

2025-11-01

E007: Testing and Quality Assurance

4,563 Tests in 45 Seconds

Part 2 · Duration: 15-20 minutes

Beginner-Friendly Visual Study Guide

🎯 **Learning Objective:** Understand test pyramid, coverage standards (85/95/100%), property-based testing, and quality gates for research vs production

The Testing Challenge

💡 Key Concept

Question: How many tests to validate 105,000 lines of code?

Answer: 4,563 tests - BUT quality > quantity!

Real question: What deserves a test? When do you have enough?

Three Hard Questions

⚠️ Common Pitfall

enumiWhat to test? One input or all possible inputs? (All is impossible \Rightarrow sample strategically)

0. enumi**When to stop?** Can always write more tests - what's "good enough"?

0. enumi**What to validate?** Implementation details (break on refactor) vs behavior (stable contract)?

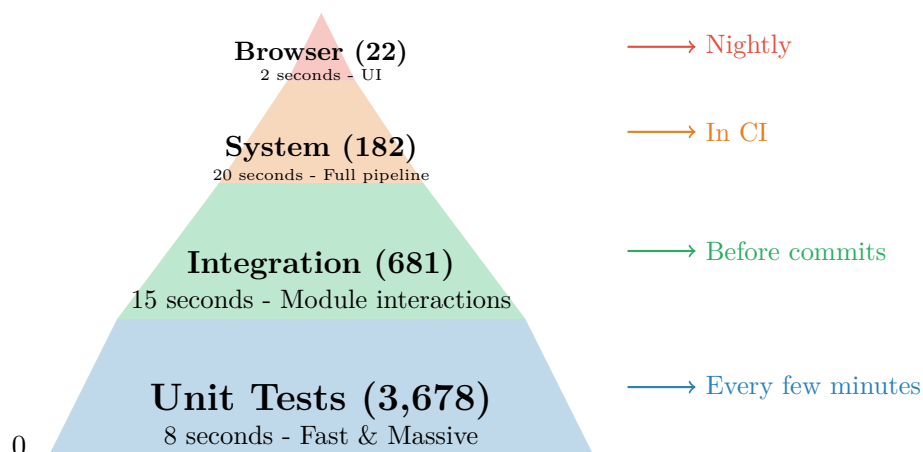
Testing is strategic choice-making under time constraints

Test Suite Breakdown: 4,563 Tests

🔧 Test Suite Distribution

Level	Count	Percent	Time/Test
Unit Tests	3,678	81%	200 μ s
Integration Tests	681	15%	50 ms
System Tests	182	4%	2 s
Browser Tests	22	0.5%	5 s
TOTAL	4,563	100%	45 seconds

The Test Pyramid



💡 Pro Tip**Pyramid Philosophy:**

- **Wide base:** Lots of fast tests (run constantly during development)
- **Narrow top:** Few slow tests (run before commits, in CI)
- **Speed enables feedback:** 45 seconds total \Rightarrow run every few minutes!

Unit Tests: The Foundation**🔗 Example**

3,678 unit tests, 200 microseconds each (8 seconds total)

Example: Classical SMC has 51 unit tests covering:

- Zero state (equilibrium)
- Maximum gains (saturation)
- Boundary layer transitions ($s \rightarrow 0$)
- Edge cases (NaN, infinity, negative values)

Pattern: Pass known state \rightarrow Get control signal \rightarrow Verify matches expected

Integration Tests: Module Interactions

681 integration tests, 50 ms each (15 seconds total)

What they test:

- Factory + Config: Parse YAML, create controller
- Controller + Dynamics: Interface compatibility
- PSO + Simulator: Batch evaluation

Example:

```
def test_factory_config():
    config = load_config("test.yaml")
    ctrl = create_controller(
        config.controller.type,
        config.controller.params
    )
    assert ctrl.gains == config.gains
```

Coverage Standards: 85 / 95 / 100

💡 Key Concept

Three-tier coverage requirements:

- enumi**Overall project:** 85% minimum (aggregate across all files)
- 0. enumi**Critical modules:** 95% minimum (controllers, dynamics, PSO)
- 0. enumi**Safety-critical:** 100% required (saturation, validation, monitoring)

Why Different Standards?

