

## 2D Translation

$$x' = x + tx$$

$$y' = y + ty$$

$$P' = P + T$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} x \\ y \end{bmatrix} + \begin{bmatrix} tx \\ ty \end{bmatrix}$$

$$\cos(\theta + \phi) = \frac{x}{r}$$

$$x' = r \cos(\theta + \phi) \quad \text{--- (1)}$$

$$y' = r \sin(\theta + \phi) \quad \text{--- (2)}$$

$$x = r \cos \phi \quad y = r \sin \phi$$

$\text{--- (3)} \qquad \text{--- (4)}$

$$x' = r \cos(\phi + \theta)$$

$$= r (\cos \phi \cos \theta - \sin \phi \sin \theta)$$

$$\sin A \cos B + \sin B \cos A$$

$$x' = r \cos \phi \cos \theta - r \sin \phi \sin \theta$$

$$y' = r [\sin \phi \cos \theta + \sin \theta \cos \phi]$$

$$\begin{aligned} x' &= x \cos \theta - y \sin \theta \\ y' &= y \cos \theta + x \sin \theta \end{aligned}$$

$$P' = RP$$

$$R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$P' = \begin{bmatrix} x' \\ y' \end{bmatrix}$$

$$P = \begin{bmatrix} x \\ y \end{bmatrix}$$

Scaling

$$x' = x \cdot S_x$$

$$y' = y \cdot S_y$$

Scaling factor

$$P' = S \cdot P$$

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} S_x & 0 \\ 0 & S_y \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

① Translate a  $\triangle ABC$  whose coordinates are  $A(0,0)$ ,  $B(5,0)$ ,  $C(5,5)$  by 2 units in x direction & 3 units in y direction.

$$x' = x + tx$$

$$y' = y + ty$$

$$P' = \begin{bmatrix} 1 & 0 & tx \\ 0 & 1 & ty \end{bmatrix} \begin{bmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ 1 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 7 & 7 \\ 3 & 3 & 8 \\ 1 & 1 & 1 \end{bmatrix}$$

Perform a  $45^\circ$  rotation of  $\Delta A(0,0) B(1,1) C(5,2)$  about the origin

	$0^\circ$	$30^\circ$	$45^\circ$	$60^\circ$	$90^\circ$
$\sin \theta$	0	$\frac{1}{2}$	$\frac{1}{\sqrt{2}}$	$\frac{\sqrt{3}}{2}$	1
$\cos \theta$	1	$\frac{\sqrt{3}}{2}$	$\frac{1}{\sqrt{2}}$	$\frac{1}{2}$	0

$$\tan \theta = \frac{\sin}{\cos}$$

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$$P' = R(\theta) P$$

$$\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$(0, 0) \quad (3/\sqrt{2}, 7/\sqrt{2})$$

$$(0, \sqrt{2})$$

Anti Clockwise Rotation

$$\begin{bmatrix} 0 & 1 & 5 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

Scaling

$A(0,0) B(1,1) C(5,2)$   
Magnified to twice its size

$$S_x = 2$$

$$S_y = 2$$

$$P = \begin{bmatrix} S_x & 0 & 0 \\ 0 & S_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 5 \\ 0 & 1 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$

$$A(0,0)$$

$$(2,2)$$

$$(10,4)$$

$$\begin{bmatrix} 0 & 0 & 3/\sqrt{2} \\ 0 & \sqrt{2} & 7/\sqrt{2} \\ 1 & 1 & 1 \end{bmatrix}$$

Homogeneous coordinates  
& matrix representation  
Translation terms  
(matrix form)

$$P' = P \sigma_1 + \sigma_2$$

Multiplication matrix

$$P' = P \sigma_1$$

$$(X, Y) = (x, y, h)$$

$$x = \frac{X}{h} \quad h = 1$$

$$y = \frac{Y}{h}$$

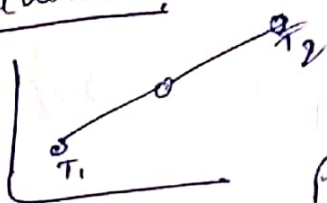


# Composite Transformation

Multiple  $\rightarrow$  More than 3 transformation

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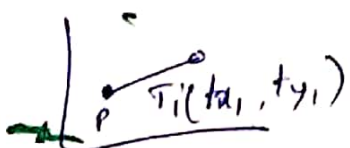
## Translation



Suppose  $P(x, y)$  - Initial  
 $P'(x', y')$  - After 2 translation

$$P' = T_2(x_2, y_2) [T_1(x_1, y_1) \cdot P]$$

Matrix Mult - Commutative & Associative



$$= [T_2(x_2, y_2) \cdot T_1(x_1, y_1)] \cdot P$$

$$T_2(x_2, y_2) = \begin{bmatrix} 1 & 0 & x_2 \\ 0 & 1 & y_2 \\ 0 & 0 & 1 \end{bmatrix} \quad T_1(x_1, y_1) = \begin{bmatrix} 1 & 0 & x_1 \\ 0 & 1 & y_1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & x_1 + x_2 \\ 0 & 1 & y_1 + y_2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$P' = T(x_1 + x_2, y_1 + y_2) \cdot P$$

