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Example.

$$\begin{aligned}(2x \sin y \cos y)y' &= 4x^2 + \sin^2 y \\ v = \sin y &\implies \\ \frac{dv}{dx} &= \cos y \frac{dy}{dx}\end{aligned}$$

Thus,

$$2xvv' = 4x^2 + v^2 \text{ (hom)}, w = v/x$$

1 population models

Recall that the most basic population model, assuming constant birth and death rates, is

$$P' = kP \text{ (separable)}$$

Now, we give birth rates and death rates the following units:

$$\begin{aligned}\beta(t) &= \text{birth rate} \frac{\# \text{ of births at } t}{(\text{unit of population at } t)(\text{unit of time})} \\ \delta(t) &= \text{death rate} \frac{\# \text{ of death at } t}{(\text{unit of population at } t)(\text{unit of time})}\end{aligned}$$

with this, for some small Δt ,

$$\begin{aligned}P(t + \Delta t) &\approx P(t) + (\# \text{ birth rate at } t - \# \text{ death rate at } t) \Delta t \implies \\ &= P(t) + \beta(t)P(t)\Delta t - \delta(t)P(t)\Delta t \\ \implies \frac{\Delta P}{\Delta t} &= \frac{P(t + \Delta t) - P(t)}{\Delta t} \approx (\beta(t) - \delta(t))P(t)\end{aligned}$$

using a diff model, the above suggest that

$$\boxed{P' = (\beta - \delta)P}$$

This is called the general population

Now, consider population with constant death rate, say δ_0 , and with a birth rate given by

$$\beta = \beta_1 - \beta_0 P$$

In context, $\beta_0, \beta_1 > 0$ by (1),

$$\begin{aligned}P' &= (\beta_1 - \beta_0 P - \delta_0)P \\ &= (\beta_1 - \delta_0)P - \beta_0 P^2 \\ &= \beta_0 P \left(\frac{\beta_1 - \delta_0}{\beta_0} - P \right)\end{aligned}$$

which has form

$$P' = kP(M - P)$$

$k = \beta_0 > 0$ and $M = (\beta_1 - \delta_0)/\beta_0$ we see that in context, $M > 0$ here (2) is separable; as

$$\begin{aligned} \frac{P'}{P(M - P)} = k &\implies \\ \int \frac{1}{P(M - P)} dP &= kt + C \end{aligned}$$

Note that

$$\frac{1}{P(M - P)} = \frac{1}{M} \left(\frac{1}{M - P} + \frac{1}{P} \right)$$

Thus,

$$\begin{aligned} \frac{1}{M} (-\ln |M - P| + \ln |P|) &= kt + C \implies \\ \ln \left| \frac{P}{M - P} \right| &= Mkt + C \end{aligned}$$

Now, $P_0 = P(0)$ yields

$$C = \ln \left| \frac{P_0}{M - P_0} \right|$$

Thus,

$$\ln \left| \frac{P}{M - P} \right| = \ln \left| \frac{P_0}{M - P_0} \right| + Mkt$$

Hence, if $P > M$ or $P_0 > M$ then

$$\begin{aligned} \frac{P}{M - P} = \frac{P_0}{M - P_0} e^{Mkt} &\implies \frac{M}{P} - 1 = \frac{M - P_0}{P_0} e^{-Mkt} \\ \implies \frac{M}{P} &= \frac{P_0 + (M - P_0)e^{-Mkt}}{P_0} \end{aligned}$$

$$\boxed{P(t) = \frac{MP_0}{P_0 + (M - P_0)e^{-Mkt}}}$$

Notice that

$$\lim_{t \rightarrow \infty} P(t) = \frac{MP_0}{P_0} = M$$

If $P < M$, so that $P_0 < M$, then

$$P' = kP(M - P) > 0$$

so, P is increasing to M

On the other hand, if $P > M$, so that $P_0 > M$, then

$$P' = kP(M - P) < 0$$

so, P is decreasing to M
 Since $P(t) \rightarrow M$ in
 either case, in context,
 $M > 0, (M = 0 \ \& \ P > M \implies \textit{extinction})$.

