

# Summary Image Processing

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## 1 course goals

- \* introduction to the fundamentals of rasterization-based image generation: rasterization is the task of taking an image described in a vector graphics format and converting it into a raster image(pixels or dots) for output on a video display or printer, or for storage in a bitmap file format.
- \* functionality of the graphics rendering pipeline: Rendering is the automatic process of generating a photorealistic or non-photorealistic image from a 2D or 3D model by means of computer graph
- \* advanced rendering effects
- \* introduction to the OpenGL graphics API

## 2 OpenGL

### 2.1 Introduction

OpenGL (Open Graphics Library) is a cross-platform API<sup>1</sup> for rendering 2D and 3D vector graphics<sup>2</sup>...

- \* display of geometric representations and attributes
- \* independent from operating system and window system

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<sup>1</sup>Application Programming Interface

<sup>2</sup>is the use of polygons(are used in Com. Graphics to compose images that are 3-dim in appearance) to represent images in computer graphics

## 2.2 GPU Data Flow

- \* data transfer to GPU: vertices with attributes and connectivity
- \* vertex shader<sup>3</sup>: a program that is executed for each vertex, with input and output is a vertex
- \* rasterizer
- \* fragment shader: also known pixel shader, a program that is executed for each fragment, with input and output is a fragment. compute color and other attributes of each fragment<sup>4</sup>
- \* framebuffer update: is portion of RAM containing a bitmap that drives a video display. It is a memory buffer containing a complete frame of data

## 3 Rendering

### 3.1 Rasterization

- \* rendering algorithm for generating 2D images from 3D scenes
- \* transforming geometric primitives such as lines and polygons into raster image representations, i.e pixels
- \* 3D objects are approximately represented by vertices(points), lines, polygons
- \* these primitives are processed to obtain a 2D image

### 3.2 Rendering Pipeline

known also as graphics pipeline is a conceptual model in computer graphics that describe what step a graphics system needs to perform to render a 3D scene to a 2D screen, plainly speaking, the graphics pipeline is the process of turning that 3D model into what the computer displays.

Characteristics of the 3D input:

1. a virtual camera: position, orientation, focal length

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<sup>3</sup>are HW or SW modules, that implement specific rendering

<sup>4</sup>a technical term usually meaning a single pixel

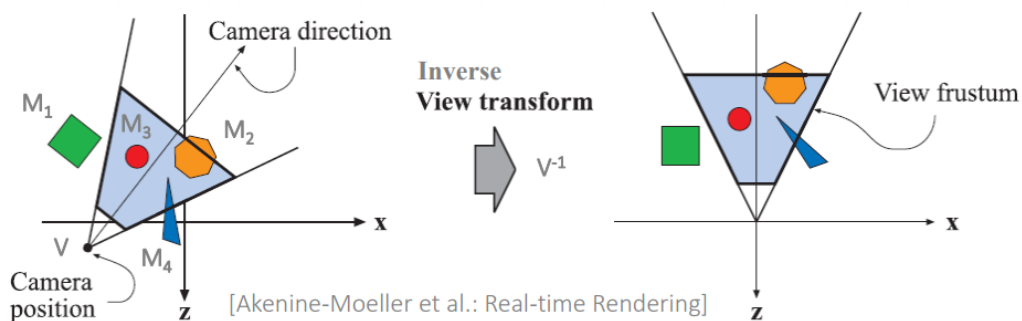
2. objects: points(vertex/vertices), lines, polygons, geometry and material properties
3. light sources: direction, position, color, intensity
4. textures(images)

Characteristics of the 2D output: per-pixel color value in the framebuffer

## 4 Transformations

- \* is used to: position, reshape, and animate objects, lights, and the virtual camera
- \* are represented with 4x4 matrices
- \* are applied to vertices and normals
- \* vertices(position) and normals(directions) are represented with 4D vectors

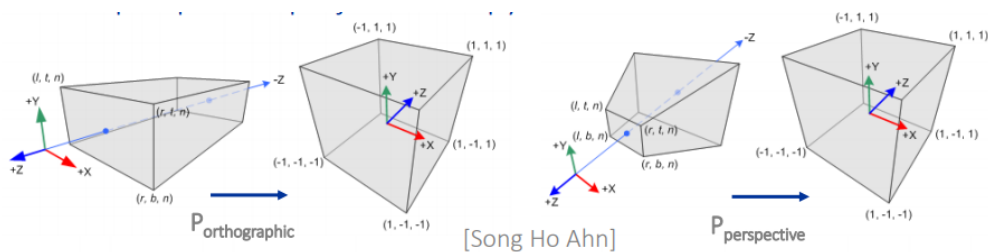
### 4.1 Modelview Transform



- \*  $M_{1..4}$  and  $V$  are matrices representing transformations
- \*  $M_{1..4}$  are model transform to place the objects in the scene
- \*  $V$  places and orientates the camera in space,  $V^{-1}$  transforms the camera to the origin looking along the negative z-axis
- \* model and view transforms are combined in the modelview transform
- \* the modelview transform  $V^{-1}M_{1..4}$  is applied to the objects

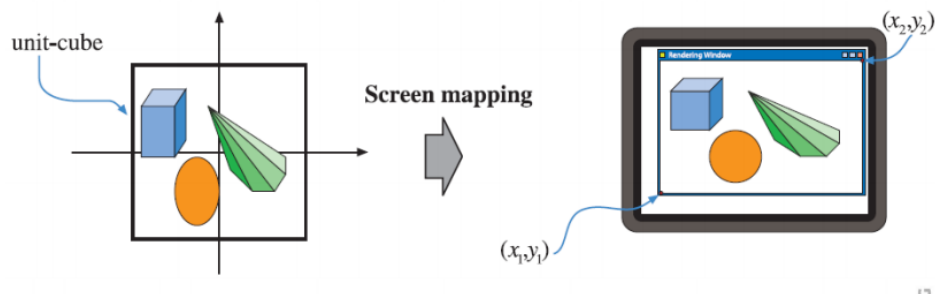
## 4.2 Projection Transform

- \* P transforms the view volume to the canonical view volume
- \* the view volume depends on the camera properties :
  1. orthographic projection ==> cuboid
  2. perspective projection ==> pyramidal frustum
- \* canonical view volume is a cube from  $(-1, -1, -1)$  to  $(1, 1, 1)$
- \* view volume is specified by near, far, left, right, bottom, top



## 4.3 Viewport Transform / Screen Mapping

- \* projected primitive coordinates  $(x_p, y_p, z_p)$  are transformed to screen coordinates  $(x_s, y_s)$
- \* screen coordinates together with depth value are window coordinates  $(x_w, y_w, z_w)$



## 4.4 Vertex Transforms

Vertex is a data structure that describes certain attribute, like the position of a point in 2D or 3D space ...

the vertex transform went through some transformation before achieving the window space, like model trans., inverse view trans., projection trans., and viewport trans.

## 4.5 Other Transformation

- \* congruent transformations (Euclidean transformations)
  - preserve shape and size
  - translation, rotation, reflection
- \* similarity transformations
  - preserve shape
  - translation, rotation, reflection, scale

## 4.6 Affine Transformations

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