ΤΜΗΜΑ ΠΛΗΡΟΦΟΡΙΚΗΣ Η ΤΗΛΕΠΙΚΟΙΝΩΝΙΩΝ







M902

Βασικές Μαθηματικές Έννοιες στη Γλωσσική Τεχνολογία

Project 3

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$$A = \begin{bmatrix} 2 & -3 & 5 \\ 1 & -2 & 7 \\ 3 & 8 & 4 \end{bmatrix}$$

$$a_{13} = 5$$

$$a_{21} = 1$$

$$a_{32} = 8$$

$$A_{13} = (-1)^{1+3} \cdot \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix} = (-1)^{1+3} \cdot \begin{vmatrix} 1 & -2 \\ 3 & 8 \end{vmatrix} = (8 - (-6)) = 14$$

$$A_{21} = (-1)^{2+1} \cdot \begin{vmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{vmatrix} = (-1)^{2+1} \cdot \begin{vmatrix} -3 & 5 \\ 8 & 4 \end{vmatrix} = -(-12 - 40) = 52$$

$$A_{32} = (-1)^{3+2} \cdot \begin{vmatrix} a_{11} & a_{13} \\ a_{21} & a_{23} \end{vmatrix} = (-1)^{3+2} \cdot \begin{vmatrix} 2 & 5 \\ 1 & 7 \end{vmatrix} = -(14-5) = -9$$

$$A = \begin{bmatrix} -1 & 3 \\ 4 & 2 \\ 2 & -1 \end{bmatrix}, B = \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix}, C = \begin{bmatrix} 3 & 4 & 2 \\ -2 & 4 & -3 \end{bmatrix}, D = \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix}$$

a) $A+B \implies$ cannot be calculated, because the summation operation can only be performed in cases of same dimension matrices. However, that is not the case, as A is a 3x2 matrix and B is a 2x2 matrix.

b)
$$C \cdot A = \begin{bmatrix} 3 & 4 & 2 \\ -2 & 4 & -3 \end{bmatrix} \cdot \begin{bmatrix} -1 & 3 \\ 4 & 2 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} -3 + 16 + 4 & 9 + 8 - 2 \\ 2 + 16 - 6 & -6 + 8 + 3 \end{bmatrix} = \begin{bmatrix} -17 & 15 \\ 12 & 5 \end{bmatrix}$$

c)
$$5B - 2D = 5 \cdot \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix} - 2 \cdot \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 10 & -15 \\ 20 & -10 \end{bmatrix} - \begin{bmatrix} 10 & -2 \\ 4 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 10 - 10 & -15 + 2 \\ 20 - 4 & -10 \end{bmatrix} = \begin{bmatrix} 0 & -13 \\ 16 & -10 \end{bmatrix}$$

$$d) \ B \cdot D - D = \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix} \cdot \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix} - \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 10 - 6 & -2 \\ 20 - 4 & -4 \end{bmatrix} - \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} -1 & -1 \\ 14 & -4 \end{bmatrix}$$

e) $B \cdot C \cdot D \implies$ cannot be calculated. In order to perform matrix multiplication of two matrices A_{nxm} , B_{kxp} , m has to be equal to k (m=k) and the final matrix will be of dimension nxp. In this example, B and C can be multiplied because they follow the aformentioned requirement, but their product of multiplication is a 2x3 matrix, so it cannot be multiplied with 2x2 matrix D.

$$A = \begin{bmatrix} -1 & 3 \\ 4 & 2 \\ 2 & -1 \end{bmatrix}, B = \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix}, C = \begin{bmatrix} 3 & 4 & 2 \\ -2 & 4 & -3 \end{bmatrix}, D = \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix}$$

a)
$$(A^T + C)^T = \begin{bmatrix} \begin{bmatrix} -1 & 3 \\ 4 & 2 \\ 2 & -1 \end{bmatrix}^T + \begin{bmatrix} 3 & 4 & 2 \\ -2 & 4 & -3 \end{bmatrix} \end{bmatrix}^T = \begin{bmatrix} \begin{bmatrix} -1 & 4 & 2 \\ 3 & 2 & -1 \end{bmatrix} + \begin{bmatrix} 3 & 4 & 2 \\ -2 & 4 & -3 \end{bmatrix} \end{bmatrix}^T$$

