

Part II

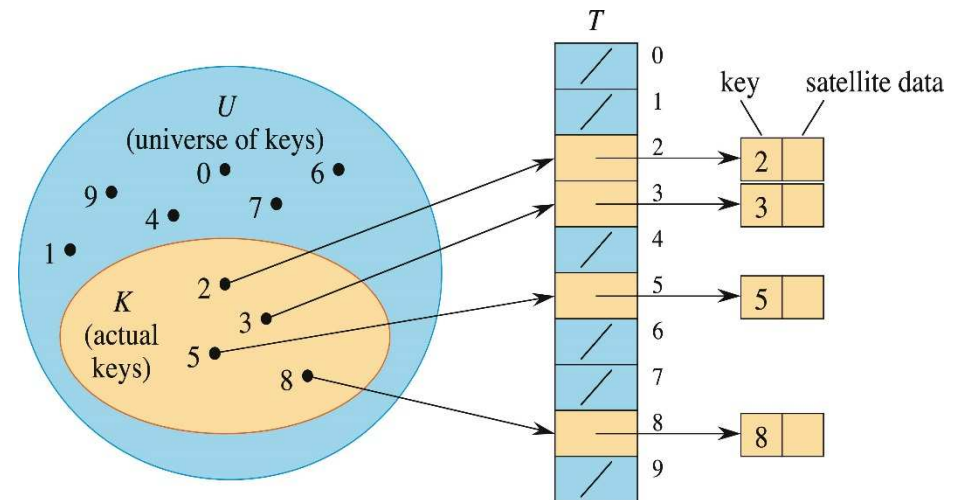
Data Structures

§ Three Types of Data Structures Considered:

- Hash Tables
- Trees
- Heaps

• Hash Table

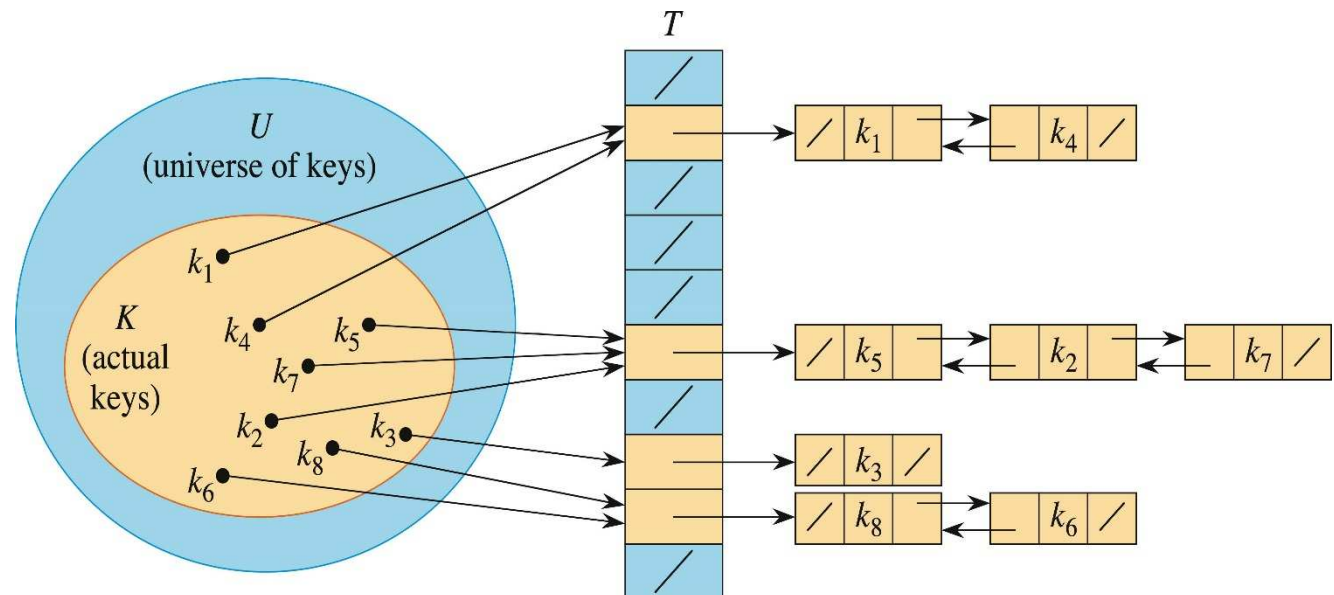
- suitable for large key space with small numbers of actual keys stored
- average search time over the hash table equal to $O(1)$
- collision-handling strategy required
- keys must be stored to ensure right items retrieved
- hash function maps a key to one table index



Hash Tables (continued)

- **Hash Table with Collision Resolution by Chaining**

- multiple elements with different keys mapped to the same table entry (collisions)
- they can be chained, with a lookup going through the chain
- for load factor of $\alpha = n/m$, where n (or m) is the number of elements (or table entries)
- under uniform distribution, one search (be successful or not) takes $\Theta(1+\alpha)$,
according to **Theorems 11.1 and 11.2**
- if hash table size (m) grows in proportion to n , then the mean search time is $\Theta(1)$
- there are other more efficient ways for handling collisions



Hash Tables (continued)

- **Hash Functions**

- division method
- multiplication method

- 1. Division method:** (more restrictive on the suitable m)

$h(k) = k \bmod m$, where the choice of $m = 2^p - 1$ is poor but
a prime not close to an exact power of 2 is often good

For example, given $n = 2000$ character strings to be stored in a hash table with
 $m = 701$ entries, then an unsuccessful search takes some 3 accesses

Hash Tables (continued)

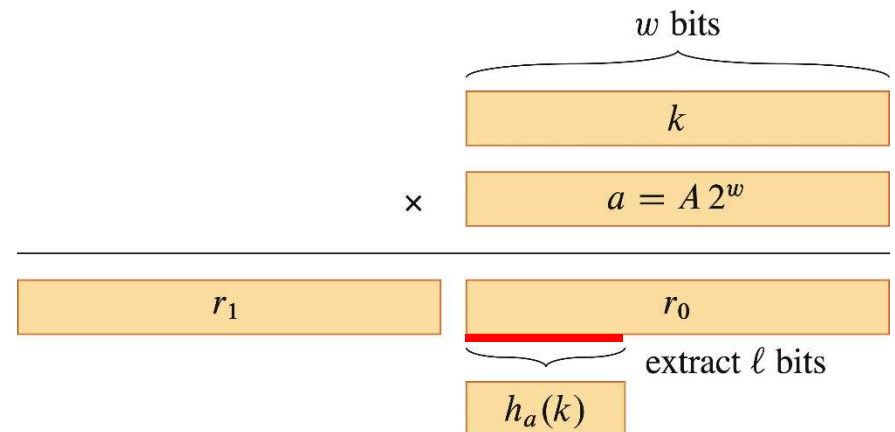
2. Multiplication method:

- Multiply k by a constant A , with $0 < A < 1$ and extract the fraction part of $k \cdot A$, e.g., $h(k) = \lfloor m (kA \bmod 1) \rfloor$, where " $kA \bmod 1$ " equals $kA - \lfloor kA \rfloor$

- table size (m) can be arbitrary, e.g., $m = 2^p$
- let A be a fraction of the form $s/2^w$ as shown in the figure below
- perform multiplication of w -bit k and w -bit s , to get a $2w$ -bit product
- product denoted by $r_1 \cdot 2^w + r_0$, then p -bit hash value is obtained from r_0
- while arbitrary A works, $A \approx (\sqrt{5} - 1)/2 = 0.6180339887 \dots$ recommended

Golden ratio: a root of $x^2 + x - 1 = 0$.

+ Let $k = 123456$, $p = 14$, $m = 2^{14}$, $w = 32$
 and $A = 2654435769/2^{32}$, we have
 $k \cdot s = (76300 \cdot 2^{32}) + 17612864$ to get $h(k) = 67$.



Hash Tables (continued)

- **Properties of Random Hashing**

- family of hash functions, \mathcal{H} , with domain U and range $R = \{0, 1, \dots, m-1\}$
- \mathcal{H} is uniform if probability of hashing a key k , $h(k)$, to q in R equals $1/m$
- \mathcal{H} is *universal* if probability of distinct keys, k_1 and k_2 , with $h(k_1) = h(k_2)$ is $\leq 1/m$
- \mathcal{H} is ε -*universal* if probability of distinct keys, k_1 and k_2 , with $h(k_1) = h(k_2)$ is $\leq 1/\varepsilon$
- \mathcal{H} is *d-independent* if distinct keys, k_1, k_2, \dots, k_d , and slots of q_1, q_2, \dots, q_d in R , with $h(k_i) = h(q_i)$ for all $1 \leq i \leq d$, has the probability of $1/m^d$

Hash Tables (continued)

- **Universal Hashing**

For the hash function of $h_{ab}(k) = ((a \cdot k + b) \bmod p) \bmod m$, where p is a large prime number, with $p > m$, $a \in \{1, 2, \dots, p-1\}$ and $b \in \{0, 1, 2, \dots, p-1\}$, the collection of such hash functions is *universal*.

In this case, m can be any number and does not have to be a prime.
For example, for $p = 17$ and $m = 8$, we have $h_{34}(15) = 7$.

$$((3 \cdot 15 + 4) \bmod 17) \bmod 8 = 7$$

Hash Tables (continued)

- **Open Addressing** (to deal with collision-chaining)
 - elements stored inside the table
 - calculating probe sequence of given key, instead of using pointers:
 $\langle h(k, 0), h(k, 1), h(k, 2), \dots, h(k, m-1) \rangle$
 - if probe sequence is a permutation of $\langle 0, 1, 2, \dots, m-1 \rangle$, every table entry is a candidate location for the element
 - the probe sequence is fixed for a given key
 - key has to be stored in the table entry

HASH-INSERT(T, k)

```
 $i = 0$   
repeat  
     $q = h(k, i)$   
    if  $T[q] == \text{NIL}$   
         $T[q] = k$   
        return  $q$   
    else  $i = i + 1$   
until  $i == m$   
error “hash table overflow”
```

HASH-SEARCH(T, k)

```
 $i = 0$   
repeat  
     $q = h(k, i)$   
    if  $T[q] == k$   
        return  $q$   
     $i = i + 1$   
until  $T[j] == \text{NIL}$  or  $i = m$   
return NIL
```


Hash Tables (continued)

- **Uniform Hashing Analysis on Open Addressing**

- key probe sequence equal likely in one of $m!$ permutations of $\langle 0, 1, 2, \dots, m-1 \rangle$

- probe sequences defined for open addressing

- + linear probing: m different sequences

- dictated by $h(k, i) = (h'(k) + i) \bmod m$

- subject to *primary clustering*

- + quadratic probing: m different sequences

- dictated by $h(k, i) = (h'(k) + c_1 \cdot i + c_2 \cdot i^2) \bmod m$

- subject to *secondary clustering*, i.e., $h(k_1, 0) = h(k_2, 0) \Rightarrow$ both keys follow the same probe sequence

- + double hashing: m^2 different sequences

- dictated by $h(k, i) = (h_1(k) + i \cdot h_2(k)) \bmod m$

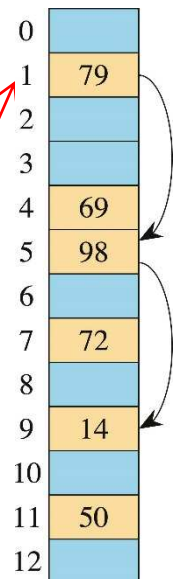
- many good choices: $h_2(k)$ relatively prime to m ; m itself a prime; m a power of 2 and $h_2(k)$ always an odd number; or below:

- m a prime and m' slightly less than m (e.g., $m-1$ or $m-2$) with

- $h_1(k) = k \bmod m$

- $h_2(k) = 1 + (k \bmod m')$

e.g., for $k=14$ under $m=13$, $m'=11$;
upon inserting $k=14$.



Hash Tables (continued)

• Open-Address Hashing Analysis

Theorem 1:

For an open-address hash table with load factor $\alpha = n/m < 1$, the expected number of probes in unsuccessful search under uniform hashing is at most $1/(1 - \alpha)$.

Note: unsuccessful search ends at seeing an empty entry.

- + if α is a constant, an unsuccessful search runs in $O(1)$ time
- + inserting an element into an open-address hash table with load factor α takes at most $1/(1 - \alpha)$ probes on an average under uniform hashing, because it has $(1-\alpha)$ for 1 probe, plus prob. $\alpha(1-\alpha)$ to take 2 probes, plus prob. $\alpha^2(1-\alpha)$ to take 3 probes, etc., yielding $1 + \alpha + \alpha^2 + \alpha^3 + \dots = 1/(1 - \alpha)$

e.g., for $\alpha = 50/100$, we have 2 probes.

