#### Sensors

#### Computational topology - group project

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### Outline

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  - Problem
  - Goals
- 2 Topological solution
  - Vietoris-Rips complex
  - Čech complex
  - Second Subsection
- Second Main Section
  - Another Subsection



# Problem description

Number of sensors on the sphere of radius 1:

- $\bullet$  each sensor gathers data from the surrounding area in the shape of a circle of radius R,
- each sensor can communicate with other sensors which are at most r away.

#### Goals

- Values of r and R are as small as possible.
- 2 The sensor network is connected.
- The sensor network covers the whole sphere.
- Remove obsolete sensors.
- Find optimal distribution of 50 sensors on sphere.

# Vietoris-Rips complex

**Connected sensor network**  $\longrightarrow$  Vietoris-Rips complex  $VR_{\delta}(S)$  is connected.

- sensors: S  $(S_i = (r_i, \phi_i, \theta_i))$ ,
- sensor connections  $\{S_i, S_j\} \subset S$ ;  $d(S_i, S_j) \leq 2\delta$ ,
- $F \subset S$  is a simplex in  $VR_{\delta}(S)$ , if diam  $F \leq 2\delta$ .

# Čech complex

The sensor network covers the whole sphere  $\longrightarrow$  Euler characteristic of Čech complex should be that of a sphere.

- sensors: S  $(S_i = (r_i, \phi_i, \theta_i))$ ,
- $B_{\delta}(x)$  closed ball with radius  $\delta$  around x,
- $\check{\mathsf{C}}_{\delta} = \{ \sigma \subset \mathsf{S}, \cap_{\mathsf{x} \in \sigma} \mathsf{B}_{\delta}(\mathsf{x}) \neq \emptyset \}.$

• First item.

- First item.
- Second item.

- First item.
- Second item.
- Third item.

- First item.
- Second item.
- Third item.
- Fourth item.

- First item.
- Second item.
- Third item.
- Fourth item.
- Fifth item.

- First item.
- Second item.
- Third item.
- Fourth item.
- Fifth item. Extra text in the fifth item.

#### **Blocks**

#### Block Title

You can also highlight sections of your presentation in a block, with it's own title

#### Theorem

There are separate environments for theorems, examples, definitions and proofs.

#### Example

Here is an example of an example block.

# Summary

- The first main message of your talk in one or two lines.
- The second main message of your talk in one or two lines.
- Perhaps a third message, but not more than that.
- Outlook
  - Something you haven't solved.
  - Something else you haven't solved.

# For Further Reading I



A. Author.

Handbook of Everything.

Some Press, 1990.



S. Someone.

On this and that.

Journal of This and That, 2(1):50-100, 2000.

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