# Automatic Memory Management

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#### Lecture Outine

- Why Automatic Memory Management?
- · Garbage Collection
- · Three Techniques
  - Mark and Sweep
  - Stop and Copy
  - Reference Counting

# Why Automatic Memory Management?

- Storage management is still a hard problem in modern programming
- C and C++ programs have many storage bugs
  - forgetting to free unused memory
  - dereferencing a dangling pointer
  - overwriting parts of a data structure by accident
  - and so on...
- Storage bugs are hard to find
  - a bug can lead to a visible effect far away in time and program text from the source

# Type Safety and Memory Management

- Can types prevent errors in programs with manual allocation and deallocation of memory?
  - some fancy type systems (linear types) were designed for this purpose but they complicate programming significantly
- Currently, if you want type safety then you must use automatic memory management

### Automatic Memory Management

- This is an old problem:
  - studied since the 1950s for LISP
- There are well-known techniques for completely automatic memory management
- Became mainstream with the popularity of Java

#### The Basic Idea

- When an object is created, unused space is automatically allocated
  - In Cool, new objects are created by new X
- After a while there is no more unused space
- Some space is occupied by objects that will never be used again
  - This space can be freed to be reused later

#### The Basic Idea (Cont.)

- How can we tell whether an object will "never be used again"?
  - in general, impossible to tell
  - we will use heuristics
- Observation: a program can use only the objects that it can find:

let 
$$x : A \leftarrow \text{new } A \text{ in } \{x \leftarrow y; ...\}$$

 After x ← y there is no way to access the newly allocated object

### Garbage

- An object x is <u>reachable</u> if and only if:
  - a register contains a pointer to x, or
  - another reachable object y contains a pointer to x
- You can find all reachable objects by starting from registers and following all the pointers
- · An unreachable object can never be used
  - such objects are garbage

#### Reachability is an Approximation

Consider the program:

```
x \leftarrow \text{new } A;

y \leftarrow \text{new } B

x \leftarrow y;

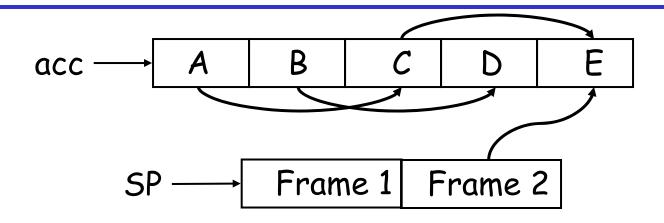
if alwaysTrue() then x \leftarrow \text{new } A \text{ else } x.\text{foo() } fi
```

- After  $x \leftarrow y$ 
  - assuming y becomes dead ...
  - the first object A is unreachable
  - the object B is reachable (through x)
  - thus B is not garbage and is not collected
    - but object B is never going to be used

### Tracing Reachable Values in Coolc

- · In coolc, the only register is the accumulator
  - it points to an object
  - and this object may point to other objects, etc.
- The stack is more complex
  - each stack frame contains pointers
    - e.g., method parameters
  - each stack frame also contains non-pointers
    - e.g., return address
  - if we know the layout of the frame we can find the pointers in it

### A Simple Example



- In Coolc we start tracing from acc and stack
  - These are the *roots*
- Note B and D are unreachable from acc and stack
  - Thus we can reuse their storage

### Elements of Garbage Collection

- Every garbage collection scheme has the following steps
  - 1. Allocate space as needed for new objects
  - 2. When space runs out:
    - a) Compute what objects might be used again (generally by tracing objects reachable from a set of "root" registers)
    - b) Free the space used by objects not found in (a)
- Some strategies perform garbage collection before the space actually runs out

# Mark and Sweep

- When memory runs out, GC executes two phases
  - the mark phase: traces reachable objects
  - the sweep phase: collects garbage objects
- · Every object has an extra bit: the mark bit
  - reserved for memory management
  - initially the mark bit is 0
  - set to 1 for the reachable objects in the mark phase

