

# Bias-Variance-Noise Decomposition

By: Behzad Asadi

# Generalization Error Decomposition

**Training:** Consider the training dataset

$$D = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\},$$

where samples are drawn i.i.d. according to the distribution  $p(\mathbf{x}, y)$ . We fit a learner to this dataset which estimates the dependent variable,  $y_i$ , using explanatory variables,  $\mathbf{x}_i$ .

**Expected Test Error:** Assuming a regression problem with squared error loss where  $h_D(\mathbf{x})$  is the regression function, the expected test error is defined as

$$E_{(\mathbf{x}, y) \sim p(\mathbf{x}, y)} \left[ (h_D(\mathbf{x}) - y)^2 \right] = \int_D \int_{\mathbf{x}} \int_y (h_D(\mathbf{x}) - y)^2 p(\mathbf{x}, y) p(D) d\mathbf{x} dy dD$$

where training points,  $D$ , and test points,  $(\mathbf{x}, y)$ , are independent from each other. The expected test error can be divided into three terms as

$$\begin{aligned} E_{\mathbf{x}, y, D} \left[ (h_D(\mathbf{x}) - y)^2 \right] &= E_{\mathbf{x}, y, D} \left[ (h_D(\mathbf{x}) - \bar{h}(\mathbf{x}) + \bar{h}(\mathbf{x}) - y)^2 \right] \\ &= E_{\mathbf{x}, D} \left[ (h_D(\mathbf{x}) - \bar{h}(\mathbf{x}))^2 \right] + E_{\mathbf{x}, y} \left[ (\bar{h}(\mathbf{x}) - y)^2 \right] \\ &\quad + 2E_{\mathbf{x}, y, D} \left[ (h_D(\mathbf{x}) - \bar{h}(\mathbf{x})) (\bar{h}(\mathbf{x}) - y) \right] \end{aligned}$$

where  $\bar{h}(\mathbf{x})$  is the expected model

$$\bar{h}(\mathbf{x}) = E_D [h_D(\mathbf{x})] = \int_D h_D(\mathbf{x}) p(D) dD.$$

# Generalization Error Decomposition

The term  $E_{\mathbf{x},y,D} [(h_D(\mathbf{x}) - \bar{h}(\mathbf{x})) (\bar{h}(\mathbf{x}) - y)]$  is equal to zero

$$\begin{aligned} E_{\mathbf{x},y,D} [(h_D(\mathbf{x}) - \bar{h}(\mathbf{x})) (\bar{h}(\mathbf{x}) - y)] \\ &= E_{\mathbf{x},y} [E_D [h_D(\mathbf{x}) - \bar{h}(\mathbf{x})) (\bar{h}(\mathbf{x}) - y)] \\ &= E_{\mathbf{x},y} [(\bar{h}(\mathbf{x}) - \bar{h}(\mathbf{x})) (\bar{h}(\mathbf{x}) - y)] \\ &= 0. \end{aligned}$$

The term  $E_{\mathbf{x},y} [(\bar{h}(\mathbf{x}) - y)^2]$  can be similarly divided into three terms as

$$\begin{aligned} E_{\mathbf{x},y} [(\bar{h}(\mathbf{x}) - y)^2] &= E_{\mathbf{x},y} [(\bar{h}(\mathbf{x}) - \bar{y}(x) + \bar{y}(x) - y)^2] \\ &= E_{\mathbf{x}} [(\bar{h}(\mathbf{x}) - \bar{y}(x))^2] + E_{\mathbf{x},y} [(\bar{y}(x) - y)^2] \\ &\quad + 2E_{\mathbf{x},y} [(\bar{h}(\mathbf{x}) - \bar{y}(x)) (\bar{y}(x) - y)], \end{aligned}$$

where  $\bar{y}(x)$  is the expected label given  $\mathbf{x}$ , calculated as  $\bar{y}(x) = \int_y yp(y | \mathbf{x})dy$ , and the last term is equal to zero

$$\begin{aligned} E_{\mathbf{x},y} [(\bar{h}(\mathbf{x}) - \bar{y}(x)) (\bar{y}(x) - y)] &= E_{\mathbf{x}} E_{y|\mathbf{x}} [(\bar{h}(\mathbf{x}) - \bar{y}(x)) (\bar{y}(x) - y)] \\ &= E_{\mathbf{x}} [(\bar{h}(\mathbf{x}) - \bar{y}(x)) E_{y|\mathbf{x}} [\bar{y}(x) - y]] \\ &= E_{\mathbf{x}} [(\bar{h}(\mathbf{x}) - \bar{y}(x)) (\bar{y}(x) - \bar{y}(x))] \\ &= 0. \end{aligned}$$

# Generalization Error Decomposition

Therefore, we can write the expected test error as

$$E_{\mathbf{x},y,D} \left[ (h_D(\mathbf{x}) - y)^2 \right] = \underbrace{E_{\mathbf{x},D} \left[ (h_D(\mathbf{x}) - \bar{h}(\mathbf{x}))^2 \right]}_{\text{Variance}} + \underbrace{E_{\mathbf{x}} \left[ (\bar{h}(\mathbf{x}) - \bar{y}(x))^2 \right]}_{\text{Bias}^2} + \underbrace{E_{\mathbf{x},y} \left[ (\bar{y}(x) - y)^2 \right]}_{\text{Noise}}$$

**Variance:** This part shows changes in the classifier as the result of changes in the training dataset. It is high when we have overfitting, and the learner is over-specialized to the training dataset.

**Bias:** This part shows the error even when we have infinite training data. It is high when we have underfitting.

**Noise:** This is due to the noise in the data.

# References

1. Kilian Weinberger, Lecture Notes,  
<https://www.cs.cornell.edu/courses/cs4780/2018fa/lectures/lecturenote12.html>.
2. Kevin P. Murphy, Machine Learning: A Probabilistic Perspective.
3. Trevor Hastie, Robert Tibshirani, and Jerome Friedman, The Elements of Statistical Learning.