Risk-based prioritization:

Utility function (formats logs):

- 0. Failure \Rightarrow Garbled log entry
- **Cost:** Annoying
- **Coverage:** 85% OK

Saturation function (limits force):

- Failure \Rightarrow Command 10,000 N to 150 N actuator
- **Cost:** Broken hardware!
- **Coverage:** 100% MANDATORY

The 100% Coverage List (10 Modules)

⚠️ Safety-Critical Modules

Safety Modules:

- Saturation - Prevents actuator damage (10,000 N \rightarrow 150 N max)
- Validation - Stops physically impossible configs (negative mass!)
- Deadband - Prevents actuator oscillation near setpoint

Correctness Modules:

- Reproducibility - Deterministic random seeds (peer review requirement!)
- State Manager - Prevents simulation corruption
- Config Validator - Catches errors before simulation

Core Interfaces:

- Base Controller - Inherited by all 7 controllers
- Dynamics Interface - Swappable plant models
- PSO Bounds - Keeps optimization within valid ranges

Monitoring:

- Latency Tracker - Detects missed control deadlines

⚠️ Common Pitfall

Why reproducibility is critical:

If reviewer can't reproduce results (bad random seeds) \Rightarrow **Paper invalid!**

Consequences: Rejected paper \rightarrow Broken \$50,000 robot

Reproducibility is not optional in research software.

CI Enforcement

</> Example

Pull Request Rules:

- enumiAdd 100 lines to critical module
- 0. enumiMust add tests to maintain 95%+ coverage
- 0. enumiIf coverage drops below 95% \Rightarrow **Build FAILS**
- 0. enumiCannot merge until tests added

This prevents "I'll add tests later" syndrome!

Property-Based Testing with Hypothesis

💡 Key Concept

Traditional testing: Write test with ONE specific input

Property-based testing: Write property that holds for ALL inputs

Hypothesis framework: Generates hundreds of random inputs, checks property for each

Example: Saturation Function

Traditional Test:

```
lstnumberdef test_saturation():
lstnumber    result = saturate(200, max=150)
lstnumber    assert result == 150
lstnumber# Tests ONE case (200)
```

Property-Based Test:

```
lstnumber@given(value=st.floats(
lstnumber    min_value=151, max_value=1e6))
lstnumberdef test_saturation_property(value):
lstnumber    result = saturate(value,
lstnumber        max=150)
lstnumber    assert result == 150
lstnumber# Tests 100 random cases!
```

What about: 151? 10,000? 1 million?

💡 Pro Tip

It's like having a robot stress-test your code while you sleep!

Hypothesis generates edge cases you never thought of: NaN, inf, negative zero, etc.

Properties We Test

🔧 System Properties

Controller Properties:

- 0. Control signal must be bounded ($|u| \leq u_{\max}$)
- Control must not contain NaN or infinity
- Control must be deterministic (same state \Rightarrow same output)

Dynamics Properties:

- State derivatives must be finite (no explosions!)
- Energy conserved in absence of friction
- Linearization matches finite-difference approximation

PSO Properties:

- Best cost must never increase (monotonic improvement)
- Final best particle within search bounds
- Optimization reproducible with same seed

Coverage Campaign: Week 3 Bug Hunt

Example

December 20-21, 2025: The 16.5-Hour Sprint

Mission: Bring 10 critical modules to 100% coverage before holidays

Results:

- 668 tests created
- 11 modules validated (beat goal by one!)
- 2 silent killers found and fixed same-day

Felt like defusing bombs while clock ticked down

Bug 1: Factory API Mismatch

Common Pitfall

Problem: Factory expected gains as `list`, config provided `numpy.ndarray`

Symptom: Worked in most cases, failed when serializing to JSON

Fix: Explicitly convert to list in factory

Found via: Integration test for controller state serialization

Bug 2: Memory Leak in Adaptive Controller

Common Pitfall

The Silent Killer:

Adaptive controller stored reference to EVERY simulation's full history (for debugging).
Never released memory (hoarding!).

