# Ingenic® Neural Network Inference Framework Venus

Programming Manual

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# **Ingenic®**

# **Neural Network Inference Framework Programming Manual**

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# Release history

Date	Author	Revision	Change
Jan.2022	Nancy	1.0.1	First release
Feb.2022	Monday	1.0.2	1. Add image preprocessing class sample

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# 1 Overview of Venus

Venus is a lightweight, efficient, easy-to-expand and high-performance netural network inference framework. It supports 8bit/4bit/2bit quantitative inference, 8bit post-quantitative inference and mixed precision inference. It supports several convolutions and operators, such as common convolution, Depthwise convolution, pooling, activation, full connection, lstm, concat and other operators, it also supports multi-input and branching networks, implements high-performance NPU accelerator and SIMD512 acceleration engine based on AIE platform. The bottom operator is deeply optimized to make full use of the computing performance of AIE platform. Through efficient and compact memory management structure design, memory reuse between nodes without computing dependence is achieved, memory resource consumption is greatly reduced, and cross-model memory reuse is supported to further reduce memory consumption and improve memory utilization. Venus supports high-speed image processing operations such as hardware-based image matting, scaling, rotation, affine transformation, perspective transformation and color space conversion, which are currently mainly used in T40, T02 and X2500 chip platforms.

# 2 API Introduction

# 2.1 Data Structure

# Tensor

■ Definition

Represents multidimensional tensor data, the main data emission format is NHWC format

**■** Interface

shape get tensor shape information [batch, height, width, channel] reshape change tensor shape information based on input shape mudata gets a readable and writable pointer to the specified type of

tensor data.

data \_\_\_\_ gets a read-only pointer to the specified type of tensor data

# shape t

■ Definition

Represents the shape information of tensor

■ Attribute

batch of four-dimensional tensor

height tensor's height width tensor's width tensor's channel

Bbox t

Definition

A coordinate frame representing the target

■ Attribute

x0 target frame's top left coordinate
 y0 target frame's top left coordinate
 x1 target frame's lower right coordinate
 y1 target frame's lower right coordinate

ObjBbox t

Definition

Coordinate frame, corresponding category and confidence level representing the output of target detection network.

■ Attribute

box coordinate frame of the target

score the confidence level for the target box

class id category of target

PaddingType

Definition

Type of image boundary filling

■ Attribute

NONE no filling

BOTTOM RIGHT bottom right filling

SYMMETRY symmetrical filling around

AddressLocate

■ Definition

Enter the source address of the pointer

■ Attribute

NMEM\_VIRTUAL pointer is a virtual address from nmem the pointer is the physical address from rmem

ChannelLayout

**■** Definition

Image format

■ Attribute

NONE defaults to null
NV12 NV12 image format
BGRA BGRA image format
RGBA RGBA image format
ARGB ARGB image format
RGB RGB image format

BsPadType

■ Definition

Type of image boundary fill

Attribute

NONE no filling

BOTTOM RIGHT bottom right filling

SYMMETRY symmetrical filling around

BsBaseParam

Definition

**Image Processing Basic Parameters** 

■ Attribute

in\_layout input image format out layout output image format

coef off enable whether to use default conversion parameters

coef nv12 to BGRA

offset nv12 to BGRA pixel offset

BsExtendParam

**■** Definition

Image processing parameters

■ Attribute

pad type the type of image boundary filling (BsPadType)

pad val boundary pixel fill value (BGR)

# BsCommonParam

**■** Definition

Image processing calls common interface parameters

■ Attribute

input\_height height of the input image width of the input image line stride line spacing of the input image

# 2.2 Forward Inference API

# • venus init

■ Function description

Initialize the running environment, return status code

■ Interface definition

int venus init(void);

■ Parameter list

None

■ Return value

0 represents success, otherwise failure.

# • venus deinit

**■** Function description

Release the running environment and return the status code

■ Interface definition

int venus deinit();

■ Parameter list

None

■ Return value

0 represents success, otherwise failure.

#### BaseNet

■ Definition

Inference Engine Base Class for Venus Framework

- load model
  - ♦ Function description

Loading model parameters from memory or from a file

◆ Interface definition

int load\_model(const char\* model\_path, bool memory\_model=false, int start\_off=0);

Parameter list

model path When memory model is True, model path represents the

pointer to the memory area of the model parameter. When memory\_model is False, model\_path represents the file name

of the model file.

memory\_model Indicates whether to load the model from the memory. When it

is set to True, it means to load the model from the memory. When it is set to False, it means to load the model from the file. It is set to False by default. Currently, only false is

supported.

start off From model path, it indicates the number of bytes skipped by

the first address of file or memory specified by path. Used for multi model packaging and loading.

#### ◆ Return value

0 represents success, otherwise failure.

# **■** get\_forward\_memory\_size

◆ Function description

Get the size of memory required for the forward inference phase of the model

◆ Interface definition

int get forward memory size(size t &memory size);

◆ Parameter list

memory\_size variable reference holding memory size

◆ Return value

0 represents success, otherwise failure.

# **■** int set forward memory

◆ Function description

When the memory sharing mode is external, set the first address of the forward reasoning memory through this interface

◆ Interface definition

int set forward memory(void \*memory);

Parameter list

memory the first address of memory

Return value

0 represents success, otherwise failure.

# get input

◆ Function description

The Tensor of the network input node is obtained by the sequence number of the network input node. If the network has more than one input, the interface can be called multiple times to get it.

◆ Interface definition

std::unique ptr<Tensor> get input(int index);

Parameter list

index the sequence number of the network input node

♦ Return value

Returns the smart pointer to the network input node Tensor

# get input by name

◆ Function description

The Tensor of the network input node is obtained by the name of the network input node. If the network has more than one input, the interface can be called multiple times to get it.

◆ Interface definition

std::unique ptr<Tensor> get\_input\_by\_name(std::string &name);

Parameter list

name the name of the network input node

♦ Return value

Returns the smart pointer to the network input node Tensor

# get output

◆ Function description

The Tensor of the network output node is obtained by the sequence number of the network output node, which can be called multiple times if the network has multiple outputs.

