

2025-11-01

Learning Objective: Understand latency monitoring (every cycle), deadline detection, weakly-hard constraints (m-of-k pattern), real-time metrics collection, and production deployment validation

The Monitoring Challenge

💡 Key Concept

Question: How do you know if your control loop is healthy in production?

Problem: Silent failures - system appears fine until catastrophic failure

Solution: Real-time monitoring infrastructure tracking every cycle

Three Types of Failures

⚠ Failure Modes

Type 1: Hard Real-Time Violation

Miss ONE deadline → System fails (e.g., aircraft flight control)

Type 2: Soft Real-Time Degradation

Miss SOME deadlines → Performance degrades gracefully (e.g., video streaming)

Type 3: Weakly-Hard Constraint Violation

Miss TOO MANY deadlines in a window → System unstable (e.g., robot control)

Pattern: "m-of-k" - At most m misses in any k consecutive cycles

Our Focus: Type 3 (weakly-hard constraints for control systems)

Latency Monitor: The Heartbeat Tracker

💡 Key Concept

Purpose: Track timing of EVERY control cycle (100 Hz = 10ms period)

Metrics: Start time, end time, duration, deadline status

Latency Monitoring Workflow

⌚ Four-Step Monitoring

Step 1: Mark Cycle Start

```
lstnumberstart_time = monitor.start()
```

Records high-resolution timestamp (nanosecond precision)

Step 2: Execute Control Loop

```
lstnumberstate = get_sensor_data()
lstnumbercontrol = controller.compute_control(state)
lstnumbersend_actuator_command(control)
```

Step 3: Mark Cycle End

```
lstnumbermissed = monitor.end(start_time)
```

Computes duration, checks if > 10ms deadline

Step 4: Log if Deadline Missed

If missed: log timestamp, duration, controller state for debugging

Deadline Detection Logic

Example

Deadline: 10 ms (for 100 Hz control)

Cycle Duration: 8.5 ms → PASS (within deadline)

Cycle Duration: 12.3 ms → MISS (exceeded deadline by 2.3 ms)

Action on Miss: Increment counter, log details, check weakly-hard constraint

Weakly-Hard Constraints: m-of-k Pattern

💡 Key Concept

Definition: At most m deadline misses in any k consecutive cycles

Example: (2, 10) constraint = At most 2 misses in any 10 consecutive cycles

Why? Control systems tolerate OCCASIONAL misses but fail if too frequent

Sliding Window Detection

💻 Window-Based Checking

Window Size: $k = 10$ cycles

Threshold: $m = 2$ misses

Algorithm:

enumiMaintain circular buffer of last k outcomes (PASS/MISS)

0. enumiOn each cycle: Add new outcome, drop oldest
0. enumiCount misses in current window
0. enumiIf misses > $m \rightarrow$ Constraint violated!

Example Sequence:

0. Cycles: [P P P M P P P P M P] → 2 misses in 10 → OK
- Cycles: [P P M P P P P M P M] → 3 misses in 10 → VIOLATION!

Constraint Violation Response

⚠ Common Pitfall

If Weakly-Hard Constraint Violated:

- Log critical alert with full system state
- Reduce controller aggressiveness (lower gains temporarily)
- Switch to failsafe mode (simpler controller)
- OR: Emergency stop (if safety-critical system)

Production Rule: System NOT ready for deployment if violates (2, 10) during stress tests

Real-Time Metrics Collection

Metrics Dashboard

Per-Cycle Metrics:

- Cycle duration (ms)
- Deadline status (PASS/MISS)
- Controller computation time (μ s)
- Network latency (UDP roundtrip, ms)

Aggregate Metrics (per 1000 cycles):

- Mean cycle duration: 8.7 ms
- 95th percentile: 9.5 ms
- 99th percentile: 11.2 ms (indicates occasional spikes)
- Miss rate: 1.2% (12 misses per 1000 cycles)
- Longest miss: 15.3 ms

Weakly-Hard Compliance:

- (2, 10) violations: 0 (100% compliant)
- (3, 20) violations: 0 (100% compliant)

Production Deployment Validation

💡 Key Concept

Criteria: System is production-ready if ALL tests pass:

enumiThread safety: 11/11 tests passing

0. enumiMemory: Zero growth over 10,000 simulations

0. enumiTiming: < 5% deadline miss rate

0. enumiWeakly-hard: Zero (2, 10) violations in 24-hour test

Status: HIL + Monitoring infrastructure meets ALL criteria [OK]

24-Hour Stress Test Results

leftrightarrow Example

Test Configuration:

- 0. Duration: 24 hours continuous operation
 - Controller: Hybrid Adaptive STA-SMC
 - Scenario: Random disturbances every 30 seconds
 - Target hardware: Raspberry Pi 4 (1.5 GHz quad-core)

Results:

- Total cycles: 8,640,000 (24 hrs × 3600 s/hr × 100 Hz)
- Deadline misses: 103,680 (1.2% miss rate) [OK]
- (2, 10) violations: 0 [OK]
- Memory: Baseline 45 MB, final 45 MB (zero growth) [OK]
- CPU temperature: 55-62°C (within safe range) [OK]

Verdict: PRODUCTION-READY

Monitoring Tools Integration

Monitoring Stack

Real-Time Dashboard (Streamlit UI):

- Live cycle duration plot (rolling 1000 cycles)
- Miss rate gauge (target: < 5%)
- Weakly-hard compliance status
- CPU/memory usage graphs

Logging System:

- Structured JSON logs (timestamp, duration, status, controller state)
- Rotating log files (100 MB max, keep last 10)
- Location: academic/logs/monitoring/

Alert System:

- Email on weakly-hard violation
- Slack notification if miss rate > 10%
- SMS for emergency stop events

Key Takeaways

Quick Summary

Monitoring Purpose: Track health of control loop in production (detect silent failures)

Latency Monitor: Tracks EVERY cycle (start time, end time, duration, deadline status)

Deadline: 10 ms for 100 Hz control (duration > 10 ms = MISS)

Weakly-Hard Constraints: m-of-k pattern (e.g., (2, 10) = at most 2 misses in 10 cycles)

Sliding Window: Circular buffer of last k outcomes, count misses, check threshold

Violation Response: Log alert, reduce gains, switch to failsafe, or emergency stop

Real-Time Metrics: Per-cycle duration + Aggregate statistics (mean, 95th/99th percentile, miss rate)

Production Criteria: Thread safety (11/11), memory (zero growth), timing (< 5% miss), weakly-hard (zero violations in 24-hour test)

24-Hour Test: 8.64M cycles, 1.2% miss rate, 0 (2,10) violations [PASS]

Monitoring Stack: Real-time dashboard (Streamlit), structured logs (JSON), alert system (email/Slack/SMS)

Quick Reference: Monitoring Commands

Enable Latency Monitoring

```
lstnumbermonitor = LatencyMonitor(dt=0.01) 100 Hz
lstnumberIn control loop start = monitor.start() ... execute control ... missed =
    print(f"Missrate: {missrate:.1f} %")
lstnumberGet statistics stats = monitor.get_statistics() print(f"Missrate: {stats['missrate']:.1f}
```

What's Next?

💡 Key Concept

E014: Development Tools & Workflow

Testing infrastructure, CI/CD pipelines, code quality gates, contributor guidelines

Remember: Monitor EVERY cycle - silent failures are the deadliest!