Theorem 2:

For an open-address hash table with load factor $\alpha < 1$, the expected number of probes in a successful search under uniform hashing is at most $\frac{1}{\alpha} \cdot \ln \frac{1}{1 - \alpha}$.

- successful search for a key equals the sequence of inserting the key

2nd key insertion takes $\leq 1/(1 - (1/m))$ probes, on an average, when α is $1/m$

3rd key takes $\leq 1/(1 - (2/m))$ probes, on an average, when α is $2/m$

:

$i+1^{\text{th}}$ key takes $\leq 1/(1 - (i/m))$ probes

Mean no. of probes equals results over all n keys inserted

This is because **insertion and probes** follow the same hash function.

We have: $1/n (\sum_{i=0}^{n-1} 1/(1 - i/m))$

e.g., for $\alpha = 50/100$, we have ≈ 1.39 probes, as $\ln(2) \sim 0.693$. (base $e \sim 2.718$)

Hash Tables (continued)

- **Cuckoo Hashing**[§]

- move keys around upon insertion for worst probe case of $O(1)$
 - + quick search but possibly lengthy insertion
 - + multiple hash functions required for separate hash tables

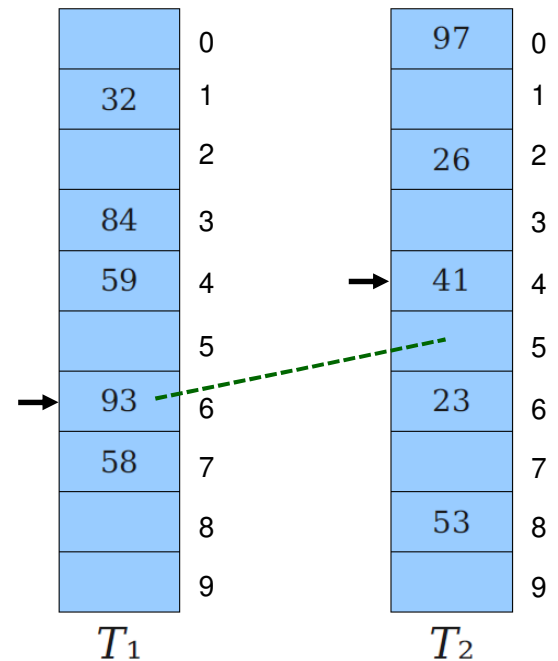
- delete keys in the worst-case of $O(1)$

- example with two hash functions below:

- + two hash tables, each with m elements
- + two hash functions, h_1 and h_2 , one for a table
- + each key x at either $h_1(x)$ or $h_2(x)$
- + new key '10' with $h_1(10) = 6$ and $h_2(10) = 4$
 - * move key '93' around, if $h_2(93)=5$, for insertion

- Algorithm

1. insert "new key" to T_1 located at $h_1(\text{new key})$, when available
2. otherwise, "new key" displaces "existing key" in T_1 ; place "existing key" in T_2 located at $h_2(\text{existing key})$; repeat the displacement process, if needed.



§ R. Pagh and F. Rodler, "Cuckoo Hashing," *Journal of Algorithms*, Aug. 2001, pp. 121-133.

Hash Tables (continued)

- **Cuckoo Graph**

- derived from cuckoo hash tables

- + each table entry is a node

- + each key is an edge, which links the entries that can hold the key

- + an insertion adds a new edge to the graph

- * let $h_1(88) = 4$ and $h_2(88) = 6$

- * displace key '58' in T_1 to make room for key '88'

- * displace key '91' in T_2 to make room for key '58'

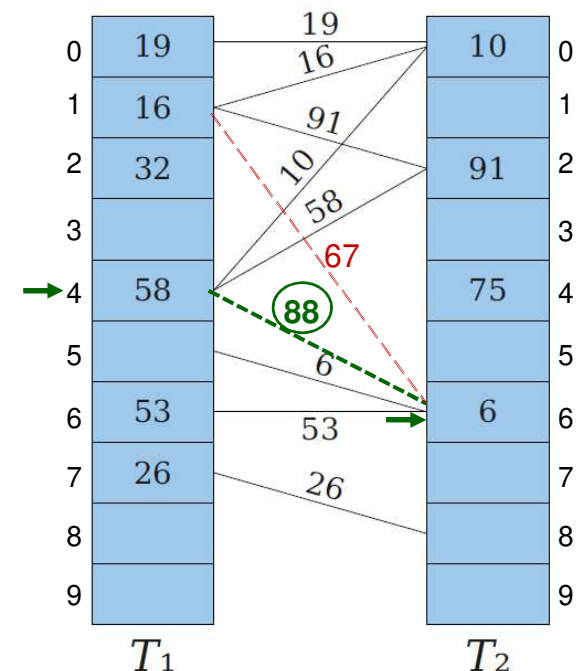
- * displace key '16' in T_1 to make room for key '91'

- * displace key '10' in T_2 to make room for key '16'

- * repeat

- + insertion done by tracing a path over the graph

- + what about inserting next key "67" with
 $h_1(67) = 1$ and $h_2(67) = 6$?



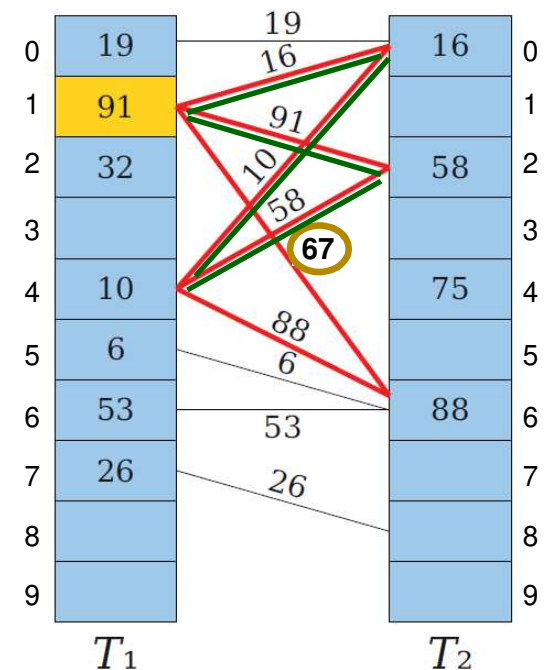
Hash Tables (continued)

- **Cuckoo Graph**

- insertion succeeds if and only if the new edge (defined by the new key) is on at most one cycle

Proof sketch:

1. each edge denotes a key and requires a table entry (i.e., node) to hold it
2. for a cycle exists, the number of its edges equals the number of its nodes involved, so that all nodes (table entries) are taken
3. if a new edge (after added) is on two cycles, the edge must link two taken nodes AND all nodes on the two cycles have been used
4. the new key (edge) *cannot* be accommodated.



Side note: two cycles (one with 4 distinct nodes and the other with at least one distinct node) that share one edge, will include (at least) 5 distinct nodes but they contain (at least) 6 distinct edges; impossible.

Binary Search Trees

§ Binary Search Tree Property

- + Given tree node x , if node y is in the left (or right) subtree of x , we have $y.key \leq x.key$ (or $y.key \geq x.key$).

Theorem 1

INORDER-TREE-WALK(x) across an n -node subtree rooted at x takes $\Theta(n)$.

(because the tree height may equal n)

Proof.

The tree walk has to visit every node, and hence, the time complexity $T(n)$ is lower bounded by $\Omega(n)$.

Next, considering that INORDER-TREE-WALK(x) is called on x whose left and right subtrees have k and $(n-k-1)$ nodes, respectively, we have

$T(n) \leq T(k) + T(n-k-1) + d$ for some $d > 0$. For simplicity, we may let d equal 1 here.

By the substitution method, we prove that $T(n) \leq (c+d)n + c$, for a constant c , below:

$$\begin{aligned} T(n) &\leq T(k) + T(n-k-1) + d \\ &\leq ((c+d)k + c) + ((c+d)(n-k-1) + c) + d \\ &= (c+d)n + c - (c+d) + c + d \\ &= \underline{(c+d)n + c} \quad (\text{upper bounded}) \end{aligned}$$

For simplicity, we may let c equal 1 here to have $T(n) \leq 2 \cdot n + 1$.

Binary Search Trees (continued)

- **Querying binary search trees**

- + searching
- + successor and predecessor
- + insertion and deletion

+ Searching via TREE-SEARCH
in time complexity $O(h)$

TREE-SEARCH(x, k)

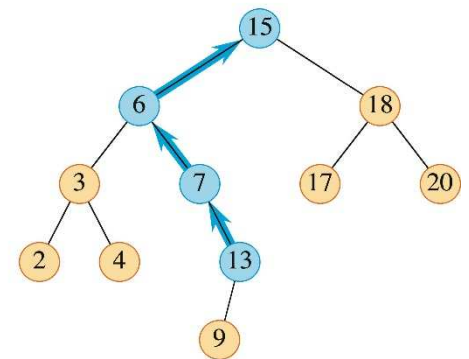
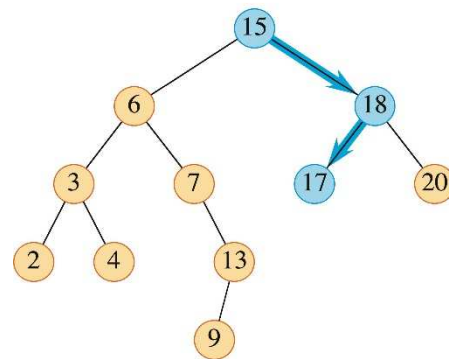
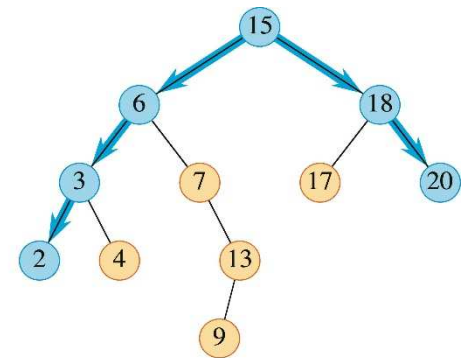
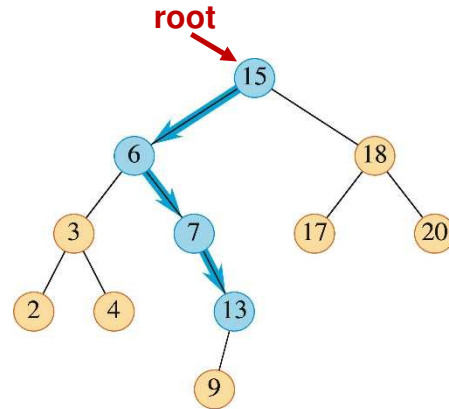
if $x == \text{NIL}$ or $k == \text{key}[x]$

return x

if $k < x.\text{key}$

return TREE-SEARCH($x.\text{left}, k$)

else return TREE-SEARCH($x.\text{right}, k$)



search path from root to $\text{key} = 13$ is

$15 \rightarrow 6 \rightarrow 7 \rightarrow 13$

Binary Search Trees (continued)

- Successor and predecessor
 - + by inorder tree walk
 - + separate results for non-empty right subtree and for empty right subtree
 - + time complexity for a tree of height h is $O(h)$

TREE-SUCCESSOR(x)

if $x.right \neq \text{NIL}$

return TREE-MINIMUM($x.right$)

$y = x.p$ y is the parent node of x.

