c:5 d:8 e:13 f:21 g:34 h:15 i:27 j: 9 (10%) The recurrence of Procedure CUT-ROD(p, n) is given by $T(n) = 1 + \sum_{j=1}^{n-1} T(j)$, with T(0) = 1. 5. Follow depth-first search (DFS), starting from Node 3. to traverse the graph shown below.

2. The problem of optimal parenthesization over a chain of matrix multiplications can be solved by a divide-and-conquer approach recursively. Let m[i, j] denote the minimum number of scalar multiplications needed to compute $A_i \cdot A_{i+1} \cdot A_{i+2} \cdot \cdots \cdot A_j$, with A_k sized as $P_{k-1} \times P_k$ (for $i \le k \le j$), give the recurrence definition of the problem. (10%)

The recurrence leads to exponential complexity but can be solved by dynamic programming much faster. What is the resulting time complexity and how do you get that complexity result? (6%)

3. Given a set of 4 keys, with the following probabilities, determine the cost and the structure of an optimal binary search tree, following the tabular, bottom-up method realized in the procedure of OPTIMAL-BST below to construct and fill e[1..5, 0..4], w[1..5, 0..4], and root[1..4,1..47.

i	0	ndere l	2 genera	3	time complexity of A		
Pi		0.12	0.08	0.15	0.18	are to the report	
q_i	0.08	0.06	0.09	0.10	0.14		van
3 3 st	atement	s in the	procedu	ire. (6	%)	W, E,	000

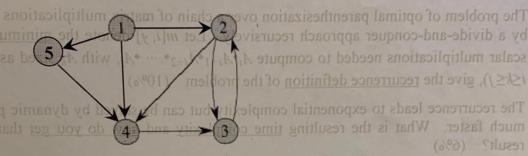
(a) Fill in the missing 3 statements in the procedure. (6%)

(b) Construct and fill the three tables, and show the optimal BST obtained. (30%)

```
OPTIMAL-BST(p,q,n)
     let e[1..n+1,0..n], w[1..n+1,0..n],
               and root[1..n, 1..n] be new tables
      for i = 1 to n + 1
  3
          e[i, i-1] = q_{i-1}
          w[i, i-1] = q_{i-1}
  5
     for l = 1 to n
          for i = 1 to n - l + 1
  6
              j = i + l - 1
  7
              e[i, j] = \infty
 8
              w[i, j] = w[i, j-1] + p_j + q_j
 9
              for r = i to
10
11
                   if t < e[i, j]
12
13
14
    return e and root
```

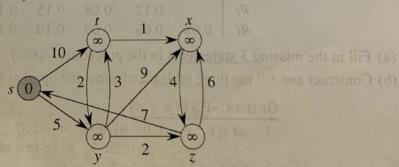
1. The recurrence of Procedure CUT-ROD(p, n) is given by T(n) = 1 + T

5. Follow depth-first search (*DFS*), starting from Node 3, to traverse the graph shown below. Mark (1) the type of every edge and (2) the discovery and the finish times of each node.



6. The Dijkstra's algorithm (DIJ) solves the single-source shortest-path problem in a weighted directed graph G = (V, E). Given the graph G below, follow DIJ to find shortest paths from vertex s to all other vertexes, with all predecessor edges shaded and estimated distance values from s to all vertexes provided at the end of each iteration. (12%)

What is the time <u>complexity</u> of *DIJ* for a general graph G = (V, E), if candidate vertexes are kept in a binary min-heap? (4%)



Good luck!