# Machine Learning

Bias-Complexity Trade-off

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### Our Goal in Learning

#### Given:

- training set:  $S = ((x_1, y_1), \dots, (x_m, y_m))$
- loss function:  $\ell(h,(x,y))$

**Want**: a function  $\hat{h}$  such that  $L_{\mathcal{D}}(\hat{h})$  is small

We can pick: the learning algorithm  $\overline{A}$  that given  $\overline{S}$  will produce  $\hat{h} = \overline{A(S)}$ 

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**We can pick**: the learning algorithm A, that given S will produce  $\hat{h} = A(S)$ 

**Note:** A comprises:

- the hypothesis set H
- the procedure to pick  $\hat{h} = A(S)$  from  $\mathcal{H}$

**Question**: is there a *universal learner*, i.e., an (implementable) algorithm  $\underline{A}$  that predicts the best  $\hat{h}$  for any distribution  $\underline{\mathcal{D}}$ ?

#### The No Free Lunch Theorem

The following answers the previous question for some specific settings.

#### Theorem (No-Free Lunch)

Let A be any learning algorithm for the task of binary classification with respect to the 0-1 loss over a domain  $\mathcal{X}$ . Let m be any number smaller than  $|\mathcal{X}|/2$ , representing a training set size. Then, there exists a distribution  $\mathcal{D}$  over  $\mathcal{X} \times \{0,1\}$  such that:

- there exists a function  $f: \mathcal{X} \to \{0,1\}$  with  $L_{\mathcal{D}}(f) = 0$
- with probability of at least 1/7 over the choice of  $S \sim \mathcal{D}^m$  we have that  $L_{\mathcal{D}}(A(S)) \geq 1/8$ .

Note: there are similar results for other learning tasks.

### No Free Lunch and Prior Knowledge

#### Corollary

Let  $\mathcal{X}$  be an infinite domain set and let  $\mathcal{H}$  be the set of all functions from  $\mathcal{X}$  to  $\{0,1\}$ . Then,  $\mathcal{H}$  is not PAC learnable.

What's the implication?

We need to use our prior knowledge about  $\mathcal{D}$  to pick a *good* hypothesis set.

How do we choose  $\mathcal{H}$ ?

- we would like  $\mathcal{H}$  to be *large*, so that it may contain a function h with small  $L_{\mathcal{D}}(h)$
- no free lunch ⇒ H cannot be too large!

## **Error Decomposition**

Let 
$$h_s$$
 be an ERMA hypothesis.

$$L_0(h_s) = L_0(h_s) - \min_{h \in \mathcal{H}} L_0(h) + \min_{h \in \mathcal{H}} L_0(h)$$
estimation error
$$\mathcal{E}_{est}$$
approximation error
$$\mathcal{E}_{spp}$$

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### **Error Decomposition**

Let  $h_S$  be an ERM<sub>H</sub> hypothesis.

Then

$$L_{\mathcal{D}}(h_{\mathcal{S}}) = \epsilon_{\mathsf{app}} + \epsilon_{\mathsf{est}}$$

where

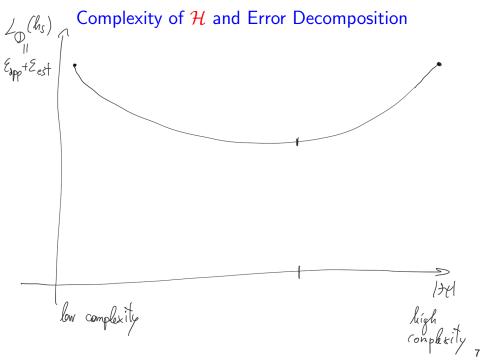
- $\epsilon_{\mathsf{app}} = \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h)$  (approximation error)
- $\epsilon_{\mathsf{est}} = L_{\mathcal{D}}(h_{\mathsf{S}}) \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h)$  (estimation error)

# Approximation error: $\epsilon_{app} = \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h)$

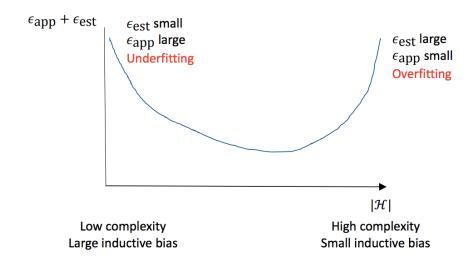
- derives from our choice of H
- once we have chosen  $\mathcal{H} \Rightarrow \epsilon_{app}$  is unavoidable!
- to decrease it, chose a "larger"  ${\cal H}$

### Estimation error. $\epsilon_{\text{est}} = L_{\mathcal{D}}(h_S) - \min_{h \in \mathcal{H}} L_{\mathcal{D}}(h)$

- derives from our inability to choose (with ERM) the best hypothesis in  ${\mathcal H}$
- could be avoided if had chosen the best hypothesis!
- to decrease, we need a low number of hypotheses in H so that training error is good estimate of generalization error for all of them ⇒ need a "small" H



## Complexity of $\mathcal{H}$ and Error Decomposition



## Estimating $L_{\mathcal{D}}(h_{\mathcal{S}})$

How can we estimate the generalization error  $L_{\mathcal{D}}(h)$  for a function h, for example  $h_S \in \mathsf{ERM}_{\mathcal{H}}$ ?

We can use a **test set**: new set of samples not used for picking  $h_S$  (=the training set).

#### Notes:

- the test must not be looked at until we have picked our final hypothesis!
- in practice: we have 1 set of samples and we split it in *training set* and *test set*.

# Bibliography

[UML] Chapter 5