◆ Interface definition

std::unique ptr<const Tensor> get output(int index);

Parameter list

index the sequence number of the network output node

◆ Return value

Returns the smart pointer to the network output node tensor

# **■** get output by name

◆ Function description

Obtain the tensor of the network output node through the name of the network output node. If the network has multiple outputs, you can call the interface for multiple times.

◆ Interface definition

std::unique ptr<const Tensor> get output by name(std::string &name);

◆ Parameter list

name the name of network output node

◆ Return value

Returns the smart pointer to the network output node tensor

#### **■** run

◆ Function description

Perform model forward reasoning and return status codes.

◆ Interface definition

int run();

Parameter list

None

◆ Return value

0 represents success, otherwise failure.

#### • net create

**■** Function description

Create inference engine handle, return engine handle

■ Interface definition

std::unique\_ptr<BaseNet> net\_create(TensorFormat input\_data\_fmt=TensorFormat::NHWC, ShareMemoryMode smem mode=ShareMemoryMode::DEFAULT);

■ Parameter list

input\_data\_fmt representing the type of input image, has two options: NHWC

and NV12.

smem\_mode which indicates how memory is shared. DEFAULT, SHARE\_

ONE\_THREAD, SET\_FROM\_The EXTERNAL options represent three memory sharing modes, one for the model, one for multiple models in the same thread, and one for users

exploiting inferential memory from outside.

■ Return value

Returns the inference engine handle. NULL represents failure, otherwise success.

# 2.3 Tools API

# Image Preprocessing API

- **■** warp\_resize
  - ◆ Function description
    Scale the input image to return the scaled image
  - ◆ Interface definition int warp resize(const Tensor &input, Tensor &output, BsExtendParam \*param)

Parameter list

input input image output output image

param image scaling parameters

Parameter specification

Parameter	Supported image	Alignment	resolving power
name	types	Requirement	resolving power
input	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
output	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048

#### ◆ Return value

0 represents success, otherwise failure.

# ♦ Notes

- When the aspect ratio of the input and output images is inconsistent, you can select the output direct zoom image, the equal-scale zoom image filled around, and the equal-scale zoom image filled at the bottom right by param->padtype.
- When the input is in NV12 format, the width and height of the input must be multiple of 2. When the input is in BGRA, RGBA, ARGB formats, the input width is required to be a multiple of 2, and the output format is consistent with the input format.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When the output is in BGRA, RGBA, ARGB formats, there is no alignment requirement for the width and height of the output.

# **■** crop\_resize

◆ Function description

The input image is scaled by the boxes coordinate set, and the scaled image set is returned.

◆ Interface definition

int crop\_resize(const Tensor &input, std::vector<Tensor> &output,
std::vector<Bbox t>&boxes,BsExtendParam \*param)

◆ Parameter list

Input image

output image collection

boxes the coordinates of the boxes that need to be scaled and the set

of widths and heights.

param image scaling parameters

◆ Parameter specification

Parameter	Supported image	Alignment	resolving power
name	types	Requirement	resolving power
input	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
output	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
boxes	_	See Notes	2x2 ~ 1024x2048

# ◆ Return value

0 represents success, otherwise failure.

#### Notes

When the aspect ratio of the picked ROI image and the output image is not consistent, you can select the output direct zoom image, the equal-scale zoom image

filled around, and the equal-scale zoom image filled at the bottom right by parampadtype.

- When the input is in NV12 format, that is, Bbox\_t. The x0, y0, x1, Y1 in the data structure must all be even numbers; When the input is in BGRA, RGBA, ARGB formats, the input width (x1-x0) is required to be a multiple of 2, and the output format is consistent with the input format.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When the output is in BGRA, RGBA, ARGB formats, there is no alignment restriction for the width and height of the output.

# **■** warp affine

◆ Function description

Perform affine transformation on input image based on affine transformation matrix.

◆ Interface definition

int warp\_affine(const Tensor &input, Tensor &output, Tensor &matrix, BsExtendParam \*param)

Parameter list

input input image
Output output image

matrix set of affine transformation matrices

param parameters of the image affine transformation

◆ Parameter specification

Parameter	Supported image	Alignment	resolving power
name	types	Requirement	lesolving power
input	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
output	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048

# ♦ Return value

0 represents success, otherwise failure.

#### Notes

- When the input is in NV12 format, the width and height of the input must be multiple of 2. When the input is in BGRA, RGBA, ARGB formats, the input width is required to be a multiple of 2, and the output format is consistent with the input format.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When the output is in BGRA, RGBA, ARGB formats, there is no alignment requirement for the width and height of the output.

# **■** crop\_affine

◆ Function description

Carry out a matting operation on the original map according to the input boxes, and then perform an affine transformation on the matted graph according to its affine transformation matrix.

◆ Interface definition

int crop\_affine(const Tensor &input,std::vector<Tensor> &output,
std::vector<Tensor> &matrix, std::vector<Bbox\_t>&boxes,BsExtendParam
\*param)

◆ Parameter list

input input image

output output image collection

matrix set of affine transformation matrices

boxes the coordinates of the box requiring an affine transformation

and a set of widths and heights

param parameters of the image affine transformation

# ◆ Parameter specification

Parameter	Parameter name	Parameter	resolving power
name	rarameter name	name	resolving bower
input	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
output	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
boxes	_	See Notes	2x2 ~ 1024x2048

#### ◆ Return value

0 represents success, otherwise failure.

# Notes

- When the input is in NV12 format, that is, Bbox\_t The x0, y0, x1, Y1 in the data structure must all be even numbers; When the input is in BGRA, RGBA, ARGB formats, the input width (x1-x0) is required to be a multiple of 2, and the output format is consistent with the input format.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When the output is in BGRA, RGBA, ARGB formats, there is no alignment requirement for the width and height of the output.

# **■** warp\_perspective

Function description

Perform perspective transformation on the input image (NV12) based on the perspective transformation matrix

◆ Interface definition

int warp\_perspective(const Tensor &input, Tensor &output, Tensor &matrix, BsExtendParam \*param)

# Parameter list

input input image output output image

matrix set of affine transformation matrices

param parameters of the image perspective transformation

# ◆ Parameter specification

Parameter	Supported image	Alignment	resolving power
name	types	Requirement	resolving power
input	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
output	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048

# ◆ Return value

0 represents success, otherwise failure.