$$= \begin{bmatrix} -1+3 & 4+4 & 2+2 \\ 3-2 & 2+4 & -1-3 \end{bmatrix}^{T} = \begin{bmatrix} 2 & 8 & 4 \\ 1 & 6 & -4 \end{bmatrix}^{T} = \begin{bmatrix} 2 & 1 \\ 8 & 6 \\ 4 & -4 \end{bmatrix}$$

$$b) - C^{T} - A = -\begin{bmatrix} 3 & 4 & 2 \\ -2 & 4 & -3 \end{bmatrix}^{T} - \begin{bmatrix} -1 & 3 \\ 4 & 2 \\ 2 & -1 \end{bmatrix} = -\begin{bmatrix} 3 & -2 \\ 4 & 4 \\ 2 & -3 \end{bmatrix} - \begin{bmatrix} -1 & 3 \\ 4 & 2 \\ 2 & -1 \end{bmatrix} =$$

$$\begin{bmatrix} -3+1 & -2-3 \\ -4-4 & -4-2 \\ -2-2 & 3+1 \end{bmatrix} = \begin{bmatrix} -2 & -5 \\ -8 & -6 \\ -4 & 4 \end{bmatrix}$$

$$A = \begin{bmatrix} -1 & 3 \\ 4 & 2 \\ 2 & -1 \end{bmatrix}, B = \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix}, C = \begin{bmatrix} 3 & 4 & 2 \\ -2 & 4 & -3 \end{bmatrix}, D = \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix}$$

a)
$$B \cdot D = \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix} \cdot \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 10 - 6 & -2 \\ 20 - 4 & -4 \end{bmatrix} = \begin{bmatrix} 4 & -2 \\ 16 & -4 \end{bmatrix}$$

b)
$$D \cdot B = \begin{bmatrix} 5 & -1 \\ 2 & 0 \end{bmatrix} \cdot \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix} = \begin{bmatrix} 10 - 4 & -15 + 2 \\ 4 & -6 \end{bmatrix} = \begin{bmatrix} 6 & -13 \\ 4 & -6 \end{bmatrix}$$

c)
$$B^2 = B \cdot B = \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix} \cdot \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix} = \begin{bmatrix} 4 - 12 & -6 + 6 \\ 8 - 8 & -12 + 4 \end{bmatrix} = \begin{bmatrix} -8 & 0 \\ 0 & -8 \end{bmatrix} =$$

$$= -8 \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = -8 \cdot I_2$$

$$B = \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix}$$

- a) Find B^{-1}
- b) Verify $B \cdot B^{-1} = B^{-1} \cdot B = I$

Following the formula of the inverse matrix:

a)
$$B^{-1} = \frac{1}{|B|} \cdot adj(B) = \frac{1}{|B|} \cdot \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix}^T = \frac{1}{|B|} \cdot \begin{bmatrix} B_{11} & B_{21} \\ B_{12} & B_{22} \end{bmatrix}$$

$$\det(B) = |B| = \begin{vmatrix} 2 & -3 \\ 4 & -2 \end{vmatrix} = 2 \cdot (-2) - (4 \cdot (-3)) = -4 + 12 = 8 \tag{1}$$

$$adj(B) = \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix}^T = \begin{bmatrix} B_{11} & B_{21} \\ B_{12} & B_{22} \end{bmatrix} = \begin{bmatrix} b_{22} & -b_{12} \\ -b_{21} & b_{11} \end{bmatrix} = \begin{bmatrix} -2 & 3 \\ -4 & 2 \end{bmatrix}$$
(2)

$$\stackrel{(1), (2)}{\Longrightarrow} B^{-1} = \frac{1}{|B|} \cdot adj(B) = \frac{1}{8} \cdot \begin{bmatrix} -2 & 3 \\ -4 & 2 \end{bmatrix} = \begin{bmatrix} -\frac{2}{8} & \frac{3}{8} \\ -\frac{4}{8} & \frac{2}{8} \end{bmatrix} = \begin{bmatrix} -\frac{1}{4} & \frac{3}{8} \\ -\frac{1}{2} & \frac{1}{4} \end{bmatrix}$$
(3)

