

Team DRC-Hubo

Kickoff Meeting, Oct 23-25, 2012, Arlington VA Presented by Paul Oh (Team Lead, Drexel University)















Aligning our "Why" with the DRC Vision...

Background:









Korea: Leadership in Humanoid Design

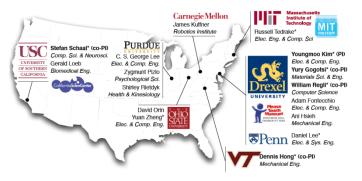
US: Leadership in Al and IT

http://dasl.mem.drexel.edu/pire/

2007-2012

Less than 3% of US S&T students are prepared for international design teams. Use humanoids to motivate, inspire and train global and systems engineering skills







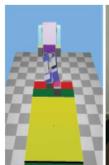
Major Research Infrastructure (MRI-R2)

2010-2013

Humanoid research is eclectic, ad-hoc and difficult to verify. Acquire 6 Hubo+ to benchmark results, formulate practice, and establish foundational theory

Conviction: The "brains" must be developed in <u>concert</u> with the "body"; realizing the DRC vision must attend to <u>both</u> hardware and underlying motion planning software

Why Hubo?





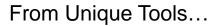


- (1) Virtual-Hubo
- (2) Mini-Hubo
- (3) Online-Hubo



To Public Realizations...

http://www.youtube.com/watch?v=OA_u5Q3D57o&feature=g-all-u





DOF	40
Height	130 cm
Mass	41 kg
Battery Run-tim e	1 hour
Battery Type	17-cell LIPO (8 A-hr)
Com puting	Two x86 SBC
Running Speed	3.6 km/hr
Carrying capacity	10 kg

Sensors: IMU (6-axis), Force/Torque (each foot and each write), monocular camera, stereo microphone

- Hubo: Form-and-function "top of class"
- Open Architecture
- 20+ person-years US-Korea Collaboration
- Proven 3-tier infrastructure for T&E and V&V
- 10-year old boy size: suitable for DRC events
- 7-Hubos: parallel development
- Program-Modify-Perfect vs. Design-Build-Hack
- Regional distribution of Hubos
- RP T&E and V&V Cycle
- OpenHubo drive DRC-Hubo retrofits

Hubo: Latest Capabilities Underscore Promise for DRC



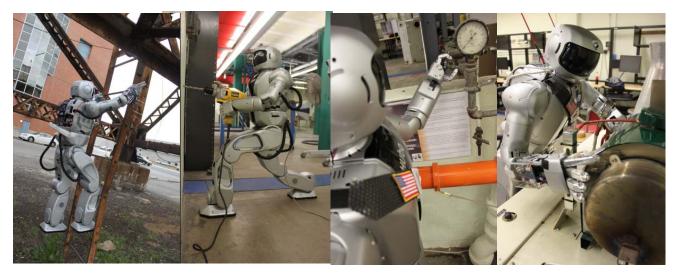


Videos of capabilities: http://dasl.mem.drexel.edu/DRC

DRC-Hubo: Notional

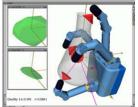


Event 1: Vehicle Event 2: Terrain Event 3: Debris Event 4: Door



Event 5: Ladder Event 6: Wall Break Event 7: Valve Event 8: Pump

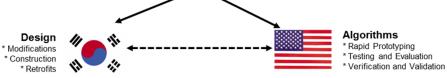




Dream Team: Domain Experts

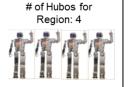
(aka: Ocean's 11 Approach)





Northeast Partner Korean Partner

Hardware Support & Modifications KAIST/Rainbow LLC: J.H. Oh (Hubo Lab)



Event 1 - Ingress/Drive/Egress Drexel: P. Oh

UD: C. Rasmussen, Poulakakis, Tanner Event 4 - Open Door



Region: 2



Purdue - IU: G. Lee, K. Hauser

of Hubos for South Partner



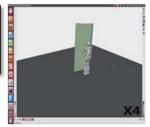
Event 3 - Debris Removal Georgia Tech Event 6 - Wall Break-through Georgia Tech: M. Stilman, Egerstedt, Bobick

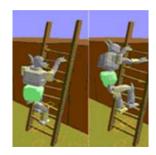
Team DRC-Hubo 200+ person-years Expertise in Humanoids















P. Oh Drexel

J.H. Oh KAIST









Y. Zheng Ohio State



G. Lee

Purdue

C. Rasmussen M. Stilman





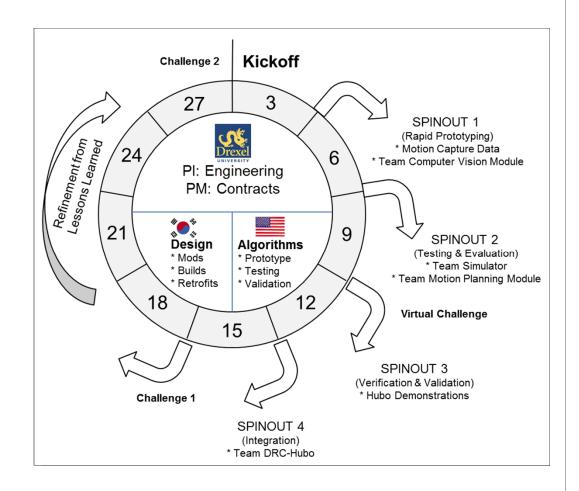
M. Zucker

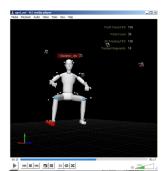


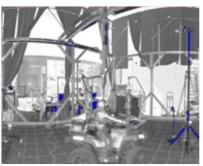
K. Hauser D. Berenson Indiana U WPI

P. Allen Columbia

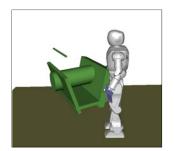
Spiral Development & 3-stage Design Cycle







(1) RP: Rapid Prototyping

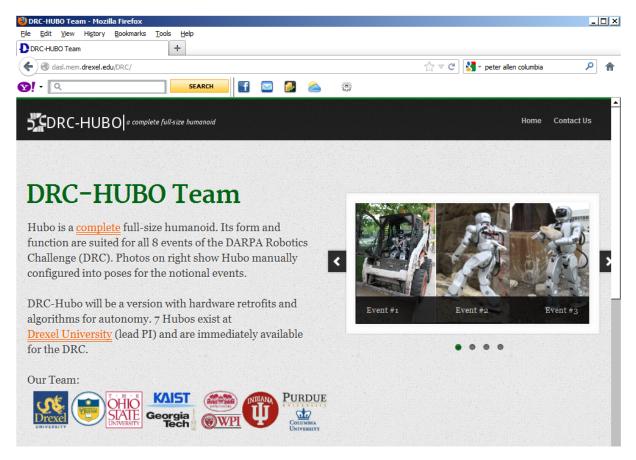




(2) T&E: OpenHubo



(3) V&V: Hubo+ and DRC-Hubo



Please follow us on: http://dasl.mem.drexel.edu/DRC/

- DRC: Validate training of US students in global design teaming and complex systems engineering (education)
- DRC: Validate "Ocean's 11" approach and benchmark results (research)
- DRC: Validate design coupling of "brains" and "body"

"The views expressed are those of the author and do not reflect the official policy or position of the Department of Defense or the U.S. Government"