#### ◆ Notes

- When the input is in NV12 format, that is, Bbox\_t The x0, y0, x1, Y1 in the data structure must all be even numbers; When the input is in BGRA, RGBA, ARGB formats, the input width (x1-x0) is required to be a multiple of 2, and the output format is consistent with the input format.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When the output is in BGRA, RGBA, ARGB formats, there is no alignment requirement for the width and height of the output.

# **crop\_perspective**

◆ Function description

Perform a cutout operation on the original drawing based on the boxes input, and then a perspective transformation on the finished drawing based on their respective perspective transformation matrices

◆ Interface definition

int crop\_perspective(const Tensor &input,std::vector<Tensor> &output,
std::vector<Tensor> &matrix, std::vector<Bbox\_t>&boxes,BsExtendParam
\*param)

Parameter list

input input image output output image set

matrix set of affine transformation matrices

boxes the coordinates of the box requiring an affine transformation

and a set of widths and heights

param parameters of the image perspective transformation

◆ Parameter specification

Parameter	Supported image	Alignment	resolving power
name	types	Requirement	resolving bower
input	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
output	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048
boxes	-	See Notes	2x2 ~ 1024x2048

#### ◆ Return value

0 represents success, otherwise failure.

#### Notes

- ➤ When the input is in NV12 format, that is, Bbox\_t The x0, y0, x1, Y1 in the data structure must all be even numbers; When the input is in BGRA, RGBA, ARGB formats, the input width (x1-x0) is required to be a multiple of 2, and the output format is consistent with the input format.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When the output is in BGRA, RGBA, ARGB formats, there is no alignment requirement for the width and height of the output.

# **common resize**

◆ Function description

The input image (NV12) is scaled to return the scaled image data (BGRA/RGBA/ARGB/NV12).

◆ Interface definition

common\_resize(const void \*input, Tensor &output, AddressLocate input locate,BsCommonParam \*param)

Parameter list

input input data pointer output output output image

input locate address properties of the input image

param image scaling parameters

◆ Parameter specification

Parameter	Supported image	Alignment	resolving power
name	types	Requirement	lesolving power
input	NV12	Width height	$2x2^{-1024}x2048$

		even alignment	
output	BGRA、RGBA、 ARGB、NV12	See Notes	2x2 ~ 1024x2048

#### ♦ Return value

0 represents success, otherwise failure.

#### Notes

- When the aspect ratio of the input and output images is inconsistent, you can select the output direct zoom image, the equal-scale zoom image filled around, and the equal-scale zoom image filled at the bottom right by padtype.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When the output is in BGRA, RGBA, ARGB formats, there is no alignment requirement for the width and height of the output.
- The memory of the input image must come from memory space (rmem/nmem) with a continuous physical address. When "input\_locate" is set to NMEM\_VIRTUAL, so the input must be a virtual address on nmem (a pointer obtained from Tensor's data/mudata interface, or a memory pointer requested through nmem\_memalign); When "input\_locate" is set to RMEM\_PHYSICAL, the input must be a physical address on rmem (the physical address of the video stream obtained through the relevant interface of the isyp platform).

#### **■** similar transform

◆ Function description

The similarity transformation matrix is calculated based on the input and output coordinates.

◆ Interface definition

similar transform(Tensor & input src, Tensor & input dst, Tesnor & output)

Parameter list

input\_src enter matrix coordinates
Input\_dst output matrix coordinates

output similarity transformation matrix parameters

◆ Parameter specification

Parameter name	data format
input_src	1*3*2*1
input_dst	1*3*2*1
output	1*3*3*1

# ◆ Return value

0 represents success, otherwise failure.

#### Notes

The call function generates a 3\*3 matrix parameter for subsequent similarity transformation calculations

# **get** affine transform

◆ Function description

The affine transformation matrix is calculated based on the input and output coordinates.

◆ Interface definition

get affine transform(Tensor &input src, Tensor &input dst, Tesnor &output)

Parameter list

input\_src coordinates of the input matrix
Input dst coordinates of the output matrix

Parameter specification

Parameter	data format	
name	uata 101111at	
input_src	1*3*2*1	
input_dst	1*3*2*1	
output	1*3*2*1	

#### ◆ Return value

0 represents success, otherwise failure.

- Notes
  - ➤ Call function to generate a 3\*2 matrix parameter for subsequent affine transformation calculations

# (The following is the old version API, which will not be updated later. It is recommended to use the API described above)

# ■ warp covert nv2bgr

◆ Function description

Perform color space conversion on the input image (NV12), returning the converted image (BGRA)

◆ Interface definition

int warp covert nv2bgr(const Tensor &input, Tensor &output)

Parameter list

input input image output output image

◆ Parameter specification

Parameter	Supported	Alignment	resolving
name	image types	Requirement	power
		Multiple of	
input	NV12	width and	$2x2^{-1024}x2048$
		height of 2	
100		Multiple of	
output	BGRA	width and	$2x2^{-1024}x2048$
	•	height of 2	

#### ♦ Return value

0 represents success, otherwise failure.

#### ◆ Notes

➤ The formula of YUV to BGR (bt601) is as follows:

B = 1.164(Y - 16) + 2.018(U - 128)

G = 1.164(Y - 16) - 0.391(U - 128) - 0.813(V - 128)

R = 1.164(Y - 16) + 1.596(V - 128)

The conversion parameters of other formats (bt709 / bt656, etc.) can be configured.

# warp resize bgra

◆ Function description

Scale the input image (BGRA) to return the scaled image (BGRA)

◆ Interface definition

int warp\_resize\_bgra(const Tensor &input, Tensor &output,
PaddingType padtype,uint8 t padval)

Parameter list

input input image output output image

padtype boundary pixel filling

padval boundary pixel fill value (BGR)

Parameter specification

Parameter name	Supported image types	Alignment Requirement	resolving power
input	BGRA	Multiple of width 2	2x2 ~ 1024x2048
output	BGRA	_	2x2 ~ 1024x2048

#### ♦ Return value

0 represents success, otherwise failure.

#### Notes

When the aspect ratio of the input and output images is inconsistent, you can select the output direct zoom image, the equal-scale zoom image filled around, and the equal-scale zoom image filled at the bottom right by padtype.