## Rotation

2 times

$$P' = R(\theta_2) [R(\theta_1) \cdot P]$$

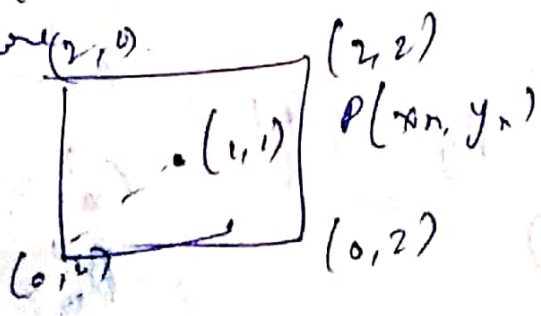
$$= [R(\theta_2) \cdot R(\theta_1)] \cdot P$$

$$P' = R(\theta_1 + \theta_2) \cdot P$$

## Scaling

$$P' = S \begin{pmatrix} Sx_1 \cdot Sx_2 \\ Sy_1 \cdot Sy_2 \end{pmatrix} P$$

A Square with vertices  $(0,0)$   $(2,0)$   $(2,2)$  &  $(0,2)$  in scaled 2 units in x or y direction about the fixed point which is the center of square  $(1,1)$  find coordinates of new square.



- 1) Translate the fixed point at the origin
- 2) Scaling the object
- 3) Inverse translation of object

$$S' = T_v S (S_x, S_y) T_v$$

$$= \begin{bmatrix} 1 & 0 & x_n \\ 0 & 1 & y_n \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} S_x & 0 & 0 \\ 0 & S_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -x_n \\ 0 & 1 & -y_n \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & -1 \\ 0 & 2 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

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$$P = S(x, y) \cdot P'(\text{Square})$$

$$= \begin{bmatrix} 2 & 0 & -1 \\ 0 & 2 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 2 & 2 & 0 \\ 0 & 0 & 2 & 2 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} -1 & 3 & 3 & -1 \\ -1 & -1 & 3 & 3 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{matrix} x \\ y \end{matrix}$$

Consider a <sup>unit</sup> square centered at origin the coordinates of square are translated by a factor  $(\frac{1}{2}, \frac{1}{2})$  and rotated by angle of  $90^\circ$ . What will be coordinates of new square

- A  $(-\frac{1}{2}, 0)$   $(\frac{1}{2}, 1)$   $(-\frac{3}{2}, 1)$   $(-\frac{3}{2}, 0)$   
 B  $(-\frac{1}{2}, 0)$   $(\frac{1}{2}, 1)$   $(\frac{3}{2}, 1)$   $(\frac{3}{2}, 0)$   
 C  $(-\frac{1}{2}, 0)$   $(\frac{1}{2}, 0)$   $(-\frac{3}{2}, 1)$   $(-\frac{3}{2}, 0)$   
 D  $(-\frac{1}{2}, 0)$   $(\frac{1}{2}, 1)$   $(\frac{3}{2}, 1)$   $(\frac{3}{2}, 0)$

$$t_x = \frac{1}{2} \quad t_y = 1$$

$$x' = x + t_x$$

$$y' = y + t_y$$

$$A x' = \frac{1}{2} + \frac{1}{2}$$

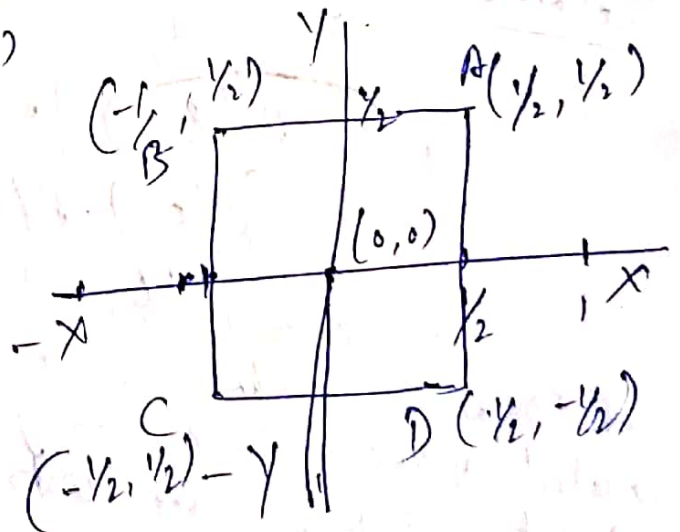
$$A' = (1, \frac{3}{2})$$

$$A y' = \frac{1}{2} + 1$$

$$B x' = (0, \frac{3}{2})$$

$$C x' = (0, \frac{1}{2})$$

$$D x' = (1, \frac{1}{2})$$



$$x' = x \cos \theta - y \sin \theta$$

$$y' = x \sin \theta + y \cos \theta$$

$$x = \frac{1}{2} \cos 30^\circ - \frac{3}{2} \sin 30^\circ$$

$$A' = (-3/2, 1)$$

$$B(-3/2, 0)$$

$$C(-1/2, 0) \quad D(-1/2, 1)$$

A point  $P(5, 1)$  is rotated by  $90^\circ$  about a pivot point  $P'(2, 2)$  what is the coordinate of new transformed point  $P'$ .