Recall: logistics population model

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$$P(t) = \frac{MP_0}{P_0 + (M - P_0)e^{-Mkt}}$$

Example. Page 88 Problem # 22

$M = 100 \times 10^3$ total population At $t = 0$, half the population have heard a rumor, roughly the rumors increases by 1000 people after 1 day

$$P_0 = 50 \times 10^3 \text{ \& } P(1) = 51 \times 10^3$$

we can solve for k

$$\begin{aligned} 51 \times 10^3 &= \frac{(100 \times 10^3)(50 \times 10^3)}{50 \times 10^3 + (100 \times 10^3 - 50 \times 10^3)e^{-Mk}} \\ \implies 51 &= \frac{5000}{50 + 50e^{-Mk}} = \frac{100}{1 + e^{-Mk}} \\ \implies \frac{51}{100} &= \frac{1}{1 + e^{-Mk}} \implies \\ 1 + e^{-Mk} &= \frac{100}{51} \implies e^{-Mk} = \frac{100}{51} - 1 \implies \\ -Mk &= \ln\left(\frac{100}{51} - 1\right) \\ \implies k &= -\frac{\ln\left(\frac{100}{51} - 1\right)}{10 \times 10^3} > 0 \end{aligned}$$

Therefore we can now solve $P(t) = 80 \times 10^3$
for t.

2 Doomsday/Extinction Model:

Here we assume that

$$\beta = kP, \quad k > 0$$

$$\text{\& } \delta = \delta_0$$

Thus, the gen pop ODE, $P' = (\beta - \delta)P$, becomes

$$P' = (kP - \delta_0)P = kP(P - \delta/k) \quad (1)$$

put $M = \delta/k > 0$, (1) becomes

$$P' = kP(P - M) \quad (2)$$

constant (2) with the logistics

ODE: $P' = kP(M - P)$ we can solve (2); it is separable. Thus,

$$\frac{P'}{P(P - M)} = k \implies$$

$$\int \frac{1}{P(P-M)} dP = kt + C$$

Note:

$$\frac{1}{P(P-M)} = \frac{1}{M} \left(\frac{1}{P-M} - \frac{1}{P} \right)$$

Therefore

$$\begin{aligned} \frac{1}{M} (\ln |P-M| - \ln P) &= kt + C \\ \implies \ln \left| \frac{P-M}{P} \right| &= Mkt + C \\ \implies \frac{|P-M|}{P} &= e^{Mkt+C} \end{aligned}$$

If $P_0 = P(0)$ then

$$C = \ln \left| \frac{P_0 - M}{P_0} \right|$$

so,

$$\frac{P-M}{P} = \frac{P_0-M}{P_0} e^{Mkt}$$

Now, in any case

$$\begin{aligned} \frac{P-M}{P} &= \frac{P_0-M}{P_0} e^{Mkt} \implies \\ 1 - \frac{M}{P} &= \frac{P_0-M}{P_0} e^{Mkt} \implies \\ \frac{M}{P} &= \frac{P_0 - (P_0-M)e^{Mkt}}{P_0} \implies \\ \boxed{P} &= \frac{MP_0}{P_0 + (M-P_0)e^{Mkt}} \end{aligned}$$

contrast with logistic ODE soln:

$$P = \frac{P_0 M}{P_0 + (M-P_0)e^{-Mkt}}$$

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With explosion/extinction model

Notice that

$$P > M \implies P' > 0 \implies P \text{ is increasing;}$$

$$P < M \implies P' < 0 \implies P \text{ is decreasing;}$$

Now, if $P > 0$, then P has a vertical asymptote at t_0 such that.

$$P_0 + (M - P_0)e^{Mkt_0} = 0 \implies$$

$$e^{Mkt_0} = \frac{P_0}{P_0 - M} > 0 \implies$$

$$Mkt_0 = \ln \frac{P_0}{P_0 - M}$$

$$\boxed{t_0 = \frac{1}{Mk} \ln \left(\frac{P_0}{P_0 - M} \right)}$$

which is the time of "doomsday," i.e., the explosion of the population

$$\lim_{t \rightarrow t_0^-} P(t) = \infty$$

On the other hand, if $P < M$, then $M - P_0 > 0$; the

$$\lim_{t \rightarrow \infty} P(t) = 0$$

j This is to say, over time, extinction occurs.

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equilibuim solns and stability

Def. An autonomous ODE has the form

$$\frac{dx}{dt} = f(x) \quad (1)$$

Notice that the slope field in (1) is "independent" of t.