# ■ warp\_resize\_nv12

Function description

Scale the input image (NV12) to return the scaled image (BGRA/NV12)

◆ Interface definition

int warp\_resize\_nv12(const Tensor &input, Tensor &output, bool cvtbgra,PaddingType padtype, uin8 t padval)

Parameter list

input input image output output image

cvtbgra convert output image to bgra padtype boundary pixel filling method

padval pixel fill (BGR)

Parameter specification

Parameter name	Supported image types	Alignment Requirement	resolving power
input	NV12	Multiple of width and height of 2	2x2 ~ 1024x2048
output	NV12、BGRA	See Notes	2x2 ~ 1024x2048

#### ◆ Return value

0 represents success, otherwise failure.

#### Notes

- When the aspect ratio of the input and output images is inconsistent, you can select the output direct zoom image, the equal-scale zoom image filled around, and the equal-scale zoom image filled at the bottom right by padtype.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When output is in BGRA format, there is no alignment requirement for output width and height.

# crop resize bgra

◆ Function description

The input image (BGRA) is scaled based on the input boxes coordinate set, and the scaled image (BGRA) set is returned.

◆ Interface definition

int crop resize bgra(const Tensor &input, std::vector<Tensor> &output,

std::vector<Bbox t>&boxes, PaddingType padtype, uint8 t padval)

Parameter list

input input image output output image set

boxes the coordinates of the boxes that need to be scaled and the set

of widths and heights.

padtype boundary pixel filling

padval boundary pixel fill value (BGR)

◆ Parameter specification

Parameter	Supported	Alignment	resolving power
name	image types	Requirement	resolving power
input	BGRA	Multiple of	2x2 ~ 1024x2048
		width 2	
output	BGRA	_	$2x2^{-1024}x2048$
boxes	_	See Notes	$2x2 \sim 1024x2048$

#### ◆ Return value

0 represents success, otherwise failure.

#### Notes

- When the aspect ratio of the input and output images is inconsistent, you can select the output direct zoom image, the equal-scale zoom image filled around, and the equal-scale zoom image filled at the bottom right by padtype.
- The width of each box in boxes must be a multiple of 2, or Bbox\_the (x1-x0) of T is a multiple of 2.

# crop\_resize nv12

◆ Function description

The input image (NV12) is scaled by the boxes coordinate set input, and the scaled image (NV12) set is returned.

◆ Interface definition

int crop\_resize\_nv12(const Tensor &input, std::vector<Tensor> &output, std::vector<Bboxt>&boxes, PaddingType padtype, uint8 t padval)

◆ Parameter list

input input image

output image collection.

boxes the coordinates of the boxes that need to be scaled and the set

of widths and heights.

padtype boundary pixel filling.

padval boundary pixel fill value (BGR)

# Parameter specification

Parameter name	Supported image types	Alignment Requirement	resolving power
input	NV12	Multiple of width and height of 2	2x2 ~ 1024x2048
output	NV12、BGRA	Multiple of width and height of 2	2x2 ~ 1024x2048
boxes	_	See Notes	2x2 ~ 1024x2048

0 represents success, otherwise failure.

#### Notes

- When the stripped ROI image and the output image do not have the same aspect ratio, you can select the output direct zoom image, the equal-scale zoom image filled around, and the equal-scale zoom image filled at the bottom right by padtype.
- The upper left and lower right coordinates of each box in boxes must be even (divisible by 2), that is, Bbox\_t The x0, y0, x1, Y1 in the data structure must all be even numbers

# **■** common resize nv12

Function description

The input image (NV12) is scaled to return the scaled image data (BGRA/NV12).

◆ Interface definition

common\_resize\_nv12(const void \*input, Tensor &output, int img\_h, int img\_w, int line\_stride, bool cvtbgra, PaddingType padtype, uint8\_t padval, AddressLocate input locate)

#### Parameter list

input input data pointer
output output image
img\_h input image height
img\_w input image width
line stride enter image line spacing

cvtbgra whether to convert the output image to BGRA

padtype boundary pixel filling.

input\_locate enter image address properties padval boundary pixel fill value (BGR)

#### Parameter specification

a	nameter speem	cation		
	Parameter	Supported	Alignment	resolving power
	name	image types	Requirement	resolving power
			Multiple of	
	input	NV12	width and	2x2 ~ 1024x2048
			height of 2	
			Multiple of	
	output	NV12、BGRA	width and	$2x2^{-1024}x2048$
			height of 2	

# ♦ Return value

0 represents success, otherwise failure.

#### Notes

- When the aspect ratio of the input and output images is inconsistent, you can select the output direct zoom image, the equal-scale zoom image filled around, and the equal-scale zoom image filled at the bottom right by padtype.
- When the output is in NV12 format, the width and height of the output should be multiple of 2. When output is in BGRA format, there is no alignment requirement for output width and height.
- The memory of the input image must come from memory space (rmem/nmem) with a continuous physical address. When "input\_locate" is set to NMEM\_VIRTUAL, so the input must be a virtual address on nmem (a pointer obtained from Tensor's data/mudata interface, or a memory pointer requested through nmem\_memalign); When "input\_locate" is set to RMEM\_PHYSICAL, the input must be a physical address on rmem (the physical address of the video stream obtained through the relevant interface of the isvp platform).

# **■** wrap\_affine\_bgra

◆ Function description

Perform affine transformation on input image (BGRA) based on affine transformation matrix

◆ Interface definition

int wrap affine bgra(const Tensor &input, Tensor &output, Tensor &matrix)

Parameter list

input input image output output image

matrix affine transformation matrix

◆ Parameter specification

ч	rameter specification				
	Parameter	Supported image	Alignment	resolving power	
	name	types	Requirement	resorving power	
	input	BGRA	Multiple of width 2	2x2 ~ 1024x2048	
	output	BGRA	_	$2x2^{-1024x2048}$	

◆ Return value

0 represents success, otherwise failure.

◆ Notes

Default fill beyond bounds 0.

# ■ wrap\_affine nv12

Function description

Perform affine transformation on input image (NV12) based on affine transformation matrix.

