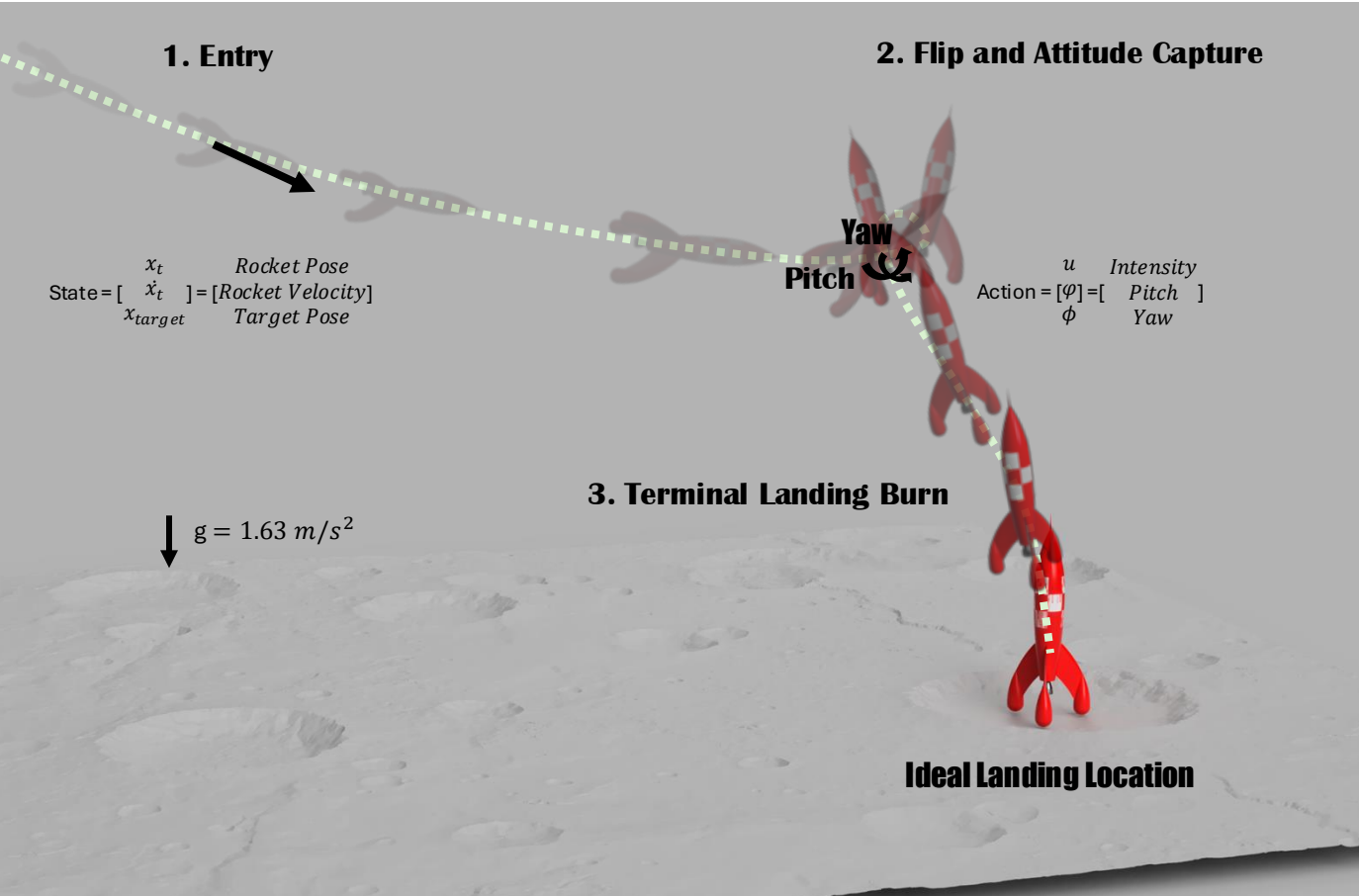
1. Entry
2. Flip and Attitude Capture
Yaw
Pitch
State = [x_t ; $\dot{x}_t$; x_{target}] = [Rocket Pose ; Rocket Velocity ; Target Pose]
Action = [φ] = [u Intensity ; Pitch ; ϕ Yaw]
3. Terminal Landing Burn
g = 1.63 m/s^2
Ideal Landing Location