

2025-11-01

E014: Development Infrastructure

DIP-SMC-PSO Educational Series

January 25, 2026

Overview

This episode covers development infrastructure from the DIP-SMC-PSO project.

Part: Part3 Advanced

Duration: 15-20 minutes

Source: Comprehensive Presentation Materials

section0 Educational System Overview

Mission: Democratize access to advanced control theory
 44 episodes covering Phases 1-4, 40 hours audio content
 Convert written materials to commute-friendly learning format

section0 Beginner Roadmap: Path 0

Target: Zero prerequisites (no coding/control theory background)
 Duration: 125-150 hours over 4-6 months
 Phase Breakdown:

- **Computing Fundamentals (30 hrs)**
- Terminal/command line basics - Git version control - Package management (pip, conda)
- **Python Programming (40 hrs)**
- Variables, functions, classes - NumPy/SciPy fundamentals - Matplotlib visualization
- **Physics & Mathematics (35 hrs)**
- Classical mechanics (pendulum dynamics) - Linear algebra (matrices, eigenvalues) - Differential equations (ODEs)
 - **Control Theory (20 hrs)**
- PID control introduction - State-space representation - Lyapunov stability basics

section0 Tutorial System Architecture

Progressive Learning Structure:		
Tutorial	**Topic**	**Duration**
Tutorial 01	Getting Started CLI basics, first simulation	1-2 hrs
Tutorial 02	Controller Comparison All 7 controllers, PSO tuning	3-4 hrs
Tutorial 03	Advanced Features Batch simulation, monitoring	4-5 hrs
Tutorial 04	Web Interface Streamlit dashboard, real-time plots	2-3 hrs
Tutorial 05	Research Workflow Reproducible experiments, paper figures	5-8 hrs

Every tutorial includes runnable code, expected outputs, troubleshooting tips

section0 NotebookLM Podcast Series

Innovation: Convert documentation to podcast-style audio
 Series Statistics:

- **44 episodes** covering Phases 1-4 - **40 hours** total audio content - **125 hours** equivalent learning material - TTS optimization for commute/exercise listening
- **Episode Structure:**
 - **Phase 1:** Foundations (Python, Git, Physics) – 12 episodes - **Phase 2:** Control Theory (SMC, PSO) – 10 episodes - **Phase 3:** Implementation (Controllers, Simulation) – 14 episodes - **Phase 4:** Advanced Topics (HIL, Monitoring, Research) – 8 episodes
 - Episode templates, TTS optimization checklist, phase-specific examples

See: '.ai_workspace/guides/notebooklm_guide.md'

section0 Learning Path Integration

Seamless Progression Across Paths:

[Visual diagram - see PDF]

Resources

- **Repository:** <https://github.com/theSadeQ/dip-smc-pso.git>
- **Documentation:** See docs/ directory
- **Getting Started:** docs/guides/getting-started.md