Newtons law of cooling

$$T' = k(A - T), \quad k > 0$$

Recall:

$$\begin{aligned} \int \frac{1}{A - T} dt &= \int k dt = kt + C \implies \\ -\ln |A - T| &= kt + C \implies \\ |A - T| &= e^{-kt - C} \end{aligned}$$

where $T_0 = T(0) \implies$

$$-C = \ln |A - T_0|$$

thus,

$$\begin{aligned} |A - T| &= |A - T_0| e^{-kt} \implies \\ A - T &= (A - T_0) e^{-kt} \implies \\ \boxed{T(t) &= A + (T_0 - A) e^{-kt}} \end{aligned}$$

Notice that

$$\lim_{t \rightarrow \infty} T(t) = A$$

Also, notice that $T(t) \equiv A$, i.e, $T(t) = A$ for all t, in a soln to the autonomous ODE $T' = k(A - T)$. this is an example of an "equilibruim soln"

Definition. $x(t) \equiv C \in \mathbb{R}$ is an equilibrium soln to $x' = f(x)$ iff $x(t) \equiv C$ is a soln to $x' = f(x)$

Definition. $x = C \in \mathbb{R}$ is a critical point of $x' = f(x)$ iff $f(C) = 0$

Notice that we say that "x is a critical point" iff $0 = f(C) = \frac{dx}{dt}$, which is similar to use in calc I of "critical pt."

Prop. $x = C$ is a critixcal pt
of $x' = f(x) \iff x(t) \equiv C$
is an equilibrium soln to $x' = f(x)$

proof. easy.

Def. $C \in \mathbb{R}$ is a stable critical point of $x' = f(x)$ iff C is a critical pt of $x' = f(x)$ and

$$\forall \epsilon > 0 \exists \delta > 0 \forall \\ |x_0 - C| < \delta \implies |x(t) - C| < \epsilon$$

Ex (Logistics Modle)

$$P' = kP(M - P) \implies \\ P(t) = \frac{MP_0}{p_0 + (M - P)e^{-Mkt}} \implies \\ \lim_{t \rightarrow \infty} P(t) = M$$

Ex(Standard pop Model)

$$P' = kP \implies P(t) = P_0 e^{kt}$$

Here $P = 0$ is a critical pt; however, $P = 0$ is not stable. Notice that $P' = kP(M - P)$ has two critical pts, namely, $P = 0$ and $P = M$. Here $P(t) = M$ is stable, whereas, $P(t) \equiv 0$ is not stable.

Ex(explosion/ extinction model)

$$P' = kP(P - M), k, M > 0 \\ \implies P(t) = \frac{MP_0}{P_0 + (M - P_0)e^{Mkt}}$$

Both $P = 0$ and $P = M$ are critical pts. however, if $P_0 > M$ then ? a stable, whereas if $P_0 < M$ then only $P = 0$ is stable.

$$|x_0 - C| < \delta \implies \\ (x(t) - C) < \epsilon$$

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3 Logistics Population Model with Harvesting

Recall the Logistics Pop Model:

$$P' = kP(M - P), \quad k, M > 0$$

We now consider

$$P' = kP(M - P) - h$$

where h is a constant, think: $h > 0 \implies$ harvesting;

$$h < 0 \implies \text{stocking}$$

Notice that

$$\begin{aligned} P' &= -kP^2 + kMP - h \\ &= -k(P^2 - MP + h/k) \\ &= -k(P - H)(P - N) \end{aligned}$$

where

$$H, N = \frac{M \pm \sqrt{M^2 - 4h/k}}{2}$$

Here H and N are distinct reals if and only if $M^2 - 4h/k > 0 \iff M^2 > 4h/k \iff h < kM^2/4$. so, if $h > 0$ and H, N are distinct and real, then

$$0 < h < \frac{kM^2}{4}$$

Say, $H < N$. Notice that

$$\begin{aligned} h > 0 &\implies \\ \sqrt{M^2 - 4h/k} &< \sqrt{M^2} \implies \\ M - \sqrt{M^2 - 4h/k} &> 0 \\ \therefore 0 < H &; \text{ where, } 0 < H < N \end{aligned}$$

Now, "separating," yields that

$$\begin{aligned} \frac{P'}{(P - H)(P - N)} &= -k \implies \\ \int \frac{1}{(P - H)(P - N)} dP &= -kt + C \end{aligned}$$

Notice that

$$\frac{1}{(P - H)(P - N)} = \left(\frac{1}{P - N} - \frac{1}{P - H} \right) \frac{1}{N - H}$$