#### The Mark Phase

```
let todo = { all roots }
while todo \neq \emptyset do
    pick v ∈ todo
    todo \leftarrow todo - \{v\}
    if mark(v) = 0 then (* v is unmarked yet *)
       mark(v) \leftarrow 1
       let v_1,...,v_n be the pointers contained in v
       todo \leftarrow todo \cup \{v_1,...,v_n\}
od
```

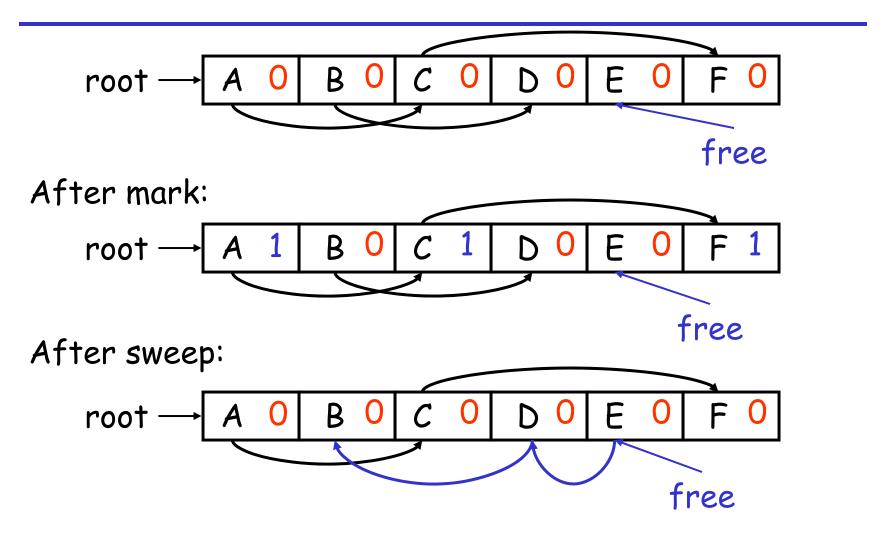
#### The Sweep Phase

- The sweep phase scans the heap looking for objects with mark bit 0
  - these objects were not visited in the mark phase
  - they are garbage
- · Any such object is added to the free list
- The objects with a mark bit 1 have their mark bit reset to 0

### The Sweep Phase (Cont.)

```
(* sizeof(p) is the size of block starting at p *) p \leftarrow bottom of heap while p < top of heap do if mark(p) = 1 then mark(p) \leftarrow 0 else add block p...(p+sizeof(p)-1) to freelist fi p \leftarrow p + sizeof(p) od
```

# Mark and Sweep Example



#### Details

- While conceptually simple, this algorithm has a number of tricky details
  - typical of GC algorithms
- A serious problem with the mark phase
  - it is invoked when we are out of space
  - yet it needs space to construct the todo list
  - the size of the todo list is unbounded so we cannot reserve space for it a priori

### Mark and Sweep: Details

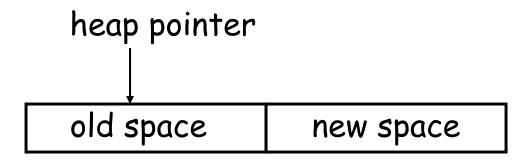
- The todo list is used as an auxiliary data structure to perform the reachability analysis
- There is a trick that allows the auxiliary data to be stored in the objects themselves
  - pointer reversal: when a pointer is followed it is reversed to point to its parent
  - For more info: Look up the (Deutsch)-Schorr-Waite algorithms
- Similarly, the free list is stored in the free objects themselves

#### Evaluation of Mark and Sweep

- Space for a new object is allocated from the new list
  - a block large enough is picked
  - an area of the necessary size is allocated from it
  - the left-over is put back in the free list
- Mark and sweep can fragment the memory
- Advantage: objects are not moved during GC
  - no need to update the pointers to objects
  - works for languages like C and C++

#### Another Technique: Stop and Copy

- Memory is organized into two areas
  - old space: used for allocation
  - new space: used as a reserve for GC