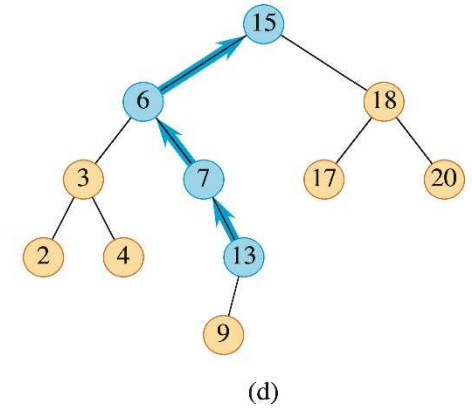
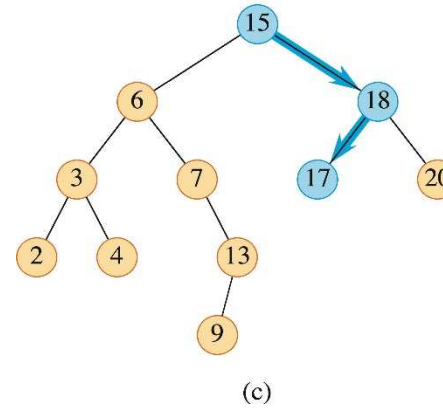
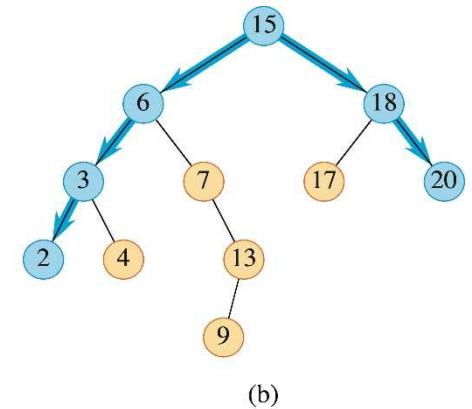
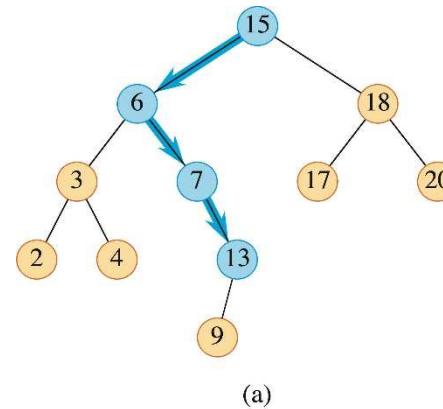
while $y \neq \text{NIL}$ and $x == y.right$

$x = y$ climb up the tree.

$y = y.p$

return y

If node x has no right subtree, its successor is the lowest ancestor of x whose left subtree contains x .



successor of $key = 15$ is 17
 successor of $key = 13$ is 15

Binary Search Trees (continued)

– Insertion

- + tree node (say, z) to be added, with $z.key = v$, $z.left = \text{nil}$, $z.right = \text{nil}$
- + z added to one appropriate node with an **absent** left or right child (never a full node)
- + tree in-order walk, with the trailing pointer y maintained
- + time complexity for a tree of height h is $\underline{O(h)}$

TREE-INSERT(T, z)

$y = \text{NIL}$

$x = T.\text{root}$

while $x \neq \text{NIL}$

$y = x$

if $z.key < x.key$

$x = x.left$

else $x = x.right$

y is the parent node of x after
 x is reassigned to move down

tree traversal downward until
the insertion point, with the
added node as a **leaf node**

$z.p = y$ // y is the parent node of z .

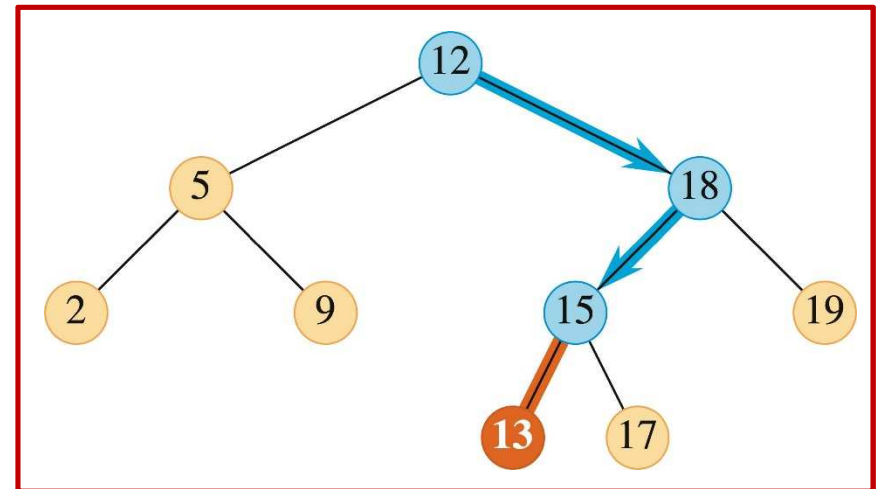
if $y == \text{NIL}$

$T.\text{root} = z$ // tree T was empty

elseif $z.key < y.key$

$y.left = z$

else $y.right = z$



Inserting $\text{key} = 13$ into binary search tree, with affected path marked.

Binary Search Trees (continued)

– Deletion (on z)

- + three basic cases involved: z having no child, exactly one child, two children
- + based on TRANSPLANT that replaces sibling subtree with another subtree
- + time complexity for a tree of height h is $O(h)$

TRANSPLANT(T, u, v)

```

if  $u.p == \text{NIL}$ 
     $T.\text{root} = v$ 
elseif  $u == u.p.\text{left}$ 
     $u.p.\text{left} = v$ 
else  $u.p.\text{right} = v$ 
if  $v \neq \text{NIL}$ 
     $v.p = u.p$ 
    
```

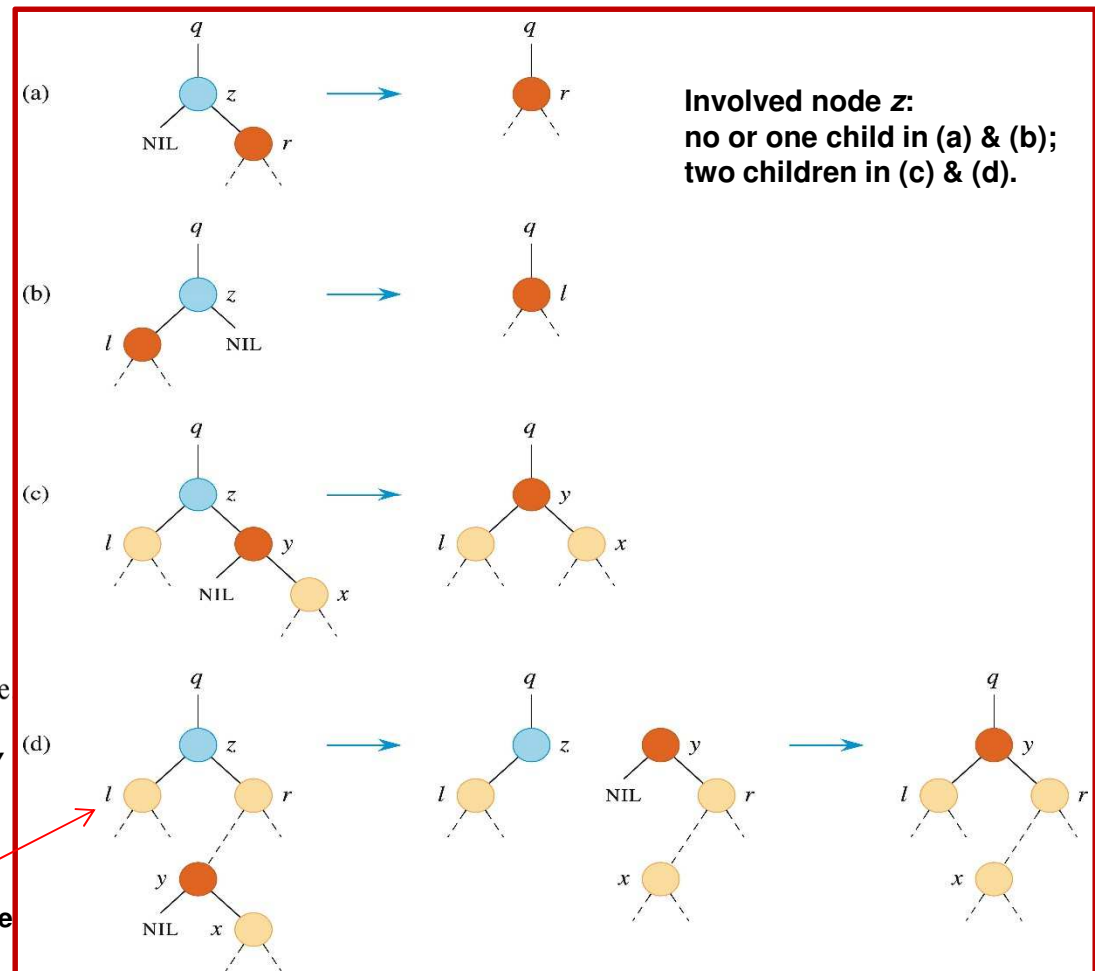
TREE-DELETE(T, z)

```

if  $z.\text{left} == \text{NIL}$ 
    TRANSPLANT( $T, z, z.\text{right}$ )    //  $z$  has no left child
elseif  $z.\text{right} == \text{NIL}$ 
    TRANSPLANT( $T, z, z.\text{left}$ )     //  $z$  has just a left child
else //  $z$  has two children.
     $y = \text{TREE-MINIMUM}(z.\text{right})$  //  $y$  is  $z$ 's successor
    if  $y.p \neq z$  ← This is case (d) shown in the figure.
        //  $y$  lies within  $z$ 's right subtree but is not the root of this subtree
        TRANSPLANT( $T, y, y.\text{right}$ )
         $y.\text{right} = z.\text{right}$ 
         $y.\text{right}.p = y$ 
        // Replace  $z$  by  $y$ .
        TRANSPLANT( $T, z, y$ )
         $y.\text{left} = z.\text{left}$ 
         $y.\text{left}.p = y$ 
    
```

Prepare a subtree rooted at y whose left subtree is empty.

Alternatively, one may cut the left-hand subtree of z and move it to become the left-hand subtree of y .



Binary Search Trees (continued)

- Randomly build binary search trees
 - + worst-case tree height (h) being $n-1$
 - + can be shown that $h \geq \lfloor \lg n \rfloor$, which is the best case
 - + like quicksort, average case proven to be much closer to best case than worst case
 - + special case of creating binary search trees (via insertion alone) with random keys, we have following theorem:

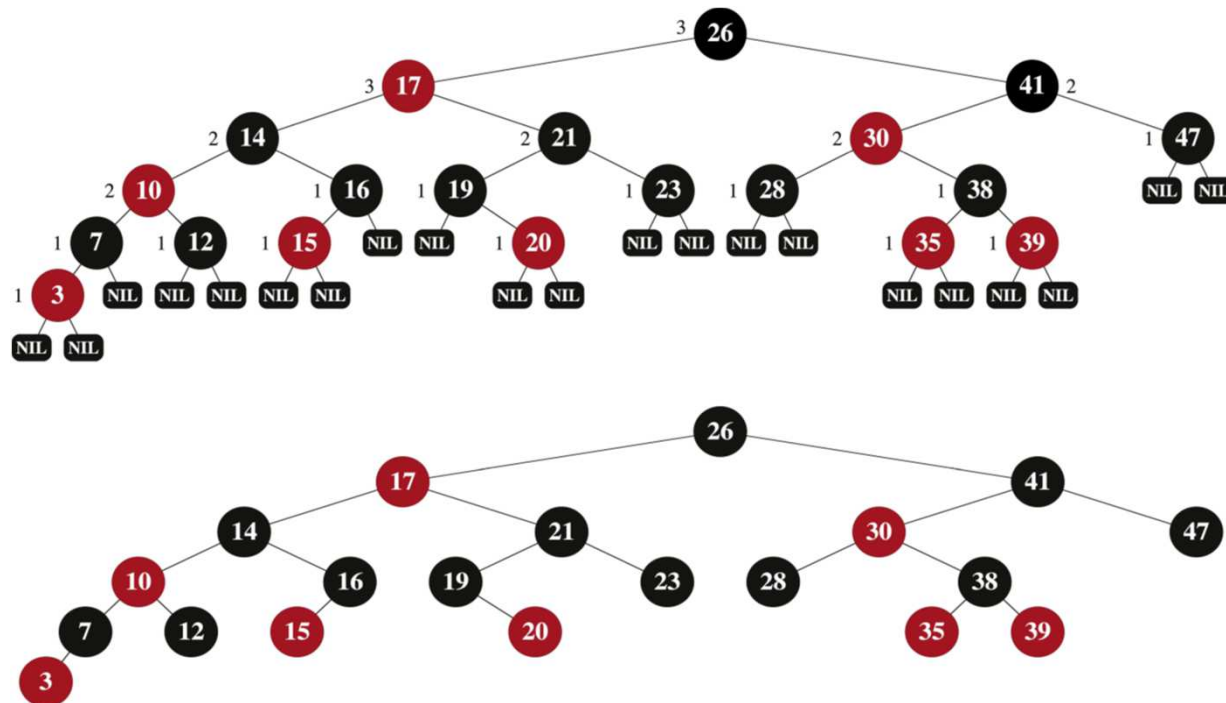
Theorem 2.

← This theorem refers to the special case that the tree is created by insertion alone (and no deletion).

The expected height of a randomly built binary search tree on n distinct keys is $O(\lg n)$.