b)
$$B \cdot B^{-1} = \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix} \cdot \begin{bmatrix} -\frac{1}{4} & \frac{3}{8} \\ -\frac{1}{2} & \frac{1}{4} \end{bmatrix} = \begin{bmatrix} -\frac{2}{4} + \frac{3}{2} & \frac{6}{8} - \frac{3}{4} \\ -\frac{4}{4} + \frac{2}{2} & \frac{12}{8} - \frac{2}{4} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2$$

$$B^{-1} \cdot B = \begin{bmatrix} -\frac{1}{4} & \frac{3}{8} \\ -\frac{1}{2} & \frac{1}{4} \end{bmatrix} \cdot \begin{bmatrix} 2 & -3 \\ 4 & -2 \end{bmatrix} = \begin{bmatrix} -\frac{2}{4} + \frac{12}{8} & \frac{3}{4} - \frac{6}{8} \\ -\frac{2}{2} + \frac{4}{4} & \frac{3}{2} - \frac{2}{4} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2$$

Let
$$A = \begin{bmatrix} a_1^T \\ a_2^T \\ a_3^T \end{bmatrix} = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 0 & -1 \\ 0 & 1 & 2 \end{bmatrix}$$
, the unknown vector $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ and the dot products vector

$$b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 8 \\ 9 \end{bmatrix}.$$

This system of linear equations in its condensed form, is written as follows:

$$A \cdot x = b$$

The unknown vector x is calculated by:

$$A \cdot x = b \implies A^{-1} \cdot A \cdot x = A^{-1} \cdot b \implies I \cdot x = A^{-1} \cdot b \implies x = A^{-1} \cdot b \tag{1}$$

$$A^{-1} = \frac{1}{|A|} \ adj(A) \qquad (2)$$

Determinant of matrix *A*:

$$\det(A) = |A| = \begin{vmatrix} 1 & 2 & 0 \\ 2 & 0 & -1 \\ 0 & 1 & 2 \end{vmatrix} = (-1)^{1+1} \cdot 1 \cdot \begin{vmatrix} 0 & -1 \\ 1 & 2 \end{vmatrix} + (-1)^{1+2} \cdot 2 \cdot \begin{vmatrix} 2 & -1 \\ 0 & 2 \end{vmatrix} + (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix}$$
$$= 1 \cdot 1 \cdot (0 \cdot 2 - (-1) \cdot 1) - 1 \cdot 2 \cdot (2 \cdot 2) + 0 = +1 - 8 = -7 \tag{3}$$

Adjoint matrix (transpose of cofactor matrix) of A:

$$adj(A) = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix}^T = \begin{bmatrix} A_{11} & A_{21} & A_{31} \\ A_{12} & A_{22} & A_{32} \\ A_{13} & A_{23} & A_{33} \end{bmatrix},$$

where the ij-th cofactor $cof(A)_{ij}=A_{ij}=(-1)^{i+j}\cdot\det(M_{ij}),\ i,\ j$ the rows and columns of matrix A respectively and M_{ij} the matrix made by removing row i and column j of matrix A. The proper signs of the cofactors in the **adjoint** (adjugate) matrix, are included in the calculation of A_{ij} .

$$A_{11} = \ (-1)^{1+1} \cdot \left| \begin{array}{ccc} 0 & -1 \\ 1 & 2 \end{array} \right| = \ 1, \ A_{12} = \ (-1)^{1+2} \cdot \left| \begin{array}{ccc} 2 & -1 \\ 0 & 2 \end{array} \right| = -4, \ A_{13} = \ (-1)^{1+3} \cdot \left| \begin{array}{ccc} 2 & 0 \\ 0 & 1 \end{array} \right| = \ 2$$