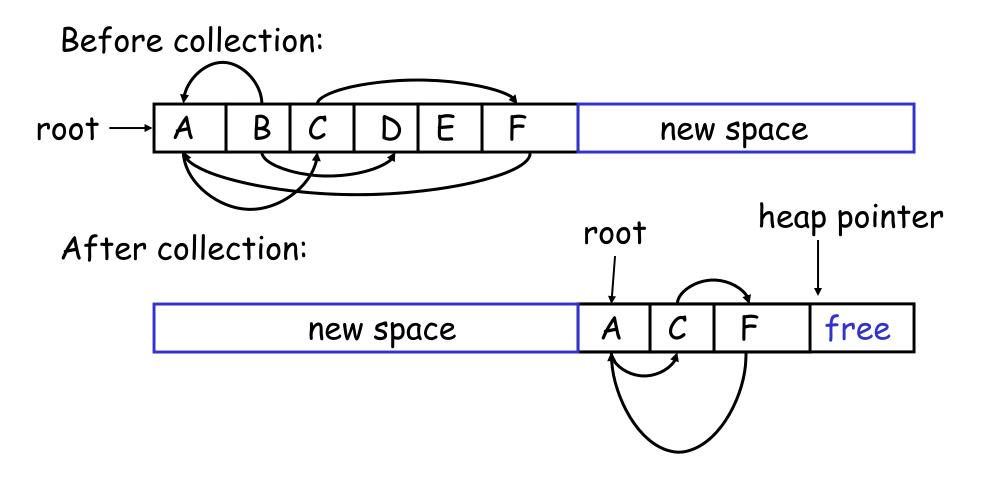


- The heap pointer points to the next free word in the old space
  - allocation just advances the heap pointer

# Stop and Copy Garbage Collection

- Starts when the old space is full
- Copies all reachable objects from old space into new space
  - garbage is left behind
  - after the copy phase the new space uses less space than the old one before the collection
- After the copy the roles of the old and new spaces are reversed and the program resumes

# Example of Stop and Copy Garbage Collection

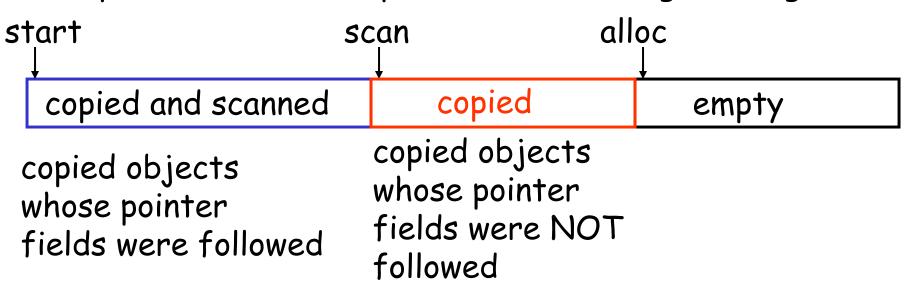


# Implementation of Stop and Copy

- We need to find all the reachable objects, as for mark and sweep
- As we find a reachable object we copy it into the new space
  - And we have to fix ALL pointers pointing to it!
- As we copy an object we store in the old copy a forwarding pointer to the new copy
  - when we later reach an object with a forwarding pointer we know it was already copied

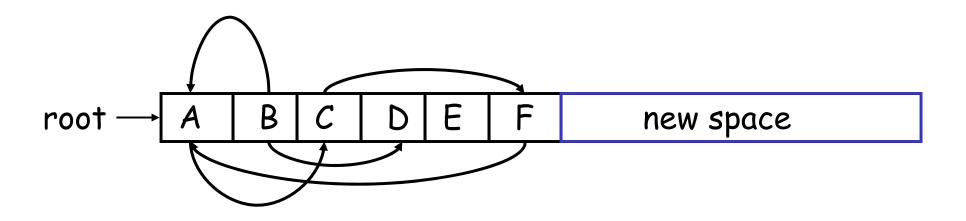
# Implementation of Stop and Copy (Cont.)

