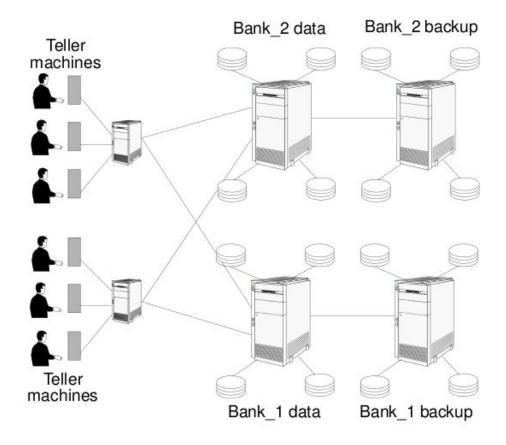
Chapter 8 Distributed OS

--By R.G.B

Introduction

- Multiple CPUs connected together to gain performance or redundancy
- Appears to end user as single system
- It has 2 different aspect hardware and software
- Eg: Parallel machine, Network servers, file server, webservers

Eg: Bank's Server



Advantages and Disadvantages

- Performance
- Distribution of Information evenly
- Reliability (fault tolerance)
- Incremental growth
- Sharing of data/resources
- Communication

- Difficulties of developing distributed software
- Networking problems
- Security problems

- 1. Transparency
- 2. Communication
- 3. Performance & scalability
- 4. Heterogeneity
- 5. Openness
- 6. Reliability & fault tolerance
- 7. Security

- <u>Transparency</u> System look like single computer
- a) Access Transparency
- b) Location Transparency
- c) Mobility Transparency
- d) Replication Transparency
- e) Concurrency Transparency
- f) Failure Transparency
- g) Performance Transparency

- <u>Communication</u>: Components of a distributed system have to communicate in order to interact
- 1. Networking infrastructure (interconnections & network software)
- 2. Appropriate communication primitives and models and their implementation
 - 1. Communication primitives
 - a. Message Passing (send, receive)
 - **b.** Remote Procedure Call
 - b) Communication Models
 - a) Client-Server
 - b) Group Multicast

• <u>Performance</u>:

- Several factors are influencing the performance of a distributed system
- 1. Performance of individual workstations
- 2. Speed of the communication infrastructure

Scalability

- System should remain efficient even with a significant increase in the number of users and resources connected
- 1. Cost of adding resources should be reasonable
- 2. Performance loss with increased number of users and resources should be controlled
- 3. software resources should not run out because of increase in hardware

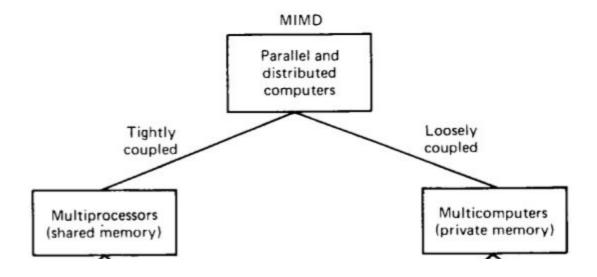
- Heterogeneity: Systems that use more than one kind of processor
- Openness:

Be able to interact with services from other open systems, irrespective of the underlying environment

- 1. Systems should have to well-defined interfaces
- 2. Systems should support portability of applications
- 3. Systems should easily interoperate

Network Architecture

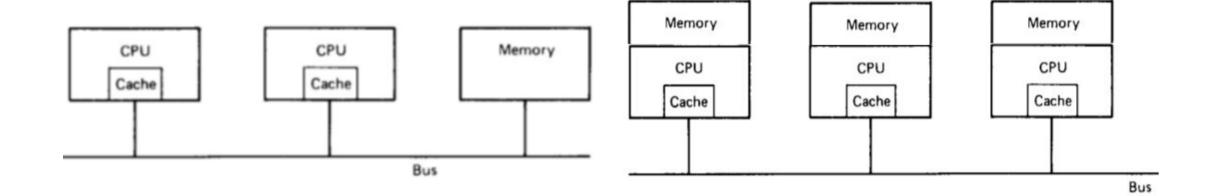
Divided into two



Network Architecture

Multi Processors(Shared Primary memory)