Thus,

$$\ln \left| \frac{P - N}{P - H} \right| = -(N - H)kt + C$$

If $P_0 = P(0)$ then

$$C = \ln \left| \frac{P_0 - N}{P_0 - H} \right|$$

Hence $\left| \frac{P - N}{P - H} \right| = e^C e^{-(N-H)kt} = \left| \frac{P_0 - N}{P_0 - H} \right| e^{-(N-H)kt}$ Now, in any case,

$$\frac{P - N}{P - H} = \frac{P_0 - N}{P_0 - H} e^{-(N-H)kt}$$

$$\lim_{t \rightarrow \infty} \frac{P - N}{P - H} = \lim_{t \rightarrow \infty} \frac{P_0 - N}{P_0 - H} e^{-(N-H)kt}$$

$$\therefore \lim_{t \rightarrow \infty} (P - N) = 0 \text{ or } \lim_{t \rightarrow \infty} (P - H) = \pm \infty$$

Q: Is $N < M$?

Q: $P(t) = ?$

Recall:

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$$\frac{P-N}{P-H} = \frac{P_0-N}{P_0-H} e^{-(N-H)kt} \implies$$

$$(P-N)(P_0-H) = (P-H)(P_0-N) e^{-(N-H)kt} \implies$$

$$P(P_0-H) - N(P_0-H) = P(P_0-N) e^{-(N-H)kt} - H(P_0-N) e^{-(N-H)kt} \implies$$

$$P(P_0-H - (P_0-N) e^{-(N-H)kt}) = N(P_0-H) - H(P_0-N) e^{-(N-H)kt} \implies$$

$$\boxed{P(t) = \frac{N(P_0-H) - H(P_0-N) e^{-(N-H)kt}}{P_0-H - (P_0-N) e^{-(N-H)kt}}}$$

\therefore

$$\lim_{t \rightarrow \infty} P(t) = \frac{N(P_0-H)}{P_0-H} = N$$

Now, if $0 < h < kM^2/4$ then

$$0 < H < N < M$$

For recall that

$$H, N = \frac{M \pm \sqrt{M^2 - 4h/k}}{2}$$

so since $h > 0 \implies M^2 - 4h/k < M^2 \implies$

$$\sqrt{M^2 - 4h/k} < M \implies M + \sqrt{M^2 - 4h/k} < 2M$$

$$N = \frac{M + \sqrt{M^2 - 4h/k}}{2} < M$$

Here

$$N(P_0-H) - H(P_0-N) e^{-(N-H)kt_E} = 0$$

which has a soln if $P_0 < H$

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Vertical Motion with Air Resistance

Recall Newton's 2nd Law:

$$ma = \sum F_i \text{ (net forces)}$$

Here $a = v' = dv/dt$, F_G (force due to gravity)
and F_R (force due to air resistance). Now,

$$F_G = -mg \text{ \& } (F_R < 0 \iff v > 0)$$

where $g \approx 9.8m/s^2$ Empirically,

$$F_R = kv^p$$

where $1 \leq p \leq 2$ & $k > 0$
two cases, namely $p = 1$ & $p = 2$.

$p = 1$ Here, we have that

$$mv' = F_G + F_R \implies$$

$$mv' = -mg - kv$$

since $F_R = -kv$. Notice that

$$\begin{aligned} (1) \quad v' &= -g - \frac{k}{m}v \\ &= -\left(\frac{k}{m}v + g\right) \end{aligned}$$

Also, notice that (1) is a 1st order linear ODE,

$$v' + \frac{k}{m}v = -g$$

where $\rho = k/m$, called the drag constant. Thus

$$v' = (\rho v + g) \implies$$

(sup)

$$\begin{aligned} \frac{v'}{\rho v + g} &= -1 \implies \int \frac{1}{\rho v + g} dv = -t + c \\ \implies \frac{1}{\rho} \ln |\rho v + g| &= -t + c \\ \implies \ln |\rho v + g| &= -\rho t + c \\ c &= \ln |\rho v_0 + g| \\ |\rho v + g| &= |\rho v_0 + g| e^{-\rho t} \\ \rho v + g &= |\rho v_0 + g| e^{-\rho t} \implies \end{aligned}$$

$$v(t) = \frac{1}{\rho}((\rho v_0 + g)e^{-\rho t} - g)$$

Notice that $\lim_{t \rightarrow \infty} v(t) = -g/\rho$; this is called terminal velocity. we denote this as

$$v_\tau = -g/\rho$$

Thus,

$$v(t) = (v_0 - v_\tau)e^{-\rho t} + v_\tau$$

Now,

$$x(t) = v_\tau t - \frac{1}{\rho}(v_0 - v_\tau)e^{-\rho t} + c \implies$$

$$c = x_0 + \frac{1}{\rho}(v_0 - v_\tau) \implies$$

$$x(t) = x_0 + v_\tau t + \frac{1}{\rho}(v_0 - v_\tau)(1 - e^{-\rho t})$$

Recall that $F_R = \pm kv^p$, $F_G = -mg$, and

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$$ma = \sum F = F_G + F_R \implies$$

$$v' = -g \pm \frac{k}{m} v^p = -g \pm \rho v^p \quad (1)$$

where drag $\rho = k/m$.

