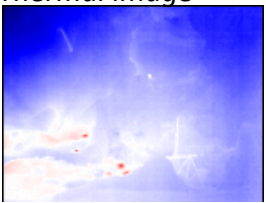


*Inputs:*

*Thermal image*



+

*LiDAR mesh*



*DMCP*



*Output:*

*Camera pose in mesh*