Red-Black Trees

- Red-black tree is a binary search tree that satisfies:
 - (1) every node is either red or black
 - (2) root is black
 - (3) every leaf (NIL) is black
 - (4) red node has its both children being black → CANNOT have two connected red nodes
 - (5) all simple paths from any node to its descendant leaves contains the same number of black nodes (called the node's black-height, *bh*)



Red-Black Trees (continued)

+ Red-black tree is a good search tree because of its bounded small height.

Lemma 1:

A red-black tree with n internal nodes has the height of $\leq 2 \cdot \lg(n+1)$.

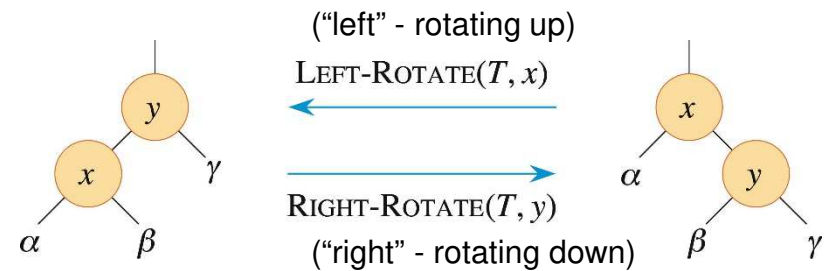
- proof by showing that any subtree rooted at Node x has at least $2^{bh(x)} - 1$ internal nodes by induction, as the bh of each x 's child is $\geq bh(x) - 1$ to contain $\geq 2^{bh(x)-1} - 1$ internal nodes
- from RB tree property (4), if the height of x is h , then $bh(x) \geq h/2$, to yield $n \geq 2^{h/2} - 1$

– Lemma 1 signifies that all operations (SEARCH, MIN, MAX, SUCCESSOR, PREDECESSOR) on an RB tree with n internal nodes take $O(\lg n)$ each.

Red-Black Trees (continued)

Rotations

- + insertion to, and deletion from, an RB tree involves subtree rotations
- + left rotations and right rotations



LEFT-ROTATE(T, x)

```
1   $y = x.right$ 
2   $x.right = y.left$     // turn  $y$ 's left subtree into  $x$ 's right subtree
3  if  $y.left \neq T.nil$  // if  $y$ 's left subtree is not empty ...
4       $y.left.p = x$     // ... then  $x$  becomes the parent of the subtree's root
5   $y.p = x.p$           //  $x$ 's parent becomes  $y$ 's parent
6  if  $x.p == T.nil$     // if  $x$  was the root ...
7       $T.root = y$       // ... then  $y$  becomes the root
8  elseif  $x == x.p.left$  // otherwise, if  $x$  was a left child ...
9       $x.p.left = y$     // ... then  $y$  becomes a left child
10 else  $x.p.right = y$  // otherwise,  $x$  was a right child, and now  $y$  is
11      $y.left = x$       // make  $x$  become  $y$ 's left child
12      $x.p = y$ 
```

Red-Black Trees (continued)

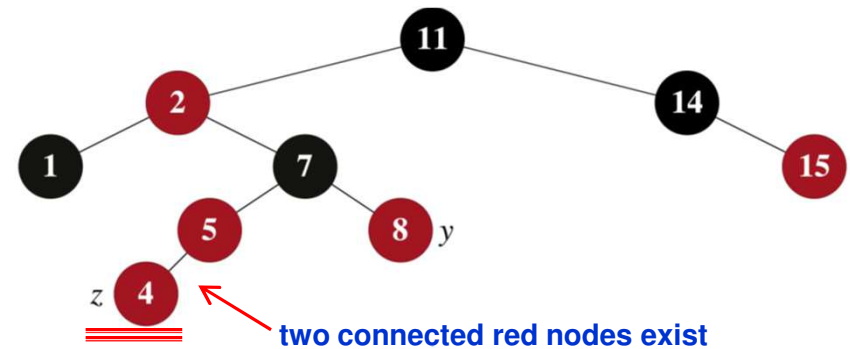
Insertion

- + inserts a node to an RB tree, $\text{RB-INSERT}(T, z)$, with the inserted node z in red and descending to a tree leaf node
- + requires $\text{RB-INSERT-FIXUP}(T, z)$ to ensure RB properties after insertion

RB-INSERT(T, z)

```
1   $x = T.\text{root}$ 
2   $y = T.\text{nil}$ 
3  while  $x \neq T.\text{nil}$ 
4       $y = x$ 
5      if  $z.\text{key} < x.\text{key}$ 
6           $x = x.\text{left}$ 
7      else  $x = x.\text{right}$ 
8   $z.p = y$ 
9  if  $y == T.\text{nil}$ 
10      $T.\text{root} = z$ 
11 elseif  $z.\text{key} < y.\text{key}$ 
12      $y.\text{left} = z$ 
13 else  $y.\text{right} = z$ 
14  $z.\text{left} = T.\text{nil}$ 
15  $z.\text{right} = T.\text{nil}$ 
16  $z.\text{color} = \text{RED}$ 
17  $\text{RB-INSERT-FIXUP}(T, z)$ 
```

// node being compared with z
// y will be parent of z
// descend until reaching the sentinel
// found the location—insert z with parent y
// tree T was empty
// both of z 's children are the sentinel
// the new node starts out red
// correct any violations of red-black properties



Red-Black Trees

+ RB-INSERT-FIXUP(T, z) to ensure RB properties

RB-INSERT-FIXUP(T, z)

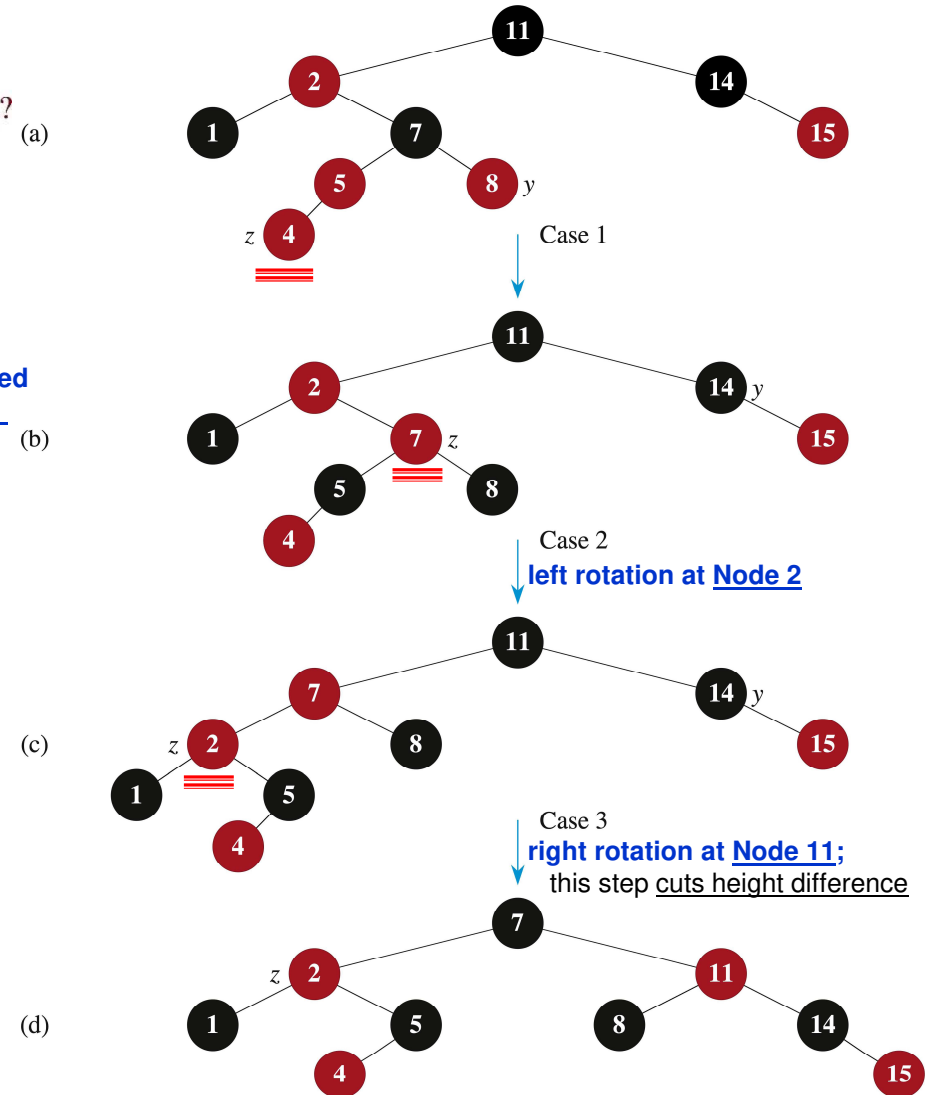
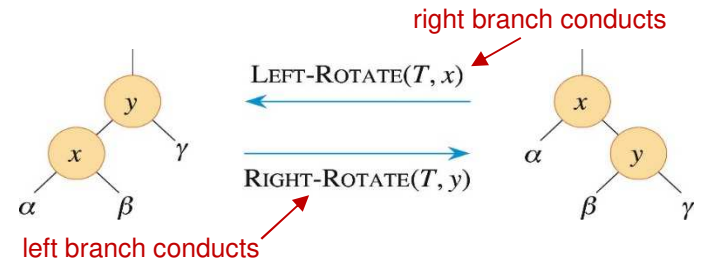
```

1  while  $z.p.color == RED$ 
2      if  $z.p == z.p.p.left$            // is  $z$ 's parent a left child?
3           $y = z.p.p.right$            //  $y$  is  $z$ 's uncle
4          if  $y.color == RED$            // are  $z$ 's parent and uncle both red?
5               $z.p.color = BLACK$ 
6               $y.color = BLACK$ 
7               $z.p.p.color = RED$ 
8               $z = z.p.p$ 
9      else
10         if  $z == z.p.right$ 
11              $z = z.p$ 
12             LEFT-ROTATE( $T, z$ )
13              $z.p.color = BLACK$ 
14              $z.p.p.color = RED$ 
15             RIGHT-ROTATE( $T, z.p.p$ )
16         else // same as lines 3–15, but with “right” and “left” exchanged
17              $y = z.p.p.left$ 
18             if  $y.color == RED$ 
19                  $z.p.color = BLACK$ 
20                  $y.color = BLACK$ 
21                  $z.p.p.color = RED$ 
22                  $z = z.p.p$ 
23             else
24                 if  $z == z.p.left$ 
25                      $z = z.p$ 
26                     RIGHT-ROTATE( $T, z$ )
27                  $z.p.color = BLACK$ 
28                  $z.p.p.color = RED$ 
29                 LEFT-ROTATE( $T, z.p.p$ )
30   $T.root.color = BLACK$ 
    
```

(a) case 1

(b) case 2 rotation performed if two connected red nodes exist

(c) case 3



Red-Black Trees (continued)

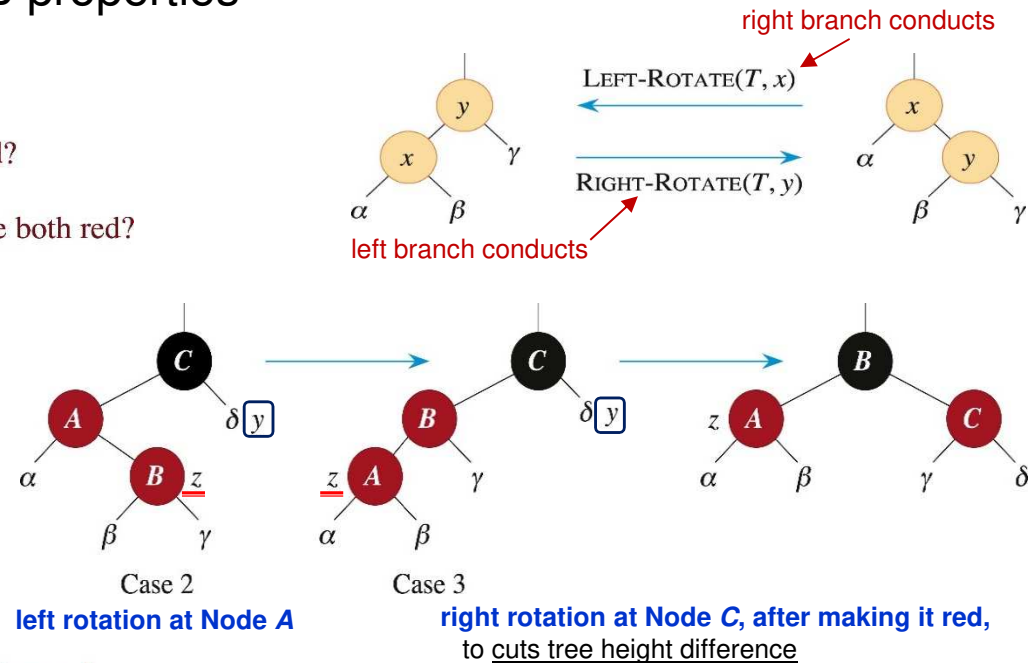
+ RB-INSERT-FIXUP(T, z) to ensure RB properties

