ΤΜΗΜΑ ΠΛΗΡΟΦΟΡΙΚΗΣ Η ΤΗΛΕΠΙΚΟΙΝΩΝΙΩΝ







M902

Βασικές Μαθηματικές Έννοιες στη Γλωσσική Τεχνολογία

Project 3

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Let
$$A = \begin{bmatrix} a_1^T \\ a_2^T \\ a_3^T \end{bmatrix} = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 0 & -1 \\ 0 & 1 & 2 \end{bmatrix}$$
, the unknown vector $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ and the dot products vector

$$b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 8 \\ 9 \end{bmatrix}.$$

This system of linear equations in each condensed form, is written as follows:

$$A \cdot x = b$$

The unknown vector x is calculated by:

$$A \cdot x = b \implies A^{-1} \cdot A \cdot x = A^{-1} \cdot b \implies I \cdot x = A^{-1} \cdot b \implies x = A^{-1} \cdot b$$

$$A^{-1} = \frac{1}{|A|} \ adj(A)^{T} \quad (1)$$

Determinant of matrix *A*:

$$det(A) = \begin{vmatrix} 1 & 2 & 0 \\ 2 & 0 & -1 \\ 0 & 1 & 2 \end{vmatrix} = (-1)^{1+1} \cdot 1 \cdot \begin{vmatrix} 0 & -1 \\ 1 & 2 \end{vmatrix} + (-1)^{1+2} \cdot 2 \cdot \begin{vmatrix} 2 & -1 \\ 0 & 2 \end{vmatrix} + (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = (-1)^{1+3} \cdot 0 \cdot \begin{vmatrix} 2 & 0 \\ 0 &$$

$$1 \cdot 1 \cdot (0 \cdot 2 - (-1) \cdot 1) - 1 \cdot 2 \cdot (2 \cdot 2) + 0 = +1 - 8 = -7$$
 (2)

Adjugate matrix (transpose of cofactor matrix) of A:

$$adj(A) = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix}^{T} = \begin{bmatrix} A_{11} & A_{21} & A_{31} \\ A_{12} & A_{22} & A_{32} \\ A_{13} & A_{23} & A_{33} \end{bmatrix}$$

$$A_{11} = (-1)^{1+1} \cdot \begin{vmatrix} 0 & -1 \\ 1 & 2 \end{vmatrix} = 1, \ A_{12} = (-1)^{1+2} \cdot \begin{vmatrix} 2 & -1 \\ 0 & 2 \end{vmatrix} = -4, \ A_{13} = (-1)^{1+3} \cdot \begin{vmatrix} 2 & 0 \\ 0 & 1 \end{vmatrix} = 2$$

$$A_{21} = \ (-1)^{2+1} \cdot \left| \begin{array}{ccc} 2 & 0 \\ 1 & 2 \end{array} \right| = -4, \ A_{22} = \ (-1)^{2+2} \cdot \left| \begin{array}{ccc} 1 & 0 \\ 0 & 2 \end{array} \right| = \ 2, \ A_{23} = \ (-1)^{2+3} \cdot \left| \begin{array}{ccc} 1 & 2 \\ 0 & 1 \end{array} \right| = -1$$

$$A_{31} = (-1)^{3+1} \cdot \begin{vmatrix} 2 & 0 \\ 0 & -1 \end{vmatrix} = -2, \ A_{32} = (-1)^{3+2} \cdot \begin{vmatrix} 1 & 0 \\ 2 & -1 \end{vmatrix} = 1, \ A_{33} = (-1)^{3+3} \cdot \begin{vmatrix} 1 & 2 \\ 2 & 0 \end{vmatrix} = -4$$

$$adj(A) = \begin{bmatrix} 1 & -4 & -2 \\ -4 & 2 & 1 \\ 2 & -1 & -4 \end{bmatrix}$$
 (3)

(2)

