ROS Melodic Installation

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1. Update the Ubuntu 18.04

1. Ctrl + Alt + t -----> Open the Terminal

@ the Terminal

1. $ sudo apt update

                        let's have a cup of tea

2. $ sudo apt upgrade

                        let's have a cup of tea

2. Install some packages that needed by ROS

@the same Terminal

1. $ sudo apt install curl gnupg2 lsb-release git meld build-essential libfontconfig1 mesa-common-dev libglu1-mesa-dev

2. $ cd

3. Add ROS's packages source into Ubuntu

1. $ sudo sh -c 'echo "deb http://packages.ros.org/ros/ubuntu $(lsb_release -sc) main" > /etc/apt/sources.list.d/ros-latest.list'

2. $ sudo apt-key adv --keyserver 'hkp://keyserver.ubuntu.com:80' --recv-key C1CF6E31E6BADE8868B172B4F42ED6FBAB17C654

3. $ sudo apt update -y

Add ROS2's packages source into Ubuntu

1. $ sudo locale-gen en_US en_US.UTF-8
2. $ sudo update-locale LC_ALL=en_US.UTF-8 LANG=en_US.UTF-8
3. $ export LANG=en_US.UTF-8
4. curl -s https://raw.githubusercontent.com/ros/rosdistro/master/ros.asc | sudo apt-key add -
5. $ sudo sh -c 'echo "deb [arch=amd64,arm64] http://package.ros.org/ros2ubuntu `lsb_release -cs` main" > /etc/apt/sources.list.d/ros2.latest.list'
6. $ sudo apt update -y

4. ROS Melodic Install

1. $ sudo apt install ros-melodic-desktop-full
2. $ sudo apt install python-wstool python-catkin-tools
3. $ sudo apt install ros-melodic-perception ros-melodic-urdf-tutorial
    ros-melodic-moveit
4. $ sudo apt install ros-melodic-openni-camera
    ros-melodic-openni-launch ros-melodic-openni2-camera
    ros-melodic-openni2-launch
5. sudo apt install pcl-tools

ROS2 (dashing) Install

1. $ sudo apt install ros-dashing-desktop
2. $ sudo apt install python3-colcon-common-extensions python3-argcomplete

5. ROS Dependency Setup

1. $ sudo rosdep init
2. $ rosdep update
3. $ `echo "source /opt/ros/melodic/setup.bash" >> ~/.bashrc`
4. `source ~/.bashrc`

WIFI : Turtlebot5
Turtlebot2.4
Password : BURLBURL