RB-INSERT-FIXUP(T, z)

```

1  while  $z.p.color == RED$ 
2      if  $z.p == z.p.p.left$            // is  $z$ 's parent a left child?
3           $y = z.p.p.right$            //  $y$  is  $z$ 's uncle
4          if  $y.color == RED$            // are  $z$ 's parent and uncle both red?
5               $z.p.color = BLACK$ 
6               $y.color = BLACK$ 
7               $z.p.p.color = RED$ 
8               $z = z.p.p$ 
9      else
10         if  $z == z.p.right$ 
11              $z = z.p$ 
12             LEFT-ROTATE( $T, z$ )
13              $z.p.color = BLACK$ 
14              $z.p.p.color = RED$ 
15             RIGHT-ROTATE( $T, z.p.p$ )
16         else // same as lines 3–15, but with “right” and “left” exchanged
17              $y = z.p.p.left$ 
18             if  $y.color == RED$ 
19                  $z.p.color = BLACK$ 
20                  $y.color = BLACK$ 
21                  $z.p.p.color = RED$ 
22                  $z = z.p.p$ 
23             else
24                 if  $z == z.p.left$ 
25                      $z = z.p$ 
26                     RIGHT-ROTATE( $T, z$ )
27                  $z.p.color = BLACK$ 
28                  $z.p.p.color = RED$ 
29                 LEFT-ROTATE( $T, z.p.p$ )
30   $T.root.color = BLACK$ 

```



Red-Black Trees (continued)

Deletion

- + deletes an arbitrary node from RB tree, $\text{RB-DELETE}(T, z)$
- + requires $\text{RB-DELETE-FIXUP}(T, z)$ to ensure RB properties after deletion

$\text{RB-DELETE}(T, z)$

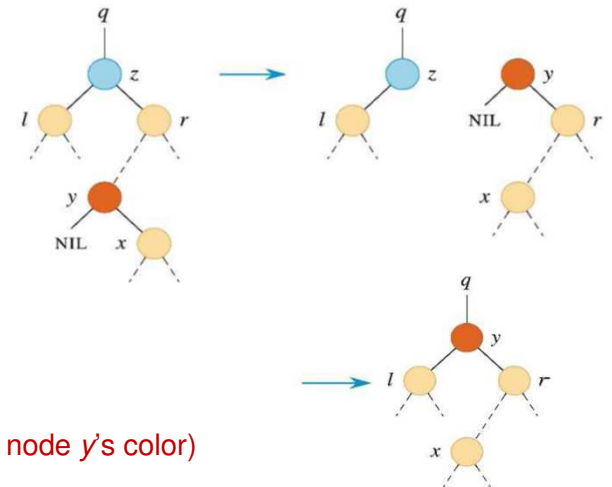
```

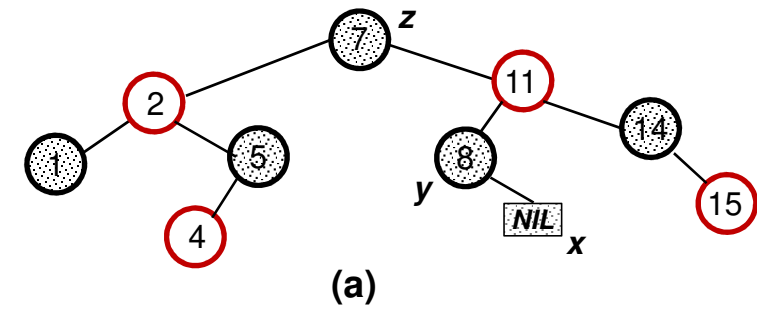
1   $y = z$ 
2   $y\text{-original-color} = y.\text{color}$ 
3  if  $z.\text{left} == T.\text{nil}$ 
4       $x = z.\text{right}$ 
5       $\text{RB-TRANSPLANT}(T, z, z.\text{right})$            // replace  $z$  by its right child
6  elseif  $z.\text{right} == T.\text{nil}$ 
7       $x = z.\text{left}$ 
8       $\text{RB-TRANSPLANT}(T, z, z.\text{left})$            // replace  $z$  by its left child
9  else  $y = \text{TREE-MINIMUM}(z.\text{right})$            //  $y$  is  $z$ 's successor
10      $y\text{-original-color} = y.\text{color}$ 
11      $x = y.\text{right}$ 
12     if  $y \neq z.\text{right}$                        // is  $y$  farther down the tree?
13          $\text{RB-TRANSPLANT}(T, y, y.\text{right})$    // replace  $y$  by its right child
14          $y.\text{right} = z.\text{right}$                //  $z$ 's right child becomes
15          $y.\text{right}.p = y$                    //  $y$ 's right child
16     else  $x.p = y$ 
17      $\text{RB-TRANSPLANT}(T, z, y)$              // replace  $z$  by its successor  $y$ 
18      $y.\text{left} = z.\text{left}$                    // and give  $z$ 's left child to  $y$ ,
19      $y.\text{left}.p = y$                        // which had no left child
20      $y.\text{color} = z.\text{color}$ 
21 if  $y\text{-original-color} == \text{BLACK}$            // if any red-black violations occurred,
22      $\text{RB-DELETE-FIXUP}(T, x)$              // correct them (based on replaced node  $y$ 's color)
    
```

$\text{RB-TRANSPLANT}(T, u, v)$

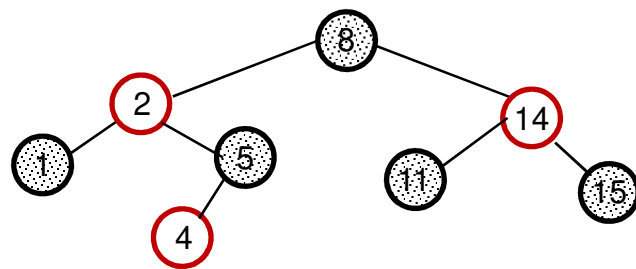
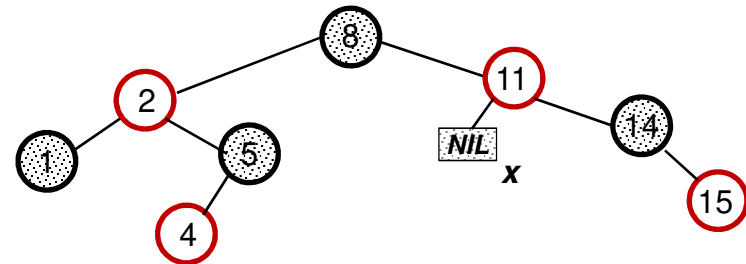
```

1  if  $u.p == T.\text{nil}$ 
2       $T.\text{root} = v$ 
3  elseif  $u == u.p.\text{left}$ 
4       $u.p.\text{left} = v$ 
5  else  $u.p.\text{right} = v$ 
6       $v.p = u.p$ 
    
```

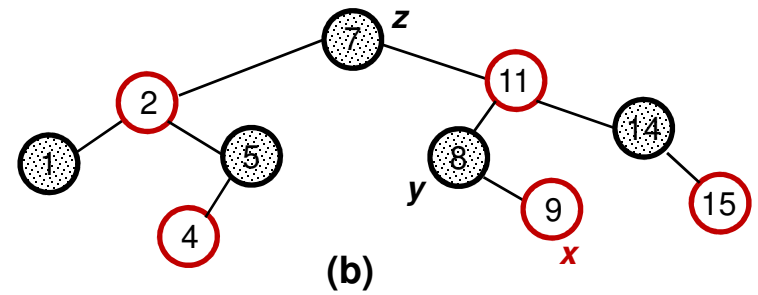




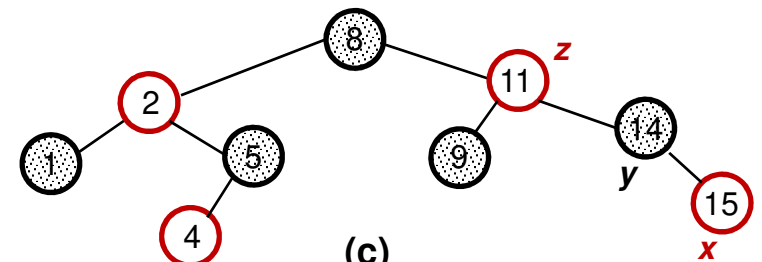
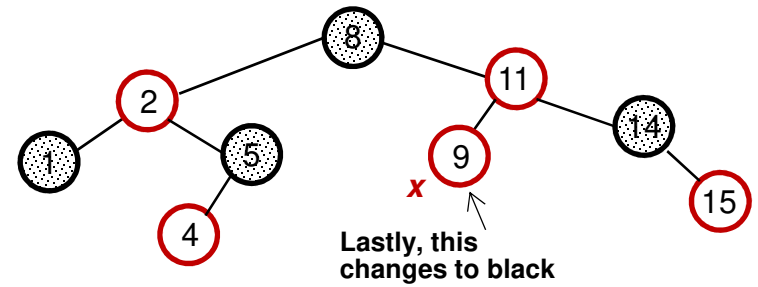
Delete '7'



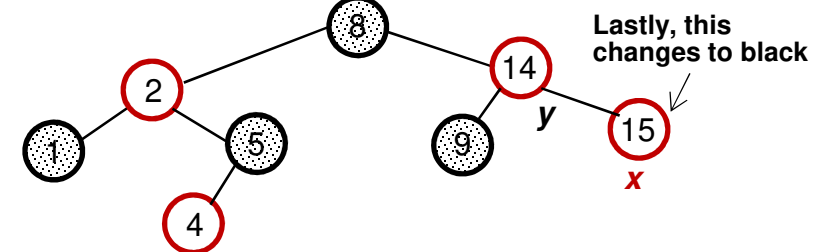
Deleting '2' then delete '11'

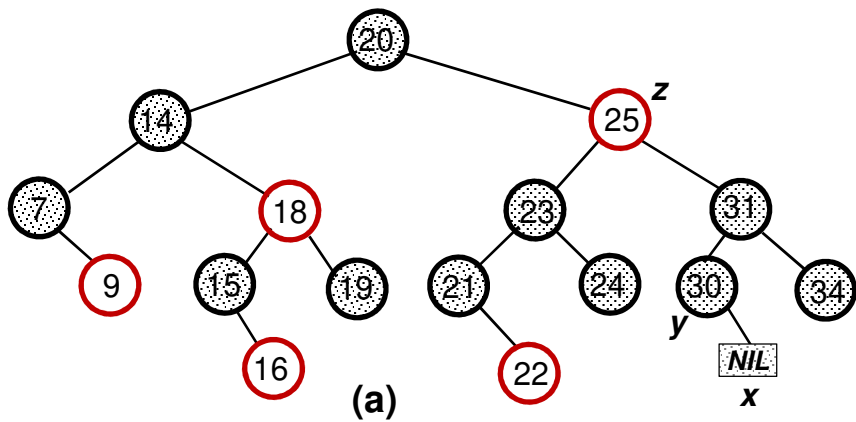


Delete '7'