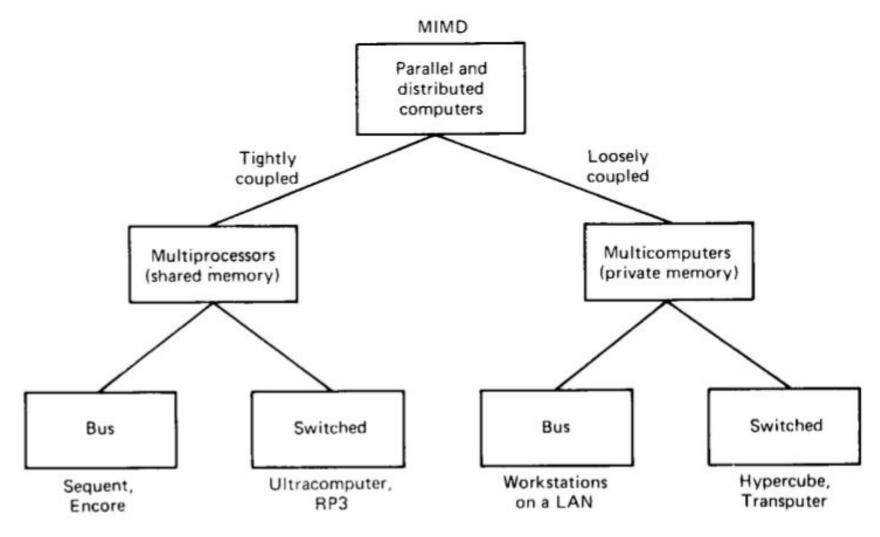
Multi Computers(Separate Primary memory)



Hardware and Software Concept

- Even though all distributed system consists of multiple CPUs
- Several ways the hardware can be organized in terms of how they are interconnected and how they communicate
- Flynn proposed the following categories
 - 1. Single Instruction Single Data (SISD) stream
 - 2. Single Instruction Multiple Data (SIMD) stream
 - 3. Multiple Instruction Single Data (MISD) stream
 - 4. Multiple Instruction Multiple Data (MIMD) stream

Topologies/Taxonomy (All Distributing system are MIMD)

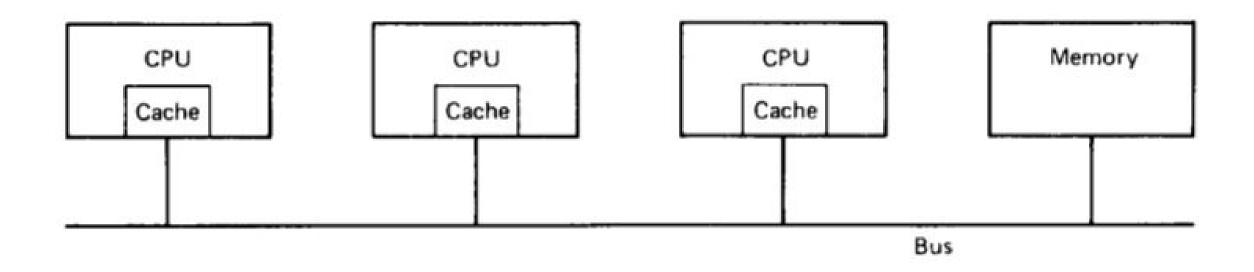


Topologies/Taxonomy

- Distributed Computer
- 1. Multiprocessor(Tightly Coupled → Shared memory)
 - a) Bus
 - b) Switched \rightarrow Crossbar Switch and Omega Switch
- 2. Multicomputer(Loosely Coupled → Independent memory)
 - a) Bus
 - b) Switched

Topologies- Bus based multiprocessor

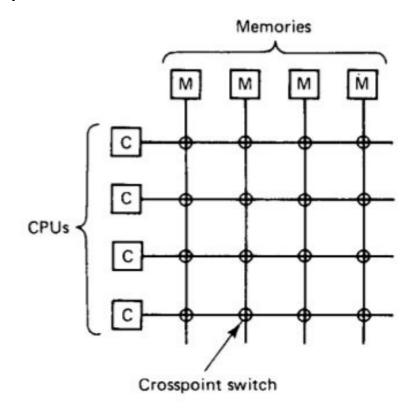
 Bus based multiprocessor consists of some number of CPUs all connected to a common bus, along with a memory module



Topologies- Cross bar switching multiprocessor

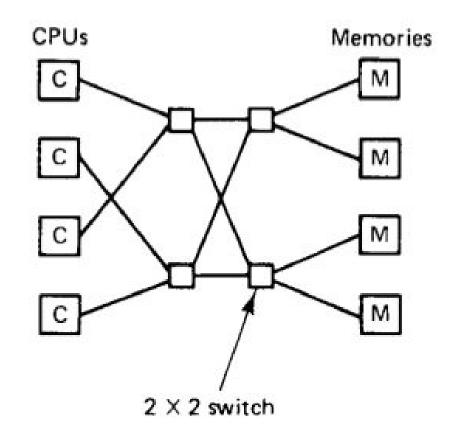
- Memory is divided into the modules and are connected to the CPUs with the crossbar switch
- Each CPU and each memory has a connection coming out of it
- At every intersection is a tiny electronic crosspoint switch that can be opened and closed in hardware
- When a CPU wants to access a particular memory, the crosspoint switch connecting them is closed, to allow the access to take place
- If two CPUs try to access the same memory simultaneously, one of them will have to wait.

