

Modeling and simulating ERTMS/ETCS using VDM++

Christian Marius Lillelund (201408354)

School of Engineering, Aarhus University

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Abstract

Modeling of critical systems is an important tool in software engineering, as it allows us to design a system from specification and verify its properties in a unambiguous way early in the development process. In this report, we use the object-oriented Vienna Development Method (VDM++) to model, simulate and verify a subset of the specifications for the safety-critical European Rail Traffic Management System (ERTMS) level 2 focusing on those properties of ERTMS that concern interlocking of tracks and safety of the trains. In ERTMS, these features are controlled by the European Train Control System (ETCS) component. With VDM++, we can perform system design analysis and model verification to catch potential faults early before the system is constructed in an implementation language like Java and deployed to a real system. We start by defining requirements and invariants based on the ERTMS/ETCS specification and then use VDM++ to design a formal model followed by model-checking. The abstract implementation of ERTMS detailed in this report provide a simple but fundamental understanding of the signaling system's behavior and how to describe its constraints.

Keywords: ERTMS, ETCS, VDM++, Formal methods, Interlocking, Safety

1. Introduction

The railway domain was identified as a grand challenge of computing science in 2004 because it is understandable by the general public, provides useful features in terms of transportation and pose many concerns for design and controllability. One part of the challenge is improving the feasibility and capacity of modern railway as the world's population is increasing and rail traffic now moves cross borders.

The European Rail Traffic Management System (ERTMS) is a signaling and control system developed in the start 2000's to address the interoperability issues with cross-border rail traffic in Europe and lack of capacity with legacy systems. Currently many European countries have their own national stand-alone signaling and control system implemented by a certain set of rules that differ from each country. ERTMS is designed to replace the national systems to make rail transport more frictionless, improve rail capacity and more attractive to consumers. It consists of two primary parts, the European Train Control and Command System (ETCS) to govern the positions and safety of trains, known as the Interlocking (ITL), and the GSM-R radio communications system to send messages between trains and the Radio Block Center (RBC). There are three different levels of ERTMS, L1, L2 and L3. We consider L2 in this report. L2 introduces the RBC, a Eurobalise that register train movement and omits any track side signaling equipment. For a train to enter a new track section, it must request a movement authority (MA) for that section from the RBC, which will be further explained in section X. ERTMS defines end of authority (EoA) as the point the train is allowed to move to. We consider this aspect as well.

Figure 1 shows the essential components of ERTMS level 2. The train control (EVC) requests movement authorities from the RBC over GSM-R. A typical national rail way will have multiple RBC's for each region. The RBC's communicate with a central interlocking service, that receives the physical location of trains using the Eurobalises, in order to either grant or deny movement authority to a train.

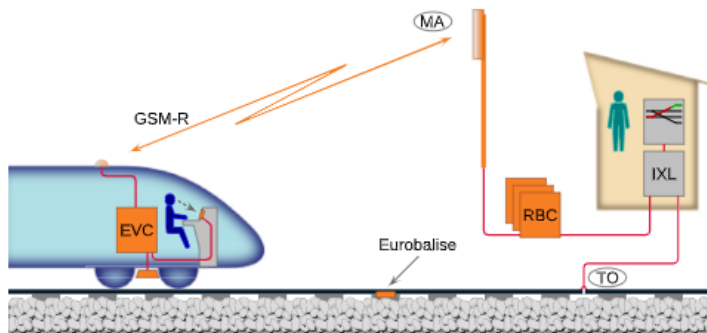


Figure 1: An overview of the ERTMS/ETCS level 2 components.

2. Requirements

The purpose of the model is to design and verify the interlocking properties and operating rules of the ETCS system, a part of ERTMS. With our model we aim to show how VDM++ can be used to create and satisfy a subset of the real requirements of ETCS interlocking, abstracting away most of the physical constraints you would have in a real system and focusing on the control mechanisms you find in the RadioBlockCenter and Interlocking components, described in the introduction. Our model should demonstrate a simulated train that interacts with the control system when traversing a set of tracks, as it would in real life, while simultaneously monitoring and adhering to the safety features of the system. We address the following requirements:

- R1: A train shall not enter a track section which is occupied by another train (same track).
- R2: A train shall not pass a track boundary without being given a movement authority (MA) to do so.
- R3: A train shall respect the maximum permitted speed of its current track.
- R4: When a train has traversed half of its current track, it shall request a MA for the next track.
- R5: Two trains cannot have a MA for the same track at the same time.
- R6: The system shall not provide an MA for a track that is occupied by a train.
- R7: The RBC shall not answer MA's for tracks it is not responsible for.
- R8: The eurobalise shall report train movement to the interlocking system.