p=2 there are 2 cases:

- (i) upward motion, $F_R = -kv^2$;
- (ii) downward motion, $F_R = kv^2$.

(i) Upward motion Here (1) becomes

$$\begin{aligned} v' &= -g - \rho v^2 = -g \left(\frac{\rho}{g} v^2 + 1 \right) = -g \left(\left(v \sqrt{\frac{\rho}{g}} \right)^2 + 1 \right) \\ \implies \int \frac{1}{(v \sqrt{\rho/g})^2 + 1} dv &= -gt + c \implies \\ \frac{1}{\sqrt{\rho/g}} \arctan(v \sqrt{\rho/g}) &= -gt + c \implies \arctan(v \sqrt{\rho/g}) = -t \sqrt{\rho g} + c \\ \implies c &= \arctan(v_0 \sqrt{\rho/g}) \implies \\ v \sqrt{\rho/g} &= \tan(\arctan(v_0 \sqrt{\rho/g}) - t \sqrt{\rho g}) \implies \\ \boxed{v(t) = \sqrt{g/\rho} \tan(\arctan(v_0 \sqrt{\rho/g}) - t \sqrt{\rho g})} \end{aligned}$$

Thus,

$$\begin{aligned} x(t) &= \sqrt{g/\rho} \frac{1}{\sqrt{\rho g}} \ln |\cos(\arctan(v_0 \sqrt{\rho/g}) - t \sqrt{\rho g})| + c \\ \implies &= \frac{1}{\rho} \ln |\cos(\arctan(v_0 \sqrt{\rho/g}) - t \sqrt{\rho g})| + c \\ \implies c &= x_0 - \frac{1}{\rho} \ln |\cos(\arctan(v_0 \sqrt{\rho/g}))| \implies \\ \boxed{x(t) = x_0 + \frac{1}{\rho} \ln \left| \frac{\cos(\arctan(v_0 \sqrt{\rho/g}) - t \sqrt{\rho g})}{\cos(\arctan(v_0 \sqrt{\rho/g}))} \right|} \end{aligned}$$

Here $v(t) = 0$ allows us to find
time of max height, say t_m

$$\boxed{t_m = \frac{1}{\sqrt{\rho g}} \arctan(v_0 \sqrt{\rho/g})}$$

(ii) Downward Motion

$$v' = -g + \rho v^2 = -g(1 - (v \sqrt{\rho/g})^2) \implies$$

$$\int \frac{1}{1 - (v\sqrt{\rho/g})^2} dv = -gt + c$$

$$\frac{1}{\sqrt{\rho/g}} \operatorname{arctanh}(v\sqrt{\rho/g}) = -gt + c \implies$$

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$$\operatorname{arctanh}(v\sqrt{\rho/g}) = -\sqrt{\rho g}t + c \implies$$

$$c = \operatorname{arctanh}(v_0\sqrt{\rho/g}) \implies$$

$$v\sqrt{\rho/g} = \tanh(\operatorname{arctanh}(v_0\sqrt{\rho/g}) - t\sqrt{\rho g}) \implies$$

$$\boxed{v(t) = \sqrt{g/\rho} \tanh(\operatorname{arctanh}(v_0\sqrt{\rho/g}) - t\sqrt{\rho g})}$$

\therefore

$$x(t) = \sqrt{g/\rho} \left(-\frac{1}{\sqrt{\rho g}} \ln |\cosh(\operatorname{arctanh}(v_0\sqrt{\rho/g}) - t\sqrt{\rho g})| + c \right)$$

$$= -\frac{1}{\rho} \ln |\cosh(\operatorname{arctanh}(v_0\sqrt{\rho/g}) - t\sqrt{\rho g})| + c$$

$$\implies c = x_0 + \frac{1}{\rho} \ln |\cosh(\operatorname{arctanh}(v_0\sqrt{\rho/g}))|$$

$$\therefore \boxed{x(t) = x_0 - \frac{1}{\rho} \ln \left| \frac{\cosh(\operatorname{arctanh}(x_0\sqrt{\rho/g}) - t\sqrt{\rho g})}{\cosh(\operatorname{arctanh}(v_0\sqrt{\rho/g}))} \right|}$$

