Construction of planar triangulations with minimum degree 5 : Computer Program Part I Version 1.0.3

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26th May 2002

Abstract

In this article, we describe a computer program based on basic operation to construct a planar triangulations with minimum degree five, denoted $MPG5$. Actually current version doesn't exhaustive, in some sense we know that there exists $MPG5$ such that we doesn't construct. In return at the beginning and during all step we will assume a plan orientation.

Key-Words: Graph Theory, Planar, Triangulation, Maximal, Construction, minimum degree five, computer program

1 Approach

In order to construct an $MPG5$ with $n > 14$ vertices we will use the following (not exhaustive):

- Starting by the only graph in $MPG5_{14}$.

- Apply an operation called T which increment n by adding one vertex. This operation conserving all properties : planarity, triangulation, degree minimal, plan orientation and increment number of vertices by adding one vertex.

2 Definitions

Definition 1 *Let $G = (X, E)$ be an $MPG5_{n>14}$ and x with $dg(x) > 5$. We describe $N(x)$ in clockwise order by $\{x_1, \ldots, x_k, \ldots, x_q\}$ where $k \in [4, q-2]$ and $q > 5$. A such path is denoted by $[x; x_1, x_k]$. See figure 2.*

Definition 2 *$T[x; x_1, x_k]$ is the graph G after the explosion of x in two new adjacent vertices x', x'' such that in clockwise order $N(x') = \{x_1, x_2, \ldots, x_{k-1}, x_k, x''\}$ and $N(x'') = \{x_1, x', x_k, x_{k+1}, \ldots, x_q\}$. See figure 2.*
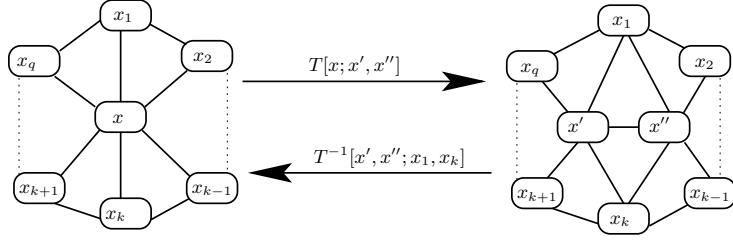
Figure 2. T and T^{-1} transformations.

Definition 3 *Let $G = (X, E)$ be an MPG5. We denote*

$$X_{sup6} = \{x \in X/dg(x) \geq 6\},$$
$$X_{inf6} = \{x \in X/dg(x) \leq 5\}.$$

3 Algorithm

Program is defined by a main loop between 14 and n (ie number of vertices), each step add a vertex by T. Inside the main loop, first select a vertex x with at least six neighbors. Secondly, we have to select two neighbors of x called x_1 and x_k such that $k \in [4, q-2]$. Third, dispatch and update neighborhood.

Algorithm 4

```
TITLE: MPG5_n construction programming
INPUT: n number of vertices
OUTPUT: At random MPG5 with n vertices
(0)     n_i = 14; G = Load (MPG5_14);
(1)     While n_i ≤ n do
(2)         x = random(X_sup6,1,|X_sup6|);
(3)         x_1 = random(N(x),1,dg(x)-3);
(4)         x_k = random(N(x),position(N(x),x_1,3), position(N(x),x_1,-3);
(5)         N(x) = {x_1,...,x_k,n_i+1} in clockwise order
(6)         N(n_i+1) = {x_k,x_{k+1},...,x_1,x} in clockwise order
(7)         ForAll vertices y in {N(n_i+1) - x - x_1 - x_k} Do
(8)             In N(y) Replace x by n_i+1
(9)         End ForAll
(10)        In N(x_1) add n_i+1 after x
(11)        In N(x_k) add n_i+1 before x
(12)        n_i = n_i + 1
(13)    End While
```

3.1 x_1, x_k choices

We looking a couple such that always we have `position`(x,x_1)<`position` (x,x_k), where `position`(v,i) function are giving index position of i in $G[v]$ array. In this way without restriction, we will simplify computer program.

3.2 Details

`position`(N,v,α) This function give position of a vertex v in a neighborhood N with an offset α modulo $|N|$.

Example: In algorithm 4, Let $x = 1$ and $N(x) = \{2, 3, 4, 5, 6, 7, 8, 9\}$. Possibilities for x_1 are $\{2, 3, \ldots, 6\}$. We are considering different choices :

- Let $x_1 = 6$. Possibilities for x_k are only 9.

- Let $x_1 = 2$. Possibilities for x_k are $\{5, 6, 7\}$.

- Let $x_1 = 3$. Possibilities for x_k are $\{4, 5, 6, 7, 8\}$.

4 Data structure

Actually, we have using a simple matrix G such that for all vertex x we have defining neighborhood in clockwise order see following algorithm.

Algorithm 5

TITLE: Load initial graph in Data structure
INPUT: $MPG5_{14}$
OUTPUT: G Data structure
(0)   **For** *(i = 1 ; i ≤ 14 ; i + +)* **do**
(1)   **For** *(j = 1 ; i ≤ dg(i) ; j + +)* **do**
(2)   *G[i][j]= j th neighbor of vertex i in clockwise order*
(3)   **End For***;*
(4)   **End For**

5 Checking

In order to verifying plan orientation either each step during 14 and n or only on the final stage, we have programmed an orientation checking, here we are detailing this checking.

Let x a vertex, and x_i, x_{i+1} two consecutive neighbors of x in clockwise order. Algorithm 6 will check :

- there exists x_{i+1}, x two consecutive neighbors of x_i in clockwise order.

- there exists x, x_i two consecutive neighbors of x_{i+1} in clockwise order.

This will be check for all vertex x and all two consecutive neighbors of x.

Algorithm 6

TITLE: Plan orientation checking
INPUT: $MPG5$ data structure with $n > 14$ vertices
OUTPUT: boolean
(0)   **For** *(x = 1 ; x ≤ n ; x + +)* **do**
(1)   **For** *(i = 1 ; i < dg(x) ; i + +)* **do**
(2) $x_i = G[x][i]$ *;*$x_{i+1} = G[x][i + 1]$
(3)   **check***() = looking for x_{i+1}, x around x_i*
(4)   **check***(x_{i+1}) = looking for x, x_i around x_{i+1}*
(5)   **If** *(***check***(x_i)==TRUE)* ***AND*** *(***check***(x_{i+1})==TRUE))* ***THEN*** *continue*
(6)   **Else** *print "Wrong Orientation around (x,x_i,x_{i+1})"; Exit*
(7)   **End For***;*
(8)   **End For**