$$\text{Resultant Matrix} = T_v R(\theta) T_{-v} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 2 & 1 \end{bmatrix} \begin{bmatrix} \cos 90^\circ & \sin 90^\circ & 0 \\ \sin 90^\circ & \cos 90^\circ & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 3 \\ 5 \\ 1 \end{bmatrix}$$

Consider a  $\Delta A(0, 0), B(1, 1), C(5, 2)$ . The  $\Delta$  has to be rotated by  $45^\circ$  angle about pivot  $P(-1, -1)$ . Find coordinates of new triangle.

$$T_m = T_v R(\theta) T_{-v}$$

$$t_x = -1$$

$$t_y = -1$$

$$\begin{bmatrix} 1 & 0 & 1.5 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

Reflection along x axis

Shearing

$x$  - shear

$y$  - shear

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & sh_x \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$x$  axis

$$y' = y \quad \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & sh_x \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$y$  axis

$$x' = x + sh_y \cdot y \quad \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$x' = x \quad \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

$$y' = y + sh_x \cdot x$$

Rotation about both axes

$$x' = x + sh_x \cdot y$$

$$y' = y + sh_y \cdot x$$

Along origin

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

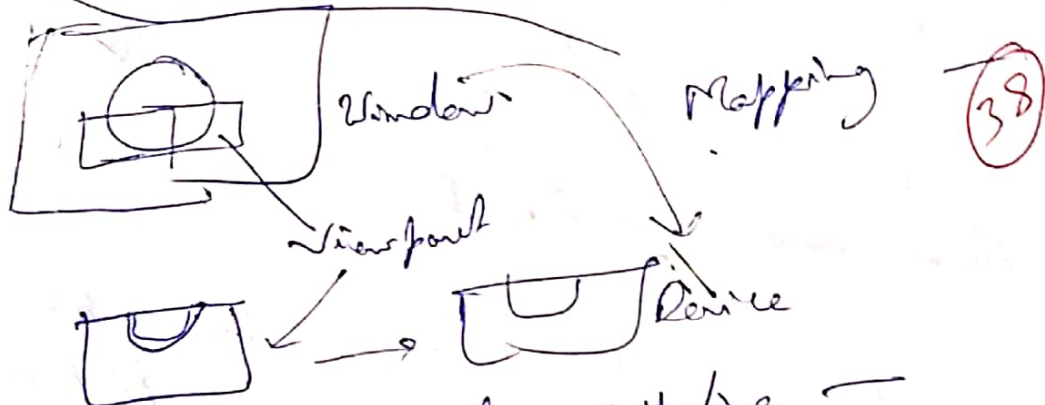


$(2,2) (4,2) (3,4) - \Delta$

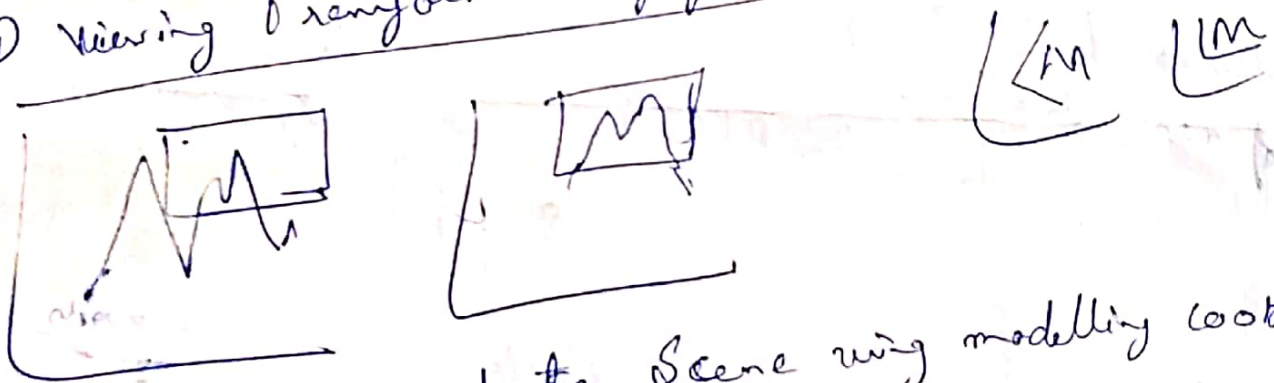
## Viewing Transformation

Camera  $\rightarrow$  View  $\rightarrow$  normalized coordinates  $\rightarrow$  Mapping  $\rightarrow$  Device coordinates

Window  $\rightarrow$  Viewport  $\rightarrow$  Device



## 2D Viewing Transformation pipeline



Construct world coordinate scene using modelling coordinates

- System  $\rightarrow$  World coordinates
- Convert world coordinate to viewing coordinates (VC)
- Map view coordinates to normalized VC using window viewport specification
- Map normalized viewport to Device coordinates