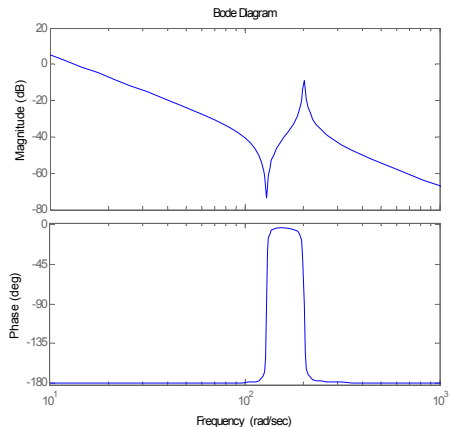


Desired System

$$\frac{\theta_a(s)}{T(s)}$$



System With TR

$$\frac{\theta_a(s)}{T(s)}$$