Thrm(Inverse Function thm). if $f'(x) \neq 0$ then f^{-1} is
diff at $y = f(x)$ and

$$\frac{df^{-1}}{dy}(y) = \frac{1}{\frac{df}{dx}(x)}$$

$$\left(\frac{dx}{dy} = \frac{1}{\frac{dy}{dx}} \right)$$

where $y = f(x) \iff x = f^{-1}(y)$

Aside:

$$\text{Ex } y = f(x) = \tanh x \implies$$

$$\frac{df^{-1}}{dy}(y) = \frac{1}{\frac{df}{dx}(x)} = \frac{1}{\operatorname{sech}^2 x} = \frac{1}{1 - \tanh^2 x} = \frac{1}{1 - y^2}$$

$$\text{Ex } \int \tanh x dx = \int \frac{\sinh x}{\cosh x} dx = \int \frac{1}{u} du = \ln |\cosh x| + c$$

$$u = \cosh x$$

$$u' = \sinh x$$

Aside:

$$\cosh x = \frac{e^x - e^{-x}}{2}$$

$$\sinh x = \frac{e^x - e^{-x}}{2}$$

$$\cosh' x = \sinh x$$

$$\sinh' x = \cosh x$$

$$\frac{f(x) \pm f(-x)}{2}$$

Ex

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Escape Velocity

Recall Newton's Gravitational Law:

$$F = \frac{GmM}{r^2}$$

where $G \approx 6.67 \times 10^{-11}$. Let m be the mass of a projectile from a planet's surface of mass M of radius R . By Newton's 2nd Law,

$$ma = -\frac{GmM}{r^2} \implies$$

$$v' = -\frac{GM}{r^2}$$

By the chain rule,

$$\frac{dv}{dt} = \frac{dv}{dr} \frac{dr}{dt} = v \frac{dv}{dr}$$

Thus,

$$v \frac{dv}{dr} = -\frac{GM}{r^2} \text{ (separable)}$$

$$\int v dv = -GM \int r^{-2} dr \implies$$

$$\frac{v^2}{2} = \frac{GM}{r} + c \implies$$

$$c = \frac{v_0^2}{2} - \frac{GM}{r_0}$$

where $r_0 = R$.

$$\frac{v^2}{2} = \frac{v_0^2}{2} - \frac{GM}{R} + \frac{GM}{r} \implies$$

$$v^2 = v_0^2 - \frac{2GM}{R} + \frac{2GM}{r}$$

$$> v_0^2 - \frac{2GM}{R}$$

To "escape" the gravitational force of the planet, we must have that $v > 0$ for all r . This happens if

$$v^2 > v_0^2 - \frac{2GM}{R} > 0 \iff$$

$$v_0^2 > \frac{2GM}{R} \implies$$

Ex (p.109) # 30

Newton's 2nd Law:

$$ma = \text{net forces} = F_e + F_m$$

By Newton's Gravitational law,

$$F_e = -\frac{GmM_e}{r^2} \text{ \&}$$

$$F_m = \frac{GmM_m}{(s-r)^2}$$

\therefore

$$\frac{dv}{dt} = \frac{GMm}{(s-r)^2} - \frac{GM_e}{r^2}$$

As before,

$$v \frac{dv}{dr} = G \left(\frac{M_m}{(s-r)^2} - \frac{M_e}{r^2} \right)$$

which is separable. Thus,

$$\frac{v^2}{2} = G \left(M_m \int \frac{1}{(s-r)^2} dr - M_e \int \frac{1}{r^2} dr \right)$$

$$= G \left(\frac{M_m}{s-r} + \frac{M_e}{r} + c \right) \implies$$

$$\frac{v_0^2}{2} = G \left(\frac{M_m}{s-R} + \frac{M_e}{R} \right) + c$$

\implies

$$\frac{v^2}{2} = G \left(\frac{M_m}{s-r} + \frac{M_e}{r} \right) + \frac{v_0^2}{2} - G \left(\frac{M_m}{s-R} + \frac{M_e}{R} \right)$$

