- 1. The recurrence of Procedure CUT-ROD(p, n) is given by $T(n) = 1 + \sum_{j=0}^{n-1} T(j)$, with T(0) = 1. Solve T(n). (12%)
- 2. The problem of optimal parenthesization over a chain of matrix multiplications can be solved by a divide-and-conquer approach recursively. Let m[i, j] denote the minimum number of scalar multiplications needed to compute $A_i \cdot A_{i+1} \cdot A_{i+2} \cdot \cdots \cdot A_j$, with A_k sized as $p_{k-1} \times p_k$ (for $i \le k \le j$), give the recurrence definition of the problem. (10%)

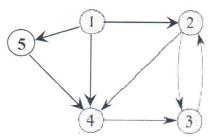
The recurrence leads to exponential complexity but can be solved by dynamic programming much faster. What is the resulting <u>time complexity</u> and <u>how do you get</u> that complexity result? (6%)

3. Given a set of 4 keys, with the following probabilities, determine the <u>cost</u> and the <u>structure</u> of an <u>optimal binary search tree</u>, following the <u>tabular</u>, <u>bottom-up method</u> realized in the procedure of OPTIMAL-BST below to construct and fill e[1..5, 0..4], w[1..5, 0..4], and root[1..4, 1..4].

- (a) Fill in the missing 3 statements in the procedure. (6%)
- (b) Construct and fill the three tables, and show the optimal BST obtained. (30%)

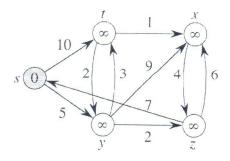
```
OPTIMAL-BST(p,q,n)
 1 let e[1...n+1,0...n], w[1...n+1,0...n],
             and root[1..n, 1..n] be new tables
    for i = 1 to n + 1
 3
         e[i, i-1] = q_{i-1}
         w[i, i-1] = q_{i-1}
 4
 5
    for l = 1 to n
 6
         for i = 1 to n - l + 1
 7
             i = i + l - 1
 8
             e[i,j] = \infty
 9
             w[i, j] = w[i, j-1] + p_i + q_i
10
11
12
13
14
15 return e and root
```

- 4. Show your construction of an optimal Huffman code for the set of 7 frequencies: a:2 b:3 c:5 d:8 e:13 f:21 g:34 h:15 i:27 j:9. (10%)
- **5.** Follow depth-first search (*DFS*), starting from Node 3, to traverse the graph shown below. Mark (1) the type of every edge and (2) the discovery and the finish times of each node. (10%)



6. The Dijkstra's algorithm (DIJ) solves the single-source shortest-path problem in a weighted directed graph G = (V, E). Given the graph G below, follow DIJ to find shortest paths from vertex s to all other vertexes, with all <u>predecessor edges shaded</u> and <u>estimated distance values</u> from s to all vertexes <u>provided</u> at the end of each iteration. (12%)

What is the time <u>complexity</u> of *DIJ* for a general graph G = (V, E), if candidate vertexes are kept in a binary <u>min-heap</u>? (4%)



Good luck!