• The downside of the crossbar switch is that with n CPUs and n memories, n^2 crosspoint switches are needed



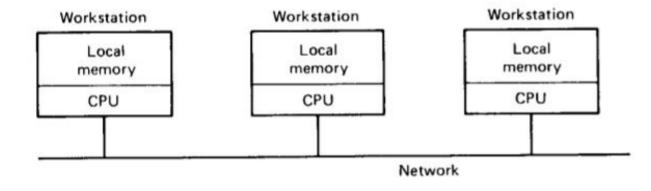
Topologies- Omega switching multiprocessor

- It contains 2X2 switches each having two inputs and two outputs
- every CPU can access every memory.
- In general case, with n CPUs and n memories, the omega network requires $\log_2 n$ switching stages, each containing n/2 switches, for a total of $\frac{2\log_2 n}{2}$ switches



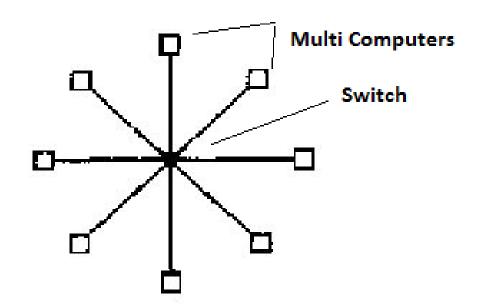
Topologies- Bus based multicomputer

- Each CPU has a direct connection to its own local memory.
- CPUs communicate with each other with help of LAN/ Network Cable



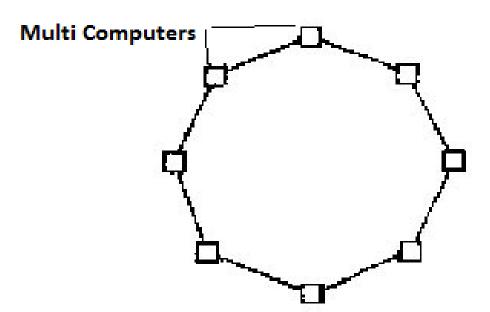
Topologies- Multicomputer Star

- Central Controlling device (Switch) connect all multi computer together
- All data traffic goes through switch



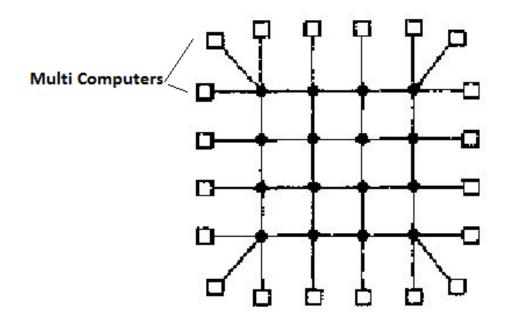
Topologies- Multicomputer Ring

- All multi computer connected in ring structure
- Each computer have an in and out interface
- Data will be passed through 2,3 if you send data from 1 to 4



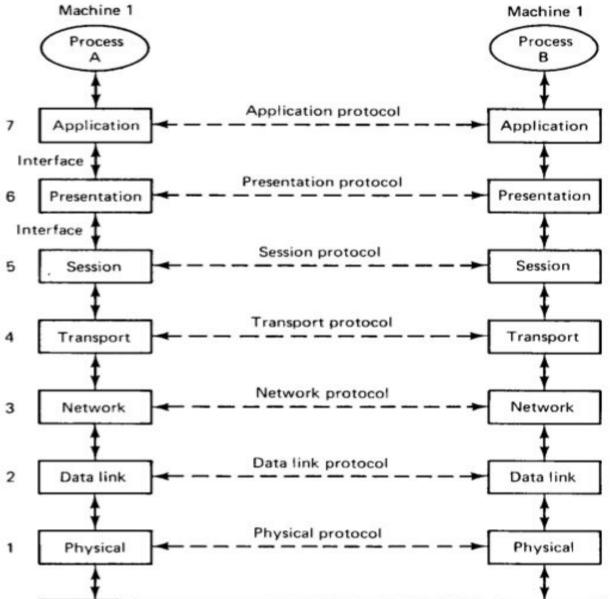
Topologies- Multicomputer Grid

- All computer have connection to all the other computer
- Arranged in Grid structure
- Even if one connection is all other work properly



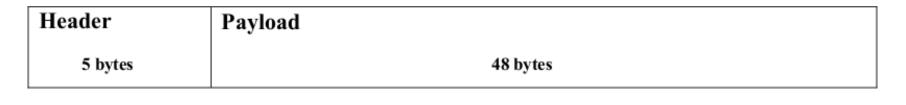
Communication in Distributed OS(ISO/OSI

Model)