Recall:

$$ma = \sum F_i, (r_0 = R) \\ (r_0 = R), R \leq r \leq s$$

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where

$$F_e = -\frac{GmM_e}{r^2} \text{ \& } F_m = \frac{GmM_m}{(s-r)^2}$$

thus,

$$a = \frac{d^2r}{dt^2} = F_m + F_e = \frac{GM_m}{(s-r)^2} - \frac{GM_e}{r^2}$$

By chain rule,

$$\frac{d^2r}{dt^2} = \frac{dv}{dt} = \frac{dv}{dr} \frac{dr}{dt} = v \frac{dv}{dr}$$

so,

$$v \frac{dv}{dr} = \frac{GM_m}{(s-r)^2} - \frac{GM_e}{r^2} \text{ (sep)} \\ \frac{v^2}{2} = \frac{GM_m}{s-r} + \frac{GM_e}{r} + c \implies \\ c = \frac{v_0^2}{2} - \frac{GM_m}{s-R} - \frac{GM_e}{R}$$

Hence,

$$\frac{v^2}{2} \frac{GM_m}{s-r} + \frac{GM_e}{r} + \frac{v_0^2}{2} - \frac{GM_m}{s-R} - \frac{GM_e}{R}$$

we want $v > 0$

$$a = 0 \implies \\ \frac{GM_m}{(s-r)^2} = \frac{GM_e}{r^2} \implies \\ \left(\frac{s-r}{r}\right) = \frac{M_m}{M_e} \implies \\ \frac{s}{r} - 1 = \sqrt{M_m/M_e} \implies \\ \frac{s}{r} = 1 + \sqrt{M_m/M_e} = \frac{\sqrt{M_e}\sqrt{M_e}}{\sqrt{M_e}} \\ r = \frac{s\sqrt{M_e}}{\sqrt{M_m} + \sqrt{M_e}}$$

Also, notice that

$$v = 0 \implies \\ \frac{v_0^2}{2} = \frac{GM_m}{s-r} + \frac{GM_e}{R} - \frac{GM_m}{s-R} - \frac{GM_e}{r}$$

\therefore

$$v_0 = \sqrt{2G\left(\frac{M_m}{s-R} + \frac{M_e}{R} - \frac{M_m + M_e + 2\sqrt{M_m M_e}}{s}\right)} \implies$$

$$v_0 = \sqrt{2G\left(\frac{M_m}{s-R} + \frac{M_e}{R} - \frac{1}{s}(\sqrt{M_m} + \sqrt{M_e})^2\right)}$$

Aside:

$$\frac{1}{r} = \frac{\sqrt{M_m} + \sqrt{M_e}}{s\sqrt{M_e}} \implies$$

$$\frac{M_m}{s-r} = \frac{M_m + \sqrt{M_m M_e}}{s}$$

$$\frac{M_e}{r} = \frac{M_e + \sqrt{M_m M_e}}{s}$$

Aside:

$$r\sqrt{M_m} + r\sqrt{M_e} = s\sqrt{M_e} \implies$$

$$r\sqrt{M_m} = \sqrt{M_e}(s-r) \implies$$

$$\frac{1}{s-r} = \frac{1}{r}\sqrt{\frac{M_e}{M_m}} \implies$$

$$\frac{M_m}{s-r} = \frac{\sqrt{M_m M_e}}{r}$$

Euler's Method

Given a slope field, $y' = f(x, y)$,

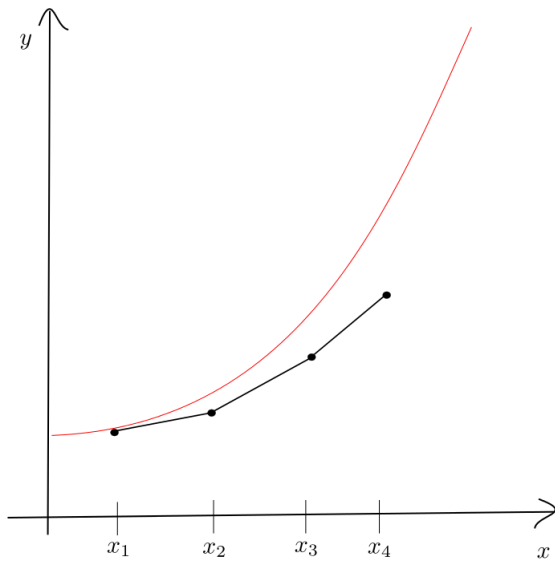
& a specific soln to the initial value problem