- We still have the issue of how to implement the traversal without using extra space
- The following trick solves the problem:
  - partition the <u>new space</u> in three contiguous regions



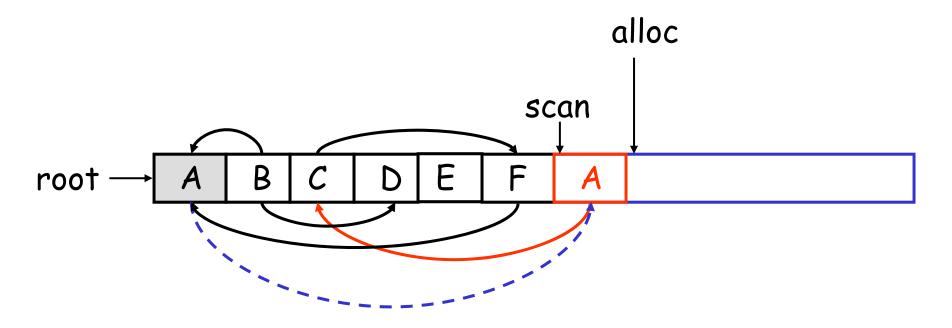
# Stop and Copy. Example (1)

Before garbage collection



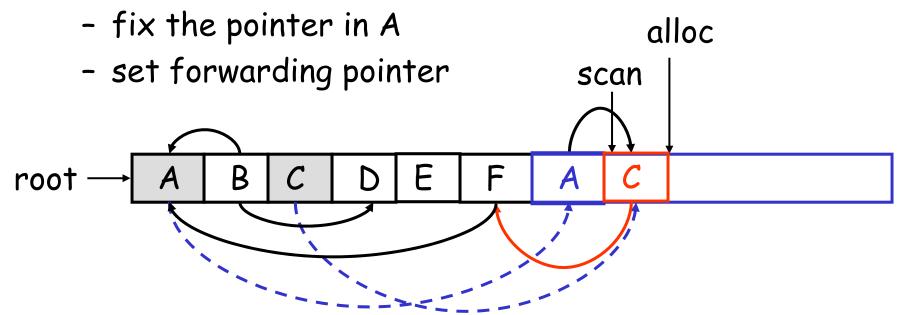
# Stop and Copy. Example (2)

 Step 1: Copy the objects pointed to by roots and set forwarding pointers



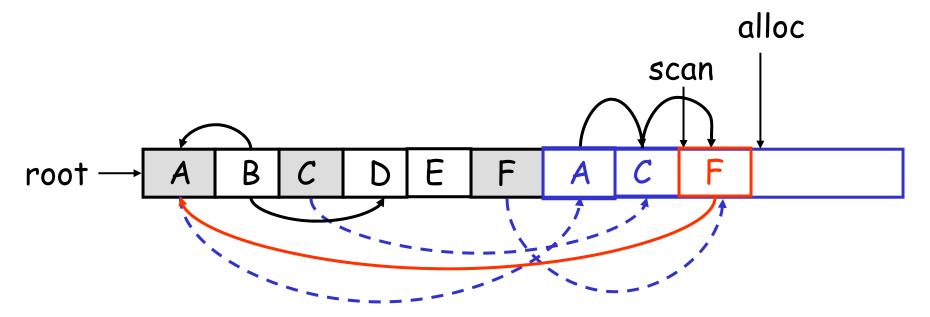
# Stop and Copy. Example (3)

- Step 2: Follow the pointer in the next unscanned object (A)
  - copy the pointed-to objects (just C in this case)



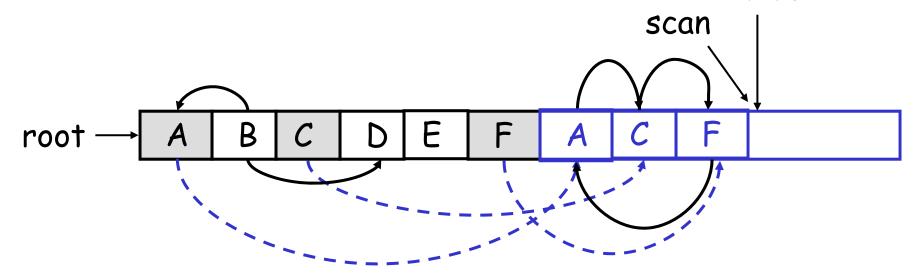
# Stop and Copy. Example (4)

- Follow the pointer in the next unscanned object (C)
  - copy the pointed objects (F in this case)