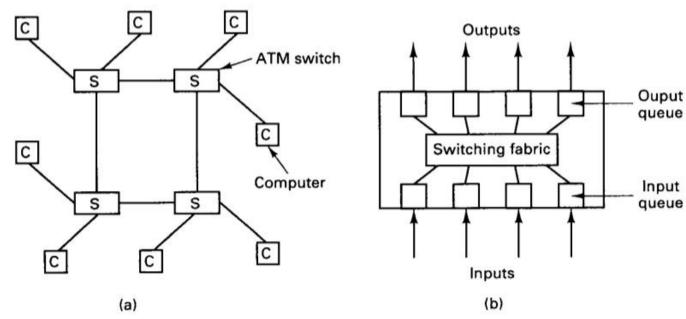
Asynchronous Transfer Mode(ATM)

- ATM devices do not send and receive information at fixed speeds or using a timer
- Negotiate transmission speeds based on hardware and information flow reliability
- Fixed-size cell structure used for packaging information.
- ATM transfers information in fixed-size units called cells
- Each cell consists of 53 octets, or bytes



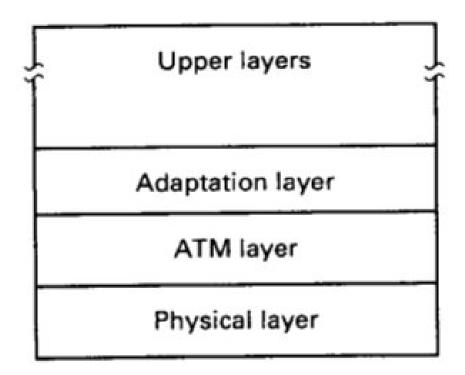
Asynchronous Transfer Mode(ATM)

- ATM network with 4 switches
- Each of these switches has 4 ports, each used for both input and output lines



Asynchronous Transfer Mode(ATM)

ATM Layers

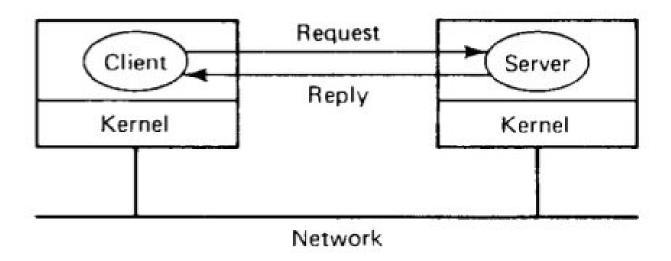


Client Server Model

- Operating-system as a group of cooperating process, called servers, that offer services to the users, called clients
- The client and server normally all run the same microkernel, with both clients and severs running as user processes
- A machine may run a single process or it may run multiple clients, multiple servers or mixture of both
- To avoid the considerable overhead of the connection oriented protocol such as TCP and OSI Model are used

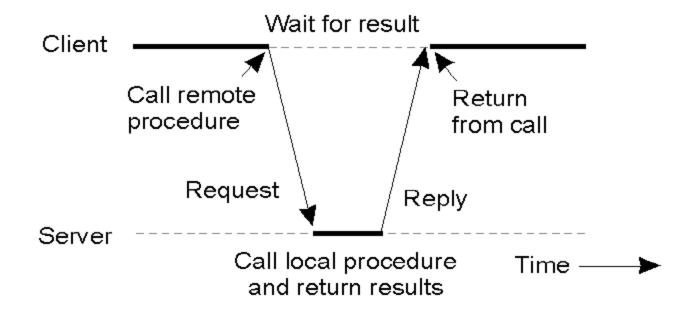
Client Server Model

- The client sends a request message to the server asking for some services (eg. read a block of a file)
- The server does the work and returns the data requested or an errorcode indicating why the work could not be performed



Remote Procedure Call(RPC)

• Inter-process communication that allows a computer program to cause a subroutine or procedure to execute in another address space (commonly on another computer on a shared network)



Remote Procedure Call(RPC)

• PRINCIPLE OF RPC:

- Client makes procedure call to the client stub
- Server is written as a standard procedure
- Stubs take care of packaging arguments and sending messages
- Packaging parameters is called marshalling
- Stub compiler generates stub automatically from specs in an Interface Definition Language(IDL)
- Simplifies programmer task

Remote Procedure Call(RPC)

Remote procedure call occurs in the following steps:

- 1. The client procedure calls the client stub in the normal way.
- 2. The client stub builds a message and calls the local operating system.
- 3. The client's OS sends the message to the remote OS.
- 4. The remote OS gives the message to the server stub.
- 5. The server stub unpacks the parameters and calls the server.
- 6. The server does the work and returns the result to the stub.
- 7. The server stub packs it in a message and calls its local OS.
- 8. The server's OS sends the message to the client's OS.
- 9. The client's OS gives the message to the client stub.
- 10. The stub unpacks the result and returns to the client.