Impact:

- After 1,000 simulations (typical PSO run): 500 MB RAM
- Overnight optimizations crashed at hour 9 of 10-hour run

Fix: Use `weakref` - "Remember where object is, but don't hold it hostage"

Found via: Property-based test running 10,000 consecutive simulations, asserting memory growth = 0

Test Execution: 45 Seconds for 4,563 Tests

🕒 Execution Breakdown

Test Type	Time	Why So Fast?
Unit (3,678)	8 seconds	No I/O, pure functions
Integration (681)	15 seconds	Load configs, few timesteps
System (182)	20 seconds	Simplified dynamics + Numba JIT
Browser (22)	2 seconds	Parallel with pytest-xdist
TOTAL	45 seconds	10 ms/test average

💡 Pro Tip

Why speed matters:

10-minute tests \Rightarrow Developers don't run during development \Rightarrow Commit broken code \Rightarrow Wait for CI failure \Rightarrow Slow iteration

45-second tests \Rightarrow Run every few minutes locally \Rightarrow Catch failures before commit \Rightarrow Fast feedback loop

Quality Gates: Research vs Production

✅ 8 Quality Gates (5/8 Pass)

Gates We PASS (Research-Ready):

- enumiZero critical bugs (all P0 issues resolved)
- 0. enumi100% test pass rate (4,563/4,563 tests)
- 0. enumiMemory validated (10,000 sims, zero growth)
- 0. enumiThread-safe (11/11 parallel PSO tests pass)
- 0. enumiZero high-priority issues

Gates We FAIL (Production Blockers):

- 0. enumiCoverage measurement broken (reports 2.86%, real is 89%)
- 5. enumiNo production CI/CD (dev pipelines only)
- 5. enumiNo hardware validation (never run on actual robot/PLC)

💡 Key Concept

Bottom Line:

Research-Ready (5/8) 🟡: Can publish papers, run experiments, validate theories

Production-Ready (8/8) 🔴: Can deploy to industrial plant (need gates 6-8)

Verdict: Science is sound. Engineering needs hardening for production.

Quick Reference: Testing Commands

Run Full Test Suite

```
lstnumberWith coverage report pytest tests/ -cov=src -cov-report=html
lstnumberParallel execution (faster on multi-core) pytest tests/ -n auto
```

Run Specific Test Levels

```
lstnumberIntegration tests (15 seconds) pytest tests/test_integration/
lstnumberSystem tests (20 seconds) pytest tests/test_system/
lstnumberBrowser tests (2 seconds) pytest tests/test_browser/
```

Property-Based Testing

```
lstnumber@given(value=st.floats(min_value = 151, max_value = 1e6))def test_saturation_property(value) : result =
    saturate(value, max = 150) assert result ==
    150 assert result <= 150 Property
```

Key Takeaways

Quick Summary

Test Pyramid: 81% unit (fast), 15% integration, 4% system, 0.5% browser

Coverage Tiers: 85% overall, 95% critical, 100% safety-critical

Property-Based Testing: Hypothesis generates 100 random cases, finds edge cases you never thought of

Quality Gates: 5/8 pass (research-ready), need 8/8 for production

Speed Enables Feedback: 45 seconds for 4,563 tests \Rightarrow run every few minutes

Bugs Found: Factory API mismatch + Memory leak (500 MB after 1,000 sims)

What's Next?

Key Concept

E008: Research Outputs & Publications - 11 research tasks, submission-ready paper (v2.1), 14 figures

Remember: Testing is strategic choice-making under constraints. Quality > quantity!