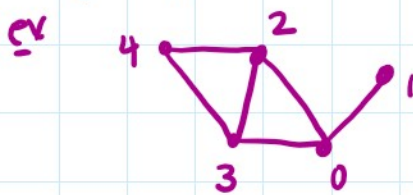


Graphs, Continued① Notation: Typically: $V = \# \text{ vertices}$  (sometimes  $n$  instead) $E = \# \text{ edges}$ ② Walks, etc

(a) defn: A **walk** is a route (intuitive sense) from a starting vertex to ending vertex (may = starting vertex) following edges. May repeat either edges or vertices.

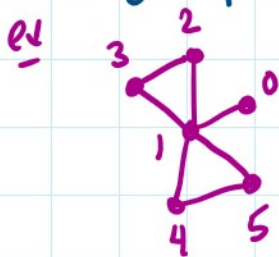


an example of a walk is:

0, 1, 0, 3, 2, 3, 4

listed as a sequence of vertices.

(b) defn: A **trail** is a walk w/ no repeated edges. Still may repeat vertices.



an ex. of a trail:

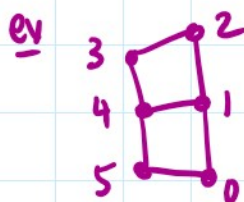
0, 1, 2, 3, 1, 5

repeats vertex 1 but no edges.

not a trail:

0, 1, 2, 3, 1, 2

(c) defn: A **path** is a walk w/ no repeated vertices (hence we cannot have repeated edges either)



an ex. of a path:

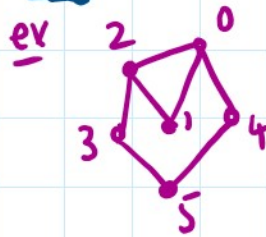
1, 4, 3, 2

not a path:

1, 4, 5, 0, 1, 2

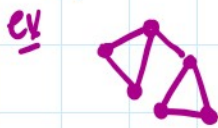
(d) defn: A **cycle** is a trail w/ no repeated vertices

(1) defn: A **cycle** is a trail w/ no repeated vertices except the starting vertex = ending vertex.



some cycles: 0,1,2,0  
0,1,2,3,5,4,0

(E) defn: A graph is **connected** if, for any two vertices,  $\exists$  path b/w them.

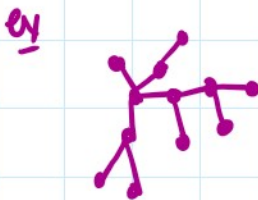


Connected

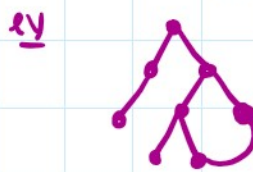


not Connected

(F) defn: A **tree** is a simple connected graph w/ no cycles.



tree



not a tree!

### (3) Graph Storage

(A) There are several ways to store a graph. Here are two.  
Assume simple, unweighted, undirected (for now).

(B) Adjacency Matrix:

Sps we have  $V$  vertices labeled  $0, 1, \dots, V-1$

Create a 0-indexed  $V \times V$  matrix  $AM$  s.t.

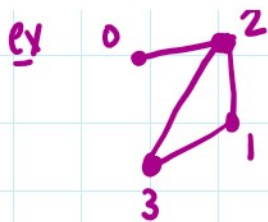
$$AM[i][j] = \begin{cases} 1 & \text{if } \exists \text{ edge b/w vertices } i \text{ and } j \\ 0 & \text{otherwise} \end{cases}$$



$$AM = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$AM[0][2] = 1$  b/c  $\exists$  edge b/w 0, 2





$$AM = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

note: Can be wasteful if  $V \gg E$  then AM has lots of 0s.

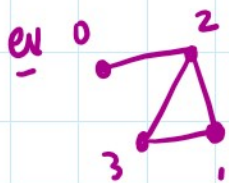
### (c) Adjacency list (of lists)

Sps we have  $V$  vertices labeled  $0, 1, \dots, V-1$ .

Create a list (of lists) AL s.t.

AL has  $V$  entries, each is a list.

AL[i] = list of vertices that  $i$  is adj. to.



$$AL = \left[ [2], [2, 3], [0, 1, 3], [1, 2] \right]$$

note not wasteful.

also if @ a vertex we have immediate access to adjacent vertices.

### (d) Pseudocode to demonstrate

(For a graph  $G$  we'll do:)

for each vertex  $x$  in  $G$ :

constant time 1

for each vertex  $w$  adj to  $x$ :

constant time 2

end for

end for

- if we have adj matrix then outer for loop runs  $V$  times and the inner one runs  $V$  times b/c for each  $x$  we have to scan  $x$ 's row in AM to look for 1s and that's  $V$  steps.  $\Theta(V^2)$ .


and that's  $V$  steps.  $\Theta(V^2)$ .

- if we have an adj list, the outer loop still  $V$  times.

But the inner loop is not  $V$  times b/c it dep. on  $x$ .

Sneaky:

- ignore inner loop we take  $\Theta(V)$  time (constant time 1)

- for each edge  the inner loop runs twice, once when  $x=a$  and once when  $x=b$ .

so the inner loop takes time  $\Theta(2E)$  over the entire run!

Thus the time is  $\Theta(V+2E)$ .