

Alignment::MoveAngleAllSafe

Alignment::MoveDistanceAllSafe

Alignment::checkLimitDownXYZ

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graph LR; A[Alignment::MoveAngleAllSafe] --> C[Alignment::checkLimitDownXYZ]; B[Alignment::MoveDistanceAllSafe] --> C;
```

The diagram illustrates a control flow or dependency. Two source functions, 'Alignment::MoveAngleAllSafe' and 'Alignment::MoveDistanceAllSafe', are shown on the left. Both have arrows pointing to a single target function, 'Alignment::checkLimitDownXYZ', which is highlighted with a gray background. This suggests that both movement functions eventually lead to a common limit-checking step.