**Local Machine DB** Resource **HPC** Resource needs to be accessible by application and nodes all trajectories stay on HPC all trajectories stay on HPC can run on local machine Shared FS Shared DB Local FS mongodb project files input files traj000000.xtc file contents traj000000.stc.restart initial.pdb initial.pdb traj000001.xtc integrator.xml integrator.xml staged files initial.pdb MD parameters integrator.xml read/write file locations on HPC meta information **Application** read/write python script or jupyter notebook adaptive strategy outgoing connection model parameters Nodes uses generators python script creates tasks has activation conditions adaptivemdworker task descriptions execute tasks as bash script generators states ['queued', 'running', ...] consume tasks pull task descriptions create task descriptions assigned workers outgoing connection stage files to/from shared FS required/create/modified files add files/models to DB adaptivemdworker logs .......... outgoing connection creation and execution of tasks is completely independent Nodes

number of workers can change at will

## **Project Setup**

```
project = Project('alanine-example')
project = Initialize(AllegroCluster({options}))
pdb_file = File('initial.pdb')
engine = OpenMMEngine(pdb_file, ...)
```

**Run trajectory** 

```
traj1 = project.new_trajectory(initial=pdb_file, length=100)
task1 = engine.run(traj1)
project.queue(task)
```

From frame

```
traj2 = project.new_trajectory(initial=traj1[28], length=50)
project.queue(traj2)

a shortcut that will generate the task
```

**Submit worker** 

```
adaptivemdworker -d {path_to_db} alanine-example
```

**Make strategy** 

runs asynchroneously

```
@event
def strategy(length, loops):
    for _ in range(loops):
        new_frames = {your way to pick new frames}
        trajs = [project.new_trajectory(f, length) for f in new_frames]
        tasks = [engine.run(t) for t in trajs]
        project.queue(tasks)
        yield [x.is_done for x in tasks]

project.add_event(strategy(100, 10))
```

if all(x.is done() for x in tasks) -> continue

set shared fs path and hpc specifics like module loading, etc

pick pdb\_file as initial coordinates

pick frame 28 from trail as initial coordinates

### **Status**

# pre-alpha release

first beta planned for end of march

#### GitHub

feel free to contribute

currently python 2.7

https://github.com/markovmodel/adaptivemd

### Installation

to get the latest version

git clone https://github.com/markovmodel/adaptivemd.git
cd adaptivemd/
python setup.py install

if you are using conda (not the latest version)

conda install -c omnia adaptivemd-dev