

getMotorDelayCmd::execute

setMotorDelayCmd::execute

a4988::getDelay

```
graph LR; A[getMotorDelayCmd::execute] --> C[a4988::getDelay]; B[setMotorDelayCmd::execute] --> C;
```

The diagram illustrates a call graph where two methods, `getMotorDelayCmd::execute` and `setMotorDelayCmd::execute`, both call the `a4988::getDelay` method. The source methods are in white boxes, and the target method is in a gray box. Blue arrows indicate the direction of the calls.