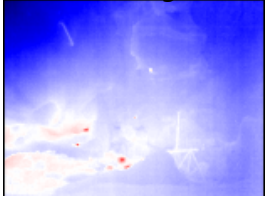


*Inputs:*  
*Thermal image*



+

*LiDAR mesh*



*DMCP*  
→

*Output:*  
*Camera pose in mesh*

