

ALGORITHM:

1. Get n of object
2. Get weight + profit for n objects
3. Calculate $ratio = Profit / float(weight)$
4. Get the total weight of bag, Capacity
5. Bubble sort ie) smallest on the right, use temp $i, j = i+1$ to sort profit, weight, ratio.

↓
for: $i = 0 \rightarrow n$
for: $j = i+1 \rightarrow n$
if ($ratio[i] < ratio[j]$)

for: $i = 0 \rightarrow n$
if ($weight[i] > Capacity$)
total = total + $ratio * Capacity$
else
total = total + profit
Capacity = Capacity - weight.

DIJKSTRA'S ALGORITHM

- * We have to find the shortest path in a directed, weighted graph b/w 2 points.
- * This is a minimisation problem + also a optimisation problem & solved by GREEDY approach.

- * It works on directed & undirected graph.
- * If there is no direct Edge from source we initially keep the distance as ∞ .

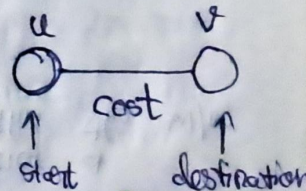
REPEATING STEP:

↑ INITIAL STEP. !

Relaxation \Rightarrow changing the distance w.r.t to the source in order to achieve the shortest path.

if ($d(u) + C(u,v) < d(v)$)
 $d(v) = d(u) + C(u,v)$

- * This is single source shortest problem.



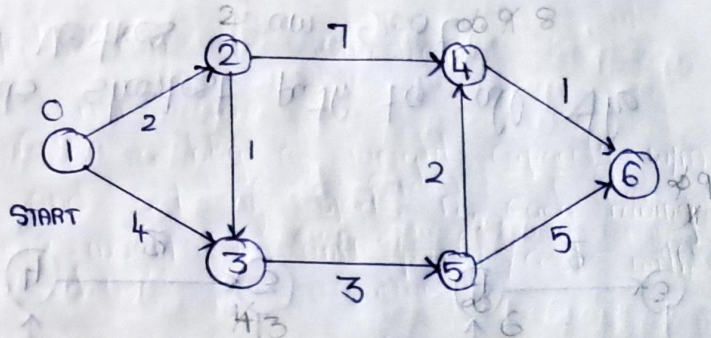
TC: $n = |V|$, no. of Vertices.

$n \times n \leftarrow$ vertices relaxed.

↑
Vertices

$\Theta(n^2) = \Theta(n)$ COMPLETE GRAPH

SHORTEST
PATH
TO ALL
VERTICES

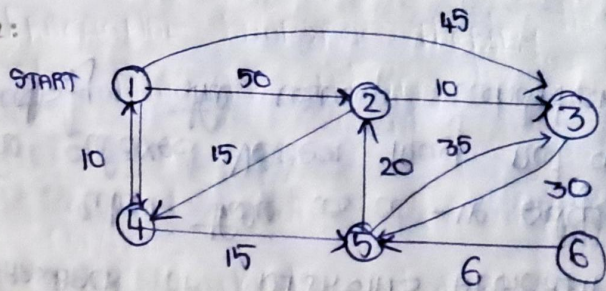


For start $V[start] = 1$

ANS:

V	2	3	4	5	6
$d[V]$	2	3	8	6	9

Eq 2:



We modify each vertex if we find the relaxation condition satisfying.

START VERTEX: 1

Smallest Value
each time.

Selected Vertex	2	3	4	5	6
Select @ $V=1$	50	45	10	∞	∞
@ $V=4$	50	45	10	25	∞
@ $V=2$	45	45	10	25	∞
@ $V=3$	45	45	10	25	∞
@ $V=6$	45	45	10	25	25

SELECTING THE SMALLEST WEIGHT

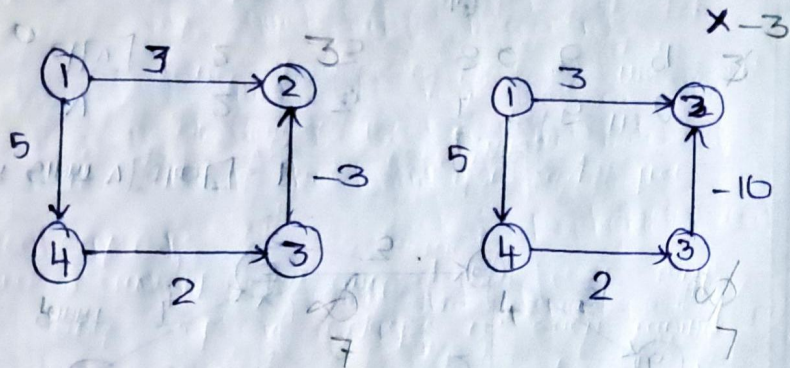
WE CAN'T REACH 6 from 1, coz we don't have a path, to reach 6.

If uncomfortable with undirected
Convert undirect $E \Rightarrow$ 2 directed anti-parallel edges.

No need to check the vertex if it is already relaxed.

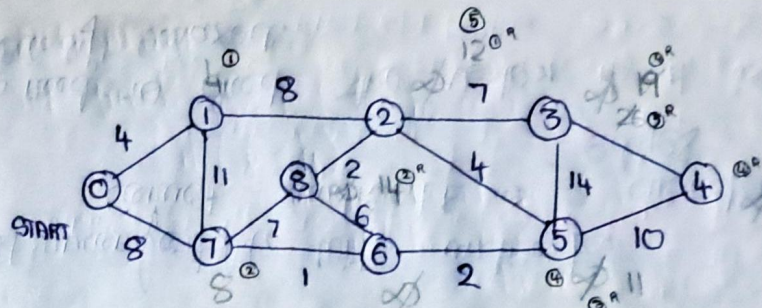
DRAWBACK OF DIJKSTRA'S ALGORITHM

When there is a -ve edge/weight the relaxed vertex may not always satisfy the usual condition



Finds shortest path to all the vertices from root.

GG has it all.



Shortest path tree
Given/taken src or root

Take a $G[V][E]$ adj matrix weighted
Visited set
Shortest path set.

Working:

Dijkstra's algorithm select a node with a shortest path and update the shortest path to other vertices

We do relaxation for the vertices, whenever we choose a shortest path we try to relax the other vertices.

Now after
making i
Compare $i+1$

\bullet

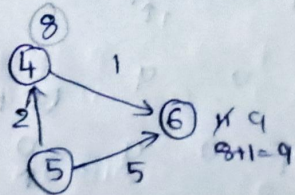
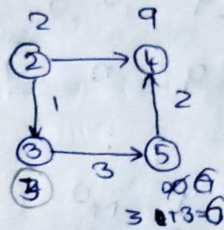
	c_5	a_6	b_7	c_8	a_9	b_{10}	a_{11}
	$\downarrow i$						

$\circ \downarrow j$

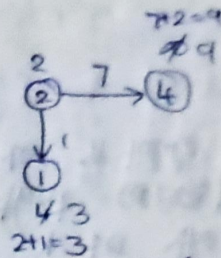
a^1	b^2	c^3	d^4	e^5			
0	0	1	2	0			

i only moved in forward direction
N times for passing through
m creating table
 $m \cdot n = O(n)$

We choose
the shortest
cut among all.



V	2	3	4	5	6
d[V]	2	3	8	6	9



Relaxation of ① + ④

