



Right Arm link coordinate parameters

Joint i	$\theta_i$	$\alpha_i$	$a_i$	$d_i$
1	$-90^\circ$	$90^\circ$	0	0
2	$90^\circ$	$-90^\circ$	0	0
3	$90^\circ$	$90^\circ$	0	$-L_{A2}$
4	0	$90^\circ$	0	0
5	0	$90^\circ$	0	$L_{A3}$
6	$90^\circ$	0	$L_{A4}$	0