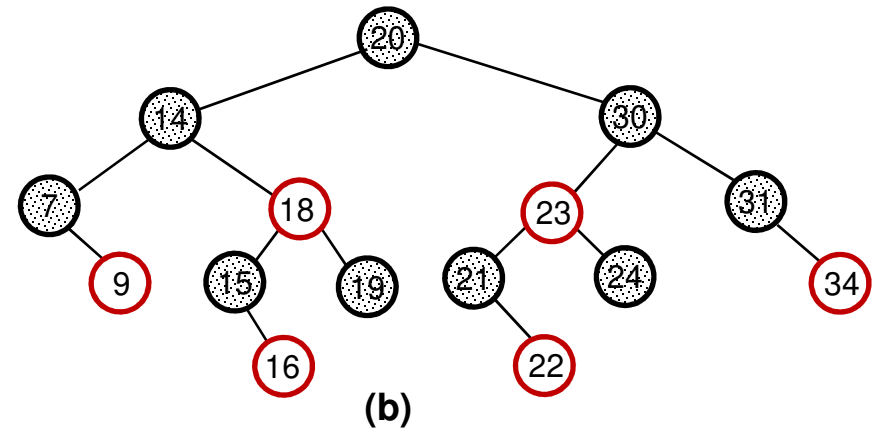
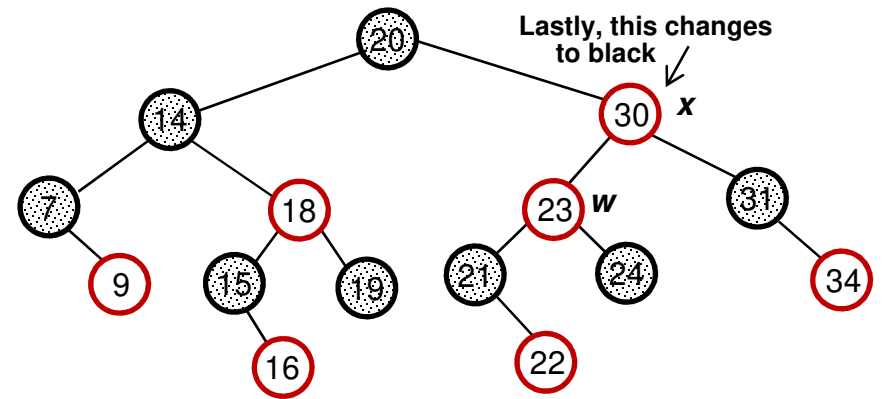
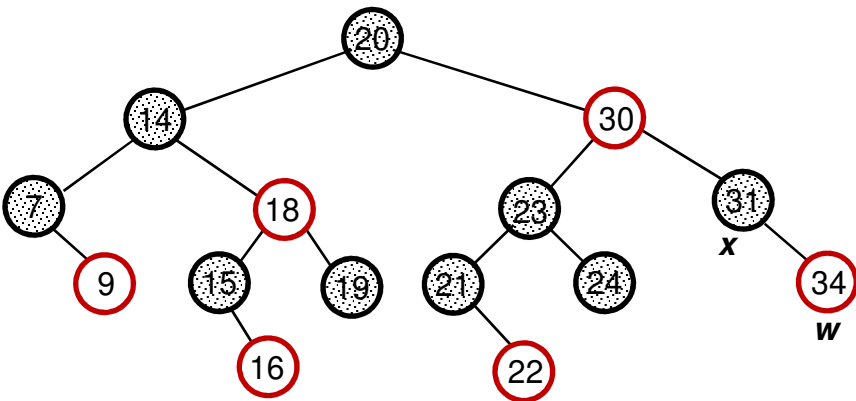
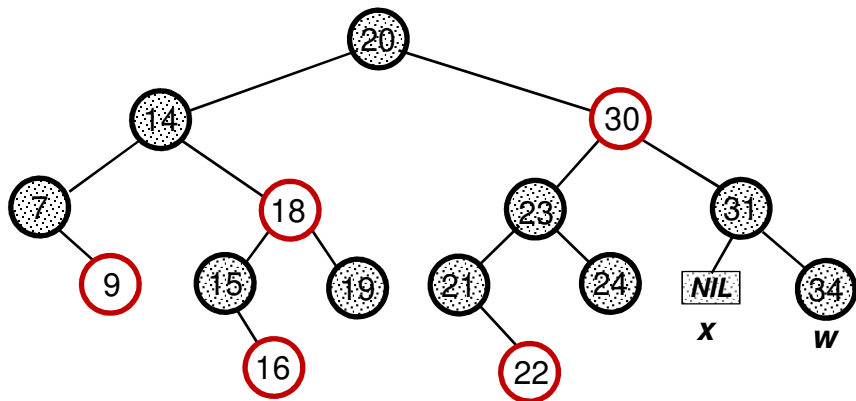


Deleting '11'

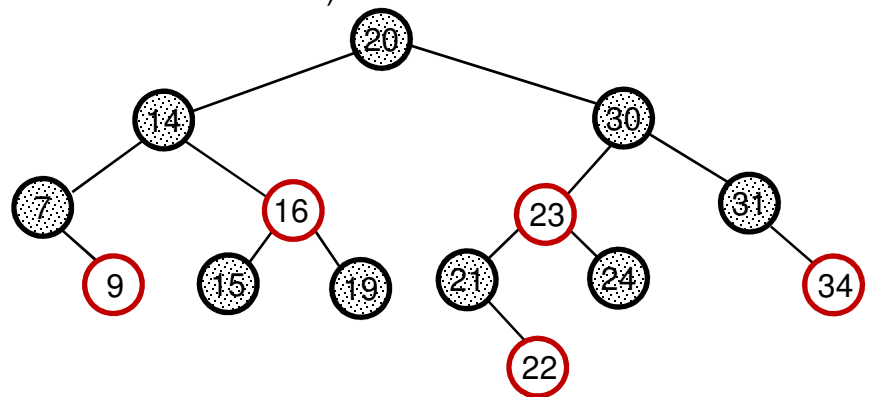




Delete '25'



Delete '18'
(via predecessor or successor)



Red-Black Trees (continued)

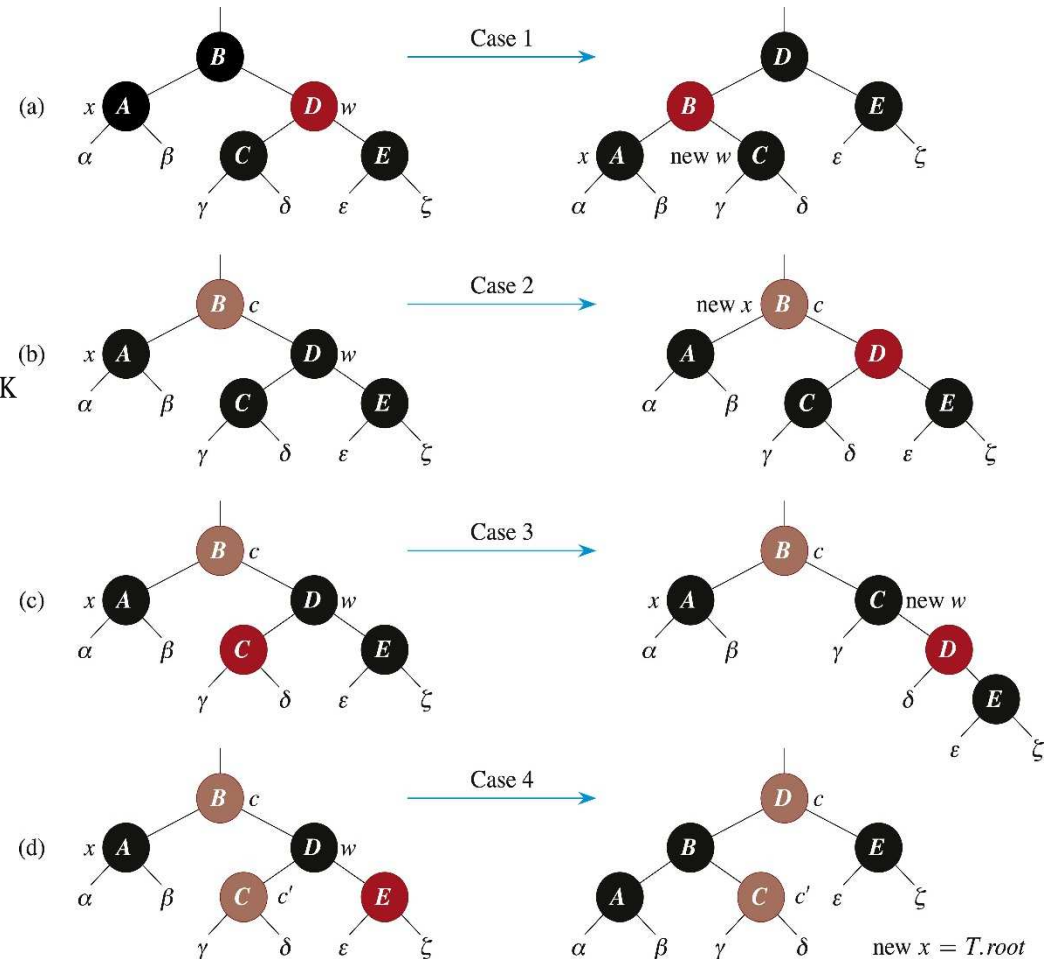
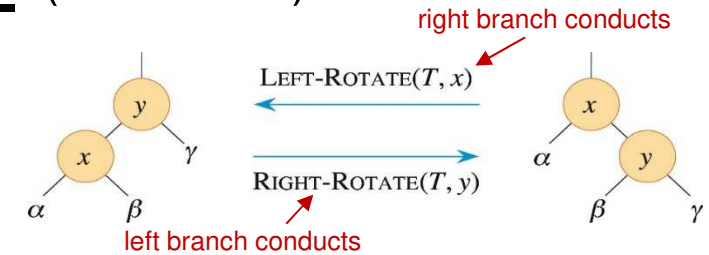
+ RB-DELETE-FIXUP(T, z) to ensure RB properties, i.e., identical black-height, *bh*, from any node

RB-DELETE-FIXUP(T, x)

```

1  while  $x \neq T.root$  and  $x.color == BLACK$  (based on the color of replacing node  $x$ )
2      if  $x == x.p.left$  // is  $x$  a left child?
3           $w = x.p.right$  //  $w$  is  $x$ 's sibling
4          if  $w.color == RED$ 
5               $w.color = BLACK$ 
6               $x.p.color = RED$ 
7              LEFT-ROTATE( $T, x.p$ )
8               $w = x.p.right$ 
9          if  $w.left.color == BLACK$  and  $w.right.color == BLACK$ 
10              $w.color = RED$ 
11              $x = x.p$ 
12         else
13             if  $w.right.color == BLACK$ 
14                  $w.left.color = BLACK$ 
15                  $w.color = RED$ 
16                 RIGHT-ROTATE( $T, w$ )
17                  $w = x.p.right$ 
18              $w.color = x.p.color$ 
19              $x.p.color = BLACK$ 
20              $w.right.color = BLACK$ 
21             LEFT-ROTATE( $T, x.p$ )
22              $x = T.root$ 

```



Red-Black Trees (continued)

+ RB-DELETE-FIXUP(T, z) to ensure RB properties,
i.e., identical black-height, *bh*, from any node

RB-DELETE-FIXUP(T, x)

(based on the color of replacing node x)

```

1  while  $x \neq T.root$  and  $x.color == BLACK$ 
2      if  $x == x.p.left$  // is  $x$  a left child?
3           $w = x.p.right$  //  $w$  is  $x$ 's sibling
4          if  $w.color == RED$ 
5               $w.color = BLACK$ 
6               $x.p.color = RED$ 
7              LEFT-ROTATE( $T, x.p$ )
8               $w = x.p.right$ 
9          if  $w.left.color == BLACK$  and  $w.right.color == BLACK$ 
10              $w.color = RED$ 
11              $x = x.p$ 
12         else
13             if  $w.right.color == BLACK$ 
14                  $w.left.color = BLACK$ 
15                  $w.color = RED$ 
16                 RIGHT-ROTATE( $T, w$ )
17                  $w = x.p.right$ 
18             if  $w.left.color == BLACK$ 
19                  $w.right.color = BLACK$ 
20                  $w.color = RED$ 
21                 LEFT-ROTATE( $T, x.p$ )
22                  $x = T.root$ 

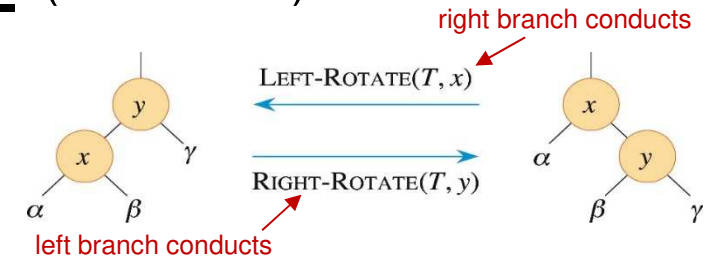
```