In order to find the similar documents based on the 3-dimensional vector representations, $d_n \in \mathbb{R}^3$, $n=1,\ldots,5$, a 5x5 matrix was constructed, with each row being each of the 3-D vectors d_1,d_2,d_3,d_4,d_5 , normalised as follows:

$$\sum_{i=1}^{5} \sum_{j=1}^{3} \frac{d_{ij}}{\|d_i\|}$$

where d_{ij} the j-th element of the i-th vector and $||d_i||=\sqrt{d_{i1}^2+d_{i2}^2+d_{i3}^2}$ the norm of the respective vector i:

$$D = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \\ d_4 \\ d_5 \end{bmatrix} \implies D_{5x3} = \begin{bmatrix} 8 & 6 & 0 \\ 0 & 6 & 8 \\ 6 & 0 & 8 \\ 2 & 3 & 0 \\ 9 & 6 & 0 \end{bmatrix} \implies D_{normal} = \begin{bmatrix} \frac{8}{10} & \frac{6}{10} & \frac{0}{10} \\ \frac{0}{10} & \frac{6}{10} & \frac{8}{10} \\ \frac{2}{3.6055} & \frac{3}{3.6055} & \frac{0}{3.6055} \\ \frac{9}{10.8166} & \frac{6}{10.8166} & \frac{0}{10.8166} \end{bmatrix} = \begin{bmatrix} 0.8 & 0.6 & 0 \\ 0 & 0.6 & 0.8 \\ 0.6 & 0 & 0.8 \\ 0.5547 & 0.8320 & 0 \\ 0.8320 & 0.5547 & 0 \end{bmatrix}$$

Finally, we multiply **normalized** matrix **D** with its **transpose**, to get the inner product of every pair of vectors and perform the comparisons between the document representations:

$$D_{normal} \cdot D_{normal}^{T} = \begin{bmatrix} 0.8 & 0.6 & 0 \\ 0 & 0.6 & 0.8 \\ 0.6 & 0 & 0.8 \\ 0.5547 & 0.8320 & 0 \\ 0.8320 & 0.5547 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0.8 & 0 & 0.6 & 0.5547 & 0.8320 \\ 0.6 & 0.6 & 0 & 0.8320 & 0.5547 \\ 0 & 0.8 & 0.8 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 0.8 & 0 & 0.6 & 0.5547 & 0.8320 \\ 0.6 & 0.6 & 0 & 0.8320 & 0.5547 \\ 0 & 0.8 & 0.8 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0.36 & 0.48 & 0.9429 & 0.9984 \\ \mathbf{0.36} & 1 & 0.64 & 0.4992 & 0.3328 \\ \mathbf{0.48} & \mathbf{0.64} & 1 & 0.3328 & 0.4992 \\ \mathbf{0.9429} & \mathbf{0.4992} & \mathbf{0.3328} & 1 & 0.9230 \\ \mathbf{0.9984} & \mathbf{0.3328} & \mathbf{0.4992} & \mathbf{0.9230} & 1 \end{bmatrix} = D_{normal_dot_product}$$

We keep only the **lower triangular matrix**, where each value represents the dot product of the j-th vector (d_j) with the i-th vector (d_j), where i, j the rows and the columns of the matrix $D_{dot\ product}$ respectively.

The formula of the dot product of two vectors, using the included angle θ , is:

$$d_i \cdot d_j = \|d_i\| * \|d_j\| * cos\theta \implies cos\theta = \frac{d_i \cdot d_j}{\|d_i\| * \|d_j\|} = cos\theta_{d_i,d_j}$$

The process we followed above, calculates exactly the value of the cosine of the included angle θ , giving information on the relation between those vectors. If the angle's value is close to 0, then the vectors are orthogonal, if it is close to 1 they are

Therefore, the results are the follwing:

| Inner Product (of normalized vectors) | Value | Similarity |
|---------------------------------------|---|------------|
| $\cos\theta_{d_1,d_2} = 0.36$ | | Low |
| $\cos\theta_{d_1,d_3} = 0.48$ | | |
| $cos\theta_{d_1,d_4} = 0.9429$ | $> 0.94 \implies \theta_{d_1,d_4} < 19^{\circ}$ | High |
| $cos\theta_{d_1,d_5} = 0.9984$ | $\sim 1 \implies \theta_{d_1,d_5} \sim 0^{\circ}$ | High |
| $cos\theta_{d_2,d_3} = 0.64$ | | |
| $cos\theta_{d_2,d_4} = 0.4492$ | | |
| $cos\theta_{d_2,d_5} = 0.3328$ | | Low |
| $cos\theta_{d_3,d_4} = 0.3328$ | | Low |
| $cos\theta_{d_3,d_5} = 0.4992$ | | |
| $cos\theta_{d_4,d_5} = 0.9230$ | $> 0.92 \implies \theta_{d_4,d_5} < 23^{\circ}$ | High |

Table 3.10

The Documents 1, 4 and 5 are very similar.

Also, for this exercise, some code was developed to validate the results (included in the uploaded .zip file).