$$A_{21} = (-1)^{2+1} \cdot \begin{vmatrix} 2 & 0 \\ 1 & 2 \end{vmatrix} = -4, \ A_{22} = (-1)^{2+2} \cdot \begin{vmatrix} 1 & 0 \\ 0 & 2 \end{vmatrix} = 2, \ A_{23} = (-1)^{2+3} \cdot \begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix} = -1$$

$$A_{31} = (-1)^{3+1} \cdot \begin{vmatrix} 2 & 0 \\ 0 & -1 \end{vmatrix} = -2, \ A_{32} = (-1)^{3+2} \cdot \begin{vmatrix} 1 & 0 \\ 2 & -1 \end{vmatrix} = 1, \ A_{33} = (-1)^{3+3} \cdot \begin{vmatrix} 1 & 2 \\ 2 & 0 \end{vmatrix} = -4$$

$$adj(A) = \begin{bmatrix} 1 & -4 & -2 \\ -4 & 2 & 1 \\ 2 & -1 & -4 \end{bmatrix}$$
 (4)

$$\stackrel{(2), (3), (4)}{\Longrightarrow} A^{-1} = \frac{1}{-7} \cdot \begin{bmatrix} 1 & -4 & -2 \\ -4 & 2 & 1 \\ 2 & -1 & -4 \end{bmatrix} = \begin{bmatrix} -\frac{1}{7} & \frac{4}{7} & \frac{2}{7} \\ \frac{4}{7} & -\frac{2}{7} & -\frac{1}{7} \\ -\frac{2}{7} & \frac{1}{7} & \frac{4}{7} \end{bmatrix}$$
 (5)

$$\stackrel{(1), (5)}{\Longrightarrow} x = A^{-1} \cdot b \implies$$

$$x = \begin{bmatrix} -\frac{1}{7} & \frac{4}{7} & \frac{2}{7} \\ \frac{4}{7} & -\frac{2}{7} & -\frac{1}{7} \\ -\frac{2}{7} & \frac{1}{7} & \frac{4}{7} \end{bmatrix} \cdot \begin{bmatrix} 5 \\ 8 \\ 9 \end{bmatrix} = \begin{bmatrix} -\frac{1}{7} \cdot 5 + \frac{4}{7} \cdot 8 + \frac{2}{7} \cdot 9 \\ \frac{4}{7} \cdot 5 - \frac{2}{7} \cdot 8 - \frac{1}{7} \cdot 9 \\ -\frac{2}{7} \cdot 5 + \frac{1}{7} \cdot 8 + \frac{4}{7} \cdot 9 \end{bmatrix} = \begin{bmatrix} \frac{45}{7} \\ -\frac{5}{7} \\ \frac{34}{7} \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\implies x_1 = \frac{45}{7}, \ x_2 = -\frac{5}{7}, \ x_3 = \frac{34}{7}$$

(coordinates of the previously-but-not-still-unknown vector \boldsymbol{x})

$$A = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$$

- a) Find A^2
- b) Find A^{-1}

a)
$$A^2 = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix} \cdot \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix} = \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & \cos \theta \sin \theta - \sin \theta \cos \theta \\ \sin \theta \cos \theta - \sin \theta \cos \theta & \sin^2 \theta + \cos^2 \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2$$

where I_2 , the identity matrix of dimension 2x2.

b)
$$A^{-1} = \frac{1}{|A|} \cdot adj(A) = \frac{1}{|A|} \cdot \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}^T = \frac{1}{|A|} \cdot \begin{bmatrix} A_{11} & A_{21} \\ A_{12} & A_{22} \end{bmatrix}$$
 (1)

$$\det(A) = |A| = \begin{vmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{vmatrix} = -\cos^2 \theta - \sin^2 \theta = -(\cos^2 \theta + \sin^2 \theta) = -1$$
 (2)

$$adj(A) = \begin{bmatrix} A_{11} & A_{21} \\ A_{12} & A_{22} \end{bmatrix} = \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix} = \begin{bmatrix} -\cos\theta & -\sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$
(3)

$$\overset{(1),\,(2),\,(3)}{\Longrightarrow}A^{-1} = \frac{1}{|A|} \cdot adj(A) = \frac{1}{|A|} \cdot \begin{bmatrix} A_{11} & A_{21} \\ A_{12} & A_{22} \end{bmatrix} = -1 \cdot \begin{bmatrix} -\cos\theta & -\sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} = \begin{bmatrix} \cos\theta & \sin\theta \\ \sin\theta & -\cos\theta \end{bmatrix} = A$$