case 1

case 2

case 3

case 4



else // same as lines 3–22, but with “right” and “left” exchanged

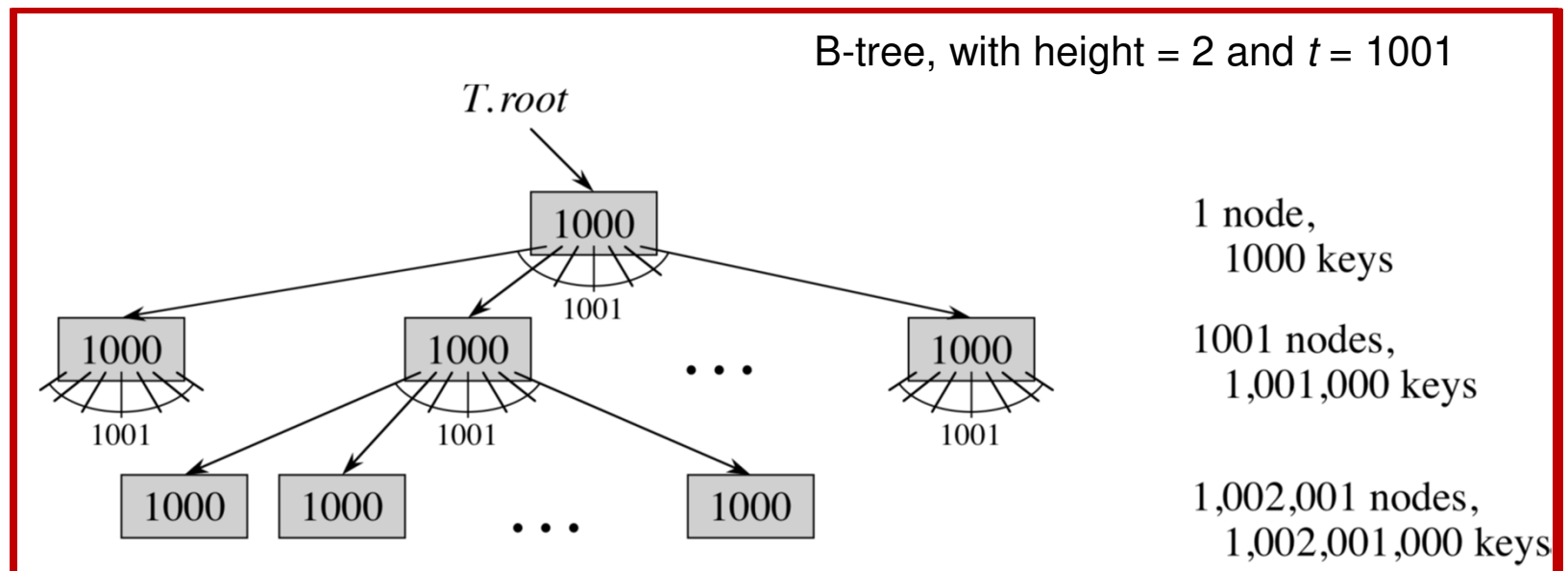
```

 $w = x.p.left$ 
if  $w.color == RED$ 
     $w.color = BLACK$ 
     $x.p.color = RED$ 
    RIGHT-ROTATE( $T, x.p$ )
     $w = x.p.left$ 
if  $w.right.color == BLACK$  and  $w.left.color == BLACK$ 
     $w.color = RED$ 
     $x = x.p$ 
else
    if  $w.left.color == BLACK$ 
         $w.right.color = BLACK$ 
         $w.color = RED$ 
        LEFT-ROTATE( $T, w$ )
         $w = x.p.left$ 
    if  $w.right.color == BLACK$ 
         $w.left.color = BLACK$ 
         $w.color = RED$ 
        RIGHT-ROTATE( $T, x.p$ )
     $x = T.root$ 
 $x.color = BLACK$ 

```


B-Trees

- § **Balanced Search Trees (B-Trees)** with t — non-root node has $\geq t$ & $\leq 2t$ children
- + balance achieved by keeping multiple (i.e., $\geq t-1$) keys in each non-root node
 - + node has at most $2t-1$ keys, called **full node** (with degree = $2t$)
 - + keys stored in a node in non-decreasing order
 - + node x (with $x.n$ keys) has $x.n+1$ children, pointed by $x.c_1, x.c_2, \dots, x.c_{x.n+1}$, then $k_1 \leq x.key_1 \leq k_2 \leq x.key_2 \leq \dots \leq x.key_{x.n} \leq k_{x.n+1}$, where k_i is a key stored in subtree rooted at $x.c_i$ and $x.key_i$ is a key stored in node x
 - + all leaves have the same height
 - + simplest B-tree is for $t = 2$, called 2-3-4 tree (each *internal node* has 2, 3, or 4 children)

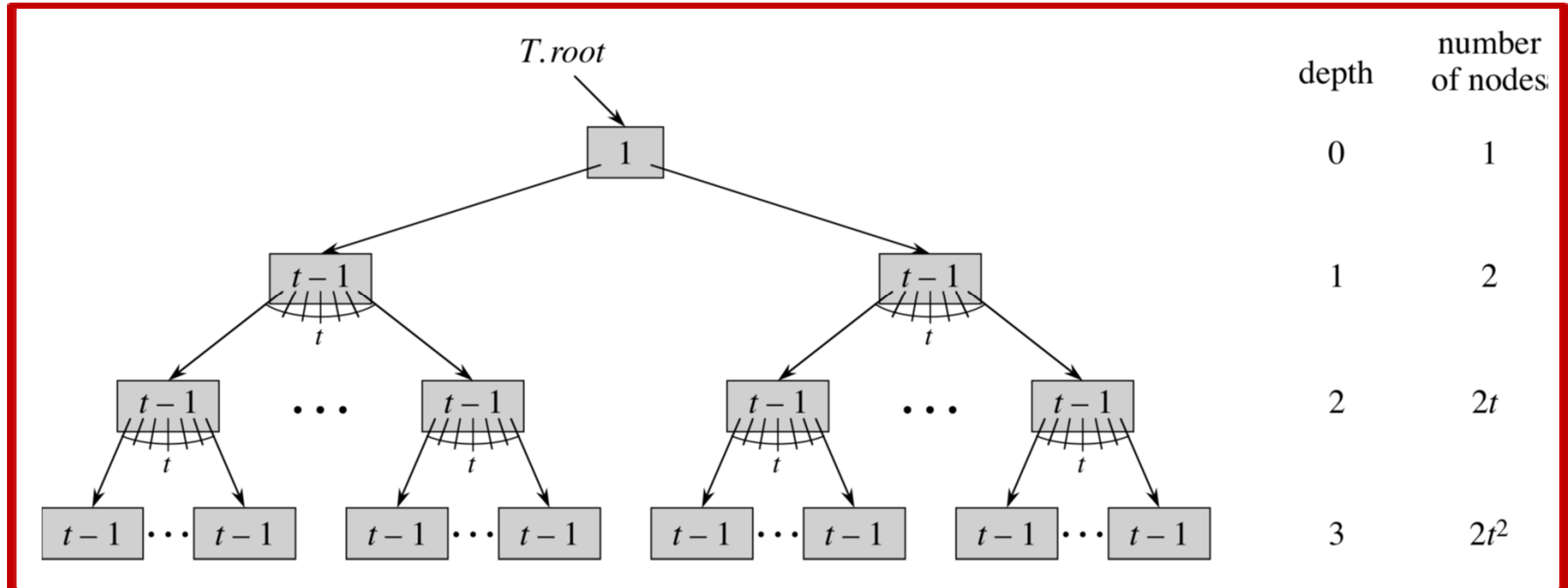


B-Trees (continued)

• Theorem

For any n -key B-tree T of height h and minimum node degree $t \geq 2$ (i.e., number of keys in each non-root node $\geq t-1$), we have $h \leq \log_t \frac{n+1}{2}$.

+ Proof follows the fact of $n \geq 1 + (t-1) \cdot \sum_{i=1}^h 2 \cdot t^{i-1}$ illustrated in the figure below (to show the minimum possible number of keys in a B-tree with height = 3).



B-Trees (continued)

- **Basic operations**

- + Searching for record with key = k : each internal node x makes an $(x.n + 1)$ -way branching decision; returning $(y, i) \rightarrow$ node y and its index i with $y.key_i = k$

B-TREE-SEARCH(x, k)

```
1   $i = 1$ 
2  while  $i \leq x.n$  and  $k > x.key_i$ 
3       $i = i + 1$ 
4  if  $i \leq x.n$  and  $k == x.key_i$ 
5      return  $(x, i)$ 
6  elseif  $x.leaf$ 
7      return NIL
8  else DISK-READ( $x.c_i$ )
9      return B-TREE-SEARCH( $x.c_i, k$ )
```

$x.leaf$: Boolean variable to indicate if it is a leaf node

B-Trees (continued)

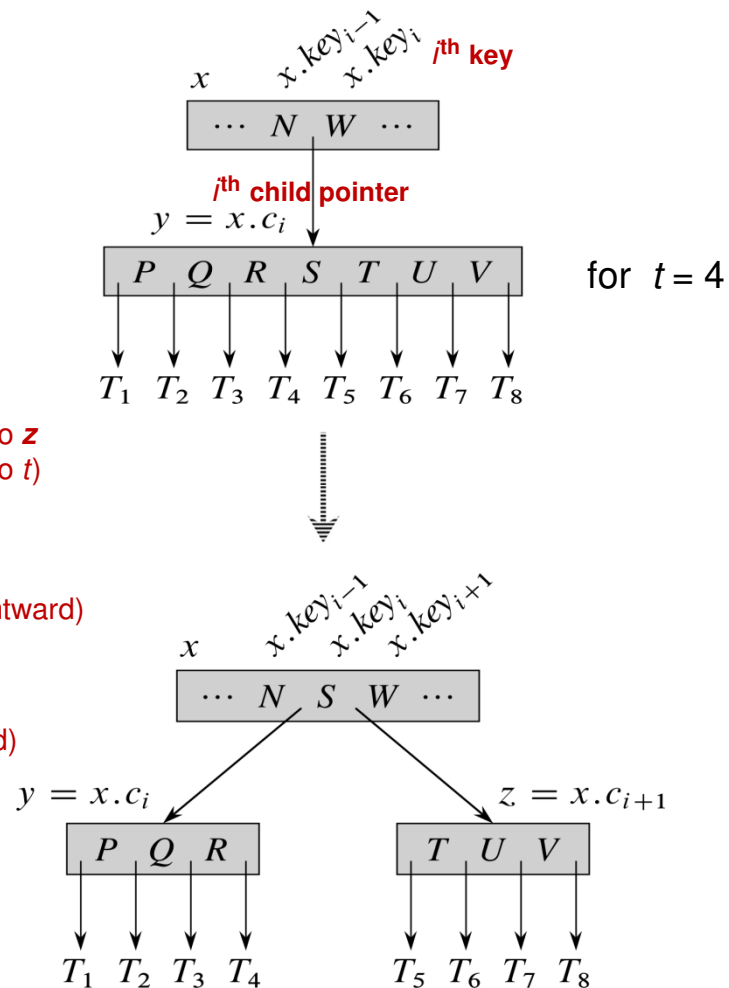
• Basic operations

- + **Splitting a full node**: for *non-full internal node* x and a *full child* of x (say, $y = x.c_i$), y is split at median key S , which moves up into x , with those $> S$ forming a new subtree

B-TREE-SPLIT-CHILD(x, i) (split i^{th} child of x)

```

1  z = ALLOCATE-NODE()
2  y = x.ci      (Node x's ith child is full)
3  z.leaf = y.leaf (status – leaf?)
4  z.n = t – 1
5  for j = 1 to t – 1
6      z.keyj = y.keyj+t
7  if not y.leaf
8      for j = 1 to t      (move child pointers from y to z
9          z.cj = y.cj+t    with pointer # from 1 to t)
10     y.n = t – 1
11     for j = x.n + 1 downto i + 1
12         x.cj+1 = x.cj      (shift child pointers in x rightward)
13     x.ci+1 = z
14     for j = x.n downto i
15         x.keyj+1 = x.keyj (shift keys in x rightward)
16     x.keyi = y.keyt      (move middle key in y up)
17     x.n = x.n + 1
18     DISK-WRITE(y)
19     DISK-WRITE(z)
20     DISK-WRITE(x)
    
```



B-Trees (continued)

• Basic operations

- + **Inserting a key**: B-tree T of height h , takes $O(h)$ disk accesses (nodes kept as disk pages)
 - *can't* insert the key into a newly created node *nor* into an internal node directly
 - so, insert it only to a **leaf node**
 - **never** descend through a **full node**, achieved by B-TREE-SPLIT-CHILD, to avoid back-tracking altogether
 - root split increases the height by 1

B-TREE-INSERT(T, k)

