Trees, Subtrees and Isomorphism: A Revisit

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Graph isomorphism : two graphs (V_1,E_1) and (V_2,E_2) , are called isomorphic, if there exists a bijection $\phi:V_1\to V_2$, such that, for every vertex pair $u,v\in V_1,\ uv\in E_1$ iff $\phi(u)\phi(v)\in E_2$.

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Subtree: a subtree of an unrooted tree T is either T itself, or one of the two components obtained by removing any edge of T.

A subtree rooted at u of a rooted tree T, is the rooted tree containing u all descendants of u.



Generalized subtree (g-subtree) A generalized subtree of unrooted tree T is a connected subgraph of T.

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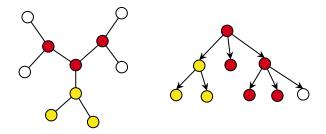


Figure: The yellow part is a subtree of the whole graph; the red part is a g-subtree of the whole tree.



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Figure: Canonicalization of trees via sorting.

We can also use tree hashing to avoid sorting.



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Theorem

We can solve the unrooted tree isomorphism problem based on rooted tree isomorphism algorithm in the same asymptotic time.

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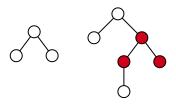
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The centroids of a tree can be found in linear time by dynamic programming or running BFS twice.



Given rooted trees S and T, decide if there exists a **g-subtree** of T isomorphic to S.



There might be exponentially many g-subtrees in a given tree!

Solution (dynamic programming)

We may use dynamic programming to solve this problem. Let for $u \in S, v \in T$, define M[u,v]=1 if S_u is isomorphic to some g-subtree of T rooted at v; otherwise M[u,v]=0. M[u,v] can be computed from M[x,y] where $x \in C(u), y \in C(v)$.

We may define a bipartite graph $C(u) \cup C(v)$ where $x \in C(u)$ and $y \in C(v)$ are connected by an edge if M[x,y]=1. Note that M[u,v]=1 if and only if the bipartite graph has a C(u)-perfect matching.

Algorithm 1 Rooted Subtree Isomorphism

```
Input: two rooted trees S and T

Output: decide if S is isomorphic to some g-subtree of T

1: initialize M[\cdot,\cdot] with 0

2: for vertex v in post-order traversal of T do

3: for each vertex u is S do

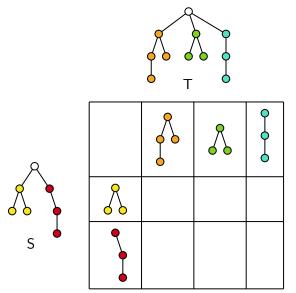
4: build bipartite graph G = (C(u) \cup C(v), M[C(u), C(v)])

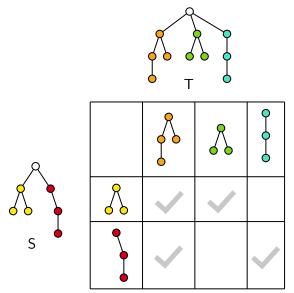
5: set M[u,v] = 1 is G has a C(u)-perfect matching

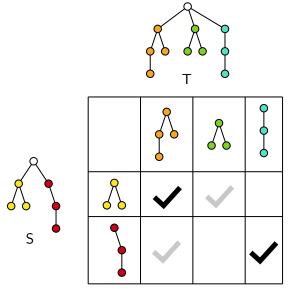
6: end for

7: end for

8: return true if M[root(S), v] = 1 for some v \in T
```







Assume we use Hopcroft-Karp algorithm (or, equivalently, Dinic's maximum flow) to find a maximum matching in $O(E\sqrt{V})$ time. The total time complexity is

$$time = \sum_{u \in S} \sum_{v \in T} time(u, v)$$

$$= \sum_{u \in S} \sum_{v \in T} \deg(u) \deg(v) \sqrt{\deg(u) + \deg(v)}$$

$$\leq \sum_{u \in S} \sum_{v \in T} \deg(u) \deg(v) \sqrt{n_s + n_t}$$

$$\leq n_s n_t \sqrt{n_s + n_t}$$

$$= O(n_s n_t^{3/2})$$

About Maximum Bipartite Matching

Algorithm 2 Hopcroft-Karp Algorithm, $O(E\sqrt{V})$

Input: a bipartite graph $U \cup V$

Output: a maximum matching ${\mathscr M}$

- 1: set $\mathscr{M} = \varnothing$
- 2: while there exists augmenting path do
- 3: let A be a **maximal** set of vertex-disjoint shortest augmenting paths
- 4: set $\mathcal{M} = \mathcal{M} \oplus A$
- 5: end while
- 6: **return** \mathcal{M}

About Maximum Bipartite Matching

Lemma

The length of shortest augmenting path strictly increases after each iteration of Hopcroft-Karp algorithm.