From questions 7.a and 7.b both, we extract the information that A is an **involutory** matrix, which means it is **its own reverse**, as it complies with the following:

$$A^2 = I_2$$

$$A^{-1} = A$$

Vectors: u = [3,4], v = [4,3]

The included angle θ of two vectors, is dependent on their respective magnitudes and inner product and is calculated as follows:

$$u \cdot v = \|u\| \cdot \|v\| \cdot \cos \theta_{uv} \implies \cos \theta_{uv} = \frac{u \cdot v}{\|u\| \cdot \|v\|} \quad (1)$$

$$\stackrel{(1)}{\Longrightarrow} \cos \theta_{uv} = \frac{u \cdot v}{\|u\| \cdot \|v\|} = \frac{[3,4] \cdot [4,3]}{\|[3,4]\| \cdot \|[4,3]\|} = \frac{12 + 12}{(\sqrt{9 + 16}) \cdot (\sqrt{16 + 9})} = \frac{24}{5 \cdot 5}$$

$$=\frac{24}{25}=0.96 \implies \cos^{-1}(0.96)=16.26^{\circ} \implies \theta_{uv}=16.26^{\circ}$$

Vectors u and v are **not collinear**, as their included angle θ is neither 0° nor 180° ($\cos\theta=1$ and $\cos\theta=-1$ respectively). They are also **not orthogonal**, as in that case, their included angle θ would be 90° ($\cos\theta=0$).

Vectors: u = [a, b], v = 2u

As described in **Question 8**, the included angle θ of two vectors, is dependent on their respective magnitudes and inner product, calculated by using formula (1):

$$u \cdot v = \|u\| \cdot \|v\| \cdot \cos \theta_{uv} \implies \cos \theta_{uv} = \frac{u \cdot v}{\|u\| \cdot \|v\|} \quad (1)$$

$$\stackrel{(1)}{\Longrightarrow} \cos \theta_{uv} = \frac{u \cdot v}{\|u\| \cdot \|v\|} = \cos \theta_{uv} = \frac{u \cdot 2u}{\|u\| \cdot \|2u\|} = \frac{[a,b] \cdot [2a,2b]}{\|[a,b]\| \cdot \|[2a,2b]\|} =$$

$$\frac{2 \cdot (a^2 + b^2)}{(\sqrt{a^2 + b^2}) \cdot (\sqrt{4a^2 + 4b^2})} = \frac{2 \cdot (a^2 + b^2)}{2 \cdot (\sqrt{a^2 + b^2})^2} = \frac{a^2 + b^2}{a^2 + b^2} = 1$$

$$\implies \cos^{-1}(1) = 0^{\circ} \implies \theta_{uv} = 0^{\circ}$$

In this case, the two vectors are **collinear**, as vector v is a **scalar multiple** of vector u ($v = k \cdot u$), and have the **same direction** as the **scalar** k is a **positive** number (k = 2), therefore their included angle θ is 0° (validated by the calculations above).

In order to find the similar documents based on the 3-dimensional vector representations, $d_n \in \mathbb{R}^3$, $n=1,\ldots,5$, a 5x5 matrix was constructed, with each row being each of the 3-D vectors d_1,d_2,d_3,d_4,d_5 , normalised as follows:

$$d_{ij_normalized} = \frac{d_{ij}}{\|d_i\|}$$

where d_{ij} the j-th element of the i-th vector and $||d_i||=\sqrt{d_{i1}^2+d_{i2}^2+d_{i3}^2}$ the norm of the respective vector i:

$$D = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \\ d_4 \\ d_5 \end{bmatrix} \implies D_{5x3} = \begin{bmatrix} 8 & 6 & 0 \\ 0 & 6 & 8 \\ 6 & 0 & 8 \\ 2 & 3 & 0 \\ 9 & 6 & 0 \end{bmatrix} \implies D_{normalized} = \begin{bmatrix} \frac{8}{10} & \frac{6}{10} & \frac{0}{10} \\ \frac{0}{10} & \frac{6}{10} & \frac{8}{10} \\ \frac{2}{3.6055} & \frac{3}{3.6055} & \frac{0}{3.6055} \\ \frac{9}{10.8166} & \frac{6}{10.8166} & \frac{0}{10.8166} \end{bmatrix} = \begin{bmatrix} 0.8 & 0.6 & 0 \\ 0 & 0.6 & 0.8 \\ 0.5547 & 0.8320 & 0 \\ 0.8320 & 0.5547 & 0 \end{bmatrix}$$

Finally, we multiply **normalized** matrix **D** with its **transpose**, to get the inner product of every pair of vectors and perform the comparisons between the document representations:

$$D_{normalized} \cdot D_{normalized}^T = \begin{bmatrix} 0.8 & 0.6 & 0 \\ 0 & 0.6 & 0.8 \\ 0.6 & 0 & 0.8 \\ 0.5547 & 0.8320 & 0 \\ 0.8320 & 0.5547 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0.8 & 0 & 0.6 & 0.5547 & 0.8320 \\ 0.6 & 0.6 & 0 & 0.8320 & 0.5547 \\ 0 & 0.8 & 0.8 & 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0.36 & 0.48 & 0.9429 & 0.9984 \\ \mathbf{0.36} & 1 & 0.64 & 0.4992 & 0.3328 \\ \mathbf{0.48} & \mathbf{0.64} & 1 & 0.3328 & 0.4992 \\ \mathbf{0.9429} & \mathbf{0.4992} & \mathbf{0.3328} & 1 & 0.9230 \\ \mathbf{0.9984} & \mathbf{0.3328} & \mathbf{0.4992} & \mathbf{0.9230} & 1 \end{bmatrix} = D_{normalized_dot_product}$$

We keep only the **lower triangular matrix**, where each value represents the dot product of the j-th vector (d_j) with the i-th vector (d_j), where i, j the rows and the columns of the matrix $D_{normalized_dot_product}$ respectively.

The formula of the dot product of two vectors, using the included angle θ , is:

$$d_i \cdot d_j = \|d_i\| \cdot \|d_j\| \cdot \cos \theta \implies \cos \theta = \frac{d_i \cdot d_j}{\|d_i\| \cdot \|d_j\|} = \cos \theta_{d_i, d_j}$$

The process we followed above, calculates exactly the value of the cosine of the included angle θ , giving information on the relation between those vectors. If the angle's value is close to 0, then the vectors are **orthogonal**, if it is close to 1 or -1 they are **collinear**.

(The correlation matrix (experimented with in python) might be able to give more information about their relation, capturing strong negative, strong positive and weak / no corellation between the vectors - not yet explicitly examined).

Therefore, the results are the following:

Inner Product (of normalized vectors)	Notes	Similarity
$\cos\theta_{d_1,d_2} = 0.36$		Low
$\cos\theta_{d_1,d_3} = 0.48$		
$\cos \theta_{d_1,d_4} = 0.9429$	$> 0.94 \implies \theta_{d_1,d_4} < 19^{\circ}$	High
$\cos \theta_{d_1,d_5} = 0.9984$	$\sim 1 \implies \theta_{d_1,d_5} \sim 0^{\circ}$	High
$\cos \theta_{d_2,d_3} = 0.64$		
$\cos \theta_{d_2,d_4} = 0.4492$		
$\cos \theta_{d_2, d_5} = 0.3328$		Low
$\cos \theta_{d_3,d_4} = 0.3328$		Low
$\cos \theta_{d_3,d_5} = 0.4992$		
$\cos \theta_{d_4, d_5} = 0.9230$	$> 0.92 \implies \theta_{d_4,d_5} < 23^{\circ}$	High

Table 3.10

In conclusion, **Documents 1**, **4** and **5** are **very similar**, especially **1** and **5**.

Notes

For some questions of project 3, some **code** was developed to **experiment** with the given tasks and **validate** the manually calculated results.