

Summary Image Processing

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1 course goals

- * introduction to the fundamentals of rasterization-based image generation: rasterization is the task of taking an image described in a vector graphics format and converting it into a raster image(pixels or dots) for output on a video display or printer, or for storage in a bitmap file format.
- * functionality of the graphics rendering pipeline: Rendering is the automatic process of generating a photorealistic or non-photorealistic image from a 2D or 3D model by means of computer graph
- * advanced rendering effects
- * introduction to the OpenGL graphics API

2 OpenGL

2.1 Introduction

OpenGL (Open Graphics Library) is a cross-platform API¹ for rendering 2D and 3D vector graphics²...

- * display of geometric representations and attributes
- * independent from operating system and window system

¹Application Programming Interface

²is the use of polygons(are used in Com. Graphics to compose images that are 3-dim in appearance) to represent images in computer graphics

2.2 GPU Data Flow

- * data transfer to GPU: vertices with attributes and connectivity
- * vertex shader³: a program that is executed for each vertex, with input and output is a vertex
- * rasterizer
- * fragment shader: also known pixel shader, a program that is executed for each fragment, with input and output is a fragment. compute color and other attributes of each fragment⁴
- * framebuffer update: is portion of RAM containing a bitmap that drives a video display. It is a memory buffer containing a complete frame of data

3 Rendering

3.1 Rasterization

- * rendering algorithm for generating 2D images from 3D scenes
- * transforming geometric primitives such as lines and polygons into raster image representations, i.e pixels
- * 3D objects are approximately represented by vertices(points), lines, polygons
- * these primitives are processed to obtain a 2D image

3.2 Rendering Pipeline

known also as graphics pipeline is a conceptual model in computer graphics that describe what step a graphics system needs to perform to render a 3D scene to a 2D screen, plainly speaking, the graphics pipeline is the process of turning that 3D model into what the computer displays.

Characteristics of the 3D input:

1. a virtual camera: position, orientation, focal length

³are HW or SW modules, that implement specific rendering

⁴a technical term usually meaning a single pixel

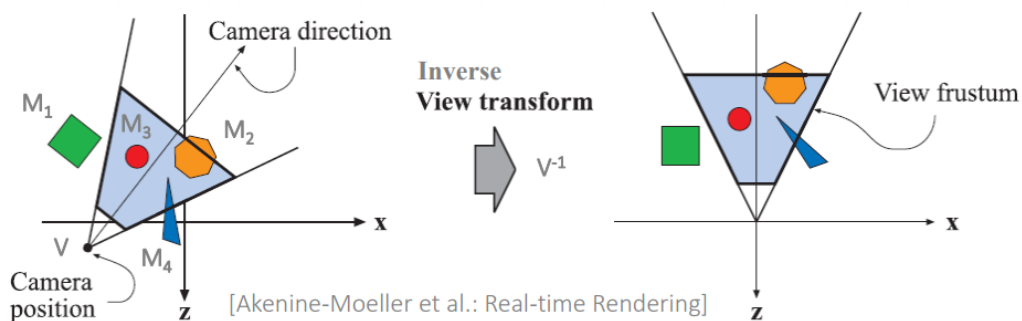
2. objects: points(vertex/vertices), lines, polygons, geometry and material properties
3. light sources: direction, position, color, intensity
4. textures(images)

Characteristics of the 2D output: per-pixel color value in the framebuffer

4 Transformations

- * is used to: position, reshape, and animate objects, lights, and the virtual camera
- * are represented with 4x4 matrices
- * are applied to vertices and normals
- * vertices(position) and normals(directions) are represented with 4D vectors

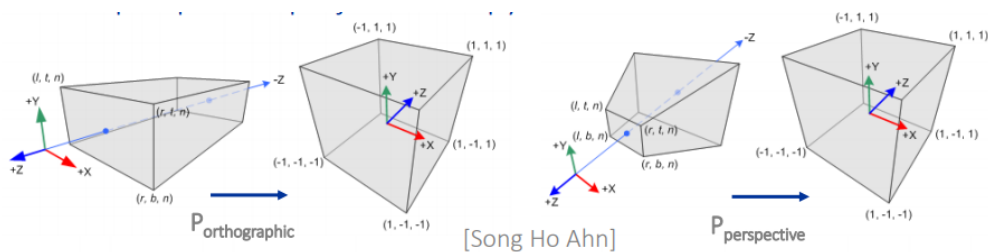
4.1 Modelview Transform



- * $M_{1..4}$ and V are matrices representing transformations
- * $M_{1..4}$ are model transform to place the objects in the scene
- * V places and orientates the camera in space, V^{-1} transforms the camera to the origin looking along the negative z-axis
- * model and view transforms are combined in the modelview transform
- * the modelview transform $V^{-1}M_{1..4}$ is applied to the objects

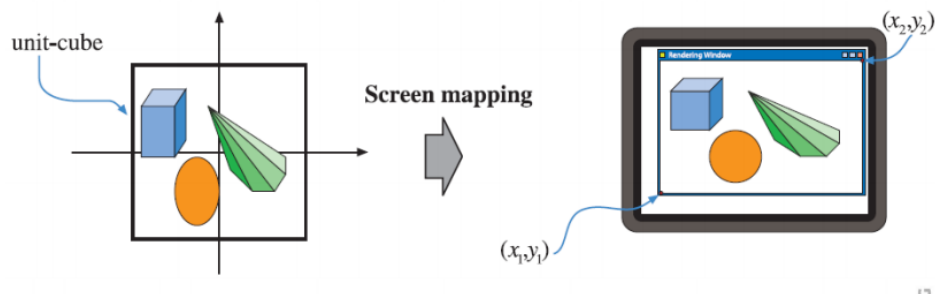
4.2 Projection Transform

- * P transforms the view volume to the canonical view volume
- * the view volume depends on the camera properties :
 1. orthographic projection ==> cuboid
 2. perspective projection ==> pyramidal frustum
- * canonical view volume is a cube from $(-1, -1, -1)$ to $(1, 1, 1)$
- * view volume is specified by near, far, left, right, bottom, top



4.3 Viewport Transform / Screen Mapping

- * projected primitive coordinates (x_p, y_p, z_p) are transformed to screen coordinates (x_s, y_s)
- * screen coordinates together with depth value are window coordinates (x_w, y_w, z_w)



4.4 Vertex Transforms

Vertex is a data structure that describes certain attribute, like the position of a point in 2D or 3D space ...

the vertex transform went through some transformation before achieving the window space, like model trans., inverse view trans., projection trans., and viewport trans.

4.5 Other Transformation

- * congruent transformations (Euclidean transformations)
 - preserve shape and size
 - translation, rotation, reflection
- * similarity transformations
 - preserve shape
 - translation, rotation, reflection, scale

4.6 Affine Transformations

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5 Lighting

5.1 Light

Light is modeled as:

- electromagnetic waves
- photons: are particles characterized by wavelength, which carry energy. They travel along a straight line at the speed of light
- geometric rays

the discipline of optical measurement techniques can be roughly subdivided into the two areas of **photometry** and **radiometry**

5.1.1 Radiometric Quantities

Radiometry deals with the measurement of energy per time also **Power**

- radiant energy Q : photons have some radiant energy
- radiant flux Φ , radiant power P : the rate of flow of radiant energy per unit time is defined as follow: $\Phi = \frac{dQ}{dt}$, for example the overall energy of photons emitted by a source per time
- flux density: is the radiant flux per unit area: $E = \frac{d\Phi}{dA}$, which is the rate at which radiation is incident on, or exiting a flat surface area dA , it describes also the strength of radiation with respect to a surface area with no directional information