◆ Interface definition

int wrap\_affine\_nv12(const Tensor &input, Tensor &output, Tensor &matrix, bool cvtbgra)

Parameter list

input input image output output image

matrix affine transformation matrix

cvtbgra output bgra image

◆ Parameter specification

rumeter specification				
Parameter	Supported	Alignment	resolving power	
name	image types	Requirement	resolving bower	
		Multiple of		
input	NV12	width and	2x2 ~ 1024x2048	
		height of 2		
		Multiple of		
output	NV12、BGRA	width and	2x2 ~ 1024x2048	
		height of 2		

◆ Return value

0 represents success, otherwise failure.

◆ Notes

➤ Default Fill Out of Boundary to Full Black.

# **■** crop\_affine\_bgra

◆ Function description

Perform a cutout on the original (BGRA) according to the input boxes, and then perform an affine transformation on the finished graph according to its affine transformation matrix.

# ◆ Interface definition

int crop\_affine\_bgra(const Tensor &input, std::vector<Tensor> &output,
std::vector<Tensor> &matrixes, std::vector<Bbox t>&boxes)

#### Parameter list

input input image

output a collection of output images

matrixes a collection of affine transformation matrices.

Boxes Boxes, the coordinates of the box that need an affine

transformation and a set of width and height.

# Parameter specification

Parameter name	Supported image types	Alignment Requirement	resolving power
input	BGRA	Multiple of width 2	2x2 ~ 1024x2048
output	BGRA	-	2x2 ~ 1024x2048
boxes	_	See Notes	$2x2 \sim 1024x2048$

#### ◆ Return value

0 represents success, otherwise failure.

#### Notes

The width of each box in boxes must be a multiple of 2, that is,  $bbox_(x1-x0)$  of T is a multiple of 2.

# **■** crop affine nv12

# ◆ Function description

Match the original graph (NV12) according to the input boxes, then affine transform the finished graph according to their affine transformation matrix.

#### ◆ Interface definition

int crop\_affine\_nv12(const Tensor &input,std::vector<Tensor> &output, std::vector<Tensor> &matrixes, bool cvtbgra, std::vector<Bbox t>&boxes)

# ◆ Parameter list

input image

output image collection

matrixes a collection of affine transformation matrices.

boxes the coordinates of the box that need an affine transformation

and a set of width and height.

cvtbgra whether to output images in BGRA format.

#### • Parameter specification

Parameter	Supported	Alignment	resolving power
name	image types	Requirement	resolving power
		Multiple of	
input	NV12	width and	2x2 ~ 1024x2048
		height of 2	
		Multiple of	
output	NV12、BGRA	width and	2x2 ~ 1024x2048
		height of 2	
boxes	_	See Notes	2x2 ~ 1024x2048

#### ♦ Return value

0 represents success, otherwise failure.

#### Notes

The upper left and lower right coordinates of each box in boxes must be even (divisible by 2), that is, x0, y0, x1, Y1 in the Bbox\_t data structure must be even.

# **■** wrap perspective bgra

Function description

Perform perspective transformation on the input image (BGRA) based on the perspective transformation matrix.

◆ Interface definition

int wrap perspective bgra(const Tensor &input, Tensor &output, Tensor &matrix)

◆ Parameter list

input input image output output image

matrix perspective transformation matrix

◆ Parameter specification

Parameter name	Supported image types	Alignment Requirement	resolving power
input	BGRA	Multiple of width 2	2x2 ~ 1024x2048
output	BGRA	-	$2x2 \sim 1024x2048$

#### ◆ Return value

0 represents success, otherwise failure.

♦ Notes

➤ Default fill beyond bounds 0

# **■** wrap perspective nv12

Function description

Performs a perspective transformation operation on the input image (NV12) according to the perspective transformation matrix.

◆ Interface definition

int wrap\_perspective\_bgra(const Tensor &input, Tensor &output, Tensor &matrix, bool cvtbgra)

Parameter list

input input image output image

matrix perspective transformation matrix

evtbgra whether to output images in BGRA format.

◆ Parameter specification

Parameter	Supported	Alignment	resolving power
name	image types	Requirement	legolving bower
		Multiple of	
input	NV12	width and	$2x2^{-1024}x2048$
		height of 2	
		Multiple of	
output	NV12、BGRA	width and	2x2 ~ 1024x2048
		height of 2	

#### ◆ Return value

0 represents success, otherwise failure.

Notes

The default fill beyond the boundary is all black.

# **■** crop perspective bgra

# ◆ Function description

Based on the input boxes, a cutout operation is performed on the original graph (BGRA), and then a perspective transformation is performed on the finished graph according to its respective perspective transformation matrix.

# ◆ Interface definition

int crop\_perspective\_bgra(const Tensor &input, std::vector<Tensor> &output,
std::vector<Tensor> &matrixes, std::vector<Bbox t>&boxes)

# Parameter list

input input image

output output image collection.

matrixes a collection of affine transformation matrices.

boxes the coordinates of the box that need an affine transformation

and a set of width and height.

# ◆ Parameter specification

Parameter	Supported	Alignment	resolving power
name	image types	Requirement	resorving power
input	BGRA	Multiple of width 2	2x2 ~ 1024x2048
output	BGRA	-	$2x2^{-1}$ 1024x2048
boxes	_	See Notes	2x2 ~ 1024x2048

# ♦ Return value

0 represents success, otherwise failure.

# Notes

The width of each box in boxes must be a multiple of 2, that is, the Bbox\_t's (x1-x0) is a multiple of 2.

# **■** crop perspective nv12

# Function description

The input boxes are used to perform a cutout operation on the original (NV12), and then the cutouts are transformed into perspective according to their respective perspective transformation matrices.

# ◆ Interface definition

int crop\_perspective\_nv12(const Tensor &input, std::vector<Tensor> &output,
std::vector<Tensor> &matrixes, bool cvtbgra, std::vector<Bbox t>&boxes)

#### ◆ Parameter list

input input image

output output image collection.

matrixes a collection of affine transformation matrices.

boxes the coordinates of the box that need an affine transformation

and a set of width and height.

cvtbgra whether to output images in BGRA format.