$$\frac{dy}{dx} = f(x, y) \text{ \& } (x_0, y_0)$$

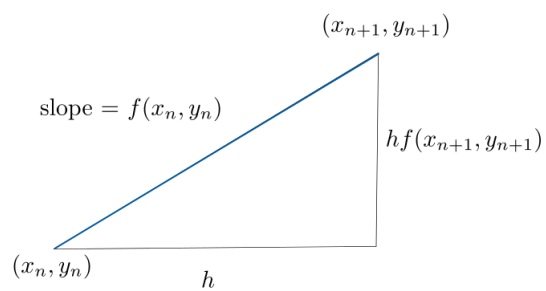
say $y = y(x)$, then $y(x_0) = y_0$, &

Euler's method gives an algorithm

for estimating the exact soln $y = y(x)$



Find y_1 & y_{n+1} in general
slope = $f(x_0, y_0)$



$$h = x_1 - x_0$$

$$y = f(x_0, y_0)(x - x_0) + y_0 \implies$$

$$y_1 = f(x_0, y_0)h + y_0$$

In general,

$$\boxed{y_{n+1} = hf(x_n, y_n) + y_n}$$

Here

$$\boxed{y_n \approx y(x_n)}$$

Recall that an n th order linear ODE has the form

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$$y^{(n)} + \sum_{k=1}^n P_k(x)y^{(n-k)} = f(x) \quad (1)$$

where P_k and f are cts for $1 \leq k \leq n$.

The associated homogeneous n th order linear ODE to (1) is
(2)

$$y^{(n)} + \sum_{k=1}^n P_k(x)y^{(n-k)} = 0$$

i.e., (1) with $f(x) \equiv 0$

Notation. put

$$V = \{y : I \rightarrow \mathbb{R} \mid y \text{ has } n\text{th order derivative on } I\}$$

then V is an \mathbb{R} -linear space. put

$$W = \{y \in V \mid y \text{ is a soln to (2)}\}$$

then the following holds

thrm. $W \leq V$, i.e., the set of all solns to (2) is a linear space.

Proof. If $y \in W$ & $c \in \mathbb{R}$ then

$$\begin{aligned} (cy)^{(n)} + \sum_{k=1}^n P_k(x)(cy)^{(n-k)} &= \\ (cy)^{(n)} + c \sum_{k=1}^n P_k(x)y^{(n-k)} &= \\ c(y^{(n)} + \sum_{k=1}^n P_k(x)y^{(n-k)}) &= \\ c \cdot 0 &= 0 \end{aligned}$$

$\therefore cy \in W$

If $y_1, y_2 \in W$ then

$$\begin{aligned} (y_1 + y_2)^{(n)} + \sum_{k=1}^n P_k(x)(y_1 + y_2)^{(n-k)} &= \\ y_1^{(n)} + \sum_{k=1}^n P_k(x)y_1^{(n-k)} + y_2^{(n)} + \sum_{k=1}^n P_k(x)y_2^{(n-k)} &= \\ 0 + 0 &= 0 \end{aligned}$$

$\therefore y_1 + y_2 \in W$. Hence, $W \in \mathbb{R}$ -linear subspace of V .

Recall: Thrm (wronskian thrm). if f_1, \dots, f_n are linearly independent in $C^{(n-1)}(I) = \{f : I \rightarrow \mathbb{R} \mid f^{(n-1)} \text{ is cts on } I\}$, then the wronskian of f_1, \dots, f_n is identically 0 for all $x \in I$, i.e., for all $x \in I$,

$$|W(f_1, \dots, f_n)(x)| = \det \begin{pmatrix} f_1(x) & \cdots & f_n(x) \\ f_1'(x) & \cdots & f_n'(x) \\ f_1''(x) & \cdots & f_n''(x) \\ \vdots & \ddots & \vdots \\ f_1^{(n-1)}(x) & \cdots & f_n^{(n-1)}(x) \end{pmatrix} = 0$$

Aside

$$A\vec{x} = \vec{b}$$

the soln space of

$$A\vec{x} = \vec{0}$$

is a linear space. the soln space of

$$A\vec{x} = \vec{b}$$

is a affine linear space, with solns

$$\vec{x} = \vec{x}_0 + \vec{x}_1$$

where \vec{x}_0 is any hom soln

Exam 2

1. hom ODE
2. ODE needing a subst to reduce to a 1st order linear/sep
3. exact ODE
4. population Model (logistic pop)
5. population Model (harvesting a logistic pop)