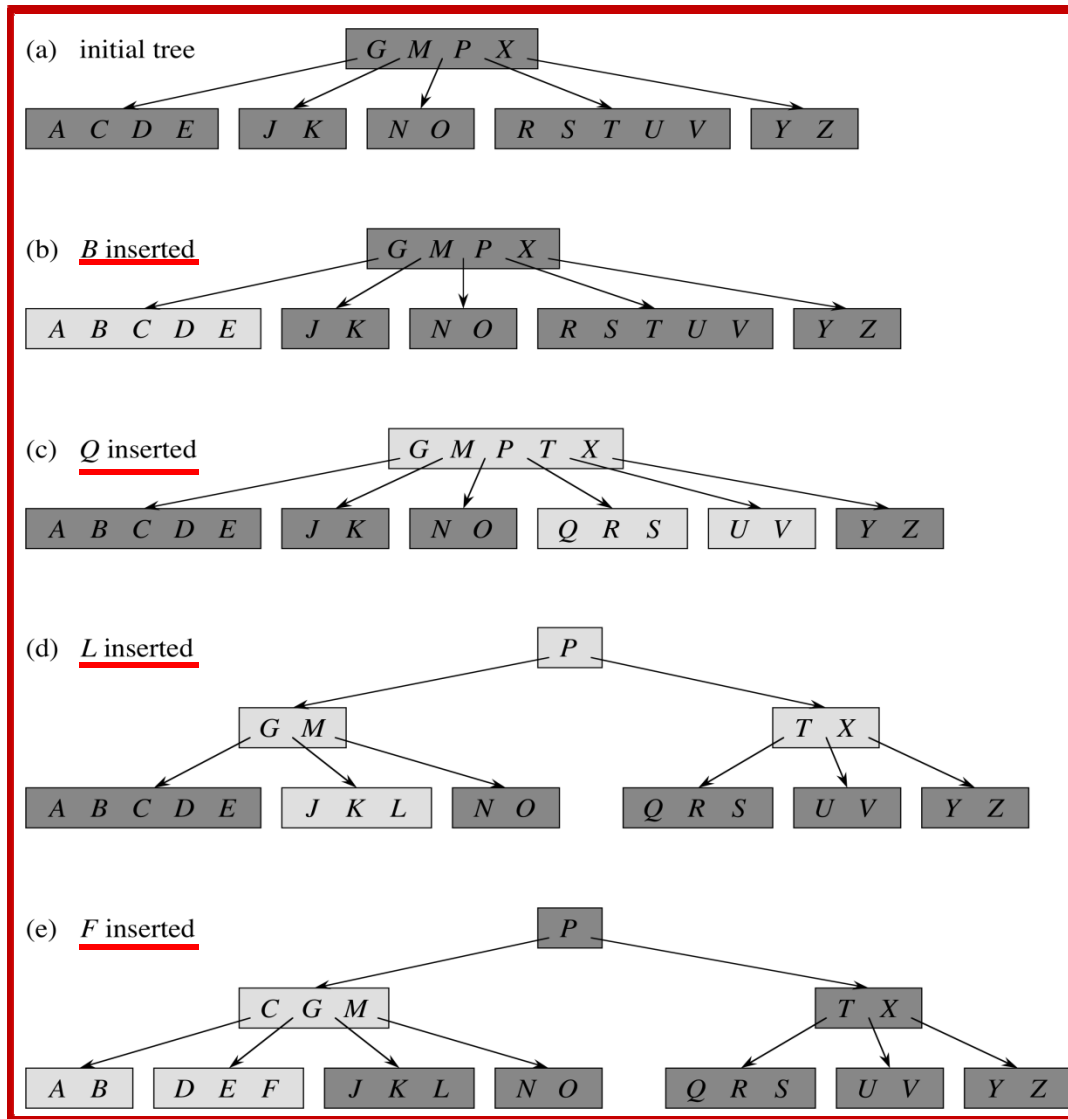
```
1   $r = T.root$ 
2  if  $r.n == 2t - 1$     // splitting the root?
3       $s = \text{ALLOCATE-NODE}()$ 
4       $T.root = s$ 
5       $s.leaf = \text{FALSE}$ 
6       $s.n = 0$ 
7       $s.c_1 = r$ 
8      B-TREE-SPLIT-CHILD( $s, 1$ ) (split 1st child of  $S$ )
9      B-TREE-INSERT-NONFULL( $s, k$ )
10 else B-TREE-INSERT-NONFULL( $r, k$ )
```

B-TREE-INSERT-NONFULL(x, k)

```
1   $i = x.n$ 
2  if  $x.leaf$  (upon a leaf, key is inserted therein)
3      while  $i \geq 1$  and  $k < x.key_i$ 
4           $x.key_{i+1} = x.key_i$  (shift key in  $x$  rightward)
5           $i = i - 1$ 
6           $x.key_{i+1} = k$ 
7           $x.n = x.n + 1$ 
8          DISK-WRITE( $x$ )
9  else while  $i \geq 1$  and  $k < x.key_i$ 
10      $i = i - 1$ 
11      $i = i + 1$ 
12     DISK-READ( $x, c_i$ ) (descend one level)
13     if  $x.c_i.n == 2t - 1$  // full child?
14         B-TREE-SPLIT-CHILD( $x, i$ )
15         if  $k > x.key_i$ 
16              $i = i + 1$ 
17         B-TREE-INSERT-NONFULL( $x.c_i, k$ )
```

B-Trees (continued)

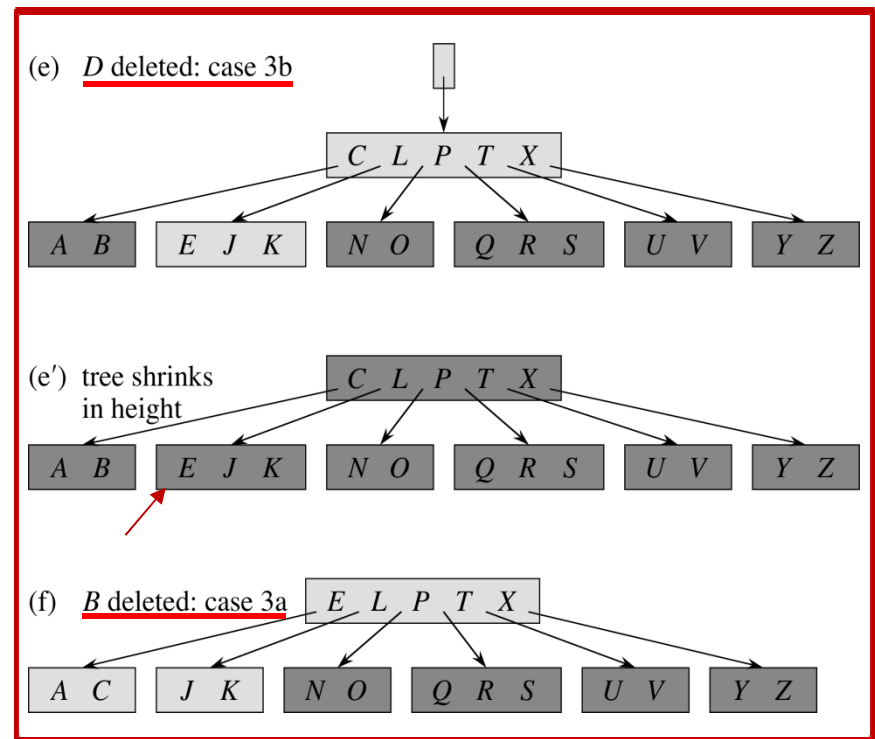
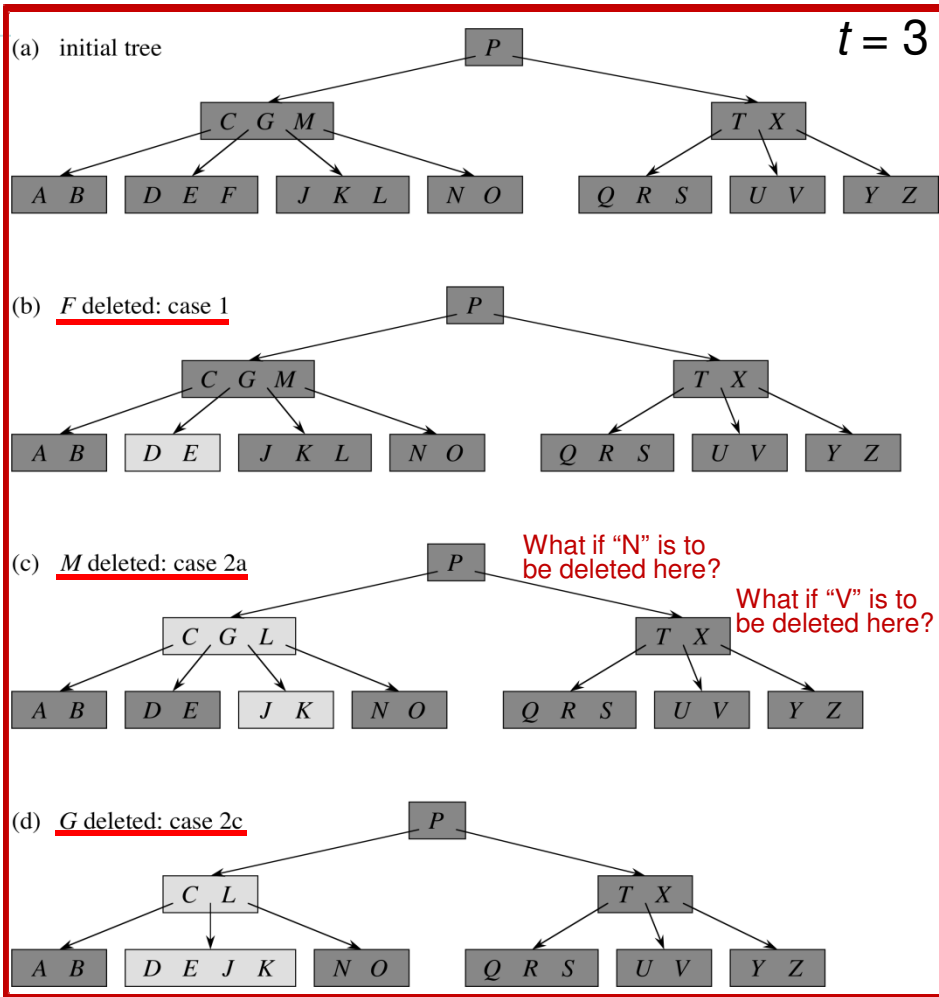
+ Inserting a key: B-tree T with $t = 3$ and modified nodes lightly shaded



B-Trees (continued)

• Basic operations

- + **Deleting a key**: delete key k from the subtree rooted at x in B-tree T with the minimum degree of t (where the key may be in any node, not just at a leaf node)
- number of keys kept in any **internal node** upon descending through would be **at least t**



B-Trees (continued)

+ Deleting key k from the subtree rooted at x in B-tree T with the minimum degree of t
– **Deletion Procedure** sketched below:

1. If the key k is in node x and x is a leaf, delete the key k from x .
2. If the key k is in node x and x is an internal node, do the following:
 - a. If the child y that precedes k in node x has at least t keys, then find the predecessor k' of k in the subtree rooted at y . Recursively delete k' , and replace k by k' in x . (We can find k' and delete it in a single downward pass.)
 - b. If y has fewer than t keys, then, symmetrically, examine the child z that follows k in node x . If z has at least t keys, then find the successor k' of k in the subtree rooted at z . Recursively delete k' , and replace k by k' in x . (We can find k' and delete it in a single downward pass.)
 - c. Otherwise, if both y and z have only $t - 1$ keys, merge k and all of z into y , so that x loses both k and the pointer to z , and y now contains $2t - 1$ keys. Then free z and recursively delete k from y .
3. If the key k is not present in internal node x , determine the root $x.c_i$ of the appropriate subtree that must contain k , if k is in the tree at all. If $x.c_i$ has only $t - 1$ keys, execute step 3a or 3b as necessary to guarantee that we descend to a node containing at least t keys. Then finish by recursing on the appropriate child of x .
 - a. If $x.c_i$ has only $t - 1$ keys but has an immediate sibling with at least t keys, give $x.c_i$ an extra key by moving a key from x down into $x.c_i$, moving a key from $x.c_i$'s immediate left or right sibling up into x , and moving the appropriate child pointer from the sibling into $x.c_i$.
 - b. If $x.c_i$ and both of $x.c_i$'s immediate siblings have $t - 1$ keys, merge $x.c_i$ with one sibling, which involves moving a key from x down into the new merged node to become the median key for that node.

Targeted node with the key, but it may be non-leaf

This is Rule 1 - Key k present:
At internal node x which contains the key (say, k) to be deleted, it checks if predecessor or successor of k can be borrowed to replace k (and in this case, only the borrowed key is moved; and its associated pointer stays).

Prepare to walk down the tree

This is Rule 2 - Key k not present:
While at internal node x , it checks if the root of the target child has at least t key
If not, it prepares that root node by borrowing a key (plus associated pointer, i.e., a subtree) from its left or right sibling, if possible.