# ◆ Parameter specification

Parameter	Supported	Alignment	resolving power	
name	image types	Requirement	resolving power	
		Multiple of		
input	NV12	width and	$2x2^{-1024}x2048$	
		height of 2		
		Multiple of		
output	NV12、BGRA	width and	$2x2^{-1024}x2048$	
		height of 2		

boxes	_	See Notes	2x2 ~ 1024x2048

♦ Return value

0 represents success, otherwise failure.

NotesNotesNotesNotes

The upper left and lower right coordinates of each box in boxes must be even (divisible by 2), that is, x0, y0, x1, y1 in the Bbox t data structure must be even.

# Network post-processing API

#### **■** nms

Function description

Non-maximum suppression of Bbox output from target detection network

◆ Interface definition

void nms(std::vector<ObjBbox\_t> &input, std::vector<ObjBbox\_t> &output,
float nms threshold = 0.3, NmsType type = NmsType::HARD NMS)

Parameter list

input input coordinate box array output output coordinate box array

nms threshold threshold of NMS

type type of NMS (HARD\_NMS, SOFT\_NMS)

Return value None

# **■** generate box

Function description

Generate candidate boxes according to anchor.

◆ Interface definition

void generate\_box(std::vector<Tensor> &features, std::vector<float> &strides,
std::vector<float> &anchor, std::vector<ObjBbox\_t> &candidate\_boxes,
int img\_w, int img\_h, int classes, int box\_num,float box\_score\_threshold,
DetectorType detector\_type = DetectorType::YOLOV3)

Parameter list

features input features map

strides the downsampling multiple corresponding to the input features

map

anchor preset anchor

candidate\_boxes generated candidate box width of network input image

img\_h the height of the network input image classes number of categories for target detection.

box num number of boxes per anchor point.

box\_score\_threshold score threshold for filtering redundant boxes detector\_type type of detector (yoov3 series or yoov5 Series)

◆ Return value

None

# Memory management API

# ■ nmem\_malloc

Function description

Request a block of memory space on nmem based on the number of bytes entered, and return the corresponding first address pointer.

◆ Interface definition

void \*nmem malloc(unsigned int size)

Parameter list

size the number of bytes of memory that need to be requested.

◆ Return value

NULL indicates that the request failed, otherwise returns the first address pointer corresponding to the block of memory requested

# ■ nmem memalign

◆ Function description

Requests a block of memory space on nmem based on the number of bytes entered, aligns the first address to the specified number of bytes, and returns the corresponding first address pointer.

◆ Interface definition

void \*nmem memalign(unsigned int align,unsigned int size)

◆ Parameter list

align the first address of the memory block is aligned by alignment

bytes.

size the number of bytes of memory that need to be requested.

◆ Return value

NULL indicates that the request failed, otherwise the first address pointer corresponding to the block of memory requested is returned.

#### **■** nmem free

◆ Function description

Freeing nmem memory pointed to by input pointer

◆ Interface definition

void nmem free(void \*ptr)

Parameter list

ptr pointer to nmem memory block

◆ Return value

None

#### **■** memcopy

◆ Function description

Copy a block of data from the source address to the destination address.

◆ Interface definition

void memcopy(void \*dst, void \*src, int n)

◆ Parameter list

dst destination address src source address

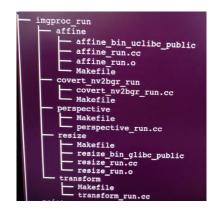
n number of bytes to copy

♦ Return value

None

# **Complete example:**

After obtaining the magik software package, please refer to the directory for details: your\_root/InferenceKit/nna1/mips720-glibc229/sample/imgproc\_run/

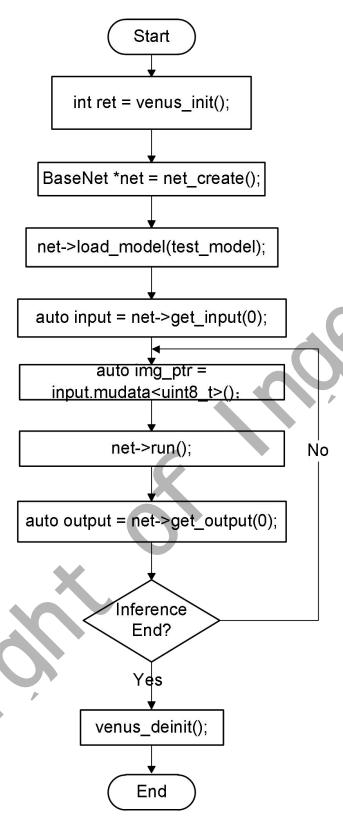


# 2.4 Inference process

For your convenience, Venus has a good API design that hides a lot of details that you don't need to invest time in. You only need seven simple steps to complete model forward inference using Venus on T40 and T02 chip platforms.

- 1. System initialization. Call venus Init, complete the initialization of the system environment.
- 2. Create a BaseNet handle. By calling net\_create, this interface creates a handle to the inference engine.
- 3. Load the model. Load the required models for inference by calling "load\_model" from the BaseNet handle.
- 4. Prepare the input data. Takes the input node Tensor of the model and copies the image data into a tensor by calling "get\_input" from the BaseNet handle.
  - 5. Perform reasoning. Model inference is performed by calling the BaseNet handle method, run.
- 6. Get results. Gets the output node Tensor of the model by calling get\_output from the BaseNet handle.
  - 7. Call venus\_deinit to release the system resources.

The specific inference flow is shown in Figure 2-1.



The inference examples configuration is as follows:

- 1. test\_model represents the file of model name.
- 2. The model have only one input node and one output node.

