Manjunath Bhat

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2015

Education	Institute	Year	CPI / %
B.Tech(Hons): Mechanical Engineering	Indian Institute of Technology, Kharagpur	2017- 2021	8.73 / 10
12th	SKCH Composite Pre-University College, Bengaluru	2015 - 2017	97.16 %

Prarthana Central School, Bengaluru

MAJOR PROJECTS

10th

• Google Summer of Code 2019 - FluxML (The Julia Language)

(March'19-August'19)

10 / 10

(Guide: Mr. Dhairya Gandhi, Mr. Elliot Saba)

- **Project**: Enriching FluxML's model zoo repository with Deep Learning models: Spatial transformer Network, VAE-GAN, EBGAN, and StarGAN.
- Contributed to the backend of the Flux library by adding dropout layers, normalization layers, and wrappers for convolution and pooling layers.
- Worked on integrating the Flux library with a new Automatic Differentiation package called Zygote.

• RoboCup Small Sized League(SSL)

(May'18-Present)

Kharagpur RoboSoccer Students' Group, Artificial Intelligence Team (Guide: Prof. Alok Kanti Deb)

- Worked on the software for controlling multiple soccer playing robots in a dynamic environment using the Finite State Machine Architecture to develop plays and strategy.
- Worked on Robot Operating System (ROS) by using its nodes, topics and services to send commands and handle game state data in a centralized manner.
- Implemented and analyzed various random sampling based path planning algorithms such as RRT (Rapidly Exploring Random Trees), RRT-Connect, RRT-Star, RRT-Star with Artificial Potential Field.

• ConnectAll - An app to enable the differently abled

(Oct'19)

- Developed a web app that bridges the communication gap that exists among deaf, blind and mute people. The app provides a chat and call platform, that converts the speaker's voice to text in realtime, so that a deaf person can understand and respond. It also enables blind people to respond to text messages by converting text to an automated voice.
- Real-time note making, when notes are being dictated. The app also provides a feature for personalized book narration. These features have been automated with a Zulip chatbot that responds on the Zulip Chat platform when pinged with a request.

Maze Solving Robot

(Sep'18-Oct'18)

 A three-wheeled robot that can find the shortest path between source and destination in a maze using Dijkstra's Algorithm, and can follow the path generated. Various techniques of Image Processing such as Edge Detection, Contour Detection, and Hough Transforms were used.

RESEARCH PAPERS

• Deep Learning rooted Potential piloted RRT* for expeditious Path Planning

(July'19)

- Proposed a deep learning based approach to predict the appropriate value of Potential Field function in the RRT*-APF algorithm, based on the position, size and number of obstacles in the configuration space.
- The paper has been accepted at the 4th International Conference on Artificial Intelligence and Robotics (ICAIR 2019), held at Shenzhen, China.

TECHNICAL SKILLS

- Languages C, C++, Python, MATLAB, Octave, Julia, LATEX
- Libraries and Tools Tensorflow, OpenCV, ROS, Git
- Fields of Interest Computer Vision, Path Planning, Machine Learning.

AWARDS AND ACHIEVEMENTS

- 2nd Runner Up, Robotics + Image Processing Event, Pixelation, NSSC, 2018.
- 2nd Runner Up, Coding + Soccer Strategy Event, Code-O-Soccer, Kshitij, 2018
- Part of the only Indian team to qualify for **RoboCup SSL** (Small Sized League) in 2018 and 2019.
- Secured **AIR 444 among 1.2 million students** in JEE Main 2017 and **AIR 1459 among 160,000 students** in JEE Advanced 2017.

POSITIONS OF RESPONSIBILITY

- Team Head of Kharagpur RoboSoccer Students' Group for the academic year 2019-20.
- Mentored over 90 first year students at an **IEEE certified Image Processing Workshop** organized at Indian Institute of Technology Kharagpur.