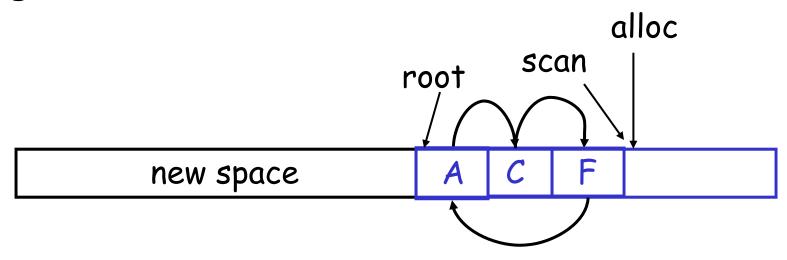
# Stop and Copy. Example (5)

- Follow the pointer in the next unscanned object (F)
  - the pointed object (A) was already copied. Set the pointer same as the forwading pointer



# Stop and Copy. Example (6)

- · Since scan caught up with alloc we are done
- Swap the role of the spaces and resume the program



# The Stop and Copy Algorithm

```
while scan <> alloc do
   let O be the object at scan pointer
   for each pointer p contained in O do
     find O' that p points to
     if O' is without a forwarding pointer
         copy O' to new space (update alloc pointer)
         set 1st word of old O' to point to the new copy
         change p to point to the new copy of O'
     else
         set p in O equal to the forwarding pointer
     fi
   end for
   increment scan pointer to the next object
od
```

# Details of Stop and Copy

- · As with mark and sweep, we must be able to tell how large an object is when we scan it
  - and we must also know where the pointers are inside the object
- We must also copy any objects pointed to by the stack and update pointers in the stack
  - this can be an expensive operation

#### Evauation of Stop and Copy

- Stop and copy is generally believed to be the fastest GC technique
- Allocation is very cheap
  - just increment the heap pointer
- · Collection is relatively cheap
  - especially if there is a lot of garbage
  - only touch reachable objects
- But some languages do not allow copying
  - C, C++

# Why Doesn't C Allow Copying?

- Garbage collection relies on being able to find all reachable objects
  - and it needs to find all pointers in an object
- In C or C++ it is impossible to identify the contents of objects in memory
  - E.g., a sequence of two memory words might be
    - A list cell (with data and next fields)
    - A binary tree node (with left and right fields)
  - Thus we cannot tell where all the pointers are

#### Conservative Garbage Collection

- But it is Ok to be <u>conservative</u>:
  - if a memory word looks like a pointer it is considered a pointer
    - it must be aligned
    - it must point to a valid address in the data segment
  - all such pointers are followed and we overestimate the set of reachable objects
- But we still cannot move objects because we cannot update pointers to them
  - what if what we thought is a pointer is actually an account number?

### Reference Counting

- Rather that wait for memory to be exhausted, try to collect an object when there are no more pointers to it
- Store in each object the number of pointers to that object
  - this is the reference count
- Each assignment operation manipulates the reference count

# Implementation of Reference Counting

- new returns an object with reference count 1
- Let rc(x) be the reference count of x
- Assume x, y point to objects o, p
- Every assignment  $x \leftarrow y$  must be changed:

```
rc(p) \leftarrow rc(p) + 1

rc(o) \leftarrow rc(o) - 1

if(rc(o) == 0) then mark o as free

x \leftarrow y
```

# Evaluation of Reference Counting

### Advantages:

- easy to implement
- collects garbage incrementally without large pauses in the execution

### Disadvantages:

- cannot collect circular structures
- manipulating reference counts at each assignment is very slow

### Evaluation of Garbage Collection

- Automatic memory management prevents serious storage bugs
- · But reduces programmer control
  - e.g., layout of data in memory
  - e.g., when is memory deallocated
- Pauses problematic in real-time applications
- · Memory leaks possible (even likely)

### Evaluation of Garbage Collection

- · Garbage collection is very important
- Researchers are working on advanced garbage collection algorithms:
  - concurrent: allow the program to run while the collection is happening
  - generational: do not scan long-lived objects at every collection
  - parallel: several collectors working in parallel