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- Each iteration of Hopcroft-Karp can be done in O(E);
- After the first \sqrt{V} iterations the length of shortest augmenting path is at least \sqrt{V} ;
- Now the symmetric difference of the current matching and the maximum matching is the disjoint union of several augmenting paths and alternating cycles; Since each augmenting path has length at least \sqrt{V} , there are at most \sqrt{V} augmenting paths;
- Conclusion: Hopcroft-Karp terminates after at most $2\sqrt{V}$ iterations.



What if the trees are unrooted?

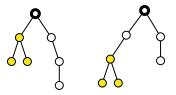
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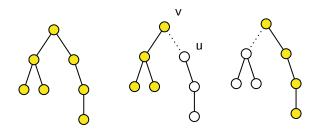
But we can still optimize the algorithm. The basic observation is, there may be common subtrees in different rootings of S.



A natural idea is to use hashmap to dedupliate subtrees. However, this helps little in the worst case (consider a star-like graph).

Note that all subtrees can be found as follows:

Root S at u. The resulting rooted tree S^u itself is a rooted subtree. Also, removing any child subtree of S^u yields a rooted subtree.



We use S[u, v] to denote the subtree rooted at v after removing child subtree u.

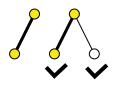
We may compute the maximum bipartite matchings for all these trees together. Formally, let U_i denote U removing the i-th element u_i , we want to compute maximum bipartite matching for $U_i \cup V$ for every i. This results in an unrooted subtree isomorphism algorithm in the same time as the rooted case.

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Note that removing u_i decreases the size of maximum matching by at most 1. In case that u_i is unmatched, or reachable from any unmatched vertex via alternating path, in any maximum bipartite matching of $U \cup V$, the removal of u_i won't decrease the size of maximum matching.

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Algorithm 3 Unooted Subtree Isomorphism

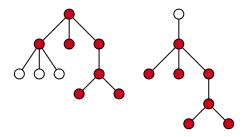
Input: two unrooted trees S and T

Output: decide if S is isomorphic to some g-subtree of T

- 1: root T arbitrarily
- 2: initialize $M[\cdot,\cdot]$ with 0
- 3: **for** vertex v in post-order traversal of T **do**
- 4: **for** each vertex *u* is *S* **do**
- 5: compute the maximum bipartite matchings of $C(S[w,u]) \cup C(v)$ for each $w \in N(u) \cup \{NIL\}$
- 6: end for
- 7: end for
- 8: **return** true if M[S[NIL, u], root(T)] = 1 for some $u \in S$

Maximum Common Subtrees, Rooted

Given two rooted trees S, T, find a maximum size g-subtree of S isomorphic to some g-subtree of T.



Consider the rooted case first.



Maximum Common Subtrees, Rooted

Algorithm 4 Rooted Maximum Common Subtrees

Input: two rooted trees S and T

Output: the size of maximum common g-subtrees of S and T

- 1: **for** vertex v in post-order traversal of T **do**
- 2: **for** each vertex u is S **do**
- 3: build a weighted bipartite graph

$$G = (C(u) \cup C(v), M[C(u), C(v)])$$

- 4: let M[u, v] be the maximum weight matching of G, plus
- 5: end for
- 6: end for
- 7: **return** $\max_{u \in S, v \in T} M[u, v]$

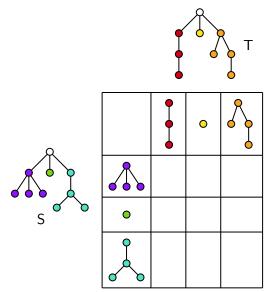


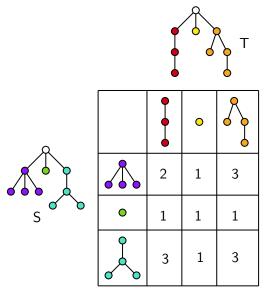
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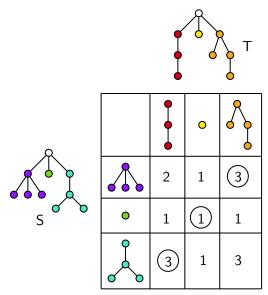
Solution (dynamic programming)

We may again use dynamic programming to solve this problem. Let for $u \in S, v \in T$, define M[u,v] as the size of maximum common subtrees rooted at u and v. The value of M(u,v) can be computed from M[x,y] $(x \in C(u), y \in C(v))$.