Figure 2-1 Venus Inference workflow

# 2.4.1 Operator set

Operator type	Reasoning bit width	remarks		
Convolution	8bit/4bit/2bit			
DepthWiseConvolution	8bit/4bit/2bit			
BatchNorm	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
BiasAdd	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
FullConnected	8bit/4bit/2bit			
Pooling	12bit/10bit/8bit/4bit/2bit	MaxPool/AvgPool/GlobalAvgPool		
UpSamp1e	Float/12bit/10bit/8bit/4bit/2bit			
Relu	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
Relu6	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
PRe1u	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
LeakyRelu	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
Silu	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
Tanh	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
Sigmoid	8bit/4bit/2bit	When reasoning, it is integrated into convolution		
Swish	8bit	When reasoning, it is integrated into convolution		
Lstm	8bit/4bit			
Concat	8bit/10bit/12bit			
Softmax	Float			
Mul	Float/12bit/10bit/8bit/4bit/2bit			
Add	12bit/10bit/8bit/4bit/2bit			
Eltwise	12bit/10bit/8bit	Min/Max/Sub		
Sum	Float			
Permute	8bit			
Slice	8bit/4bit/2bit			
Padding	8bit			
Normalize	8bit/10bit/12bit			
Table 2.1 Venus Operator list				

Table 2-1 Venus Operator list

# 2.4.1.1 Convolution Operator Description

Input bit width

2bit

4bit

8bit

Parameter support

Weight bit width

2bit/4bit

2bit/4bit/6bit/8bit

2bit/4bit/6bit/8bit

Output bit width	2bit/4bit/8bit/ float	2bit/4bit/8bit/float	4bit/8bit/float
Kernel Size	arbitrarily	arbitrarily	arbitrarily
Stride	<=2	<=2	<=2
Dilation	support	support	support
Batch	Not Supported	support	support
Act Tpye	relu/relu6	relu/relu6/prelu/leaky_r elu/tanh/silu/sigmoid/sw ish	relu/relu6/prelu/leaky_re lu/tanh/silu/sigmoid/swis h

Table 2-2 Convolution Operator Description

# 2.4.1.2 DepthWiseConvolution Operator Description

Input bit width Parameter support	2bit	4bit	8bit
Weight bit width	2bit/4bit	2bit/4bit	2bit/4bit/6bit/8bit
Output bit width	2bit/4bit	2bit/4bit	8bit
Kernel Size	arbitrarily	arbitrarily	arbitrarily
Stride	arbitrarily	arbitrarily	<=2
Batch	support	support	support
Act Tpye	relu/relu6	relu/relu6	relu/relu6/prelu/leaky_rel u/tanh/silu/sigmoid/swish

Table 2-3 DepthWiseConvolution Operator Description

# 2.4.1.3 FullConnected Operator Description

Input bit width			
Parameter	2bit	4bit	8bit
support			

Weight bit width	2bit/4bit/8bit	2bit/4bit/8bit	2bit/4bit/8bit		
Output bit width	2bit/4bit/float	2bit/4bit/8bit/float	8bit/float		
Batch	Not Supported	Not Supported	support		
Act Tpye	When output bit width is float supportrelu/relu 6/prelu/leaky_re lu/tanh/silu/sig moid/swish, For other bit widths supportrelu/relu 6	When output bit width is float supportrelu/relu6/prelu/ leaky_relu/tanh/silu/sig moid/swish, For other bit widths supportrelu/relu6	relu/relu6/prelu/leaky_re lu/tanh/silu/sigmoid/swis h		
Table 2-4 FullConnected Operator Description  2.4.1.4 Add Operator Description					
Input bit width Parameter support	2bit	4bit 8b	oit 10bit/12bit		

Parameter support	2bit	4bit	8bit	10bit/12bit
Batch	support	support	support	support
Act Tpye	None Tabl	RELU/NONE/LINEAR/R ELU6/HARD_SIGMOID TANH/SWISH/SIGMOID /SILU/LEAKY_RELU e 2-5 Add Operator De	NONE/RELU/RELU6/ SWISH/TANH/SIGMO ID	NONE/RELU/RELU6/ SWISH/TANH/SIGMO ID
2.4.1.5 Mul Operate		-	r	
Input bit	-			

Input bit width Parameter support	2bit	4bit	8bit/10bit/12bit	Fp32
Batch	support	support	support	support
Broadcast type	SINGLE/CHANNE L/ELEMET/SPAT IAL	SINGLE/CHANNEL /ELEMET/SPATIAL	SINGLE/CHANNEL /ELEMET/SPATIAL	CHANNEL

Table 2-6 Mul Operator Description

# 2.4.1.6 Pooling Operator Description

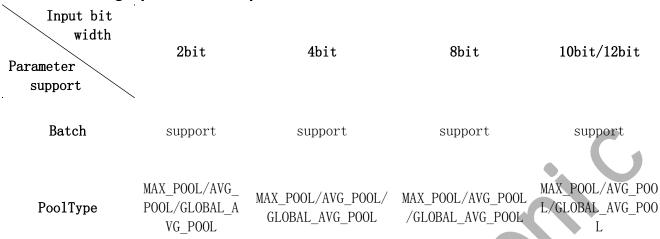


Table 2-7 Pooling Operator Description

# 2.4.1.7 Upsample Operator Description

Input bit width Parameter support	2bit	4bit	8bit	10bit/12bit	Fp32
Batch	support	support	support	support	support
UppType	FILL_ZERO/ NEARST/ PIXEEL_SHUFFL E/ RII INFAR	FILL_ZERO/ NEARST/ PIXEEL_SHUFFL E	FILL_ZERO/ NEARST/ PIXEEL_SHUFFLE	NEARST	FILL_ZERO/ NEARST
	RTI TNFAR		erator Description		

# 2.4.1.8 Concat Operator Description

Input bit width Parameter support	8bit	10bit	12bit
Batch	support	support	support

Table 2-9 Concat Operator Description

# 2.4.1.9 Normalize Operator Description

Input bit width Parameter support	8bit	10bit	12bit		
Batch	Not Supported	Not Supported	Not Supported		
	Table 2-10 Norm	alize Operator Description			

# 2.4.1.10 LSTM Operator Description

Input bit width

4bit

Parameter

support
Weight bit width

4bit

2bit/4bit/6bit/8bit

8bit

Output bit width

4bit

8bit

Batch

Not Supported

Not Supported

Table 2-11 LSTM Operator Description

# 2.4.1.11 Eltwise Operator Description

Input bit width

8bit

10bit

12bit

Parameter support

BATCH

Not Supported

Not Supported

Not Supported

EltwiseType

Sub/Max/Min

Sub/Max/Min

Sub/Max/Min

Table 2-12 Eltwise Operator Description

# 2.4.1.12 Sum Operator Description

Input bit width

float

Parameter support

\_ .

