

getMotorSpeedCmd::execute

setMotorSpeedCmd::execute

a4988::getSpeed

```
graph LR; A[getMotorSpeedCmd::execute] --> C[a4988::getSpeed]; B[setMotorSpeedCmd::execute] --> C;
```

The diagram illustrates a call graph where two methods, `getMotorSpeedCmd::execute` and `setMotorSpeedCmd::execute`, both point to the `a4988::getSpeed` method. The source methods are in white boxes, and the target method is in a grey box. Blue arrows indicate the direction of the calls.