The requirements and the behavior of the ETCS control architecture, that we elaborate on in section 3, are inspired from literature X and X, that describe, model and verify many of the real functional properties of ERTMS. In this report we choose a portion of these to model and test our requirements *R1-R8*. UML will be used to show some of the logical VDM++ classes and their relationships. From the specification of ERTMS we can define a typical usage scenario for a train that wishes to enter a track. Given a train *T1*, a track *TR1* from a set of tracks ($i=1,...,n$), an *RBC* responsible for tracks *TR_n*, a eurobalise *Eb* mounted on the track that registers physical movement and a central interlocking service *ITL*.

- *T1* wants to enter track *TR1*. *T1* requests MA for *TR1* from RBC.
- RBC contacts the ITL to verify the request.
- RBC grants MA to train *T1* for track *TR1*.

- *Tl* enters track TR1.
- Eb registers movement and informs ITL.

This functionality will be further explored in the model architecture and design.

3. Model architecture

The architecture of the model represents the entire system as entities, that are later defined in VDM++ as classes, that encapsulate functionality related to the individual entity. We consider the purpose of our model, that is to express and simulate several important aspects of ERMTS/ETCS, and use the primary components of such system as our entities. These can be seen in figure 2 that show a way to model the control architecture of ERTMS based in the real specification set for ERTMS level 2 detailed in X, but junction control and route guidance has been omitted.

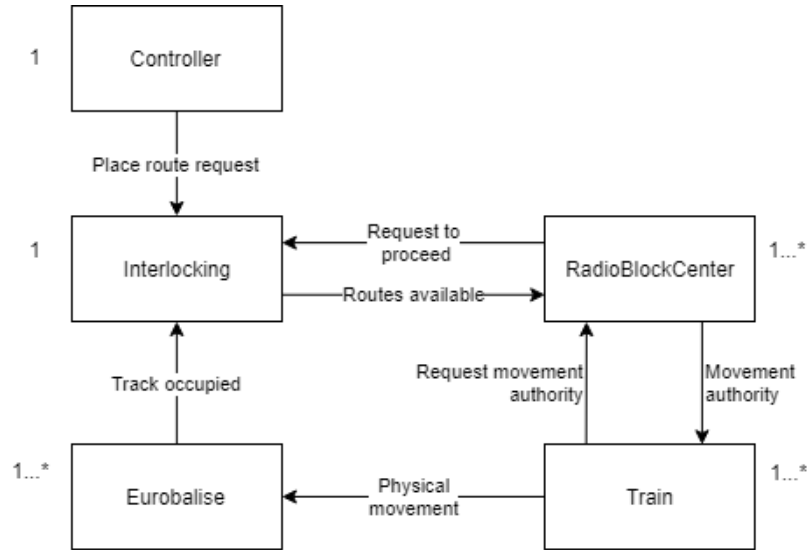


Figure 2: The ETCS control architecture partly from the real specification.

We shall describe the components in more detail before designing our model. The **controller** places route requests into the interlocking at certain time t intervals. The point is to control the flow of traffic and how many routes can be available concurrently in the rail network, a way to limit congestion. A route is

simply a set of tracks. **Interlocking** receives route requests and stores them in a control table containing available routes. It receives track occupation events from physical units along the track side and uses this information to update the control table with available routes. The **RadioBlockCenter** receives MA requests from trains, checks route availability and forwards these to the interlocking. RBC's are responsible for multiple tracks, i.e. a block. The **Train** sends MA requests to the RBC before entering a new track in a route. For each track, a line segment with a geographic starting and terminal point, the train must request and obtain a MA. This is also stated in the requirements. Each track has a certain speed limit, and the train must never exceed this. The **Eurobalise** registers physical movement when trains enter and leave tracks and conveys this to the interlocking.

In a real scenario, the eurobalise sends track and speed information to passing trains and the ETCS would monitor this and eventually slow down trains, if they go too fast. We do not consider this part in our model. The ETCS architecture in figure 2, requirements and functionality will be used to create VDM++ classes, functions and invariants in the next section.

4. Model design

In this section we will review the model in VDM++ in a top-down approach and elaborate on the design choices made. The entities in our architecture are now VDM classes, types represent information state objects, and events and requests are described with operations and functions. A full class diagram can be found in Appendix A.

4.1. *Controller*

4.2. *Interlocking*

4.3. *RadioBlockCenter*

4.4. *Eurobalise*

4.5. *Train*

5. Testing

- Bullet point one
- Bullet point two

1. Numbered list item one
2. Numbered list item two

5.1. Subsection One

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Treatment 2	0.0015681	0.910
Treatment 3	0.0009271	0.296

Table 1: Table caption

5.2. Subsection Two

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