We may similarly construct a bipartite graph. The value M[u,v] is computed from maximum weight bipartite matching (instead of maximum cardinality bipartite matching).







By using a careful implementation of Kuhn-Munkres algorithm, the maximum weight bipartite matching of $U \cup V(|U| < |V|)$ can be solved in $O(|U||V|^2)$ time.

Applying an analysis similar to the subtree isomorphism problem, the total time complexity is $O(n^3)$.

What about unrooted case?

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It is easy to obtain an $O(n^4)$ algorithm by trying all possible roots of one tree.

The same technique in subtree isomorphism may apply here to obtain a cubic time algorithm, by not taking maximum weight bipartite matching as black box.

About Maximum Weight Perfect Bipartite Matching

The maximum weight perfect matching can be written as a linear program:

The primal program:

$$\begin{aligned} \max_{\mathsf{x}_{uv}} \quad & \sum_{u,v} w_{uv} \mathsf{x}_{uv} \\ \text{s.t.} \quad & \sum_{u} \mathsf{x}_{uv} = 1 \quad \forall v \\ & \sum_{v} \mathsf{x}_{uv} = 1 \quad \forall u \\ & \mathsf{x}_{uv} \geq 0 \end{aligned}$$

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s.t.
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$$\sum_{v} x_{uv} = 1 \quad \forall u$$

$$x_{uv} \ge 0$$

The dual program:

$$\min_{y_u, y_v} \sum_{u} y_u + \sum_{v} y_v$$
s.t.
$$y_u + y_v \ge w_{uv} \quad \forall u, v$$

About Maximum Weight Perfect Bipartite Matching

Let \bar{x}_{uv} be optimal solution to primal program, \bar{y}_u, \bar{y}_v be optimal solution to dual program.

Theorem (Strong duality theorem)

$$w_{uv}\bar{x}_{uv} = \sum_{u}\bar{y}_{u} + \sum_{v}\bar{y}_{v} \quad \forall u, v$$

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Theorem (Complementary slackness theorem)

$$\sum_{uv} \bar{x}_{uv}(\bar{y}_u + \bar{y}_v - w_{uv}) = 0$$

This means only saturated edges can be in maximum matching.



About Maximum Weight Perfect Bipartite Matching

| | 0 | 4 | 3 | |
|---|---|---|---|---------------|
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| 0 | 0 | 4 | 2 | \rightarrow |
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About Maximum Weight Perfect Bipartite Matching

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Overview

• Three fundamental graph theory problems:

| | Trees | General Graphs |
|--------------------------|-----------------------|-----------------------------------|
| Graph Isomorphism | <i>O</i> (<i>n</i>) | $O(n^{\operatorname{ploylog} n})$ |
| Subgraph Isomorphism | Р | NP-Complete |
| Maximum Common Subgraphs | Р | NP-Hard |

- One problem solving framework: turns the original problem into several instances of matching problem.
- Two auxiliary algorithms:
 - Edmonds-Karp algorithm: solves maximum cardinality bipartite matching in $O(E\sqrt{V})$ time;
 - Kuhn-Munkres algorithm: solves maximum weight bipartite matching in $O(V^3)$ time.

References

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 Annals of Discrete Mathematics, 2, 91-106.
- Shamir, R., & Tsur, D. (1999). Faster subtree isomorphism.
 Journal of Algorithms, 33(2), 267-280.
 (this paper gives a slightly faster subtree isomorphism algorithm, but is of less practical significance)
- Droschinsky, A., Kriege, N. M., & Mutzel, P. Faster algorithms for the maximum common subtree isomorphism problem. 41st International Symposium on Mathematical Foundations of Computer Science (MFCS'16). (this paper describes a cubic algorithm for unrooted maximum common subtrees in detail)