshold	disp_threshold_status		

Туре	Message			
Name	disp_trans_done			
Description	Transmit	Transmittion Done Flag -> Data gets displayed		
signal name	position	Description	datatype	
done	1	done flag	uint32	

#### **CLASS DIAGRAM**



## **SEQUENCE DIAGRAM**