Batch

support

AXIS

2 (in width direction)

Table 2-13 Sum Operator Description

# 2.4.1.13 Softmax Operator Description

Input bit

width

float

Parameter

support

Batch

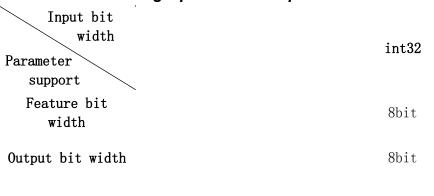
Not Supported

AXIS

2 (in width direction)/
3 (in channel direction)

Table 2-14 Softmax Operator Description

# 2.4.1.14 Embedding Operator Description



Batch Not Supported

Table 2-15 Embedding Operator Description

# 2.4.1.15 Padding Operator Description

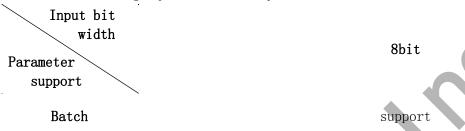


Table 2-16 Padding Operator Description

# 2.4.1.16 Slice Operator Description



Table 2-17 Slice Operator Description

# 2.4.1.17 Permute Operator Description



Table 2-18 Permute Operator Description

#### 2.4.2 Profiler Tool

Profiler is used to analyze the detailed running time of each layer of the network, the running time and the number of calls for each type of operator, and other related information, so that users can better optimize the network model structure. The statistical results of each layer of the network mainly include layer name, operator type, input feature size, output feature size, weight size, Stride information, Pad information, convolution expansion factor, current layer running time, current layer running time proportion, current layer GOPs and current layer bandwidth, etc. Profiler's

overall summary results include information such as operator type, operation time of each operator, time percentage, GOPs, bandwidth, and number of calls.

# 2.4.2.1 Opening method

When compiling a Venus-based executable with links, linking libvenus.p.so opens the Profiler tool to perform network performance analysis.

# **2.4.2.2** Use example

Instantiate the model handle to be analyzed in the main function, and then call the run interface repeatedly. After the model is executed, the profiler log information similar to the following figure will be automatically printed. Figure 2-2 is the detailed statistical information of each layer of the network, and figure 2-3 is the statistical summary information of the whole model.

	i, and figure	2 3 15 tile	Statistical	Summa	y IIIIO	matio	I OI U	IC WI	ioic i	iiiou	J1.		4
[I/magik::ven Timing cycle													
	– 5 d DispatchProfiler Sum	mary N/A Evolude	Awarm-uns =====										
LayerName	OperatorType	InputShape	OutputShape	FilterShape	Stride	Pad	Dila			Min(ms)	Last(ms)		GOPs
475	Convolution	{1,224,224,4}	{1,112,112,64}	{3,3,4,64}				0.247	0.292	0.236	0.2360	2.68%	0.058
476	Pooling	{1,112,112,64}	{1,55,55,64}	{3,3}	{2,2}	{0,0,0,0}		0.076	0.082	0.075	0.0750		0.002
485	Convolution	{1,55,55,64}	{1,55,55,64}	{1,1,64,64}		{0,0,0,0}	{1,1}	0.162	0.166	0.161	0.1610	1.76%	0.025
495	Convolution	{1,55,55,64}	{1,55,55,64}	{3,3,64,64}			{1,1}	0.149	0.154	0.148			0.223
504	Convolution	{1,55,55,64}	{1,55,55,256}	{1,1,64,256}		{0,0,0,0}	{1,1}	0.223	0.223	0.223			0.099
513	Convolution	{1,55,55,64}	{1,55,55,256}	{1,1,64,256}	{1,1}	{0,0,0,0}		0.223	0.223	0.223	0.2230	2.42%	0.099
523	Add	{1,55,55,512}	{1,55,55,256}					0.099	0.102	0.098	0.0980	1.07%	0.001
532	Convolution	{1,55,55,256}	{1,55,55,64}	{1,1,256,64}	{1,1}	{0,0,0,0}	{1,1}	0.184	0.184		0.1840	2.00%	0.099
542	Convolution	{1,55,55,64}	{1,55,55,64}	{3,3,64,64}			{1,1}	0.148	0.148	0.147			
551	Convolution	{1,55,55,64}	{1,55,55,256}			{0,0,0,0}					0.2230	2.42%	0.099
561		{1,55,55,512}	{1,55,55,256}					0.098		0.098			0.001
570	Convolution	{1,55,55,256}	{1,55,55,64}	{1,1,256,64}		{0,0,0,0}		0.184	0.184	0.184	0.1840		
580	Convolution	{1,55,55,64}	{1,55,55,64}	{3,3,64,64}			{1,1}	0.148			0.1480		
589	Convolution	{1,55,55,64}	{1,55,55,256}	{1,1,64,256}	{1,1}	{0,0,0,0}		0.223		0.223	0.2230	2.42%	0.099
599		{1,55,55,512}	{1,55,55,256}						0.099	0.098	0.0980		
608						{0,0,0,0}				0.204	0.2040		
618			{1,28,28,128}							0.125			
627						{0,0,0,0}							
636		{1,55,55,256}				{0,0,0,0}							
646		{1,28,28,1024}	{1,28,28,512}										
655		{1,28,28,512}											
665													
674						{0,0,0,0}							
684			{1,28,28,512}										
693													
703													
712													
722													
731						{0,0,0,0}							
741													
750													
760								0.057					
700		27 AA AA 81A1	21 22 22 222	21 1 F10 0F20	44 44		61 11	0.150	0.150	0.140	0.1400		0.000

Figure 2-2 Profiler Statistical results of each layer

```
[I/magik::venus]:
Timing cycle = 5
==== Concise Dispatch Profiler Summary: N/A, Exclude 0 warm-ups =====
OperatorType
                     Avg(ms) Max(ms) Min(ms) Avg(%)
                                                               CalledTimes
Add
                              0.738
                                      0.732
                                              7.95%
                                                       0.005
Convolution
                      8.392
                              8.493
                                      8.358
                                              91.03%
                                                        7.941
                                                                53
Pooling
                      0.094
                              0.103
                                      0.092
                                              1.02%
                                                       0.002
```

Figure 2-3 Profiler Overall statistical results

# 2.4.3 Complete example

After obtaining the magik package, please refer to the directory of your\_root/magik-toolkit/Models/post/soc sample/T40/venus sample ptq yolov5s/ for details.