1.1. Eack Propagation Agriffing:

(a) Tanh activation function 
$$tanh(n) = \frac{e^n - e^{-n}}{e^n + e^{-n}}$$

Ealw:  $\frac{1}{2} \leq (t_k - 0_k)^2$ 
 $\frac{\partial \mathcal{E} \mathcal{J}}{\partial v_{ji}} = \frac{\partial \mathcal{E} \mathcal{J}}{\partial v_{ji}} \times \frac{\partial \mathcal{E} \mathcal{J}}{$ 

1.2 output 
$$0 = W_0 + W_1(n_1 + n_1^2) + \dots + W_n(n_1 + n_1^2)$$

Activation function  $f(x) : \pi$ 

Learning rate  $\eta$ 

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$$\frac{\partial Ed}{\partial W_1^2} = \frac{\partial Ed}{\partial n_1 e^2} \frac{\partial n_2 e^2}{\partial W_1^2} = \frac{\partial Ed}{\partial n_1 e^2} \frac{\partial Ed}{\partial W_1^2} = \frac{\partial Ed}{\partial w_1^2} \frac{\partial Ed}{\partial w_1^2} = \frac{\partial Ed}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} = \frac{\partial Ed}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} = \frac{\partial Ed}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} = \frac{\partial Ed}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} = \frac{\partial Ed}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} \frac{\partial G}{\partial w_1^2} = \frac{\partial Ed}{\partial w_1^2} \frac{\partial G}{\partial w_1^2$$

1.3 Activation function f(n) = x for input layer & O(p) layer h(n) for hidden layer & O(p) layer

(b) Verbor notation 
$$X = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$
  $w^{(1)} : \begin{pmatrix} w_{31} & w_{32} \\ w_{41} & w_{42} \end{pmatrix}$ 

$$w^{(2)} : \begin{pmatrix} w_{53} & w_{54} \end{pmatrix}$$

$$olp of hidden larger = h(X · W^{(1)})$$

$$olp of 5, y_5 = h(W^{(2)} · h(X · W^{(1)}))$$

1.3 ( ) 
$$h_s(n) = \frac{1}{1+e^{-x}}$$
.  $h_t(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$   
 $h_t(n) = \frac{1}{1+e^{-x}}$   $\frac{1-e^{-2x}}{1+e^{-2x}} = \frac{2-1-e^{-2x}}{1+e^{-2x}}$   
 $= \frac{2}{1+e^{-2x}} - \frac{1+e^{-2x}}{1+e^{-2x}}$   
 $= \frac{2}{1+e^{-2x}} - 1$ 

This proves outputs of activation functions ho (n) and hy (n) differ by linear and constants.

4. [D. 
$$t(W)$$
:  $\frac{1}{2} \sum \sum (t_{kl} - o_{kd})^2 + \sum w_{ji}^2$ 
 $W = W + \Delta W$ ,  $\Delta W = -M \frac{\delta C}{\delta N_i}$ 
 $\frac{\delta E}{\delta W_i} = \frac{\delta E}{\delta W_i t_j} \times \frac{\delta net_j}{\delta W_i}$ 
 $\frac{\delta net_i}{\delta W_i} = \frac{1}{\delta W_i} (W_i N_i) = M_{ji}$ 
 $\frac{\delta E}{\delta N_i t_j} = \frac{1}{\delta W_i} \left[ \frac{1}{2} \sum \sum (t_{kd} - o_{kd})^2 + \frac{N \sum w_{ji}^2}{\delta W_i}^2 \right]$ 
 $= -(t_{kd} - o_{kd}) + \frac{N \sum w_{ji}^2}{\delta W_i}$ 
 $\frac{\delta}{\delta W} \left[ \frac{1}{2} \sum (t_{kd} - o_{kd})^2 \right] + \frac{\delta}{\delta W_i} (N \sum w_{ji}^2)$ 
 $= -(t_{kd} - o_{kd}) + \frac{N}{\delta W_i} + \frac{N}{\delta W_i}$ 
 $\Delta W = + M \left[ t_{kd} - o_{kd} \right] + \frac{N}{\delta W_i}$ 

Constant multiplied to meight before weight update

Scanned with CamScanner

This

and